

# Parallelization of Push-based System for Molecular Simulation Data Analysis

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**Abstract**—Thanks to the advancement of the modern computer simulation systems and state-of-the-art instrumentation, many scientific fields generate, and require manipulation of large amounts of data. Known scientific data analysis systems, as well as traditional DBMSs, follow a pull-based type of architectural design, where the executed queries mandate the data needed on their part. This design, while suitable for traditional transaction-based workloads where number of queries retrieve small parts of data located at various places of the database, is ill-fitted for applications involving complex analysis on most of the data. Such design involves random I/O, considerably affecting the data throughput in the system. All of this gives rise of redundant and high I/O traffic in the process of scientific data analysis in pull-based type systems. In this paper, we design and implement a push-based type system which allows high-throughput data analysis in the process of scientific discovery. Our design improves on the aforementioned shortcomings in two ways: i) it uses a sequential scan-based I/O framework that loads the data into the main memory, and then ii) the system pushes the loaded data to a number of pre-programmed queries. These queries are being executed on the same data stream, with various data selections. This way, essentially, the system lowers the unnecessary I/O overhead imposed by the randomized, index-based scan and that of a multiple data reads if each query were to be fed separately. Considering the amount of MS data as well as the number of queries being executed, we believe our system provides substantial improvement over the current MS data analyzing systems. The efficiency of the proposed system is backed by the results of extensive experiments using MS generated data. The running times of our system are compared to those of the GROMACS system. The comparison shows the advantage and the potential of using such push-based system for MS system analysis.

**Index Terms**—Push-based system, molecular simulation, scientific databases, spatial distance histogram.

## I. INTRODUCTION

The amount of data generated by scientific applications running on advanced computer simulation systems as well as the new improved experimental devices is growing rapidly. This big volume of data is imposing a significant stress on the data analysis software. Even though the existing data analysis systems are configured to deal with large volume of data, they are not optimized for high throughput data analysis. Often times, the data is available only for certain period of time (e.g., streams) so the analyzing system should react to it

in a very efficient way. On top of the big amount of data, another challenge that is being imposed to the data analysis systems is that the data is usually being accessed through high-level analytical queries which computation is a lot more complex than the computation of simple aggregates. Some of these queries are usually the bottleneck of the data analysis systems, because they take a lot of time (often many days) to be executed and the systems are not designed to handle multiple queries on the same data stream at the same time, thus decreasing the overall efficiency of the data analysis.

One such example, where fast data analysis is crucial involves online social media [?], [?], [?]. The social media is known to be used for real-time feedback collection, which is usually associated to a particular topic or product [?]. In order for a system to be able to perform analytical examination of the data produced in such streaming media, the system should have the capability of fast data access. The reason, the millions of data records(tweets) produced every second [?]. Moreover, these tweets may have different geographical origin, introducing different languages and forms and often times containing unsolicited messages, errors, malicious content, etc. Therefore, some low level data uniformity and cleaning on top of the data access and management issues should be considered and possibly incorporated in the process of analytical investigation in order to achieve relevant result.

The aforementioned big data imposed issues are also frequently present in many other application fields, e.g., scientific data analysis. In many scientific and engineering fields, the main computational method for analyzing physical/chemical attributes of natural systems is the particle simulation. Such simulations, when performed in the field of structural and molecular biology, are commonly called Molecular Simulations. Molecular simulations (MS) (sometimes called Molecular Dynamics (MD) simulations) are computer simulations of complex biological, physical or chemical structures. These simulations, based on some basic theoretical models are widely utilized as a basic research mechanism for studying the behavior of the natural systems. The basic units of such systems/simulations are natural particles (such as atoms, molecules, stars, etc.) and they interact among each other for a certain period of time following postulated classical forces. The number of these basic units taking part in the simulations is big, usually in the range of hundreds of thousands to millions. For instance, Fig. 1 shows a snapshot of a collagen fiber, consisting of 890,000 particles. And oftentimes, the simulations produce datasets consisting of more than one snapshot (frame) of the system’s current state at various time instants. Each of these frames contain all the particles, together

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with all their measurements, such as spatial coordinates, mass, charge, velocity, forces, etc. And usually, a big number of such frames (in the tens of thousands) are being produced and stored in the course of a typical simulation. Quantities measured during the simulations are analyzed to test the theoretical model [?], [?]. In short, the MS is proven and powerful tool for understanding the inner-workings of a biological system, by supplying a model description of the biophysical and biochemical processes that are being unfold at a nanoscopic scale.

In order to achieve objective discovery and to explain the workings of the scientific systems, scientist must analyze the data produced by the MS. These analysis oftentimes comprise of computation of very complex quantities that show statistical properties of the data. Such queries are of great importance to scientist because they are the basic assembly blocks for a series of critical quantities needed to outline the scientific systems [?]. The methods by which the data is being accessed as well as these queries are executed can either increase or decrease the efficiency of an data analysis system. The known data analysis systems (e.g., Gromacs [?]) uses pull based type design in which the data is being fed to the queries only by demand. When a query needs the data, it requests it, the data is pulled through the system and delivered to the query. This type of design, we believe, introduces two types of problematic issues: 1. overhead in I/O traffic by not allowing for multiple queries to be executed on the same stream of data at the same time, and 2. cpu/data latency incurred when a request for the data is sent to the system (the time it takes from a request to the time the query can actually use the data).

