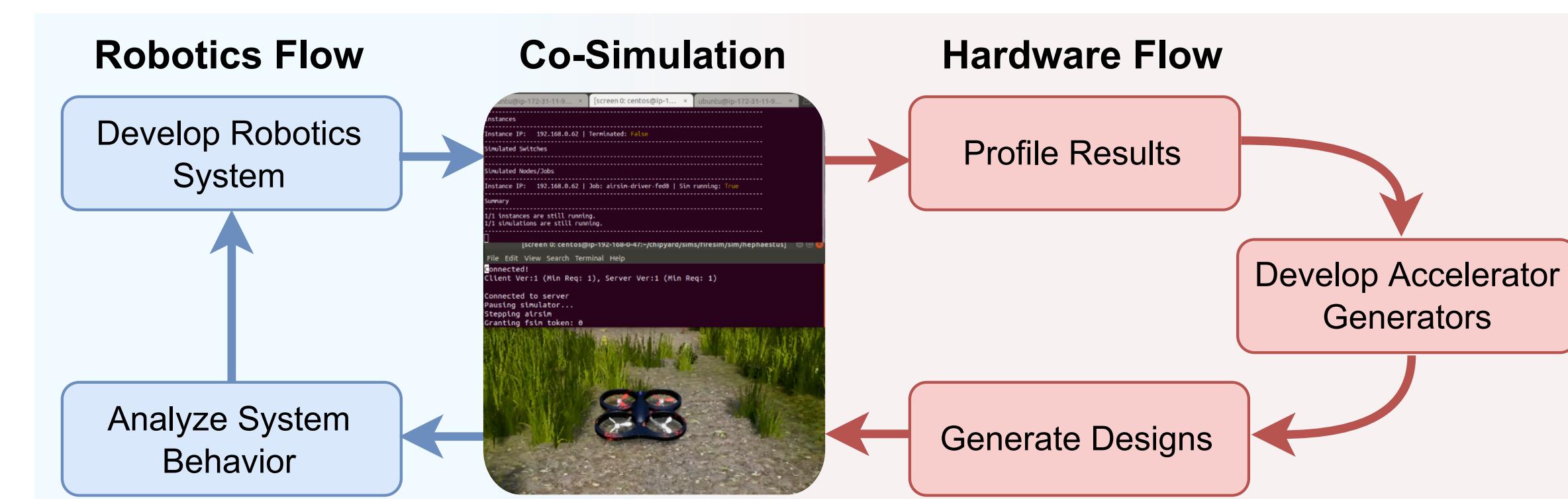


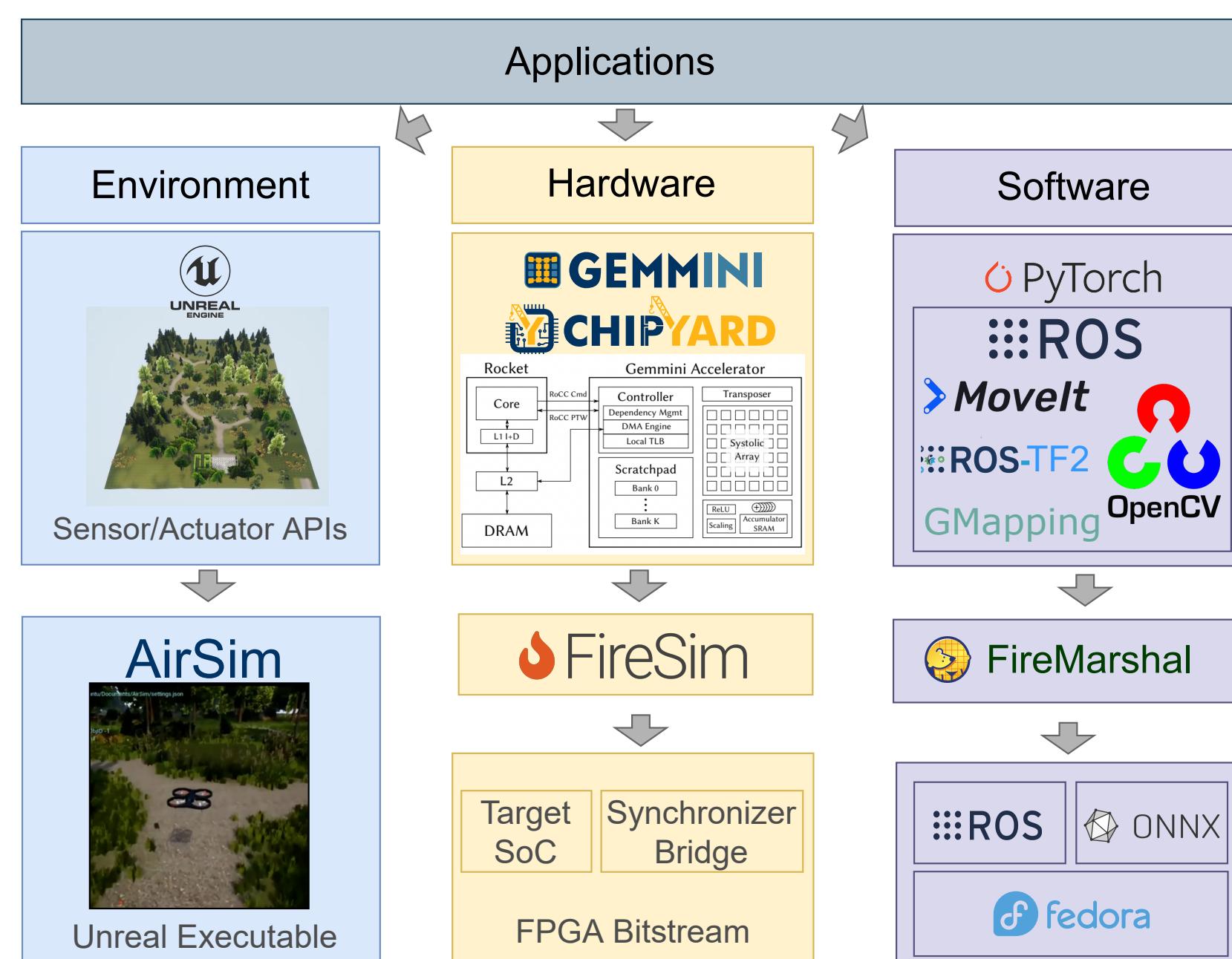


## Overview

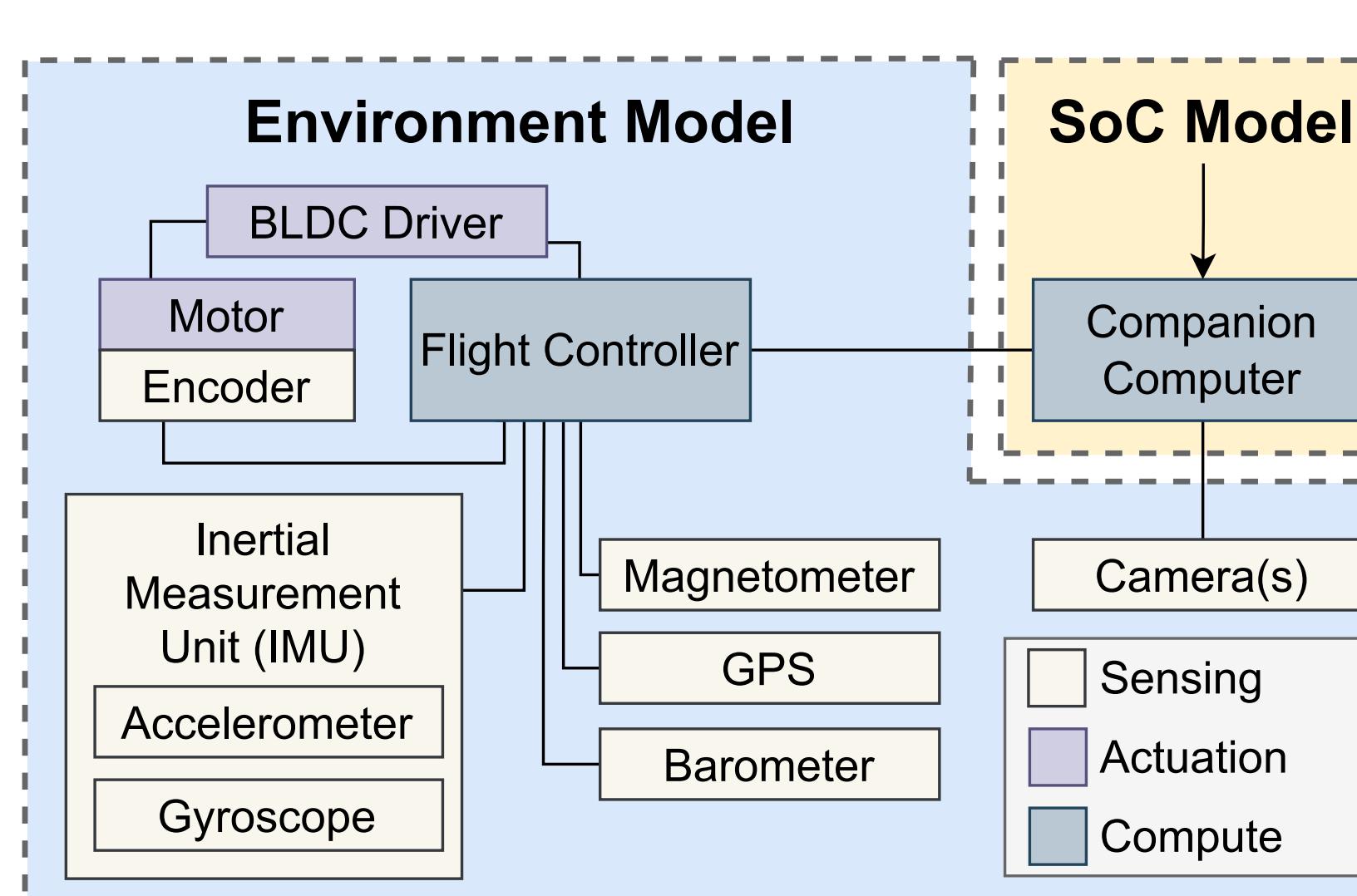
Enable robotics researchers to accurately evaluate **heterogeneous robotics SoCs** running a **full software stack** in **real-world environments**.



