

# Bridging Python and Julia

## for Enhanced Data Analysis

Ianna Osborne

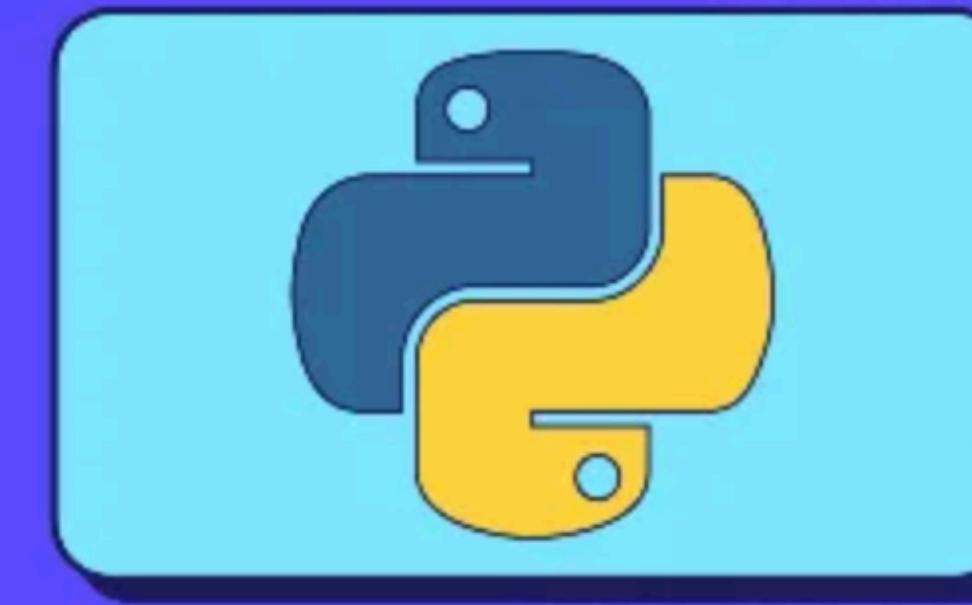
# Why Python is so popular for data analysis

- Simple and easy to understand syntax
- Rich ecosystem of libraries tailored for data analysis
- Versatile, integrates well with other languages and tools
- Vast and active community
- Various programming paradigms support, including procedural, object-oriented, and functional programming
- Jupyter notebooks as an interactive environment where users can combine code execution, visualization, and narrative text
- Scalability and performance

# Key features of Julia

## from a data scientist's perspective

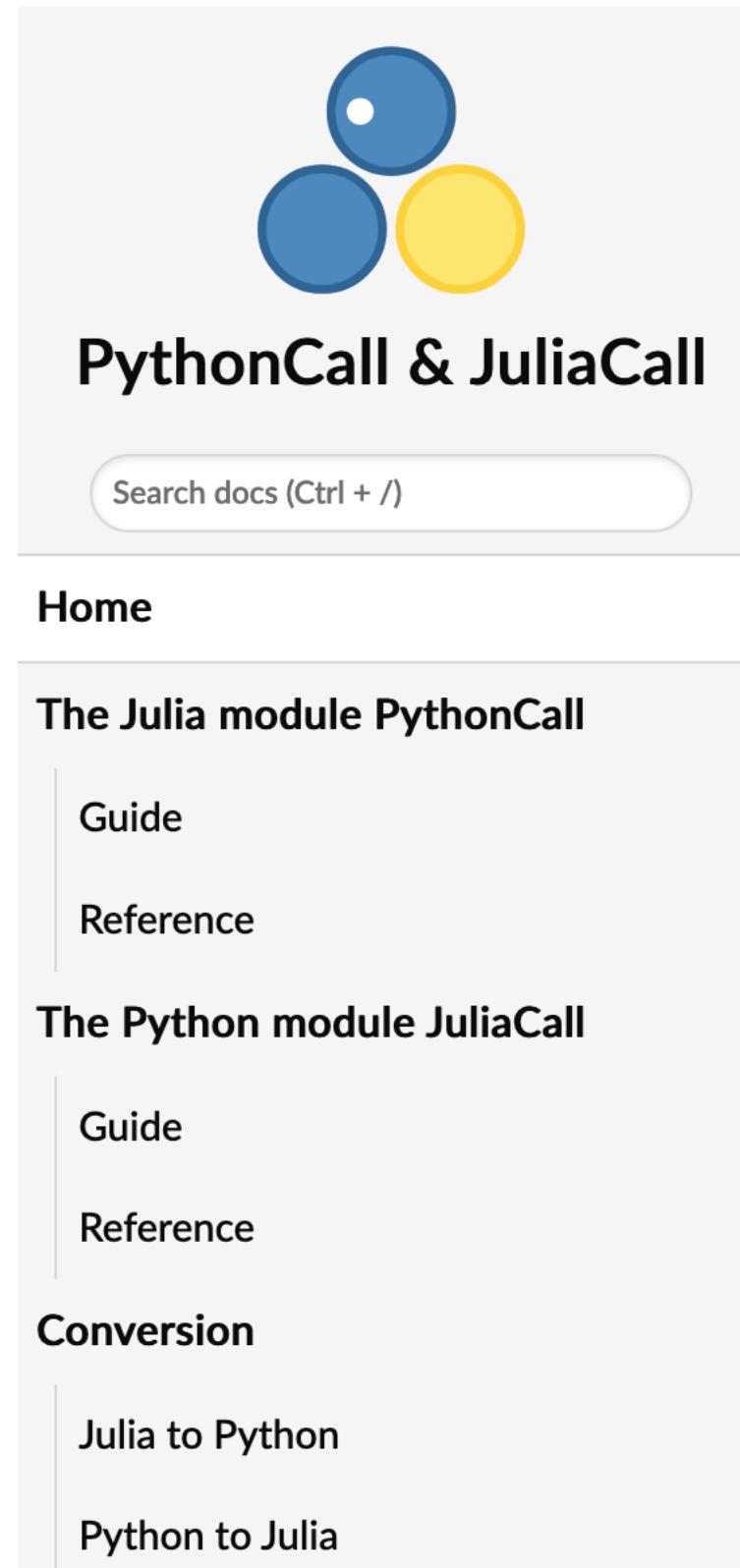
- Speed of code execution
- Designed for interactive use
- Composability, leading to highly reusable code that is easy to maintain
- Package management
- Ease of integration with other languages



