# Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the <u>assignments page</u> (<a href="https://compsci697l.github.io/assignments.html">https://compsci697l.github.io/assignments.html</a>) on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

#### In [1]:

```
import random
import numpy as np
from asgn1.data_utils import load_CIFAR10
import matplotlib.pyplot as plt
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading extenrnal modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

## Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

In [2]:

```
from asgn1.features import color histogram hsv, hog feature
def get CIFAR10 data(num training=49000, num validation=1000, num test=1000):
  # Load the raw CIFAR-10 data
  cifar10 dir = 'datasets/cifar-10-batches-py'
  X train, y train, X test, y test = load CIFAR10(cifar10 dir)
  # Subsample the data
  mask = range(num training, num training + num validation)
 X val = X train[mask]
  y val = y train[mask]
  mask = range(num training)
 X_{train} = X_{train}[mask]
  y train = y train[mask]
  mask = range(num test)
  X \text{ test} = X \text{ test[mask]}
  y test = y test[mask]
  return X train, y train, X val, y val, X test, y test
X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
```

### **Extract Features**

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for the bonus section.

The hog\_feature and color\_histogram\_hsv functions both operate on a single image and return a feature vector for that image. The extract\_features function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each row is the concatenation of all feature vectors for a single image.

#### In [36]:

```
from asgn1.features import *
num color bins = 20 # Number of bins in the color histogram
feature fns = [hog feature, lambda img: color histogram hsv(img, nbin=num color bin
X train feats = extract features(X train, feature fns, verbose=True)
X val feats = extract features(X val, feature fns)
X test feats = extract features(X test, feature fns)
# Preprocessing: Subtract the mean feature
mean feat = np.mean(X train feats, axis=0, keepdims=True)
X train feats -= mean feat
X val feats -= mean feat
X test feats -= mean feat
# Preprocessing: Divide by standard deviation. This ensures that each feature
# has roughly the same scale.
std feat = np.std(X train feats, axis=0, keepdims=True)
X train feats /= std feat
X val feats /= std feat
X test feats /= std feat
# Preprocessing: Add a bias dimension
X train feats = np.hstack([X train feats, np.ones((X train feats.shape[0], 1))])
X val feats = np.hstack([X val feats, np.ones((X val feats.shape[0], 1))])
X test feats = np.hstack([X test feats, np.ones((X test feats.shape[0], 1))])
Done extracting features for 1000 / 49000 images
Done extracting features for 2000 / 49000 images
Done extracting features for 3000 / 49000 images
Done extracting features for 4000 / 49000 images
Done extracting features for 5000 / 49000 images
Done extracting features for 6000 / 49000 images
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```

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## **Train SVM on features**

Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

In [44]:

```
# Use the validation set to tune the learning rate and regularization strength
from asgn1.classifiers.linear_classifier import LinearSVM
learning rates = [1e-9, 1e-8, 1e-7]
regularization strengths = [1e6, 1e7]
results = \{\}
best_val = -1
best svm = None
for i in learning_rates:
   for j in regularization strengths:
       svm=LinearSVM()
      loss hist = svm.train(X train feats, y train, learning rate=i, reg=j,
                  num iters=5000, verbose=True)
      y train pred = svm.predict(X train feats)
      y val pred = svm.predict(X val feats)
       results[i,j]=[np.mean(y train == y train pred),np.mean(y val == y val pred)
      print np.mean(y val == y val pred)
      if (np.mean(y_val == y_val_pred))>best_val:
          best val=np.mean(y val == y val pred)
          best svm=svm
print results
# TOD0:
                                                                    #
# Use the validation set to set the learning rate and regularization strength.
                                                                    #
# This should be identical to the validation that you did for the SVM; save
                                                                    #
# the best trained classifer in best svm. You might also want to play
                                                                    #
# with different numbers of bins in the color histogram. If you are careful
                                                                    #
# you should be able to get accuracy of near 0.44 on the validation set.
                                                                    #
END OF YOUR CODE
#
# Print out results.
for lr, reg in sorted(results):
   train accuracy, val accuracy = results[(lr, reg)]
   print 'lr %e reg %e train accuracy: %f val accuracy: %f' % (
             lr, reg, train_accuracy, val_accuracy)
print 'best validation accuracy achieved during cross-validation: %f' % best_val
iteration 0 / 5000: loss 814.040786
iteration 100 / 5000: loss 668.052533
iteration 200 / 5000: loss 548.535087
iteration 300 / 5000: loss 450.686267
iteration 400 / 5000: loss 370.584043
iteration 500 / 5000: loss 305.017112
iteration 600 / 5000: loss 251.327452
iteration 700 / 5000: loss 207.389355
iteration 800 / 5000: loss 171.402248
iteration 900 / 5000: loss 141.955037
iteration 1000 / 5000: loss 117.837085
iteration 1100 / 5000: loss 98.100998
iteration 1200 / 5000: loss 81.943173
iteration 1300 / 5000: loss 68.717304
```

```
iteration 1400 / 5000: loss 5/.884304
iteration 1500 / 5000: loss 49.022306
iteration 1600 / 5000: loss 41.758700
iteration 1700 / 5000: loss 35.821340
iteration 1800 / 5000: loss 30.957831
```