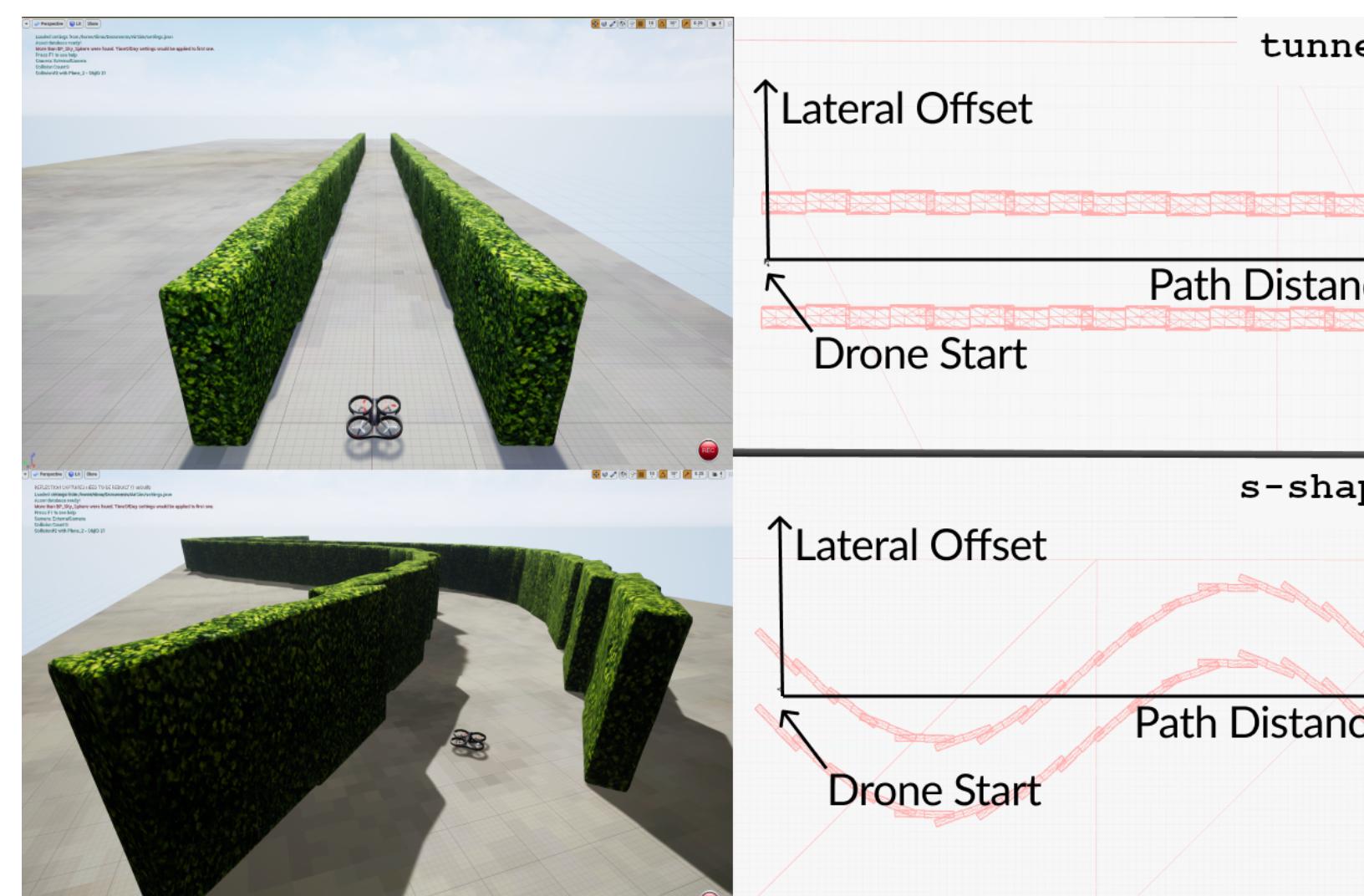
## User Flow



## System Model

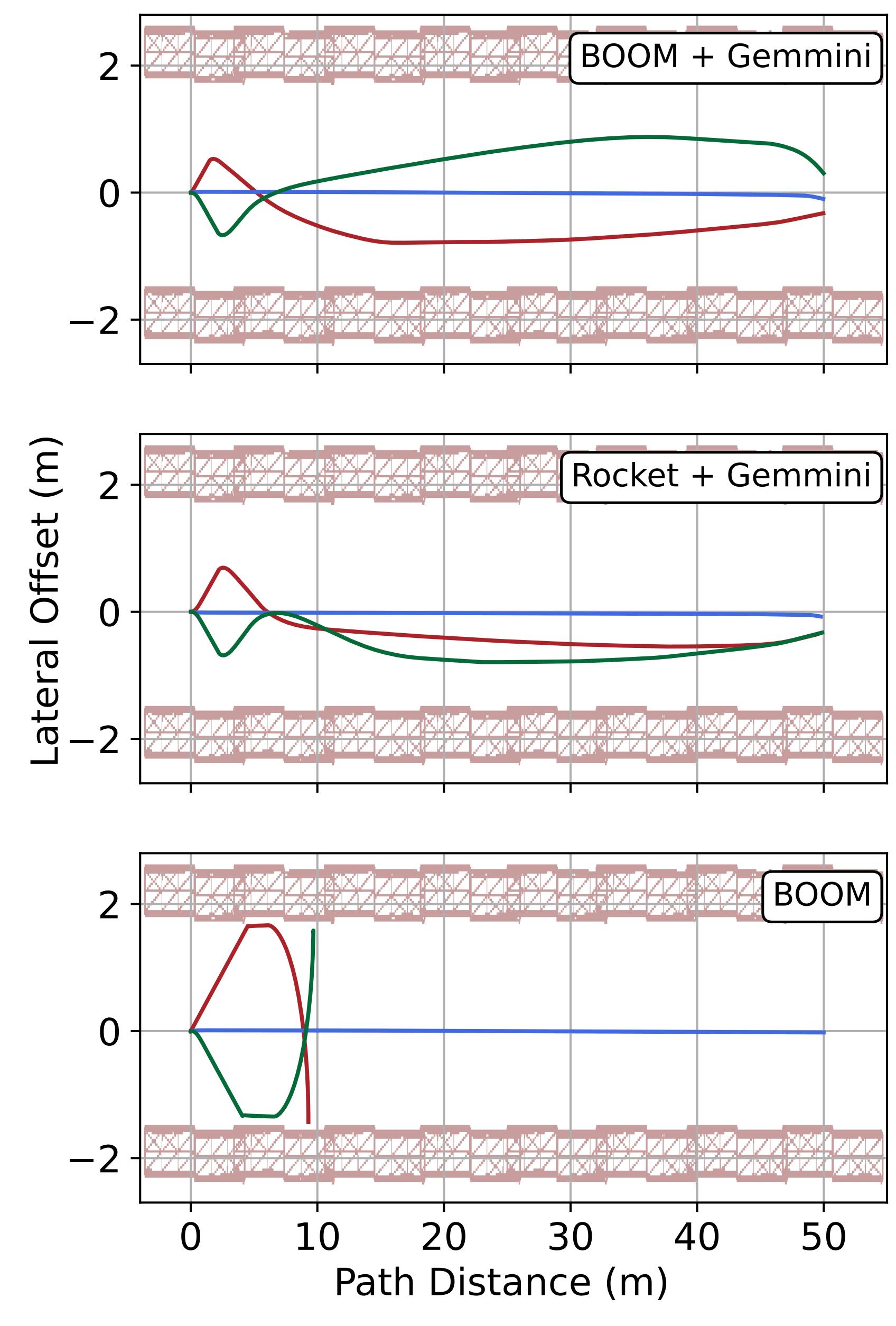