**JULIA VS. PYTHON: A COMPREHENSIVE COMPARISON**

Factor	<b>Julia</b>	<b>Python</b>
Maturity	Recent, created in 2012	Established, created in 1991
Scope	General purpose, but data-oriented	General purpose and used for almost anything
Language type	High level	High level
Typing	Dynamic and static	Dynamic
Open-source	Yes	Yes
Implementation	Compiled	Interpreted
<b>Usage</b>	<b>Data science and machine learning</b> , expanding to other areas	Mobile/web development, AI, data science, web scripting, desktop GUI development, game development
<b>Data science</b>	<b>Math functions are easy to write and understand</b> without external libraries	Requires Numoy or other libraries for advanced math
Community	Small but strong in the science community, continuously growing	Large, with more libraries and support
Performance	High-speed runtime, ideal for handling millions of data threads	Slower for production compare to Julia
Libraries	Growing library sources, but not as extensive as Python	Extensive library sources for code and application development
Code conversion	Easier to convert code from other language codes	More difficult to convert code from other languages
Popularity and community	Smaller, rapidly growing community and a majority support from developers themselves	Large, established community offering extensive support and solutions
Speed	Compiled language, often as fast as C, excellent for data analysis and statistical computing	Interpreted language, slower than Julia, relies on libraries for speed
Libraries	Limited collection, some packages not well maintained, ut expected to grow	Extensive range, supported by numerous third-party libraries
Code conversion	Straightforward process for converting code from other languages	More difficult than Julia, but possible through modules like PyCall
Linear algebra	Built for statistics and machine learning with methods easy to implement, syntax similar to math expressions	Requires libraries like Numpy, which is not as straightforward as Julia

# PythonCall and JuliaCall



The screenshot shows the homepage of the PythonCall & JuliaCall documentation. The header features a logo of three overlapping circles (blue, blue, yellow) and the text "PythonCall & JuliaCall". Below the header is a search bar with the placeholder "Search docs (Ctrl + /)". The main content area has a title "PythonCall & JuliaCall" and a subtitle "Bringing Python® and Julia together in seamless harmony:". A bulleted list details the module's features, including calling code between languages, simple syntax, and fast array conversion. Navigation links on the left side include "Home", "The Julia module PythonCall" (with "Guide" and "Reference" sub-links), "The Python module JuliaCall" (with "Guide" and "Reference" sub-links), and "Conversion" (with "Julia to Python" and "Python to Julia" sub-links).

conda install conda-forge::pyjuliacall

- PythonCall & JuliaCall allow to call Python code from Julia and Julia code from Python via a symmetric interface.
- Using PythonCall to bring Python functions and libraries into Julia
- Embed Julia code right into our Python scripts using JuliaCall

# JuliaPkg

## What if Julia is not installed?

- JuliaCall relies on JuliaPkg to discover and install Julia
- JuliaCall uses JuliaUp (which uses the default depot) IF it is already installed - you need to install it manually.  
Otherwise JuliaCall will download and install Julia directly into your Python environment, but still using the default depot

```
In [2]: import awkward as ak
         from juliacall import Main as jl

         jl.seval("using AwkwardArray")

[juliapkg] Found dependencies: /usr/local/lib/python3.10/site-packages/awkward/juliapkg.json
[juliapkg] Found dependencies: /usr/local/lib/python3.10/site-packages/juliacall/juliapkg.json
[juliapkg] Found dependencies: /usr/local/lib/python3.10/site-packages/juliapkg/juliapkg.json
[juliapkg] Locating Julia ~1.9, =1.10.0, ^1.10.3
[juliapkg] Querying Julia versions from https://julialang-s3.julialang.org/bin/versions.json
[juliapkg] WARNING: About to install Julia 1.10.4 to /home/cms-jovyan/.julia/environments/pyjuliapkg/pyjuliapkg/install.
[juliapkg] If you use juliapkg in more than one environment, you are likely to
[juliapkg] have Julia installed in multiple locations. It is recommended to
[juliapkg] install JuliaUp (https://github.com/JuliaLang/juliaup) or Julia
[juliapkg] (https://julialang.org/downloads) yourself.
[juliapkg] Downloading Julia from https://julialang-s3.julialang.org/bin/linux/x64/1.10/julia-1.10.4-linux-x86\_64.tar.gz
[juliapkg] download complete
[juliapkg] Verifying download
```

