

Feel free to work with other students, but make sure you write up the homework and code on your own (no copying homework *or* code; no pair programming). Feel free to ask students or instructors for help debugging code or whatever else, though. The starter code for problem 2 part c and d can be found under the Resource tab on course website.

Note: You need to create a Github account for submission of the coding part of the homework. Please create a repository on Github to hold all your code and include your Github account username as part of the answer to problem 2.

1 (Linear Transformation) Let $\mathbf{y} = A\mathbf{x} + \mathbf{b}$ be a random vector. show that expectation is linear:

$$\mathbb{E}[\mathbf{y}] = \mathbb{E}[A\mathbf{x} + \mathbf{b}] = A\mathbb{E}[\mathbf{x}] + \mathbf{b}.$$

Also show that

$$\text{cov}[\mathbf{y}] = \text{cov}[A\mathbf{x} + \mathbf{b}] = A\text{cov}[\mathbf{x}]A^T = A\Sigma A^T.$$

We wish to show that $\mathbb{E}[\mathbf{y}] = \mathbb{E}[A\mathbf{x} + \mathbf{b}] = A\mathbb{E}[\mathbf{x}] + \mathbf{b}$. By definition of expectation, we have

$$\mathbb{E}[\mathbf{y}] = \int_S (A\mathbf{x} + \mathbf{b})\mathbb{P}(x)dx,$$

where S is the space contains all possible x . Then, we can rearrange to get

$$\mathbb{E}[\mathbf{y}] = A \int_S \mathbf{x}\mathbb{P}(x)dx + \mathbf{b} \int_S \mathbb{P}(x)dx.$$

Note that by definition of expectation, $\mathbb{E}[\mathbf{x}] = \int_S \mathbf{x}\mathbb{P}(x)dx$. Also by definition of random variables $\int_S \mathbb{P}(x)dx = 1$. Thus, we can see that $\mathbb{E}[\mathbf{y}] = A\mathbb{E}[\mathbf{x}] + \mathbf{b}$.

Next, we wish to show that $\text{cov}[\mathbf{y}] = \text{cov}[A\mathbf{x} + \mathbf{b}] = A\text{cov}[\mathbf{x}]A^T = A\Sigma A^T$. We are given $\mathbf{y} = A\mathbf{x} + \mathbf{b}$ so that $\text{cov}[\mathbf{y}] = \text{cov}[A\mathbf{x} + \mathbf{b}]$. Then, by definition of covariance, we have $\text{cov}[A\mathbf{x} + \mathbf{b}] = \mathbb{E}[(A\mathbf{x} + \mathbf{b} - \mathbb{E}[A\mathbf{x} + \mathbf{b}])(A\mathbf{x} + \mathbf{b} - \mathbb{E}[A\mathbf{x} + \mathbf{b}])^T]$. By linearity of expectation, we can rewrite as $\text{cov}[A\mathbf{x} + \mathbf{b}] = \mathbb{E}[(A\mathbf{x} + \mathbf{b} - A\mathbb{E}[\mathbf{x}] - \mathbf{b})(A\mathbf{x} + \mathbf{b} - A\mathbb{E}[\mathbf{x}] - \mathbf{b})^T]$. Simplifying, we get $\text{cov}[A\mathbf{x} + \mathbf{b}] = \mathbb{E}[(A\mathbf{x} - A\mathbb{E}[\mathbf{x}])(A(\mathbf{x} - \mathbb{E}[\mathbf{x}]))^T]$. Applying transpose in the second term inside expectation, we get $\text{cov}[A\mathbf{x} + \mathbf{b}] = \mathbb{E}[(A\mathbf{x} - A\mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^T A^T]$. Since A and A^T are constants, by linearity, we have $\text{cov}[A\mathbf{x} + \mathbf{b}] = A\mathbb{E}[(\mathbf{x} - A\mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^T]A^T$. Lastly, by definition of covariance, we see $\text{cov}[A\mathbf{x} + \mathbf{b}] = A\text{cov}[\mathbf{x}]A^T = A\Sigma A^T$ as desired. ■