## Environments

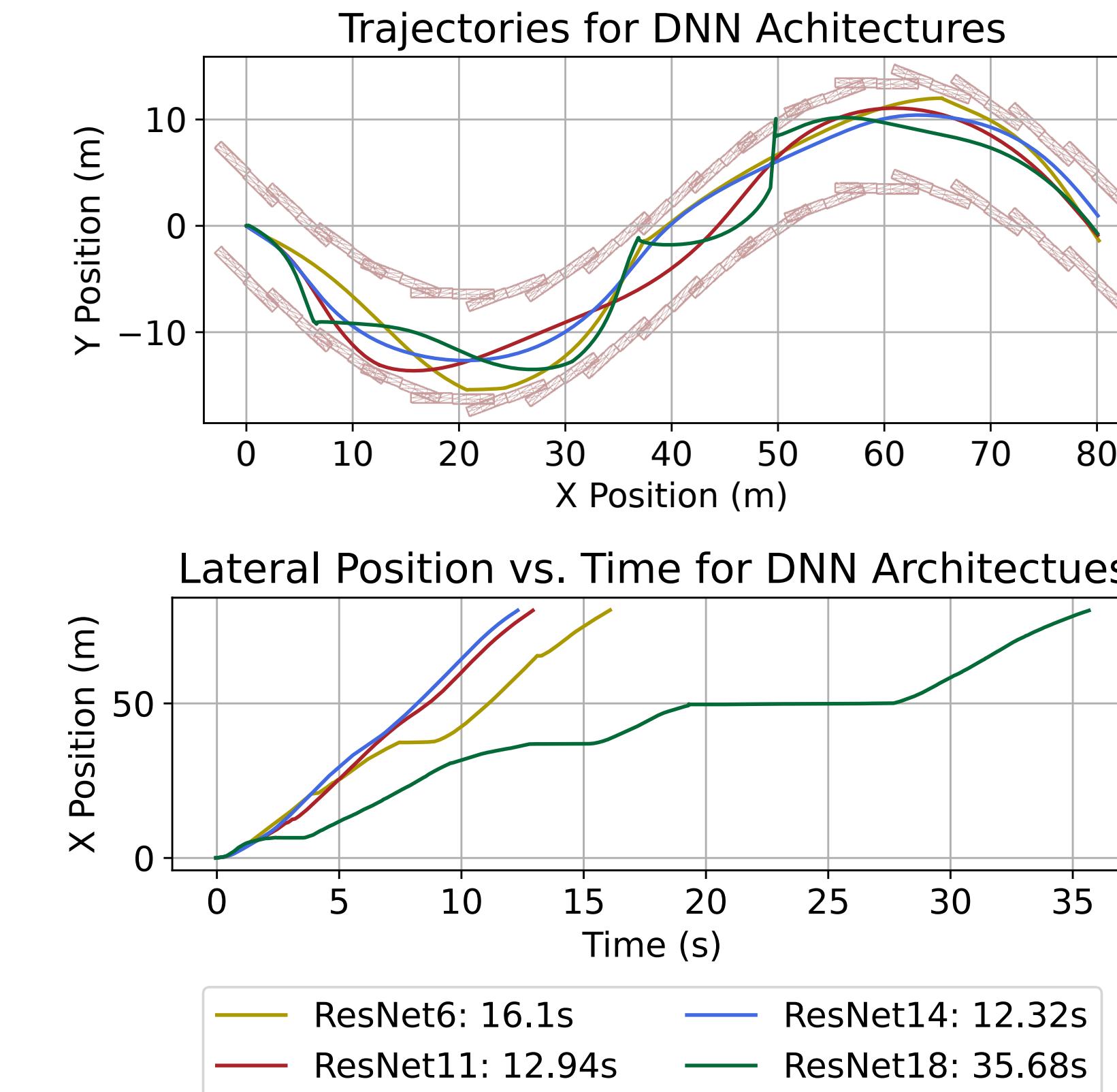


## Experimentation

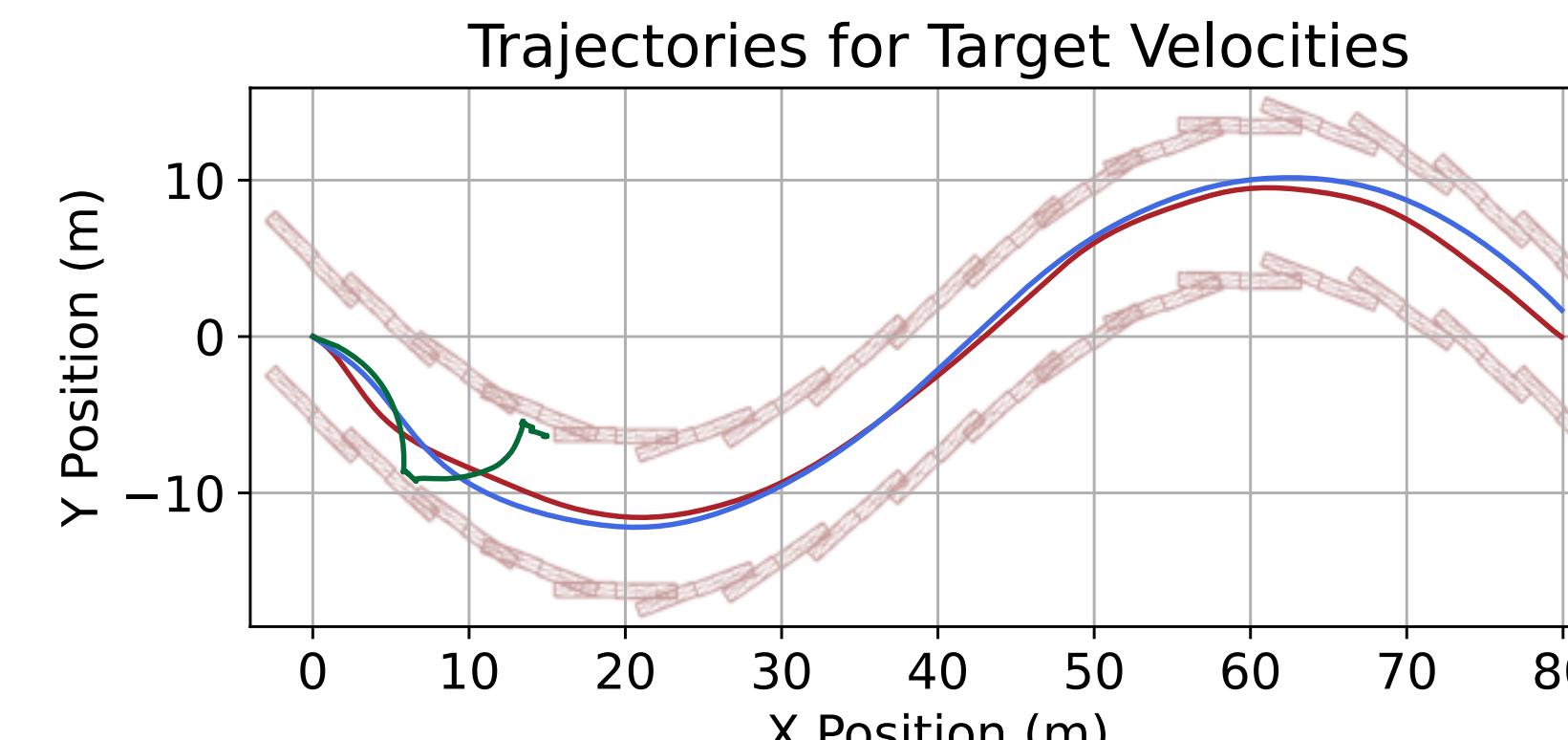