# Julia Package Manager

## a built-in state-of-the-art package manager

```
1  name = "AwkwardArray"
2  uuid = "7d259134-7f60-4bf1-aa00-7452e11bde56"
3  authors = ["Jim Pivarski <pivarski@princeton.edu>", "Jerry Ling <jerry.ling@cern.ch>", "and contributors"]
4  version = "0.1.5"

5
6  [deps]
7  Conda = "8f4d0f93-b110-5947-807f-2305c1781a2d"
8  JSON = "682c06a0-de6a-54ab-a142-c8b1cf79cde6"
9  PythonCall = "6099a3de-0909-46bc-b1f4-468b9a2dfc0d"
10 Tables = "bd369af6-aec1-5ad0-b16a-f7cc5008161c"

11
12 [compat]
13 Conda = "1.10.0"
14 JSON = "0.21.4"
15 PythonCall = "0.9"
16 Tables = "1.11.1"
17 julia = "1.9"

18
19 [extras]
20 Test = "8dfed614-e22c-5e08-85e1-65c5234f0b40"

21
22 [targets]
23 test = ["Test"]
```

- Package manager manages the computational environment state
- To fully specify the state of your Julia environment, it is enough to share **Project.toml** that uniquely identifies the package versions
- Automatically re-create the entire configuration of the runtime environment: ensures the reproducibility
- Resolves the common problem of managing dependencies of code written in other languages

# Best Practices for Managing Dependencies

## and keeping everything running smoothly

- JuliaUp is a recommended way to install Julia



```
curl -fsSL https://install.julialang.org | sh
```



yana -- zsh -- 115x36

Last login: Sun Aug 25 07:56:24 on ttys009  
(base) yana@Iannas-MacBook-Pro-2 ~ %



Last login: Sun Aug 25 07:56:24 on ttys009

(base) yana@Iannas-MacBook-Pro-2 ~ % curl -fsSL https://install.julialang.org | sh█



Last login: Sun Aug 25 07:56:24 on ttys009  
(base) yana@Iannas-MacBook-Pro-2 ~ % curl -fsSL https://install.julialang.org | sh

**info:** downloading installer  
**Welcome to Julia!**

This will download and install the official Julia Language distribution  
and its version manager Juliaup.

Juliaup will be installed into the Juliaup home directory, located at:

/Users/yana/.juliaup

The **julia**, **juliaup** and other commands will be added to  
Juliaup's bin directory, located at:

/Users/yana/.juliaup/bin

This path will then be added to your **PATH** environment variable by  
modifying the profile files located at:

/Users/yana/.profile  
/Users/yana/.bash\_profile  
/Users/yana/.zshrc

Julia will look for a new version of Juliaup itself every 1440 minutes when you start **julia**.

You can uninstall at any time with **juliaup self uninstall** and these  
changes will be reverted.

? Do you want to install with these default configuration choices? >  
❯ Proceed with installation  
Customize installation  
Cancel installation



Juliaup will be installed into the Juliaup home directory, located at:

/Users/yana/.juliaup

The **julia**, **juliaup** and other commands will be added to Juliaup's bin directory, located at:

/Users/yana/.juliaup/bin

This path will then be added to your **PATH** environment variable by modifying the profile files located at:

/Users/yana/.profile  
/Users/yana/.bash\_profile  
/Users/yana/.zshrc

Julia will look for a new version of Juliaup itself every 1440 minutes when you start julia.

You can uninstall at any time with **juliaup self uninstall** and these changes will be reverted.

✓ **Do you want to install with these default configuration choices?** · Proceed with installation

Now installing Juliaup

**Installing** Julia 1.10.4+0.x64.apple.darwin14  
Configured the default Julia version to be 'release'.  
Julia was successfully installed on your system.

Depending on which shell you are using, run one of the following commands to reload the **PATH** environment variable:

- /Users/yana/.profile
- /Users/yana/.bash\_profile
- /Users/yana/.zshrc



Juliaup will be installed into the Juliaup home directory, located at:

/Users/yana/.juliaup

The **julia**, **juliaup** and other commands will be added to Juliaup's bin directory, located at:

/Users/yana/.juliaup/bin

This path will then be added to your **PATH** environment variable by modifying the profile files located at:

/Users/yana/.profile  
/Users/yana/.bash\_profile  
/Users/yana/.zshrc

Julia will look for a new version of Juliaup itself every 1440 minutes when you start julia.

You can uninstall at any time with **juliaup self uninstall** and these changes will be reverted.

✓ **Do you want to install with these default configuration choices?** · Proceed with installation

Now installing Juliaup

**Installing** Julia 1.10.4+0.x64.apple.darwin14

Configured the default Julia version to be 'release'.

Julia was successfully installed on your system.

Depending on which shell you are using, run one of the following commands to reload the **PATH** environment variable:

- /Users/yana/.profile
- /Users/yana/.bash\_profile
- /Users/yana/.zshrc

```
# >>> juliaup initialize >>>
# !! Contents within this block are managed by juliaup !!
path=('/Users/yana/.juliaup/bin' $path)
export PATH

# <<< juliaup initialize <<<
```