We believe that by using a push-based type system we can remedy such issues. In the push-based design the queries do not request the data. Rather, the data is pushed onto the queries automatically and is being processed by the active queries. This alleviates the I/O traffic overhead as well as the cpu/data latency incurred for each query that would have been introduced by a pull-based design. Such a system design is especially suitable for many scientific applications which share the following features. First, the scientific analysis often involves executing a number of analytical queries commonly processed on a large portion, if not all of the generated data. Second, many of these fields use the same popular, and small number of data analytics primitives as the basic blocks on which they build their discovery. And three, the scientific data, once stored is never modified. New data only appends to the existing dataset, making the data perfect contender for streaming.

In this paper, we describe the idea, design and implementation of such a push-based system. We would like to point out that the work presented in this paper is an application of such push-based strategy that has been previously considered in the database community in the works presented in [?], [?], [?], as well as the idea of sharing same tuple of data or data scans across many queries previously introduced in [?], [?], [?].

To summarize, data-intensive applications often require compelling amount of storage space and intensive processing capability, but also need fast data access and high throughput

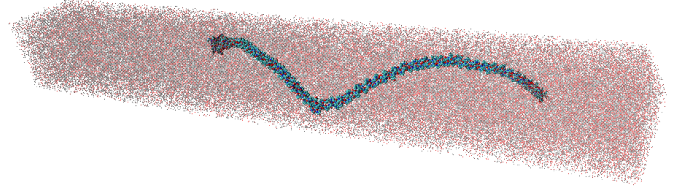


Fig. 1. A snapshot of simulated collagen fiber structure

data analysis. Therefore, the need of a system that will be optimized to access data fast, with high throughput, as well as efficiently execute the analytical queries with a possibility of running multiple queries on the same data stream is of a great importance to the scientific community.

#### A. Problem Statement

As mentioned earlier, in order to describe the scientific system, scientist must look into/analyze the critical statistical properties of the data produced by the simulation. These properties are usually computed through series of queries that are being executed on the whole, or some selection of the MS data. Most of the systems that are widely used today across many scientific fields for analysis of the MS data are part of a software systems that also run the simulation. Such examples include GROMACS [?], VMD [?], MDAnalysis [?], Wordom [?], MD-TRACKS [?], SimulaidOne [?], Charmm [?]. Once the simulation is run, the system produces a flat file with all the measurements of each particle. These systems take each query as a user's input and apply them to the data uploaded from these flat files (called trajectories in GROMACS). The biggest problem/performance issue that these system impose is the fact that for every new query issued by the user, the system has to load a significant part of the dataset into main memory before executing the query. Such pull-based design involves random I/Os that considerably affecting the data throughput in the system. And while the use of an index-based scan might seem better option to a sequential scan, this is the case only when the query accesses small portion of the data. All of this gives rise of redundant and high I/O traffic in the process of scientific data analysis in pull-based type systems. This adds greatly to the overall performance time of the analysis of the MS system. Having in mind the volume of data produced by the MS in a single frame (in gigabytes), and we add the number of frames simulated (tens of thousands) the total volume of data to be analyzed is of huge magnitude. So to have to load big chunks of this data from disk to the main memory every time a query is being executed degrades the overall system's performance greatly. In this paper we design and implement a push-based type system which allows high-throughput data analysis in the process of scientific discovery.

#### B. Our Approach

Considering the fact that the running time of the most queries used in the scientific world to analyze the MS is minuscule in comparison to the loading time of the MS data, it is safe to say that the scientific world would benefit from a

system that can remedy the aforementioned problem. Our idea is to build a system that would load the MS data from hard disk in the main memory only once and then execute as many queries as needed/wanted on that data, without the need of reloading the same data over and over again. Considering the volume of data in a single MS frame as well as the number of frames produced during a single simulation, this type of system can save a lot of time for MS analysis. The system would contain many, most often used queries that can also be run as user's input. These queries would be pre-programmed as separate modules in our system, but they would be able to take certain attributes, like data selection for instance, as user's input. Once the system is run, all (or a selection) of these queries would be executed against the MS data or certain selection. The system would act as a type of push-based system, essentially pushing the loaded data to all the queries. Once we have the data in the memory, the reading can loop as many times as the queries need it. This is useful for some non-streaming functions/queries that cannot be computed in a single run of the data. Such one query is the SDH. But we have also come up with a way to resolve this in a way, by creating a quad-tree based database for this query. This quad-tree (we called Density Map (DM)) is being populated while the data is being loaded into main memory. After the DM is populated, we can compute the SDH with much faster algorithm than the brute-force method used everywhere else.

Another improvement that our system provides is the following: by thorough observation and analysis we have discovered that many of the quantities (functions/queries) that are being computed in order to analyze the MS system share some of the same basic parts. In order to take advantage of that, our systems precomputes these basic parts and has them handy (stored in memory) whenever one of the more complex functions needs them. So, for instance, when the total mass of the system is needed, our system just pulls the precomputed value out and serves the query that needs it immediately. And if more than one query uses the same basic part, that translates into time saving, however minuscule it might be.