### Architectural Sweeps



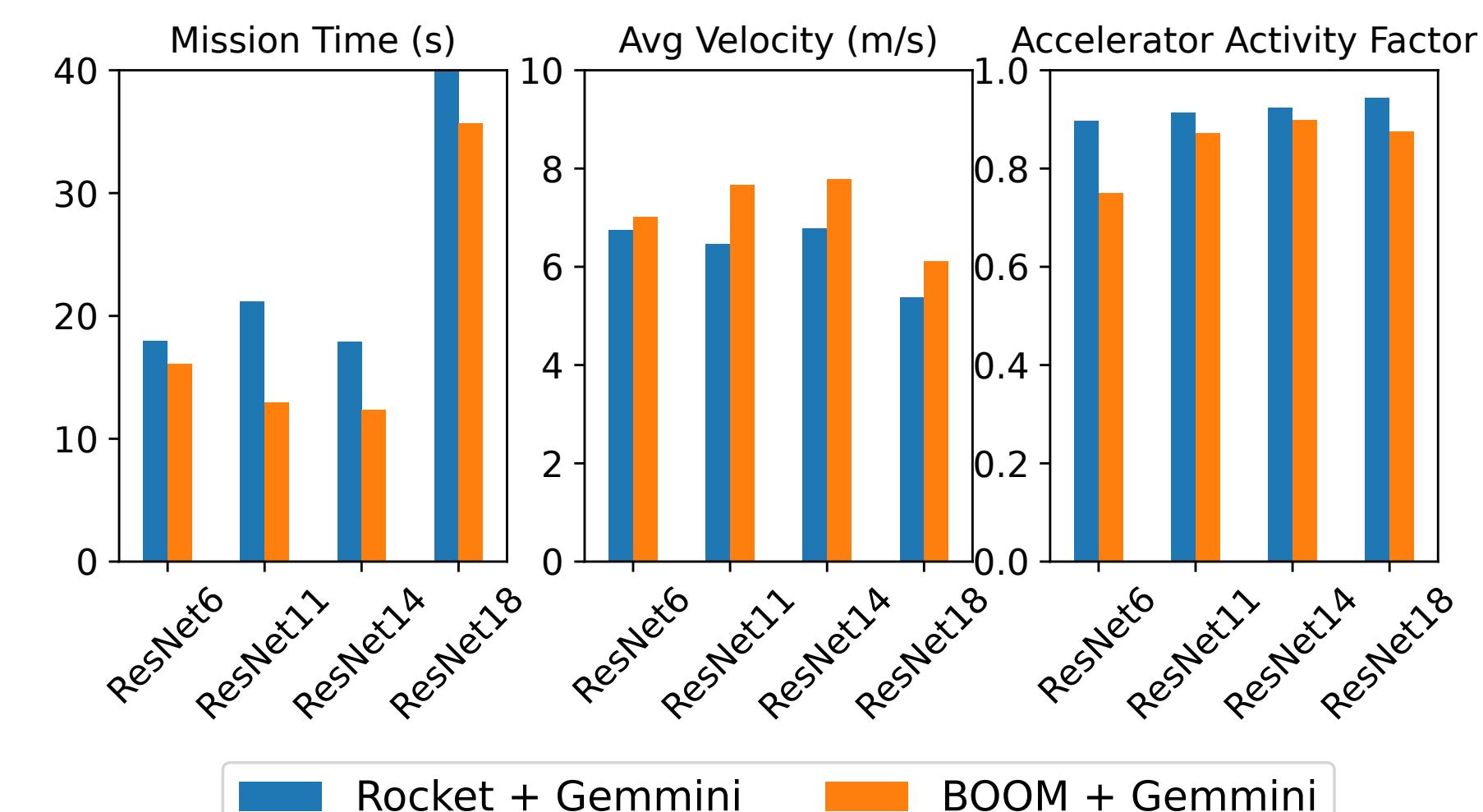
### DNN Architecture Sweep



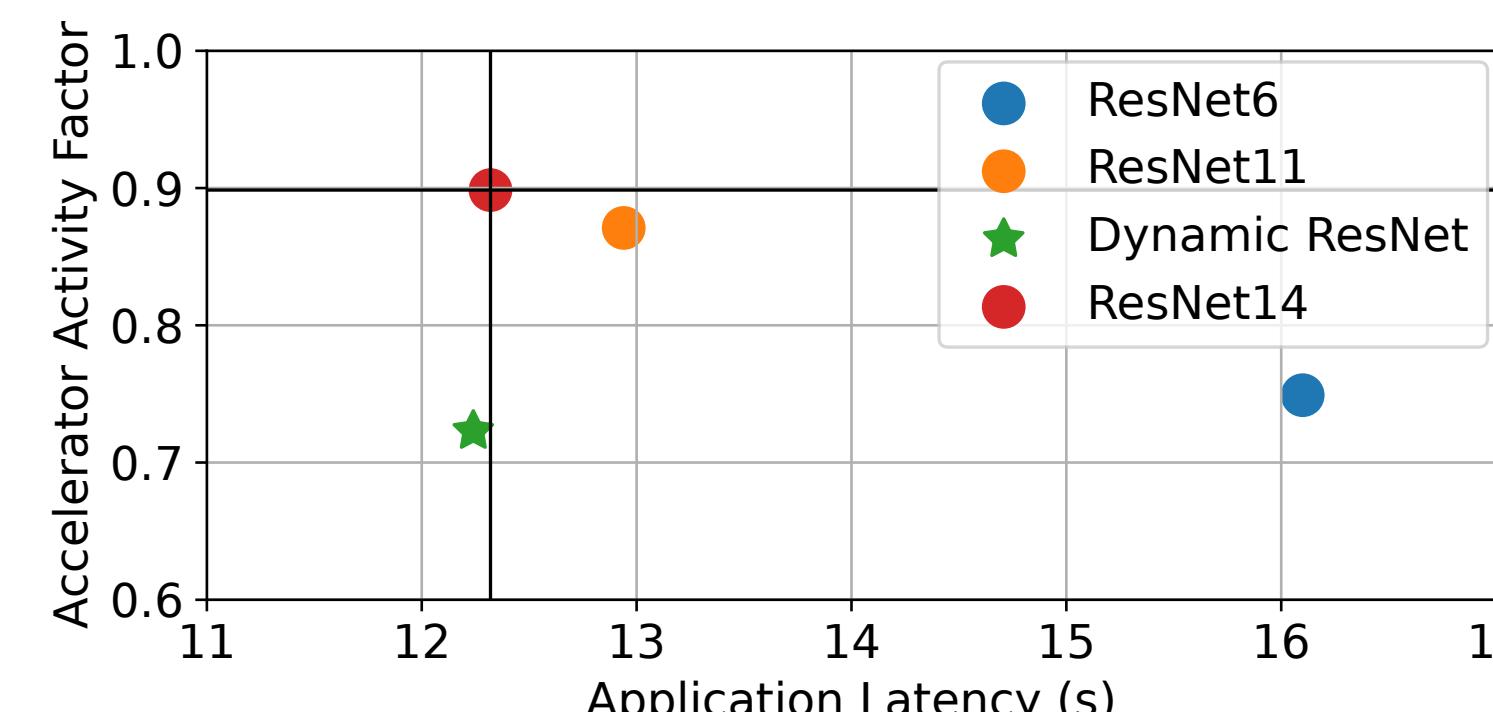