(base) yana@Iannas-MacBook-Pro-2 ~ % . /Users/yana/.zshrc

(base) yana@Iannas-MacBook-Pro-2 ~ % juliaup list

Channel	Version
0	0.7.0+0.x64.apple.darwin14
0.7	0.7.0+0.x64.apple.darwin14
0.7.0	0.7.0+0.x64.apple.darwin14
0.7.0~x64	0.7.0+0.x64.apple.darwin14
0.7~x64	0.7.0+0.x64.apple.darwin14
0~x64	0.7.0+0.x64.apple.darwin14
1	1.10.4+0.x64.apple.darwin14
1.0	1.0.5+0.x64.apple.darwin14
1.0.0	1.0.0+0.x64.apple.darwin14
1.0.0~x64	1.0.0+0.x64.apple.darwin14
1.0.1	1.0.1+0.x64.apple.darwin14
1.0.1~x64	1.0.1+0.x64.apple.darwin14
1.0.2	1.0.2+0.x64.apple.darwin14
1.0.2~x64	1.0.2+0.x64.apple.darwin14
1.0.3	1.0.3+0.x64.apple.darwin14
1.0.3~x64	1.0.3+0.x64.apple.darwin14
1.0.4	1.0.4+0.x64.apple.darwin14
1.0.4~x64	1.0.4+0.x64.apple.darwin14
1.0.5	1.0.5+0.x64.apple.darwin14
1.0.5~x64	1.0.5+0.x64.apple.darwin14
1.0~x64	1.0.5+0.x64.apple.darwin14
1.1	1.1.1+0.x64.apple.darwin14
1.1.0	1.1.0+0.x64.apple.darwin14
1.1.0~x64	1.1.0+0.x64.apple.darwin14
1.1.1	1.1.1+0.x64.apple.darwin14
1.1.1~x64	1.1.1+0.x64.apple.darwin14
1.3.1~x64	1.3.1+0.x64.apple.darwin14
1.4.1~x64	1.4.1+0.x64.apple.darwin14
1.4.2~x64	1.4.2+0.x64.apple.darwin14
1.6.0	1.6.0+0.x64.apple.darwin14
1.6.0-beta1~x64	1.6.0-beta1+0.x64.apple.darwin14
1.6.0-rc2	1.6.0-rc2+0.x64.apple.darwin14

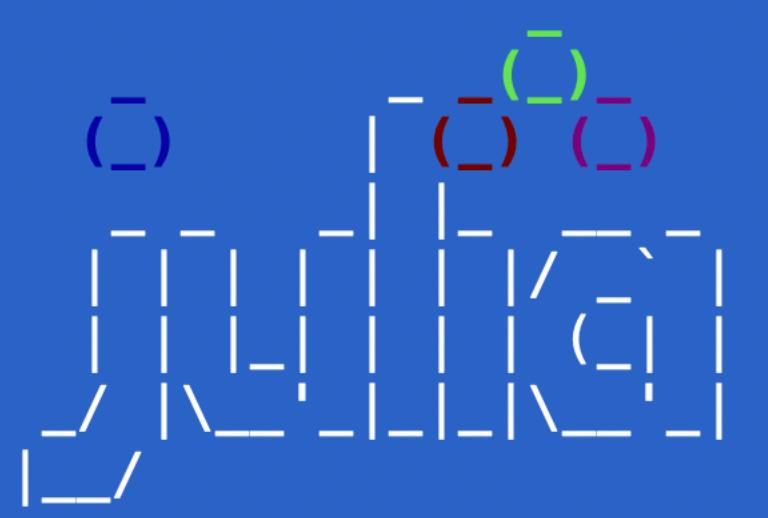
```
(base) yana@Iannas-MacBook-Pro-2 ~ % . /Users/yana/.zshrc
```

```
(base) yana@Iannas-MacBook-Pro-2 ~ % juliaup list
```

Channel	Version
0	0.7.0+0.x64.apple.darwin14
0.7	0.7.0+0.x64.apple.darwin14
0.7.0	0.7.0+0.x64.apple.darwin14
0.7.0~x64	0.7.0+0.x64.apple.darwin14
0.7~x64	0.7.0+0.x64.apple.darwin14
0~x64	0.7.0+0.x64.apple.darwin14
1	1.10.4+0.x64.apple.darwin14
1.0	1.0.5+0.x64.apple.darwin14
1.0.0	1.0.0+0.x64.apple.darwin14
1.0.0~x64	1.0.0+0.x64.apple.darwin14
1.0.1	1.0.1+0.x64.apple.darwin14
1.0.1~x64	1.0.1+0.x64.apple.darwin14
1.0.2	1.0.2+0.x64.apple.darwin14
1.0.2~x64	1.0.2+0.x64.apple.darwin14
1.0.3	1.0.3+0.x64.apple.darwin14
1.0.3~x64	1.0.3+0.x64.apple.darwin14
1.0.4	1.0.4+0.x64.apple.darwin14
1.0.4~x64	1.0.4+0.x64.apple.darwin14
1.0.5	1.0.5+0.x64.apple.darwin14
1.0.5~x64	1.0.5+0.x64.apple.darwin14
1.0~x64	1.0.5+0.x64.apple.darwin14
1.1	1.1.1+0.x64.apple.darwin14
1.1.0	1.1.0+0.x64.apple.darwin14
1.1.0~x64	1.1.0+0.x64.apple.darwin14
1.1.1	1.1.1+0.x64.apple.darwin14
1.1.1~x64	1.1.1+0.x64.apple.darwin14
1.3.1~x64	1.3.1+0.x64.apple.darwin14
1.4.1~x64	1.4.1+0.x64.apple.darwin14
1.4.2~x64	1.4.2+0.x64.apple.darwin14
1.6.0	1.6.0+0.x64.apple.darwin14
1.6.0-beta1~x64	1.6.0-beta1+0.x64.apple.darwin14
1.6.0-rc2	1.6.0-rc2+0.x64.apple.darwin14

```
(base) yana@Iannas-MacBook-Pro-2 ~ % juliaup update
```

```
(base) yana@Iannas-MacBook-Pro-2 ~ % julia
```

julia>  Documentation: <https://docs.julialang.org>  
Type "?" for help, "]??" for Pkg help.  
Version 1.10.4 (2024-06-04)  
Official <https://julialang.org/> release

# Practical Examples

where mixing Python and Julia really shines

```
[1]: import awkward as ak
      import numpy as np
      import matplotlib.pyplot as plt
```