### C. Contribution and roadmap of the paper

We have designed and implemented a push-based system that can be used as a tool for analysis of MS systems. We have tested the system on real MS datasets. The experimental results evidently show the superiority of the proposed system over one of the most widely used MS analysis system across many scientific fields, i.e., GROMACS. The efficiency improvement ranges anywhere from 3 to 100 times improvement (of the overall running time) per set of selected queries run on a different selection of the MS data. If we take in account the number of such queries that the scientist run every day, we believe our system would be of great benefit to MS community. In addition to the higher efficiency that our system achieves, we also believe that our idea will initiate a new breed of database related, push-based systems that could be used to analyze the MS systems in a more efficient way. Having a push-based like system, we were also able to improve the computation of the more complex quantities. Namely, the computation of

some such complex quantities involves computation of much less complex functions (sub-parts), and many such sub-parts are being shared among some of the complex quantities. So, by computing these more basic, sub-quantities in advance, we were able to achieve however minuscule time gain when computing the more complex queries.

The major technical contributions presented here are:

- Design the network (tree like) of the most commonly used queries in MS (physics);
- Build the system: design and build the modules, representing the quantities to be computed in an efficient manner, following the already built network;
- Develop a scientific simulation database benchmark that can be used for evaluating similar systems and products.

The remainder of this paper is arranged as follows: in Section II we give a survey of the systems used in the field of MS systems analysis. We continue the paper with Section III in which we show the design of the query network build from the most widely used quantities in MS system analysis. In Section IV we describe our push-based system for MS data analysis. Then, in Section V we present the benchmark designed to test our system as well as the results attained through comprehensive experiments run on real MS generated data. At the end, we conclude this paper with Section VI in which we give an overview of our possible future endeavors in the field of MS data analysis.

## II. RELATED WORK

The idea of data streaming has been broadly used in many fields. The main usage however is aimed at processing live data generated online. There is an ocean of references for data stream management, but we believe the presentation in [?] encapsulates the majority of the ideas, problems and solutions. In the past decade, however, the database community started to follow the data stream idea to process stored data. Processes can take advantage of the streaming data at any time the data is being pushed through the system. This gives rise to push-based type design for data management systems. The idea of such push-based design was previously considered in projects such as DataPath [?], Volcano [?] and QPipe [?] among others. These works show ideas in which the data-driven dataflow is compared to the demand-driven dataflow showing the need for the later. They also talk about maximizing the data and work sharing among queries at runtime. Essentially, we incorporate such ideas in our design of the push-based system.

On the other side, the scientific community has steadily progressed from processing massive data files towards employing database systems for the storage, acquisition, and analysis of large-scale scientific data [?], [?]. The widely used and popular relational database systems are conventionally designed and optimized to better manage the data produced by the business type applications. But such conventional database systems (DBMS) are not well equipped to deal with the type and quantity of scientific data, such as the data produced by the molecular simulations. In the recent past, the DBMS community has made some attempts into the design and construction of database systems optimized for handling

scientific data. Such examples include the BDBMS project [?] that deals with annotation and provenance of the sequence data in biosciences. and the PeriScope project [?] is designed to efficiently handle declarative queries against bio sequences. On top of the aforementioned examples, there are also ideas for new DBMS frameworks aimed at the management of scientific data [?], [?], [?]. One of those systems is the SciDB [?], [?] and it is closest to the idea presented in this paper. SciDB is data management and analytics system that is primarily used in application domains involving very big scale array data. This system, like the one presented in this paper is designed around a multi-dimensional array data-model and it uses arrays to store the data. SciDB stores petabytes of data on a number of machines and runs its queries on those machines. It is made for high performance, high-availability, fault tolerance, and scalability. However, to the best of our knowledge, it too follows the pull based design where its queries demand the data they need. As seen earlier in this paper, this type of design can impose I/O overhead and decrease the data throughput when doing the analysis. Aside the mentioned issue, the design and build of such DBMS optimized for scientific data management come with additional challenges. Such challenges as well as their probable resolution are outlined in [?]. Recently, there have been some efforts aimed at designing and building MS data managements systems on top of relational databases. Such efforts are presented through projects like BioSimGrid [?] and SimDB [?] that were developed especially for molecular simulations. However, to the best of our knowledge, such systems still lack the efficiency needed for MS data management as well as efficient query processing strategies.

Generally, the data produced in the process of molecular simulation is being stored in large, plain files with no structure whatsoever. Queries, which are implemented in a stand alone programs within simulation/analysis systems, are executed onto such files producing the quantities that scientist use to analyze the molecular system. Such simulation and/or analysis packages include: Gromacs, VMD, MDAnalysis, Wordom, MD-TRACKS, SimulaidOne, Charmm among the others. But to the best of our knowledge, all of these systems work on a similar basis: they take a user defined query and execute it onto the MS simulated data. In order for the query to be executed, the data has to be loaded into the main memory. Then the result is either produced onto the display or written to a file. When the next user query comes, the system again loads significant part of the dataset into the main memory and executes the query. We believe that there is a room for improvement of such systems, given the fact that many of the user defined queries executed during system’s analysis are fairly static. In other words, there is a number of queries that a user would always want to execute on a given simulation data. Furthermore, the selections of MS data onto which such queries might be executed, are also fairly constant (i.e., oftentimes the user selects the same group of atoms (e.g., all hydrogen atoms) to calculate given quantity, like center of mass for instance). So, by precoding many such queries and running them automatically once the system has loaded the data into memory, we believe we can save a lot of time that otherwise would have been spent in loading the same data

into main memory anytime a query is executed. On top of the automated query execution, our system can take user’s query as input as well. With this, we believe our system is an improvement over the MS analysis systems that are used today.