### Velocity Sweep



### HW/SW Co-Design



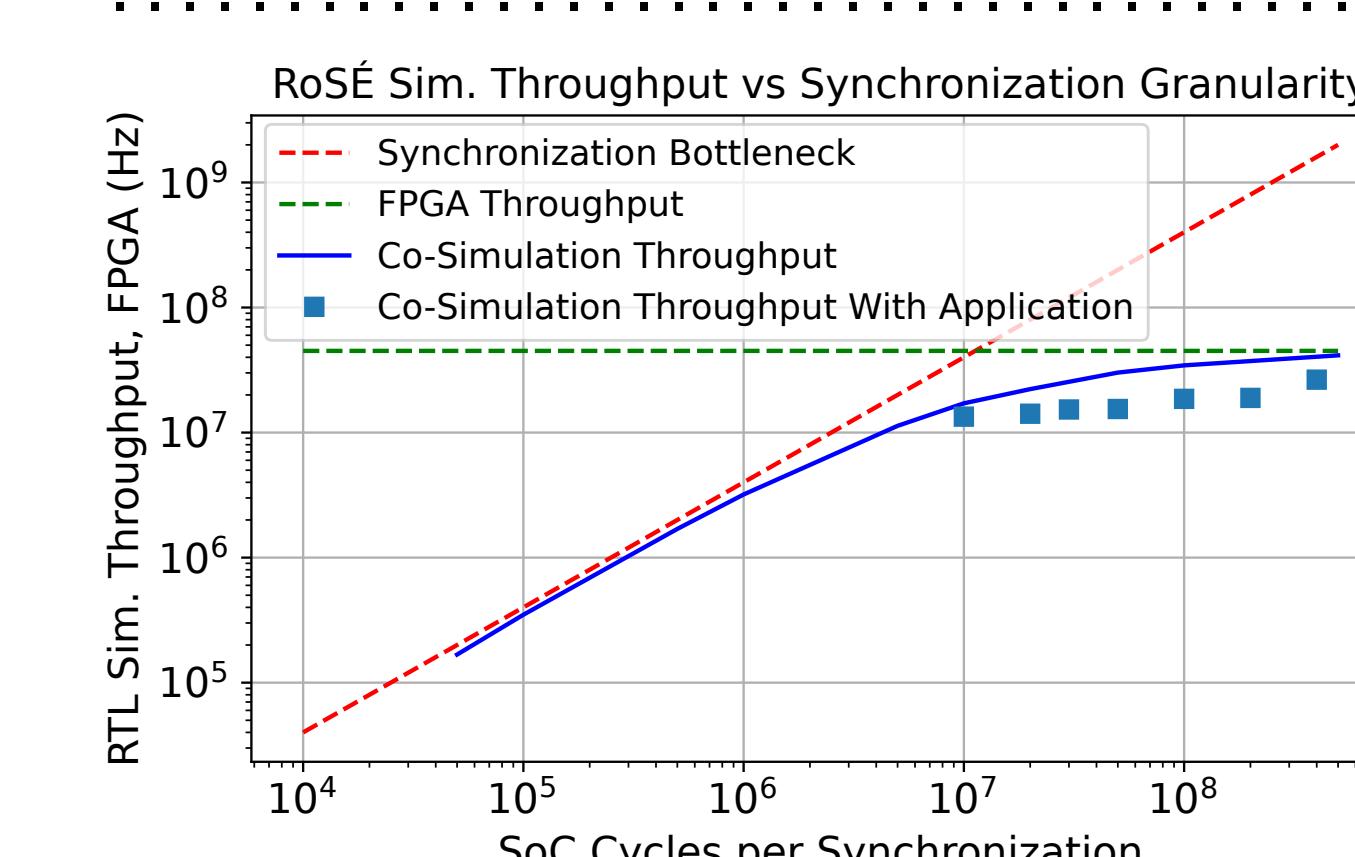
### Dynamically Scheduling DNNs