# Practical Examples

where mixing Python and Julia really shines

```
[1]: import awkward as ak
      import numpy as np
      import matplotlib.pyplot as plt
```

```
[2]: from juliacall import Main as jl
      from juliacall import Pkg
```

Detected IPython. Loading juliacall extension. See <https://juliapy.github.io/PythonCall.jl/stable/compat/#IPython>

# Practical Examples

## where mixing Python and Julia really shines

```
[3]: Pkg.add('AwkwardArray')
```

```
Updating registry at `~/.julia/registries/General.toml`
Resolving package versions...
Updating `~/anaconda3/julia_env/Project.toml`
[7d259134] + AwkwardArray v0.1.5
Updating `~/anaconda3/julia_env/Manifest.toml`
[7d259134] + AwkwardArray v0.1.5
[8f4d0f93] + Conda v1.10.2
[682c06a0] + JSON v0.21.4
[81def892] + VersionParsing v1.3.0
```

# Practical Examples

## where mixing Python and Julia really shines

```
[3]: Pkg.add('AwkwardArray')
```

```
Updating registry at `~/.julia/registries/General.toml`
Resolving package versions...
Updating `~/anaconda3/julia_env/Project.toml`
[7d259134] + AwkwardArray v0.1.5
Updating `~/anaconda3/julia_env/Manifest.toml`
[7d259134] + AwkwardArray v0.1.5
[8f4d0f93] + Conda v1.10.2
[682c06a0] + JSON v0.21.4
[81def892] + VersionParsing v1.3.0
```

```
[4]: jl.seval("using AwkwardArray")
```

# Practical Examples

## where mixing Python and Julia really shines

```
[5]: Pkg.add('ForwardDiff')
```

Resolving package versions...

No Changes to `~/anaconda3/julia\_env/Project.toml`

No Changes to `~/anaconda3/julia\_env/Manifest.toml`

```
[6]: jl.seval("using ForwardDiff")
```

```
[7]: jl.seval('g(x) = x * exp(-x) / (x^2 + 1) * sin(pi * x)')
```

```
jl.seval('g1(x) = ForwardDiff.derivative(g, x)')
```

```
jl.seval('g2(x) = ForwardDiff.derivative(g1, x)')
```

```
jl.seval('g3(x) = ForwardDiff.derivative(g2, x)')
```

```
[7]: g3 (generic function with 1 method)
```

# Practical Examples

where mixing Python and Julia really shines

```
[8]: def taylor(x, a):
    return jl.g(a) + \
        jl.g1(a) * (x - a) + \
        jl.g2(a) * (x - a)**2 / 2 + \
        jl.g3(a) * (x - a)**3 / 6
```

# Practical Examples

where mixing Python and Julia really shines

```
[8]: def taylor(x, a):
    return jl.g(a) + \
        jl.g1(a) * (x - a) + \
        jl.g2(a) * (x - a)**2 / 2 + \
        jl.g3(a) * (x - a)**3 / 6
```

```
[9]: domain = ak.Array(np.arange(-2, 2, step=0.05))
image = jl.map(jl.g, domain)
a = -0.4
```