2 Given the dataset $\mathcal{D} = \{(x, y)\} = \{(0, 1), (2, 3), (3, 6), (4, 8)\}$

- (a) Find the least squares estimate $y = \theta^\top \mathbf{x}$ by hand using Cramer's Rule.
- (b) Use the normal equations to find the same solution and verify it is the same as part (a).
- (c) Plot the data and the optimal linear fit you found.
- (d) Find randomly generate 100 points near the line with white Gaussian noise and then compute the least squares estimate (using a computer). Verify that this new line is close to the original and plot the new dataset, the old line, and the new line.

(a) Let

$$X = \begin{bmatrix} 1 & 0 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \text{ and } \mathbf{y} = \begin{bmatrix} 1 \\ 3 \\ 6 \\ 8 \end{bmatrix}.$$

To find the least square estimate using Cramer's Rule, we need to set $X^T X \theta = X^T \mathbf{y}$ where $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$. Plugging in, we get

$$X^T X \theta = \begin{bmatrix} 4 & 9 \\ 9 & 29 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = X^T \mathbf{y} = \begin{bmatrix} 18 \\ 56 \end{bmatrix}.$$

Next, we apply Cramer's Rule to solve for θ_0 and θ_1 .

$$\theta_0 = \frac{\begin{vmatrix} 18 & 9 \\ 56 & 29 \end{vmatrix}}{\begin{vmatrix} 4 & 9 \\ 9 & 29 \end{vmatrix}} = \frac{18}{35} \text{ and } \theta_1 = \frac{\begin{vmatrix} 4 & 18 \\ 9 & 56 \end{vmatrix}}{\begin{vmatrix} 4 & 9 \\ 9 & 29 \end{vmatrix}} = \frac{62}{35}$$

Thus, for the given dataset, we found the least square estimate is $y = \frac{18}{35} + \frac{62}{35}x$ using Cramer's Rule

(b) Using the normal equation we can solve for θ using the following formula,

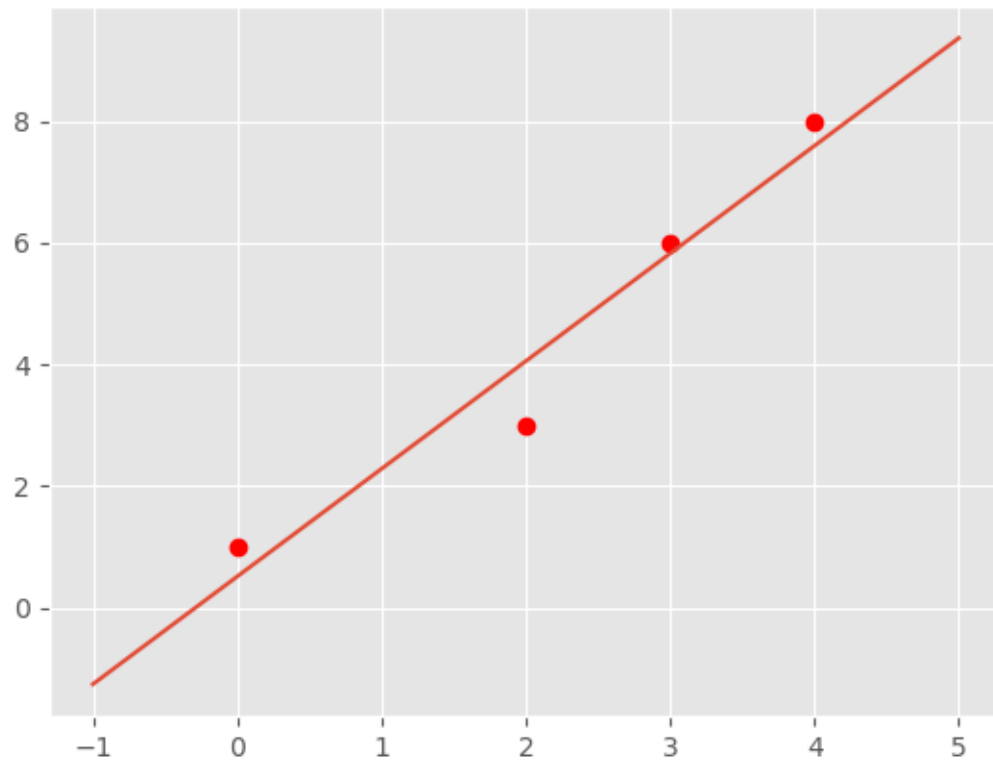
$$\theta = (X^T X)^{-1} X^T \mathbf{y}.$$