### III. NETWORK OF QUERIES

**MS Queries.** In order to study some important statistical features of an MS system, scientist need to “extract” various statistical quantities out of the data produced by the simulation. To achieve this, queries are executed against the data. Most of the queries used in the analysis of MS systems are analytical in nature. Essentially, these analytical queries are mathematical functions that translate a selection of atoms (atoms’ measurements) to a scalar, vector, a matrix, or a data cube [?]. Once the simulation is done, the analysis carried out will depend on the structure being studied as well as the features of the system that need exploring. In other words, not all system’s quantities need to be computed every time the system is being analyzed. Some of the more popular queries, including density (atom counts), first-order statistics (mean), second-order statistics (variance), and histograms among others, can be seen in Table I. The queries shown in this table are the ones that we have also incorporated in our system. Just to clarify some of the notation in Table I: we assume that the MS system comprises of  $n$  particles and  $r_i$ ,  $m_i$ ,  $c_i$  and  $q_i$  denote coordinates (vector form), mass, charge, and number of electrons of a particle  $i$ , respectively.

There are two types of queries/functions among the ones used to analyze an MS system. The first type are one-body functions. Such functions usually are algebraic functions [?] and only involve quantities(attributes) from a single atom at any given time in the process of computation. Each atom (atom’s attributes) is being processed a constant number of times, thus the total running time of such functions/queries is  $O(n)$ . This type of functions is very suitable for the idea of push-based system, or an online system in which the data is being read once and acted upon. In other words, in a single run of the incoming data, all such queries will produce useful final results. Except the SDH and the RDF (i.e., the last two in the table), all other queries shown in Table I fall into this category of one-body functions. Most of these functions are defined on a single frame of the MS data. Only the autocorrelation functions are defined on two distinct frames.

The second type of functions are multi-body functions and are holistic in nature. The computation of such functions involve more than one atom’s attributes and cannot produce final result in a single run of the MS data (i.e., if traditional methods are used for their computation). Such queries include the Radial Distribution Function (RDF) [?], [?], [?] as well as some quantities associated with chemical shifts [?]. Generally, such functions are computed through histograms. For instance, the RDF is obtained from a histogram of all pairwise atom distances (this is the Spatial Distance Histogram or SDH). The traditional, straightforward (often the brute-force) way of computing these holistic functions is a very time consuming process. On top of that, these methods cannot produce the final

Function Name	Equation/Description
Moment of Inertia	$I = \sum_{i=1}^n m_i r_i^2$
Moment of Inertia on z axis	$I_z = \sum_{i=1}^n m_i r_{zi}^2$
Sum of masses	$M = \sum_{i=1}^n m_i$
Center of mass	$CoM = \frac{I}{M}$
Radius of Gyration	$RG = \sqrt{\frac{I_z}{M}}$
Dipole Moment	$D = \sum_{i=1}^n q_i r_i$
Dipole Histogram	$D_z = \sum_{i=1}^n \frac{D}{z}$
Electron Density	$ED = \frac{\sum_{i=1}^n (e_i - q_i)}{dz \cdot x \cdot y}$
Heat Capacity	$HC = \frac{3000 \cdot \sqrt{T} \cdot boltz}{2 \cdot \sqrt{T} - n \cdot df \cdot VarT}$
Isothermal Compressibility	$I = \frac{VarV}{V_{avg} \cdot boltz \cdot T \cdot PresFac}$
Mean Square Displacement	$msd = \langle (r_{t+\Delta t} - r_t)^2 \rangle$
Diffusion Constant	$D_t = \frac{6 \cdot msd(t)}{t}$
Velocity Autocorrelation	$V_{acor} = \langle (V_{t+\Delta t} \cdot V_t) \rangle$
Force Autocorrelation	$F_{acor} = \langle (F_{t+\Delta t} \cdot F_t) \rangle$
Density Function	Histogram of atom counts
SDH	Histogram of all distances
RDF	$rdf(r) = \frac{SDH(r)}{4 \cdot \pi \cdot r^2 \cdot \sigma_r \cdot \rho}$

TABLE I: Popular analytical queries in MS

result in a single run of the MS data, making such functions unsuitable for our idea of a push-based system. However, in our previous work, we have designed a data structure together with an algorithm that opens up the possibility for such queries to be executed in a push-based type environment. Further details on this are given in Section IV.

Fig. 2 represents an idea to show how such query processing system can be improved. The idea behind it is that some of the queries share same sub-routines. Having all the queries made as separate modules, this sub-routines can be computed once the data is being pushed through the system and then be used anytime a more complex query needs it. Having in mind the amount of data in a single frame that the queries (sub-routines as well) need to go through, and the fact that in a single MS there are thousands of frames, we believe this can be immense improvement in terms of total running time.

#### IV. BUILDING THE SYSTEM

##### A. MS Data retrieval and in memory organization

A typical MS system generates and stores the data in a number of trajectory files, usually including multiple frames (snapshots of the simulated system taken at certain time

intervals). Such MS generated data oftentimes goes through a simple lossless compression and, depending on the simulation software it may be stored in a binary format. Such trajectory file format is one of most often used MS file format (e.g., GROMACS, PDB). But such format is unrecognizable to our system. So our system has to do three things before it starts executing the queries: 1) Read the MS data from a trajectory file, 2) Translate the MS data to a form recognizable to our system, and 3) Load the data to memory.