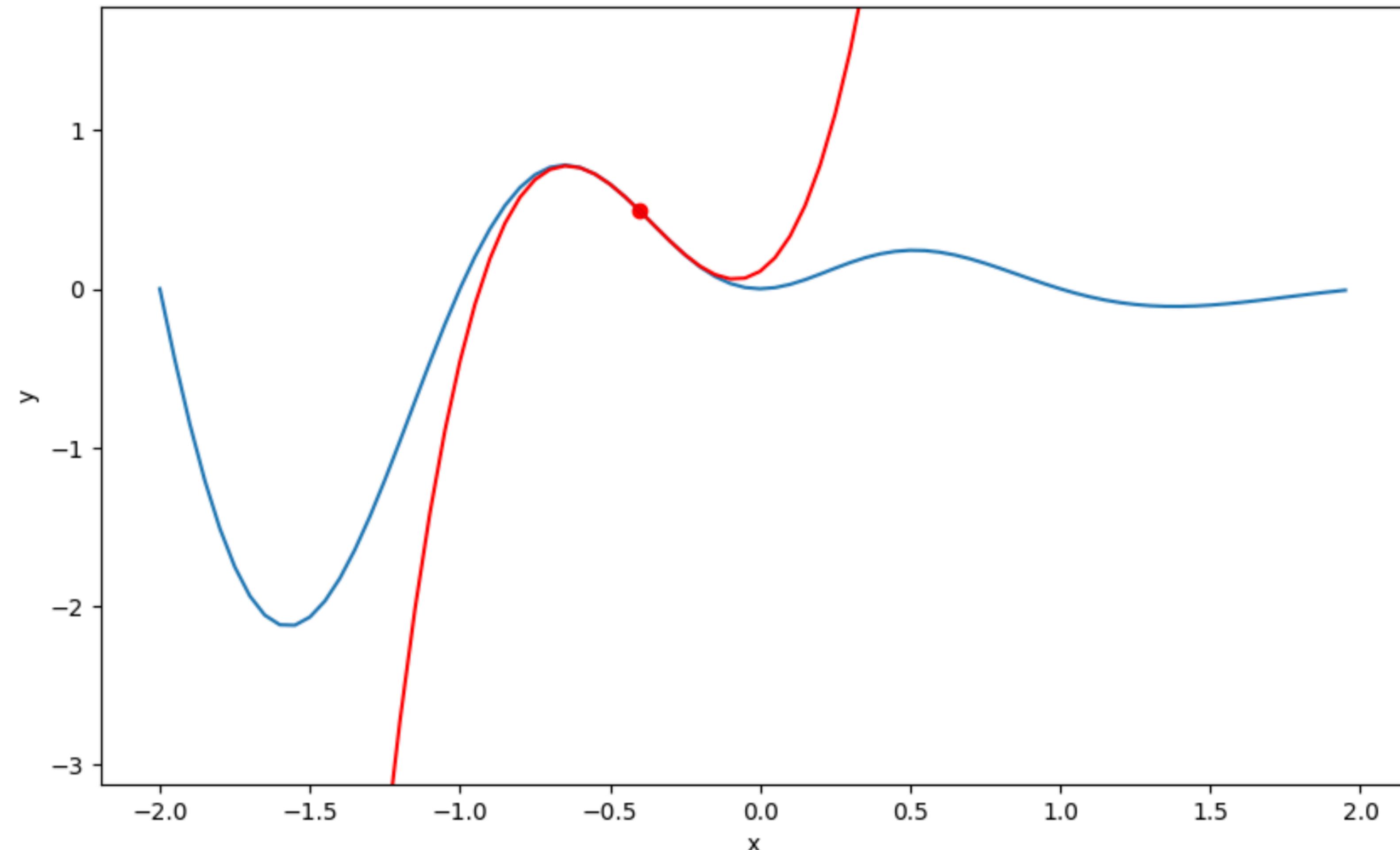
# Practical Examples

## where mixing Python and Julia really shines

```
[10]: plt.figure(figsize=(10,6))
plt.plot(domain, image, label='f(x)')
plt.scatter([a], [jl.g(a)], color='red', label='a')
plt.plot(domain, taylor(domain, a), color='red', label='3rd order Taylor poly aroun
plt.ylim(ak.min(image) - 1, ak.max(image) + 1)
plt.ylabel('y')
plt.xlabel('x');
```

# Practical Examples

## where mixing Python and Julia really shines



# Production-grade Examples

## Python package using Julia as backend

- [diffeqpy](#) is a package for solving differential equations in Python. It utilizes [DifferentialEquations.jl](#) for its core routines to give high performance solving of many different types of differential equations, including:
  - Discrete equations (function maps, discrete stochastic (Gillespie/Markov) simulations)
  - Ordinary differential equations (ODEs)
  - Split and Partitioned ODEs (Symplectic integrators, IMEX Methods)
  - Stochastic ordinary differential equations (SODEs or SDEs)
  - Random differential equations (RODEs or RDEs)
  - Differential algebraic equations (DAEs)
  - Delay differential equations (DDEs)
  - Mixed discrete and continuous equations (Hybrid Equations, Jump Diffusions) directly in Python.
- [PySR](#) is an open-source tool for Symbolic Regression: a machine learning task where the goal is to find an interpretable symbolic expression that optimizes some objective.
  - Over a period of several years, PySR has been engineered from the ground up to be (1) as high-performance as possible, (2) as configurable as possible, and (3) easy to use. PySR is developed alongside the Julia library [SymbolicRegression.jl](#), which forms the powerful search engine of PySR. The details of these algorithms are described in the PySR paper.
  - Symbolic regression works best on low-dimensional datasets, but one can also extend these approaches to higher-dimensional spaces by using "Symbolic Distillation" of Neural Networks, as explained in [2006.11287](#), where we apply it to N-body problems. Here, one essentially uses symbolic regression to convert a neural net to an analytic equation. Thus, these tools simultaneously present an explicit and powerful way to interpret deep neural networks.

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[11]: jl.seval("""  
function invariant_mass(tree)  
    layout = AwkwardArray.PrimitiveArray{Float64}()  
    for event in tree  
        if event.nMuon == 2  
            if event.Muon_charge[1] != event.Muon_charge[2]  
                result = sqrt(2 * event.Muon_pt[1] * event.Muon_pt[2] *  
                               (cosh(event.Muon_eta[1] - event.Muon_eta[2]) -  
                                cos(event.Muon_phi[1] - event.Muon_phi[2])))  
                if result > 70  
                    push!(layout, result)  
                end  
            end  
        end  
    end  
    layout  
end  
""")
```



```
[11]: invariant_mass (generic function with 1 method)
```

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[12]: Pkg.add('UnROOT')
```

```
Resolving package versions...
No Changes to `~/anaconda3/julia_env/Project.toml'
No Changes to `~/anaconda3/julia_env/Manifest.toml'
```

```
[13]: jl.seval("using UnROOT")
```

```
[14]: file = jl.Main.ROOTFile("data/SMHiggsToZZTo4L.root")
```

```
[15]: file
```

```
[15]: ROOTFile with 1 entry and 18 streamers.
data/SMHiggsToZZTo4L.root
└ Events (TTree)
    └ "run"
    └ "luminosityBlock"
    └ "event"
    └ ":"
```

- └ "Electron\_dzErr"
- └ "MET\_pt"
- └ "MET\_phi"



# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[16]: events = jl.Main.LazyTree(file, "Events")
```