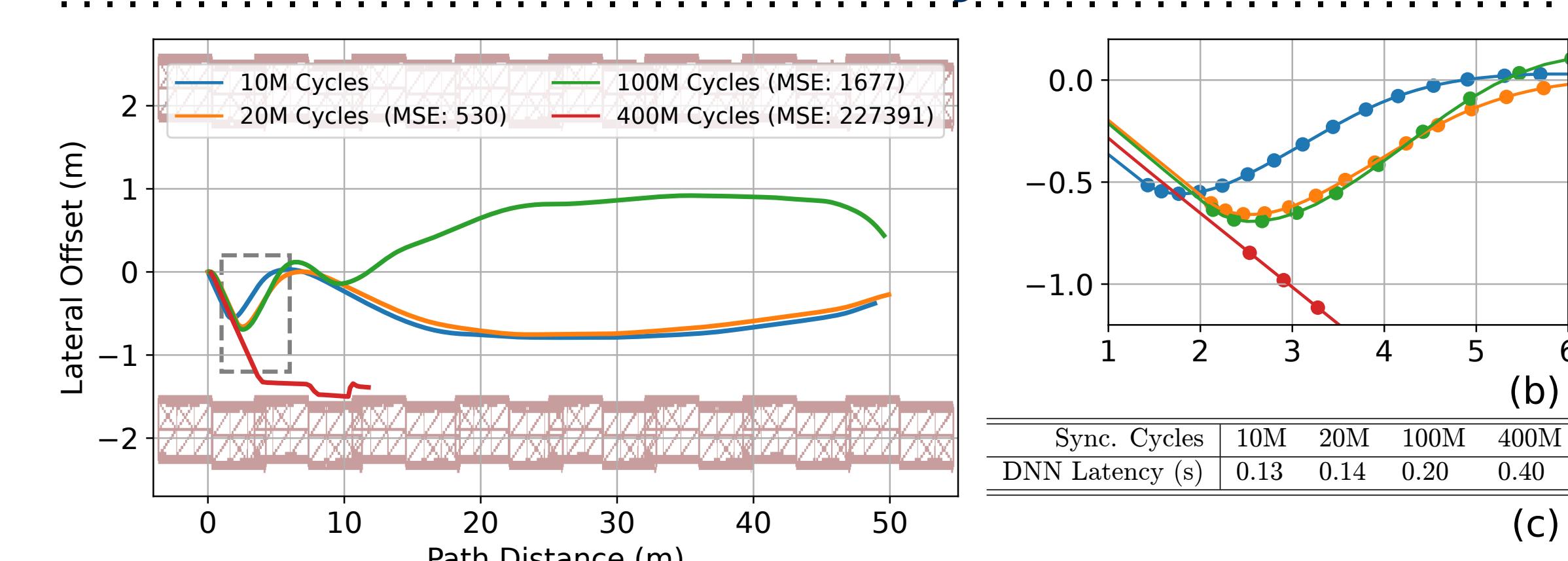
Dynamically select between ResNet14 and ResNet6 depending on depth sensor measurements.