**Data read - transform.** As mentioned above, in order for our system to be able to read the MS generated data, the data needs to be transformed. The reason for this is following: the MS data is stored in multiple files and possibly in different formats as well. One such file holds the global data (identifying the system and the simulation). Another file holds each frame's data. The frame data contain general information about the frame, but the main part is a sequential list of each atom's info, including atom's mass, position, charge, number of electrons, velocities, forces, etc. Another file (topology file) holds the molecule/residue info, essentially identifying what atom belongs to which molecule.

So, in order to extract the data from these files, we have created a sort of "extractor/transformer" of the attributes needed for the execution of the queries in our system. This transformer, essentially, is a separate piece of code that does three things: 1) it reads the MS generated data that the MS system stores in one of the often used MS file format (e.g., GROMACS); 2) it translates the data into a format that our system can read (taking only the information our system needs); and 3) it stores the data in a file that has basic structure to it. So, in the end, the data transformer produces a data file that our system takes as input. This code serves as a connection between an MS system (e.g., GROMACS) and our system. With this, our system can essentially be used as an add-on to GROMACS or other simulation systems and help improve the efficiency of the data analysis.

**Data organization in main memory.**<sup>1</sup> Once the data is in a format our system can read, the data is being loaded into the main memory one frame at a time. The organization of the in-memory particle's data is in the form of a simple, two dimensional array where a single row represents an atom in the system with all its attributes (e.g., coordinates, mass, charge, residue info, etc.). We also keep (in a one dimensional array) crucial system's information for each frame, like temperature, energy, pressure, etc. We have used such structures because they are very suitable for simulating a push-based type of system: a simple sequential read of the array gives that on-line type of data stream. So, as the system reads the array, it pushes the data onto the query-modules. As mentioned earlier, the one-body (algebraic) queries will produce a final result at the end of the first sequential read. However, the two-body (holistic) functions, like SDH and RDF, cannot do this in a

<sup>1</sup>This paragraph talks only about the data organization used by one-body queries. For two-body queries (e.g., SDH), the data organization is discussed later on.

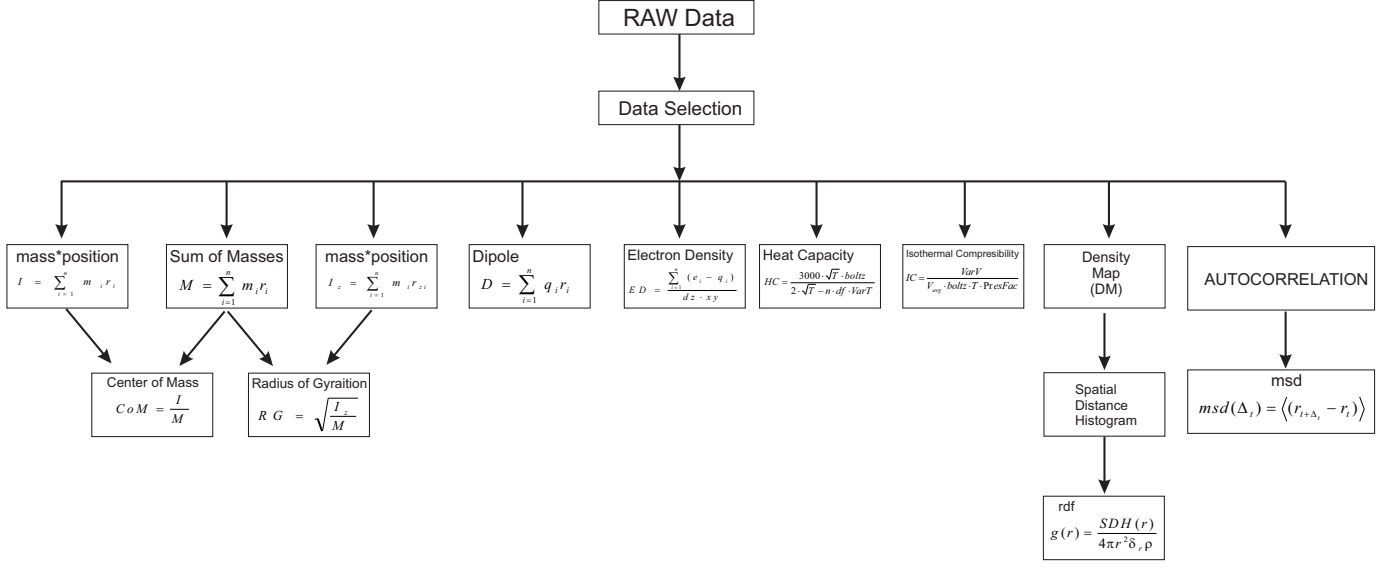


Fig. 2. MS Modules Structure

single read of the data.<sup>2</sup> Therefore, each frame's data array can be continuously read (in a loop manner) as many times as a query needs it.

### B. Query modules

As mentioned earlier, there are two types of functions/queries used for analysis of MS systems: algebraic or one-body, and holistic or two-body queries (these in general can be multi-body, but in this paper we only deal with a two-body functions).

1) *One-body queries*: Most of the query modules in Table I (except the SDH and RDF) are not that involved, only containing computations of fairly simple, one-body functions. These queries were coded as separate modules in our system. Each of these modules take few attributes as input (e.g., atom selection, frames selection (for the autocorrelation functions), number of atoms, etc.). The system pushes the data as it becomes available onto these modules. The queries are being executed on the selection and are put in a "ready" mode, awaiting the next frame's data. First, the more basic queries, like total mass, are being computed. The results of such queries are temporary stored (in main memory) and are available for use anytime a more complex query needs them.