```
[17]: events
```

[17]: Row	Electron_mass SubArray{Float3}	nElectron UInt32	luminosityBlock UInt32	nMuon UInt32	Electron_phi SubArray{Float3}	M ... F ...
1	[]	0	156	3	[]	- ...
2	[0.00544,	4	156	0	[0.134, -1	2 ...
3	[-0.00609,	2	156	0	[2.18, 1.6	- ...
4	[-0.00123]	1	156	7	[-0.643]	- ...
5	[0.0117, 0	4	156	0	[1.01, -1.	1 ...
6	[-0.00183]	1	156	2	[-0.497]	- ...
7	[-0.00183]	1	156	1	[-1.47]	- ...
8	[-0.00216]	1	156	0	[-0.633]	- ...
9	[-0.0128,	4	156	0	[2.79, -2.	- ...
10	[]	0	156	0	[]	- ...
11	[-0.00119,	2	156	1	[2.28, -2.	0 ...
12	[0.00608,	3	156	2	[-1.31, -1	2 ...
13	[-0.00765,	4	156	0	[2.52, -3.	- ...
14	[]	0	156	2	[]	- ...
15	[]	0	156	0	[]	- ...
:	:	:	:	:	:	.

27 columns and 299958 rows omitted

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[18]: jl.seval("""  
    using AwkwardArray  
  
    function make_record_array(events)  
        array = AwkwardArray.RecordArray(  
            NamedTuple{(:pt, :eta, :phi, :mass, :charge, :isolation)}((  
                AwkwardArray.from_iter(events.Muon_pt),  
                AwkwardArray.from_iter(events.Muon_eta),  
                AwkwardArray.from_iter(events.Muon_phi),  
                AwkwardArray.from_iter(events.Muon_mass),  
                AwkwardArray.from_iter(events.Muon_charge),  
                AwkwardArray.from_iter(events.Muon_pfRelIso03_all),  
            ))  
        return AwkwardArray.convert(array)  
    end  
"""")
```



```
[18]: make_record_array (generic function with 1 method)
```

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[19]: %%time  
muons = jl.make_record_array(events[1])
```

```
CPU times: user 1.29 s, sys: 14.9 ms, total: 1.31 s  
Wall time: 1.31 s
```

```
[20]: %%time  
muons = jl.make_record_array(events)
```

```
CPU times: user 581 ms, sys: 24.2 ms, total: 605 ms  
Wall time: 603 ms
```

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[21]: muons = ak.zip({
    "pt": muons.pt,
    "eta": muons.eta,
    "phi": muons.phi,
    "mass": muons.mass,
    "charge": muons.charge,
    "isolation": muons.isolation,
},
with_name="PtEtaPhiMCandidate",)
```

```
[22]: cutflow = dict()

# Sort muons by transverse momentum
muons = muons[ak.argsort(muons.pt, axis=1)]

cutflow["all events"] = ak.num(muons, axis=0)

# Quality and minimum pt cuts
muons = muons[(muons.pt > 5) & (muons.isolation < 0.2)]
cutflow["at least 4 good muons"] = ak.sum(ak.num(muons) >= 4)
```

```
[23]: # reduce first axis: skip events without enough muons
muons = muons[ak.num(muons) >= 4]
```

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient



```
[24]: jl.seval("""
using AwkwardArray

four_muons = AwkwardArray.ListArray{
    AwkwardArray.Index64,
    AwkwardArray.ListArray{
        AwkwardArray.Index64,
        AwkwardArray.PrimitiveArray{Int64},
    },
}()

function find_4lep(events_leptons)

    for leptons in events_leptons
        nlep = length(leptons)
        for i0 in 1:nlep
            for i1 in (i0 + 1):nlep
                if leptons[i0][:charge] + leptons[i1][:charge] != 0
                    continue
                end
                for i2 in 1:nlep
                    for i3 in (i2 + 1):nlep
                        if length(Set([i0, i1, i2, i3])) < 4
                            continue
                        end
                        if leptons[i2][:charge] + leptons[i3][:charge] != 0
                            continue
                        end

                        push!(four_muons.content.content, (i0 - 1)) # Julia is 1-based, subtract 1 for 0-based indexing
                        push!(four_muons.content.content, (i1 - 1))
                        push!(four_muons.content.content, (i2 - 1))
                        push!(four_muons.content.content, (i3 - 1))
                        AwkwardArray.end_list!(four_muons.content)
                    end
                end
            end
        end
    end
    AwkwardArray.end_list!(four_muons)
end
return four_muons
end""")
```

[24]: find\_4lep (generic function with 1 method)

# Real-world scenarios

how this combination can speed up our data analysis and make our work more efficient

```
[25]: fourmuon = jl.find_4lep(muons[1:10])
```

```
[26]: %%time
fourmuon = jl.find_4lep(muons)
```

```
CPU times: user 417 ms, sys: 10.4 ms, total: 427 ms
Wall time: 426 ms
```

```
[27]: fourmuon
```

```
[27]: 14963-element AwkwardArray.ListArray{Vector{Int64}, AwkwardArray.ListArray{Vector{Int64}, AwkwardArray.PrimitiveArray{Int64, Vector{Int64}, :default}, :default}, :default}:
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 2, 1, 3], [1, 3, 0, 2], [2, 3, 0, 1]]
[[0, 2, 1, 3], [0, 3, 1, 2], [1, 2, 0, 3], [1, 3, 0, 2]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 2, 1, 3], [0, 3, 1, 2], [1, 2, 0, 3], [1, 3, 0, 2]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 2, 1, 4], [0, 2, 3, 4], [0, 4, 1, 2], ..., [3, 4, 0, 2], [3, 4, 1, 2]]
0-element AwkwardArray.ListArray{Vector{Int64}, AwkwardArray.PrimitiveArray{Int64, Vector{Int64}, :default}, :default}
:
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 2, 1, 3], [1, 3, 0, 2], [2, 3, 0, 1]]
[[0, 2, 1, 3], [0, 3, 1, 2], [1, 2, 0, 3], [1, 3, 0, 2]]
[[0, 2, 1, 3], [0, 3, 1, 2], [1, 2, 0, 3], [1, 3, 0, 2]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
0-element AwkwardArray.ListArray{Vector{Int64}, AwkwardArray.PrimitiveArray{Int64, Vector{Int64}, :default}, :default}
[[0, 1, 2, 3], [0, 2, 1, 3], [1, 3, 0, 2], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 2, 1, 3], [1, 3, 0, 2], [2, 3, 0, 1]]
[[0, 1, 2, 3], [0, 3, 1, 2], [1, 2, 0, 3], [2, 3, 0, 1]]
```

