

Appendix S2: Code for Application 3.2 seals

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Load required R packages

```
require(tidyverse)
require(ggspatial)
require(ggforce)
require(patchwork)
require(sf)
require(foieGras)
```

Fit mp SSM with 12-h time.step to infer movement persistence along 4 southern elephant seal tracks

```
## Load data from .csv file
sese <- read.csv("../data/sese_ex32.csv")

## fit `mp` SSM, using speed filter of 4 m/s to exclude extreme observations
fit <- fit_ssm(sese, vmax=4, model="mp", time.step=12)
```

Plot move persistence estimates as time-series, 1 panel per seal

```
## Normalise the gamma_t estimates so they span the interval 0, 1, grouping all
## seals together so estimates are comparable among seals.
p1 <- plot(fit,
           type = 3,
           pages = 1,
           ncol = 2,
           normalise = TRUE,
           group = TRUE,
           pal = "Plasma") &
ylim(0, 1) &
theme(legend.position = "none",
      axis.text = element_text(size = 7))
```

Map move persistence estimates along the SSM-estimated seal tracks

```
## customise mapping aesthetics
my.aes <- aes_lst(conf = FALSE,
                  line = TRUE)
my.aes$df$size[1] <- 1.5
my.aes$df$size[3] <- 0.1
my.aes$df$col[3] <- grey(0.3)
```

```

my.aes$df$fill[5] <- grey(0.4)
my.aes$df$fill[6] <- grey(0.6)

## project map, add scale bar using ggspatial::annotation_scale
m1 <- map(fit,
  what = "p",
  aes = my.aes,
  crs = "+proj=stere +lon_0=95 +units=km +datum=WGS84 +no_defs",
  normalise = TRUE,
  group = TRUE,
  silent = TRUE) +
  xlab(element_blank()) +
  ylab(element_blank()) +
  ggspatial::annotation_scale(height = unit(1.25, "mm"),
    aes(width_hint = 0.2,
      location = "br",
      text_col = "white")) +
  theme(legend.position = c(0.95,0.5),
    legend.direction = "vertical",
    legend.key.width = unit(4, "mm"),
    legend.key.height = unit(7, "mm"),
    legend.title = element_text(size = 9),
    legend.text = element_text(size = 7),
    axis.text = element_text(size = 7),
    panel.grid = element_line(colour = "white"))

## define bounding box based on SSM-predicted locations - for map annotations
bb <- grab(fit, what = "p", as_sf = TRUE) %>%
  sf::st_transform(., crs = m1$coordinates$crs) %>%
  sf::st_bbox()

## create track labels & highlight circles for map annotations
label.df <- data.frame(tag = c("a","b","c","d"),
  x = c(0.75, 0.9, 0.19, 0.53) *
    (bb["xmax"] - bb["xmin"]) + bb["xmin"],
  y = c(0.32, 0.75, 0.2, 0.25) *
    (bb["ymax"] - bb["ymin"]) + bb["ymin"])
circle.df <- data.frame(x = c(0.25, 0.365, 0.485, 0.71) *
  (bb["xmax"] - bb["xmin"]) + bb["xmin"],
  y = c(0.11, 0.19, 0.24, 0.26) *
    (bb["ymax"] - bb["ymin"]) + bb["ymin"],
  r = c(125,125,125,145)
)

## add track labels & highlight circles to map
m1 <- m1 +
  geom_text(data = label.df,
    aes(x, y, label=tag),
    size = 3) +
  ggforce::geom_circle(aes(x0 = circle.df$x, y0 = circle.df$y, r = circle.df$r),
    fill = NA,
    size = 0.8,
    colour = "dodgerblue")

```

```
## arrange panels & render Figure 2 using the `patchwork` package
(p1 | m1) +
  patchwork::plot_layout(nrow = 2,
    heights = c(2, 5),
    guides = "keep") +
  patchwork::plot_annotation(tag_levels = "a") &
  theme(plot.title = element_blank(),
    plot.tag = element_text(size = 9, colour = "black"))
```