Then, we can plug in values from part a and evaluate,

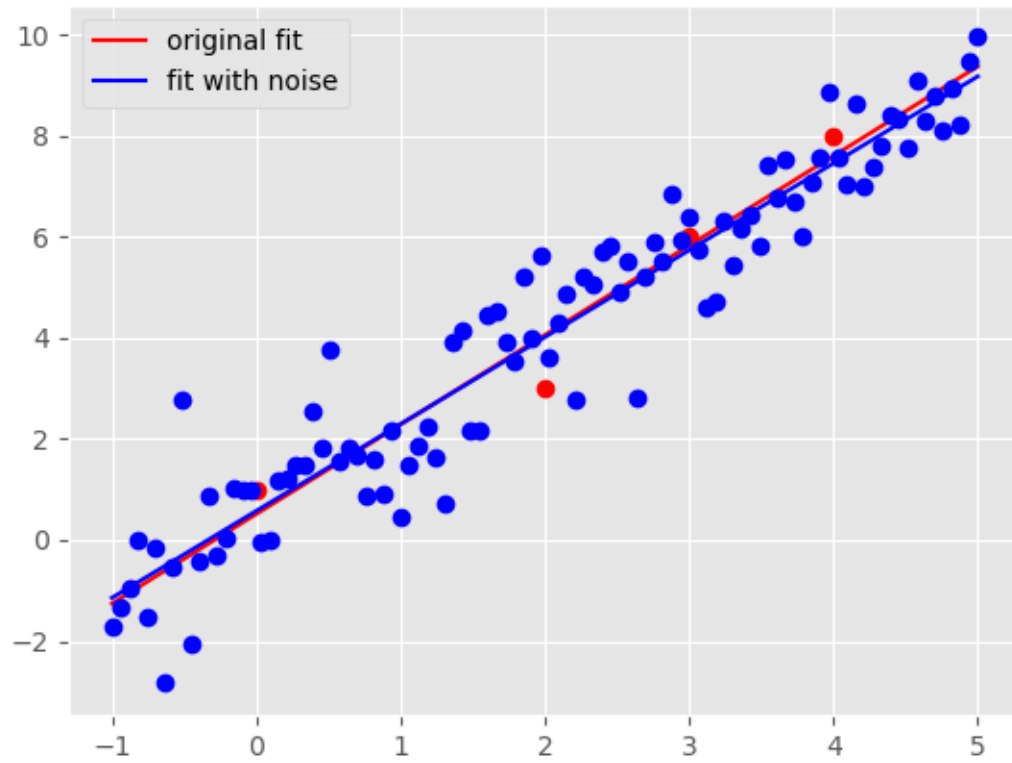
$$\theta = \begin{bmatrix} 4 & 9 \\ 9 & 29 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 6 \\ 8 \end{bmatrix} = \begin{bmatrix} \frac{18}{35} \\ \frac{62}{35} \end{bmatrix}.$$

Thus, we see that the solution using the normal equation is the same as using Cramer's rule as in part a.

(c) Plotted data and optimal linear fit.



- (d) Plotted data with Gaussian noise and new least square estimate. Note that the new line is close to the old line.



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