2) *Two-body queries*: In general, queries involving two-body functions are a bit more complex and cannot provide the final result in a single data read if a straightforward method is used for their computation. However, in the proposed system we have incorporated a data structure and an algorithm for the SDH (also RDF) from our previous work that is suitable for push-based type of system. In this subsection we give a brief description of the data structure (DM) and the algorithm (DM-SDH) designed in [?], [?] and implemented in the system

<sup>2</sup>However, we have previously designed and created a data structure and an algorithm that can take the advantage of a single data read and produce final results for SDH computation [?], [?]. We have incorporated this into our system presented in this paper.

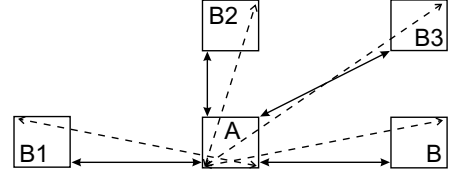


Fig. 3. Computing minimum (i.e., length of solid lines) and maximum distance (i.e., length of dashed lines) range between two cells

proposed in this paper. For more detailed information, please refer to our previously published work on this topic [?], [?]

**The data structure.** The simulation data space is represented by a conceptual data structure we named Density Map (DM). The density map splits the simulation space into a grid of equal size regions (or cells). The cells are cubes in 3D and squares in 2D<sup>3</sup>. Resolution of a density map is the reciprocal of the cell size in that density map. In order to generate higher resolution density map, we split each cell of the current resolution's grid into four smaller cells of equal size. This design allows us to use a region quad-tree [?] to organize density maps of the same data but with different resolutions. So, essentially, a node in the quad-tree represents a single cell from the DM. Therefore, a density map of a certain resolution basically is the set of all nodes of one level of the tree. Each of the tree nodes records the cell's location in the density map (coordinates of corner points) as well as the number of particles in each cell. We name the afore describe tree the Density-Map tree (DM-tree).

**The algorithm.** The essential part of the DM-SDH algorithm is a procedure named RESOLVETWOCCELLS. The input to this procedure are two cells from the density map (e.g., A and B in Fig. 3). It computes, in constant time, the minimum and maximum distance between the two cells. A pair of cells is *resolvable* if both the min and max distance between them fall into the same SDH bucket  $i$ . If that is the case, the distance

<sup>3</sup>In this paper, we focus only on the 2D data to elaborate and illustrate the proposed ideas.



count of that bucket is being increase by  $n_A n_B$  ( $n_A$  and  $n_B$  are the number of particles in cell  $A$  and  $B$ , respectively). Otherwise, the cells are non-resolvable and we either:

- (1) Go to the next density map with higher resolution and resolve all children of  $A$  with those of  $B$ , or
- (2) If leaf-level has been reached: compute every distance between particles of  $A$  and  $B$  and update the histogram accordingly.

In order to generate the complete SDH, the RESOLVETWO-CELLS procedure is executed for all pairs of cells for a given density map  $DM_k$  and the algorithm would recursively call the procedure (action (1) above) until leaf-level has been reached (action (2) above).

On top of the aforementioned DM-SDH algorithm, we have also incorporated two approximate SDH algorithms (ADM-SDH), introduced and described in [?], and [?]. These approximate algorithms are substantially faster than the brute-force algorithm and also than the DM-SDH algorithm as they take advantage of some heuristic. For more details on the ADM-SDH algorithms please see the aforementioned work.

### C. Working of the system

In this subsection we give a brief overview of how the system works at runtime. Please note that the first, preliminary part is only executed once, i.e., the data transformation from MS data files to a file that our system can read.

Here are the steps taken through out the analysis:

- (1) Execute the data transformer
  - (a) Read the MS data from trajectory files
  - (b) Extract the info needed for our system
  - (c) Save the read data to a file recognizable to the system
- (2) Load the data into main memory (one frame at a time)
  - (a) Load data into a double array (for one-body queries)
  - (b) Load data into the quad-tree structure (for two-body queries:SDH, RDF)
- (3) Push the data to all queries
- (4) A query, if available, acts upon the pushed data (first executing the lower level, sub-queries)
- (5) Store intermediate results (results of sub-queries)
- (6) Repeat steps 3-5 if needed.
- (7) Output results
- (8) Go to step 2 and load the next frame (if needed).

Fig. 4 depicts the flow of the system.

Step 2, loading the data into main memory is different for SDH query compared to the one for the one-body queries. The reason for that, as mentioned earlier, is the different data structure used to store the data in memory. While we use double array to store the data for the one-body queries, we use quad-tree like data structure to store the data needed to compute the SDH. The loading to the double array is straightforward. However, to load the quad-tree structure, we need to use some of the info from the data itself. Namely, the coordinates of the atoms are used to determine in which tree node an atom belongs. That way we build the so called density map (DM), i.e., the different regions with a certain number of atoms in them (including all the atom's attributes). So