## Simulator Parameter Tradeoffs

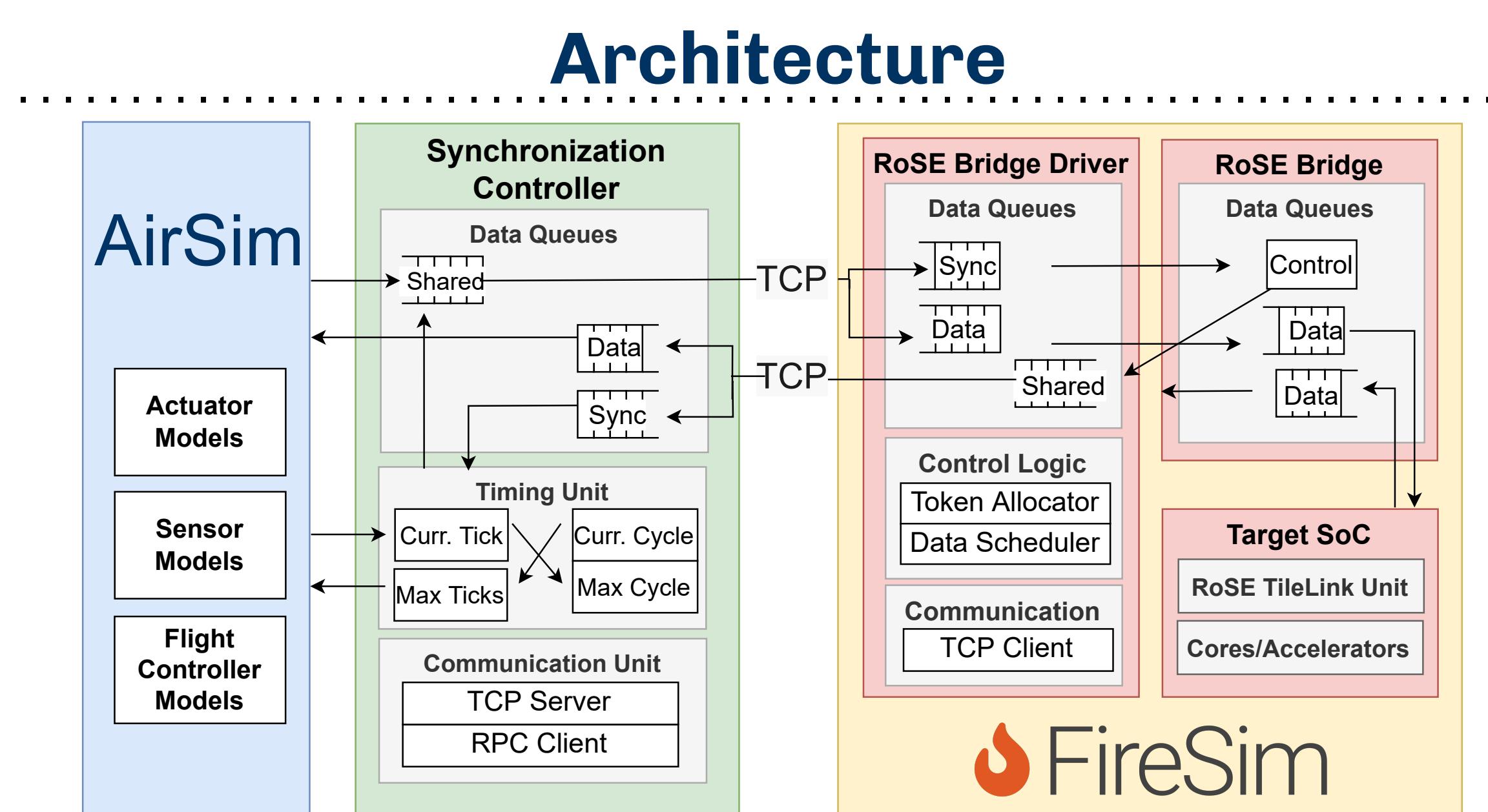
### Performance



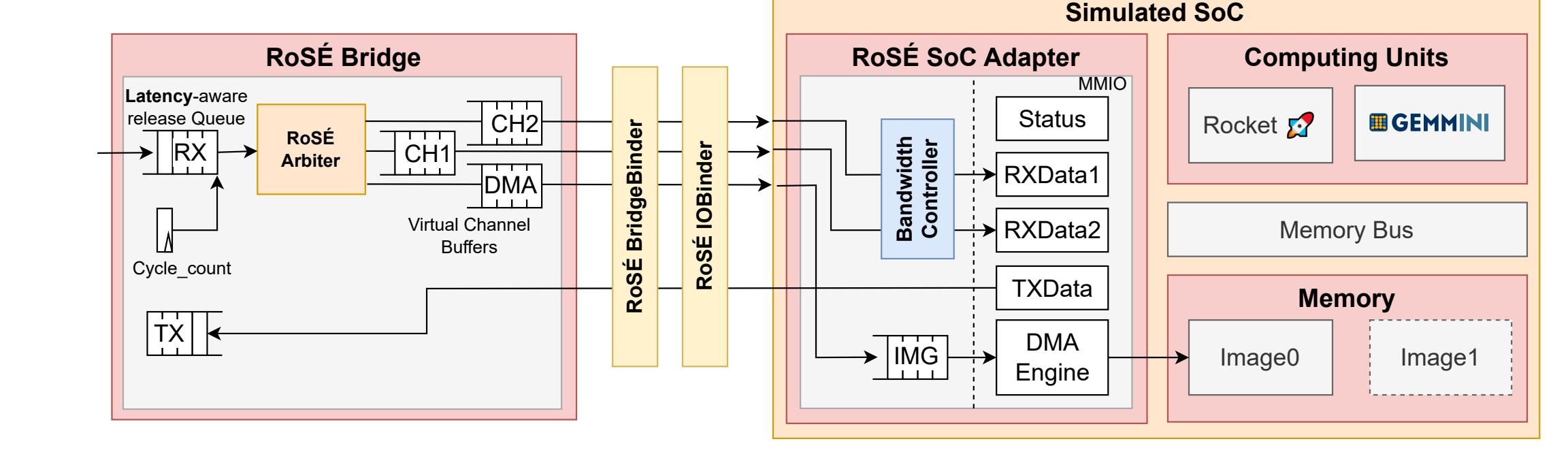
### Accuracy



## Infrastructure

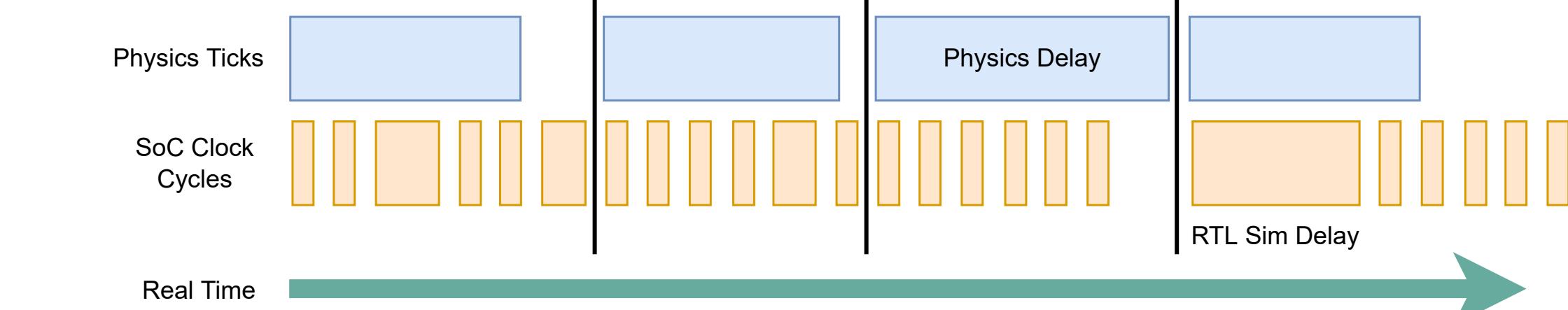


### RoSÉ Adapter



- Step-Latency injection in Synchronizer
- Cycle-Latency injection in Bridge
- Configurable MMIO & DMA Engine type, latency & BW

### Synchronization



## New Environments



## Contact Information

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