# Compatibility Tools: IPython

- The line magic **%julia** code executes the given Julia code in-line
- The cell magic **%%julia** executes a cell of Julia code
- Julia's **stdout** and **stderr** are redirected to IPython
- Calling **display(x)** from Julia will display x in IPython

```
In [1]: %load_ext juliacall
```

Detected IPython. Loading juliacall extension. See <https://juliapy.github.io/PythonCall.jl/stable/compat/#IPython>

WARNING: replacing module \_ipython.

```
In [2]: x = 2
```

```
In [3]: y = 8
```

The `%%julia` cell magic can synchronise variables between Julia and Python by listing them on the first line:

```
In [4]: %%julia x y z  
z = "$x^$y = $(x^y)";
```

```
In [5]: z
```

```
Out[5]: "2^8 = 256"
```

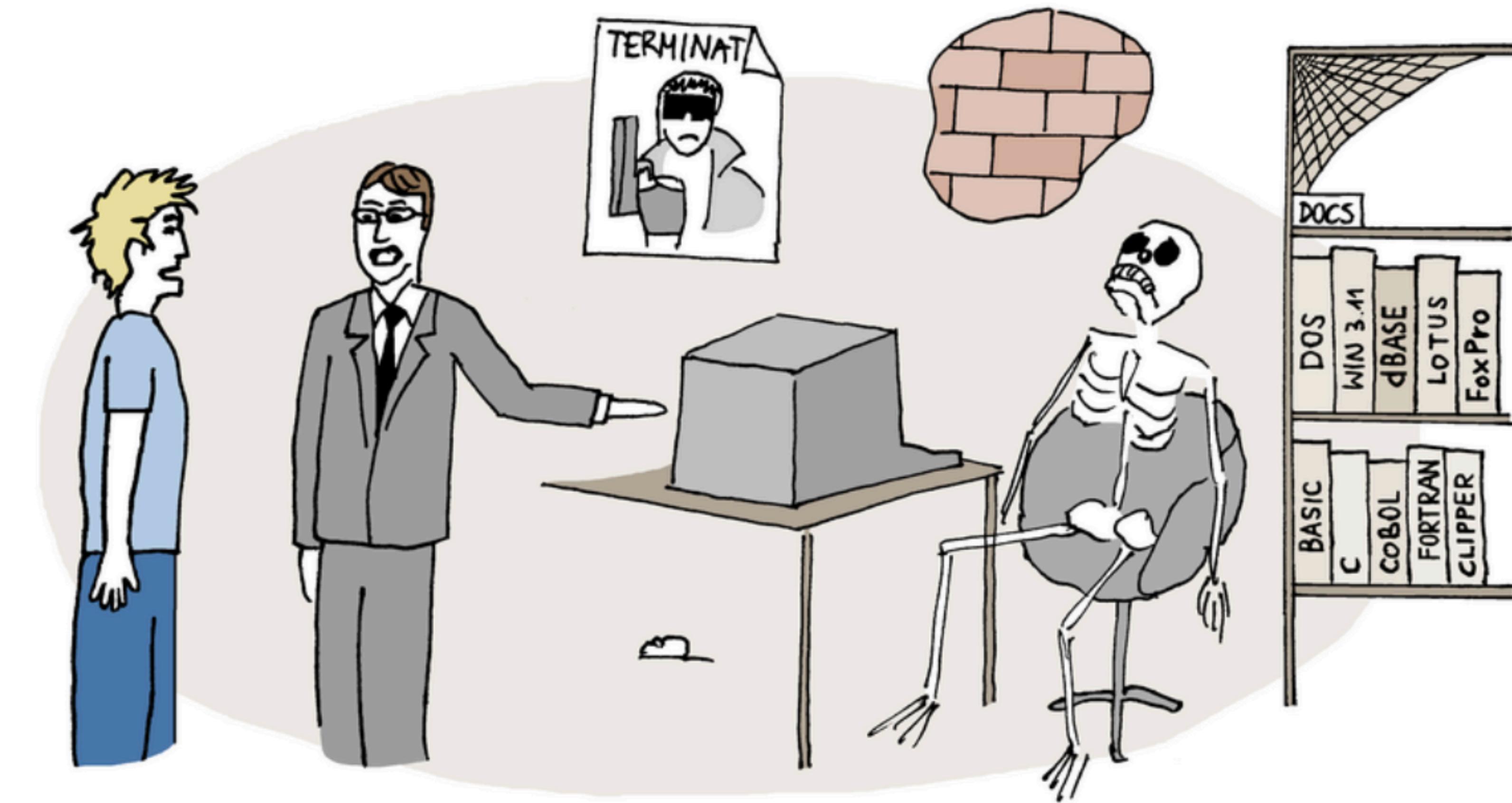
# Summary and Outlook

- Some common challenges you might face and how to overcome them
- Look ahead to the future
- Potential for deeper integration and community-driven innovation



```
julia> using Pluto
julia> Pluto.run()
[ Info: Loading...
[ Info:
└ Opening http://localhost:1234/?secret=3EMEw90i in your default browser... ~ have fun!
[ Info:
└ Press Ctrl+C in this terminal to stop Pluto
```





AND YOU WILL TAKE OVER PROJECT FROM JERRY