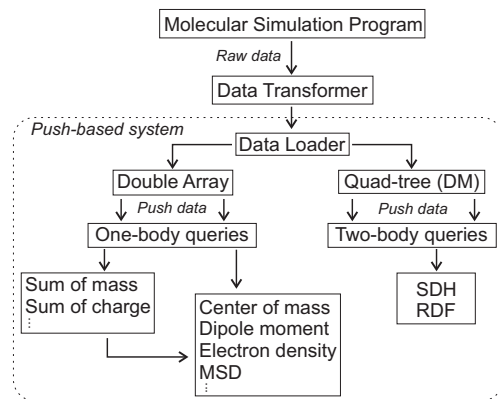


Fig. 4. Push-based system flow

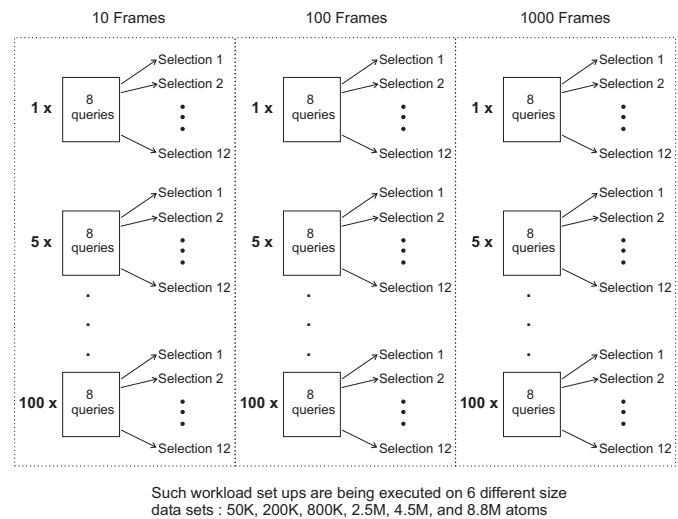


Fig. 5. Workload setup

basically, to solve the SDH problem in a push-based manner, we convert the problem into populating a data structure in push-based manner. This data structure will then be used as an input to our DM-SDH algorithm that, although not completely in “on-the-fly” way, is a great improvement over the naive methods used in much of today’s MS analysis systems (i.e., GROMACS, PDB, CHARMM, etc.).

## V. EXPERIMENTAL RESULTS

The system was implemented in C++ programming language and tested on real molecular simulation data sets. The experiments were carried out on an Apple MacPro machine with 8GB of physical memory and two Quad-Core Intel Xeon 3GHz processors. The MacPro was running OS X Mavericks 10.9.3 operating system. We have compared the results obtained by our system to those obtained by running the analysis through GROMACS (v. 4.5.7). Both systems were analyzing the same data sets.

**Data sets.** In our experiments, six data sets from different simulations were used. All simulations were done on a POPC<sup>4</sup>

<sup>4</sup>POPC is a chemical compound composed of a diacylglycerol and phospholipid. Its full name is 1-palmitoyl-2-oleoyl-sn-glycero-3-phosphocholine and it is one of the most important lipids in bio-physical molecular simulation.

lipid bilayer, but were all set to produce data of different sizes (i.e., different number of particles in the simulation). Namely, we have tested the system on simulations with 52,400; 209,600; 838,400; 2.5M; 4.4M; and 8.8M atoms. Also, since the simulations were run separately, they produced six different MS systems with distinct characteristics (distinct structure, atom’s positioning, etc.). From all of the generated data sets we have randomly selected sets of 10, 100, and 1000 consecutive frames for the purpose of our experiments. This gave us 18 different datasets on which we tested our system.

**Query work load.** Two types of query workload were used: 1) one involving one-body queries only 2) one including two-body queries (SDH and RDF) as well. The reason for this is that GROMACS, the system we used to compare our system to, only has a naive method of solving the RDF (SDH) problem (like almost all MS analysis systems). In our system we have incorporated SDH (RDF) algorithms that are far more superior to the naive method, and comparing the systems like that would not have been fair (we believe).

**One-body queries only.** The following set of one-body queries were included in the test workload: mean square displacement (msd), radius of gyration, dipole moment, center of mass, velocity autocorrelation, electron density, mass density, and charge density. This set of queries were pointed to us, by a group in the physics field with extensive MS background, as one of the most commonly used in the field of collagen bilayer MS system analysis. A workload group contains all 8 queries executed on one of the 12 selections, making 12 groups. Such groups are executed on six different size data sets, with 10, 100 and 1000 frames. This workload is then repeated 5 more times, by executing each of the queries in the groups 5, 10, 25, 50, and 100 times, essentially just magnifying the workload intensity. In total, we have  $12 \times 6 \times 3 \times 6 = 1,296$  different workload setups to test the system on. Fig. 5 shows the organization of the workload setup.

### A. Benchmark

Through extensive collaboration with a research group from the Physics department at USF, we have come up with a benchmark that can be used for testing the efficiency of an analysis system for molecular simulations. The benchmark consist of three essential parts: 1. Simulation data produced by an MS, 2. Queries that are to be executed onto that data in order to produce some information of interest, and 3. Benchmark parameters that control the size of the benchmark.

