THE UGSORT ALGORITHM

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Abstract

This paper describes the novel UGSort merge sorting algorithm. The algorithm is simple, elegant, flexible and easy to implement.

Keywords: sort, algorithm, merge

The UGSort Algorithm

The UGSort algorithm (Unexpectedly Good Sort) is a simple, elegant and flexible algorithm. It is easy to implement in different settings and is efficient.

The Algorithm

The algorithm is a merge sorting algorithm based on partitioning the input keys into an array of double ended queues (dequeues) and then merging the double ended queues into a single queue from which the results of the sort can be output.

Sorting a set of keys $KS = \{k_I, k_2...k_n\}$ with n keys begins with initialising the first element of an array (S) of double ended queues S_0 with the first key available from the input set k_I , both the head and the tail of S_0 will be set to k_I .

Each subsequent key in the input set $k_i = k_2...k_n$ will be added to the partitions by testing against the head and tail keys in each of the available double ended queues in S. If the key k_i is less than or equal to the head value of the queue, then the key is added to the head of the queue. If the key was not consumed by the head of the queue, then if it is greater than or equal to the tail value of the queue then, it is added to the tail of the queue. If the key was not consumed by any of the queues in S then a new queue is added to the end of the array initialised with the unused key k_i .

If a new queue was added to the array S then the number of elements in the array is checked against a computed maximum S_{max} if it exceeds the maximum then a pre-emptive merge is performed. The value of S_{max} is the greater of 100 or $(\frac{sqrt(\frac{i}{2})}{2})$, where i is the number of keys processed so far. The pre-emptive merge will reduce the number of queues in the array S by merging alternate elements in the array with their predecessor. Thus, S_1 is merged with S_0 and removed from the array and so on for each alternate element in the array.

After the last key k_n has been added to the queues in the array S a final merge is performed where all queues are merged into the first queue in the array S_0 .

The input set KS is now sorted into ascending sequence in the queue S₀.

Pseudocode

 $KS = \{k_1, k_2...k_n\}$ Sort Input: Partition Array: $S = \{\}$ Max Partitions: m = 100 $S_0 = double_ended_queue(k_1)$ For Each k_i in $k_2...k_n$ ForEach S_i in S If $k_i \ll S_i$.head S_i .head = k_i Key_consumed = true Exit ForEach End If If $k_i >= S_j$.tail S_j .tail = k_i Key_consumed = true Exit ForEach End If End ForEach If (!Key-consumed) $S_{j+1} = double_ended_queue(k_1)$ If (j+1 > m)// Perform pre-emptive merge ForEach S_j in S Merge S_{j+1} into S_j

Delete S_{j+1}

End ForEach

NewMax = (sqrt(i/2)/2)

If (NewMax > m) m = NewMax

End If

End If

End ForEach

// Perform final merge

ForEach S_i in S₁...S_m

Merge S_i into S_0

End ForEach

Key Stability

Key stability is the sorting property of preserving the input sequence for keys of equal value. The UGSort algorithm as presented is not stable. However, it can be made stable by making minor changes to the algorithm. The tests for addition to the head or tail of a queue must be changed from less than or equal and greater than or equal to less than and greater than. The merge processing must always give precedence to the leftmost (lowest index) queue. These changes will result in a slightly less efficient algorithm.

Best and Worst Cases

The "Best-Case" input for the algorithm is an input set SK that is pre-sorted into descending sequence, this results in a single queue being used with all keys being added to the head of the queue.

The "Worst-Case" input for the algorithm is an input set SK that is pre-sorted into ascending sequence and then reordered by taking alternating keys from the head and the tail of the sorted queue. For KS = $\{k_1, k_2...k_n\}$ the worst-case input would be $\{k_1, k_n, k_2, k_{n-1}...\}$.

Sort Properties

As noted in the previous section the UGSort algorithm is not stable but, may be transformed into a stable sort by small modifications. The algorithm is not capable of in-place sorting and is therefore an out-of-place algorithm.

It is possible to introduce parallel processing for the pre-emptive and merge phases as individual merge operations can be done in parallel, there is no additional co-ordination needed for parallel merges.