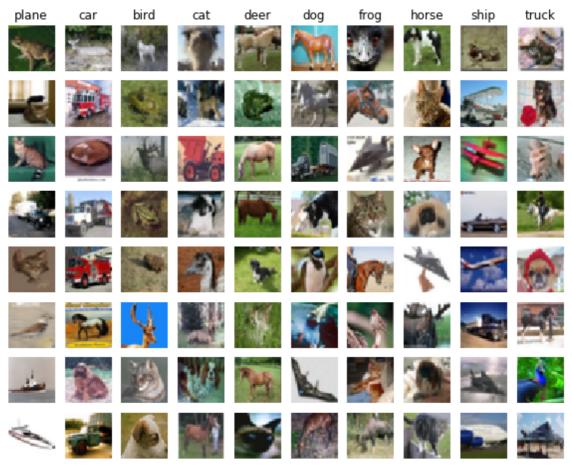
#### In [29]:

```
# Evaluate your trained SVM on the test set
y_test_pred = best_svm.predict(X_test_feats)
test_accuracy = np.mean(y_test == y_test_pred)
print test_accuracy
```

0.429

#### In [9]:

```
# An important way to gain intuition about how an algorithm works is to
# visualize the mistakes that it makes. In this visualization, we show examples
# of images that are misclassified by our current system. The first column
# shows images that our system labeled as "plane" but whose true label is
# something other than "plane".
examples per class = 8
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship',
for cls, cls name in enumerate(classes):
    idxs = np.where((y test != cls) & (y test pred == cls))[0]
    idxs = np.random.choice(idxs, examples per class, replace=False)
    for i, idx in enumerate(idxs):
        plt.subplot(examples_per_class, len(classes), i * len(classes) + cls + 1)
        plt.imshow(X test[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls name)
plt.show()
```



# **Inline question 1:**

Describe the misclassification results that you see. Do they make sense?

# **Neural Network on image features**

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

In [10]:

print X\_train\_feats.shape

(49000, 155)

In [16]:

```
from asgn1.classifiers.neural net import TwoLayerNet
input dim = X train feats.shape[1]
hidden dim = 500
num classes = 10
learning rates=np.logspace(-10, 0, 5)
regularization strengths = np.logspace(-3, 5, 5)
net = TwoLayerNet(input dim, hidden dim, num classes)
best net = None
input size = 32 * 32 * 3
for i in learning rates:
   for j in regularization strengths:
       stats = net.train(X train feats, y train, X val feats, y val,
                           num iters=1600, batch size=200,
                           learning rate=i, learning rate decay=0.95,
                               reg=j, verbose=True)
      y train pred = net.predict(X train feats)
      y val pred = net.predict(X val feats)
       results[i,j]=[np.mean(y_train == y_train_pred),np.mean(y_val == y_val_pred)
      print np.mean(y val == y val pred)
      if (np.mean(y val == y val pred))>best val:
          best val=np.mean(y val == y val pred)
          best net=net
print results
# TODO: Train a two-layer neural network on image features. You may want to
# cross-validate various parameters as in previous sections. Store your best
                                                                   #
# model in the best net variable.
                                                                   #
END OF YOUR CODE
iteration 0 / 1600: loss 2.302585
iteration 100 / 1600: loss 2.302586
iteration 200 / 1600: loss 2.302586
iteration 300 / 1600: loss 2.302586
iteration 400 / 1600: loss 2.302586
iteration 500 / 1600: loss 2.302586
iteration 600 / 1600: loss 2.302585
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iteration 1400 / 1600: loss 2.302586
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0.103
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iteration 100 / 1600: loss 2.302626
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