1) **Benchmark Data:** The data used in the benchmark was real molecular simulation data, produced through the GROMACS MS system. The initial, pre-simulation data file consisted of 200 POPC and 12000 solvent molecules, or 12200 molecules in total. This type of system was used because it is sufficiently diverse, containing enough distinct POPC and solvent molecules (e.g., each POPC molecule includes approximately 52 different atoms) and yet simple enough to be easily transformed into another system of different size. By using the *genconf* function in GROMACS, we produced pre-simulation files of different sizes (essentially by changing the system’s size (box)). Six different sized pre-simulation

files were created. A molecular simulation was then run on these 6 files, each producing an MS system of certain size (volume/number of particles). All of the simulations were set up to produce 1000 frames (snapshots in time of the systems), each frame containing the same number of particles as the base one. The produced files contained: 52,400; 209,600; 838,400; 2.5M; 4.4M; and 8.8M atoms per frame. So, for example, the file with 52,000 atoms holds 52,000,000 records in total (1000 frames, each containing 52,000 records). As mentioned earlier, this simulation data comes mostly in binary formats and in trajectory files having a lot of unneeded overhead. Therefore, it was transformed to a data arrays files containing only crucial information of the particles and the system. The size of the files ranged from 135MB for 52,000 atoms to 24GB for 8.8 million atoms (this is for data with 100 frames).

2) **Benchmark Queries:** The queries selected to be included in this benchmark were derived through a thorough observation of the way an MS system is being analyzed. They were found to be the base of the analysis of many MS systems. In other words, no matter how small or big the analysis was, these queries were included in that analysis. As mentioned earlier, they are of two types: one-body (and algebraic) and two-body (and holistic). Table I shows these queries.

3) **Benchmark Parameters:** There are several parameters that can be used to control the overall size of the system. We divide the parameters into two groups:

Data size parameters:

- Select different sized dataset
- Number of frames
- Data selection (within the selected dataset) onto which the queries are being executed

Workload size parameters:

- Number of queries to be executed
- Number of times each query is executed

By changing these parameters, we can produce a versatile testing benchmark for MS analysis systems.

### B. Results

We have run extensive experiments over all the different setups of workload mentioned previously in this section. However, in this paper we present only the workload setups of 4 data size sets: 838,400, 2.5M, 4.2M, and 8.8M atoms because we believe they convey enough information about the efficiency of our system compared to that of the Gromacs system. The running times of our push-based system were compared to those of the Gromacs system. The first set of figures, namely Figures ??-??, represent the speedup that our system obtains over the Gromacs system with various atoms selection levels. We define the selection levels based on the number of comparisons we have to make in order to extract the needed group(selection) of atoms. For example, if we want to do analysis on all molecules containing oxygen, or hydrogen, or carbon we would go over each molecule and compare its components to the selection list. The bigger the selection list, the higher the select level in our system. For better visualization, we note three different selection levels: high (at least 10 comparisons made), medium (between 1 and



10 comparisons made), and low select level (with one or less comparisons made). As seen in the figures, for high selection level, the speedup is smaller compared to that achieved in low select levels. The reason for this, we believe is in that the amount of time our system spends extracting the atoms group increases with the level of selection. Even though our system still shows considerable speedup over Gromacs in high level selections, we do believe there is room for improvement in our system and that is our immediate future work we are planning on doing. These figures also show the relation of the speedup to the workload intensity, i.e., the higher the workload intensity the higher the speedup.

The connection between the workload intensity and the speedup is better represented in the next set of figures, Figures ??-??. They show the speedup our system achieves over the Gromacs system on a varying workload intensity. Each of those figures show the speedup with different dataset sizes (e.g., 838,000, 2,567,600 atoms, etc.), including 10, 100, and 1000 data frames. The speedup is calculated simply as a ratio between the running time of our system on a certain set of workload and that of the Gromacs system on the same workload. These figures show that the speedup over varying workload intensity achieved by our system ranges anywhere from about 10 to 1000 times, depending on the size of the dataset, number of frames and the selection of the atoms.

Figure ??, shows the speedup our system achieves over all workload intensity (average workload intensity) with varying dataset sizes. It is clear that, again our system has better performance than the Gromacs system. The speedup presented in this set of figures ranges anywhere from about 15 to 650 times.

The last figure, Figure ??, shows the speedup our system achieves over all workload intensity and all select levels with varying dataset sizes. This figure, in a way, summarizes the previous two sets of figures, bringing together the workload and the different selections through the average. It is clear that, again our system has better performance than the Gromacs system. The speedup ranges anywhere from 50 to 250.

All four sets of figures show that such push-based design has clear advantages over the pull-based type of design incorporated in the Gromacs system.

## VI. CONCLUSIONS AND FUTURE WORK

The objective of our work is to design and implement improved data analysis system that can be used in the field of molecular simulation system's analysis. In this paper, we introduce the idea for such system. We build our system on a push-based type design, where data from data arrays is being pushed onto available queries in the system. These queries are being executed on the pushed data and produce intermediate / final result that would be used as part of the data analysis. We are able to achieve an improvement over existing, pull-based type designs because of the I/O overhead such designs introduce when dealing with large volumes of scientific data. Also, our queries are able to be executed on the same stream of data, making it suitable solution for streaming circumstances. We designed a benchmark that can be used

to test data analysis systems. This benchmark comprises of three parts: 1)benchmark data, 2)benchmark queries, and 3) benchmark parameters. We use this benchmark to compare our system to one of the most frequently used MS analysis systems, Gromacs. The efficiency and speedup achieved by our system is supported by extensive experiments and their results. The results show that our push-based design achieves up to about 1000 times speedup in comparison to a pull-based design, i.e., Gromacs.

One direction of our future work will be to further improve our push-based design. Through the extensive experiments we have learned that our design can be improved when the atom selection clause involves many conditions. This improvement may be in the direction of improving the algorithmic part, but it can also be in the direction of improving the data presentation/organization we have used in the system.

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