

# Ian Daniel St. Louis

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## EDUCATION

2014-Present	<b>UNIVERSITY OF CALIFORNIA, BERKELEY</b>	
	B.S. Mechanical Engineering, <i>Magna Cum Laude</i> (GPA: 3.7/4)	Dec 2018
	M.S. Mechanical Engineering (GPA: 4/4)	Dec 2019

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## TECHNICAL SKILLS

### Software

- MATLAB, SolidWorks, LabVIEW (CLAD certified), NX, AutoCAD

### Hands-on

- Instron, OMM, laser-cutting, 3D printing, soldering and interface mockups for rapid prototyping

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## EXPERIENCE

Summer, 2018	<b>MECHANICAL ENGINEERING INTERN</b>	Cupertino, CA
Jan. 2017-Aug. 2017	<b>Apple— iPhone and Apple Watch Displays</b> <ul style="list-style-type: none"><li>• Developed an electromechanical optical fixture for 6-axis, sub-micron, programmatic alignment of a substrate.</li><li>• Drove failure analysis and designed experiments to determine the root cause for the highest risk display issues faced during iPhone 8/8+ development.</li><li>• Approved SPC data and implemented corrective actions for process deviations on iPhone 8/8+ display builds.</li><li>• Built a widely used application to drastically improve engineers' efficacy in synthesizing FAI/SPC build data.</li><li>• Directed a study to evaluate the parameter-space, effectiveness and vendor-side application of new methods to test fracture strength of OLED passivation on Series 2, 3, and next-gen Apple Watch displays.</li></ul>	
Jan. 2016-Jan. 2017	<b>BIO-INSPIRED ROBOTICS RESEARCHER</b> <b>CiBER LAB— Dr. Robert Full</b> <ul style="list-style-type: none"><li>• Led the construction, design, programming, testing and documentation of an under-actuated robot as part of a research project to mimic the mobility and dynamic turning of lizards.</li><li>• Designed robot in SolidWorks, programmed in Arduino. Constructed using a laser-cutter and ProJet 3D printer.</li></ul>	Berkeley, CA
Summer 2016	<b>ENGINEERING INTERN</b> <b>Leidos— Surveillance and Reconnaissance Division</b> <ul style="list-style-type: none"><li>• Developed pseudo-data generation algorithms in MATLAB and Python as an alternative to cross-validation, to provide a robust method of determining a machine learning classification algorithm's error on new data.</li><li>• Executed spectroradiometric tests, thermal calculations and analysis, 3D modeling, FEA and presentations to iteratively design printed circuit boards for demanding military vehicular application.</li></ul>	San Diego, CA
Jan. 2016-Sep. 2016	<b>STUDENT RESEARCHER</b> <b>Drone Application for Transit Systems— Dr. Karl Hedrick</b> <ul style="list-style-type: none"><li>• Conducted a feasibility study and report with a small team, commissioned by Bay Area Rapid Transit, assessing the technological, operational and safety aspects for drone applications to their railway systems.</li></ul>	Berkeley, CA

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## PROJECTS

Jan. 2018-May. 2018	<b>BUILT TO TILT</b> <b>ME 102b, Senior Capstone Project</b> <ul style="list-style-type: none"><li>• Derived analytical models, wrote electromechanical component code, and drove the assembly design and fabrication for a beautifully intricate, survival-based arcade game.</li></ul>	Berkeley, CA
Spring 2016	<b>1<sup>ST</sup> PLACE PRIZE   LARGE-SCALE WATER CONDENSER</b> <b>UC Berkeley-wide \$12k WaterSeer Design Competition</b> <ul style="list-style-type: none"><li>• Led a team of five to the 1<sup>st</sup> place prize, driving the creation of a proof of concept design for a device which passively condenses water from the air.</li><li>• Provided the project's 3D modeling, FEA, rendering and designed the entirety of the winning turbine system.</li></ul>	Berkeley, CA