

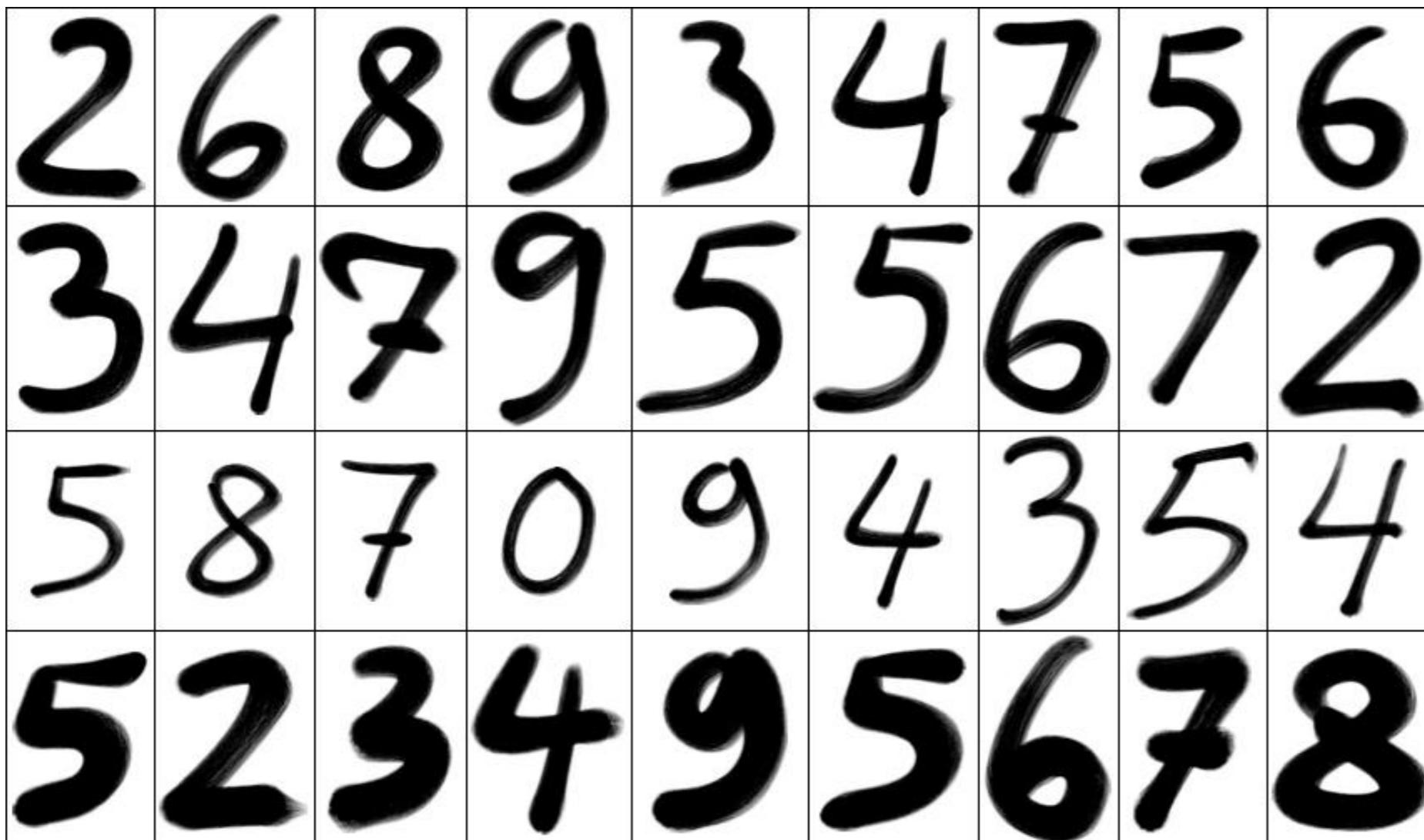
# Adaptive Intelligence

Prof. Eleni Vasilaki

# Types of Learning

- Supervised
- Unsupervised
- Reinforcement

# Supervised Learning



MNIST Database

# Supervised Learning

$$\{ (x^1, t^1) (x^2, t^2) \dots (x^P, t^P) \}$$

- An expert (supervisor) has provided labels for the data (e.g. class 1, class 2 etc).
- Parameters are updated so that the total error, evaluated using the training (labeled) data, is minimised.
- The system, if correctly trained, is expected to perform also with unseen samples from the same classes.

# Unsupervised Learning



# Unsupervised Learning

$$\{ x^1, x^2, x^3, \dots, x^p \}$$

- Just data - NO labels!
- Detect intrinsic structure in the data.
- Leads to clusters (not classes).

# Reinforcement Learning

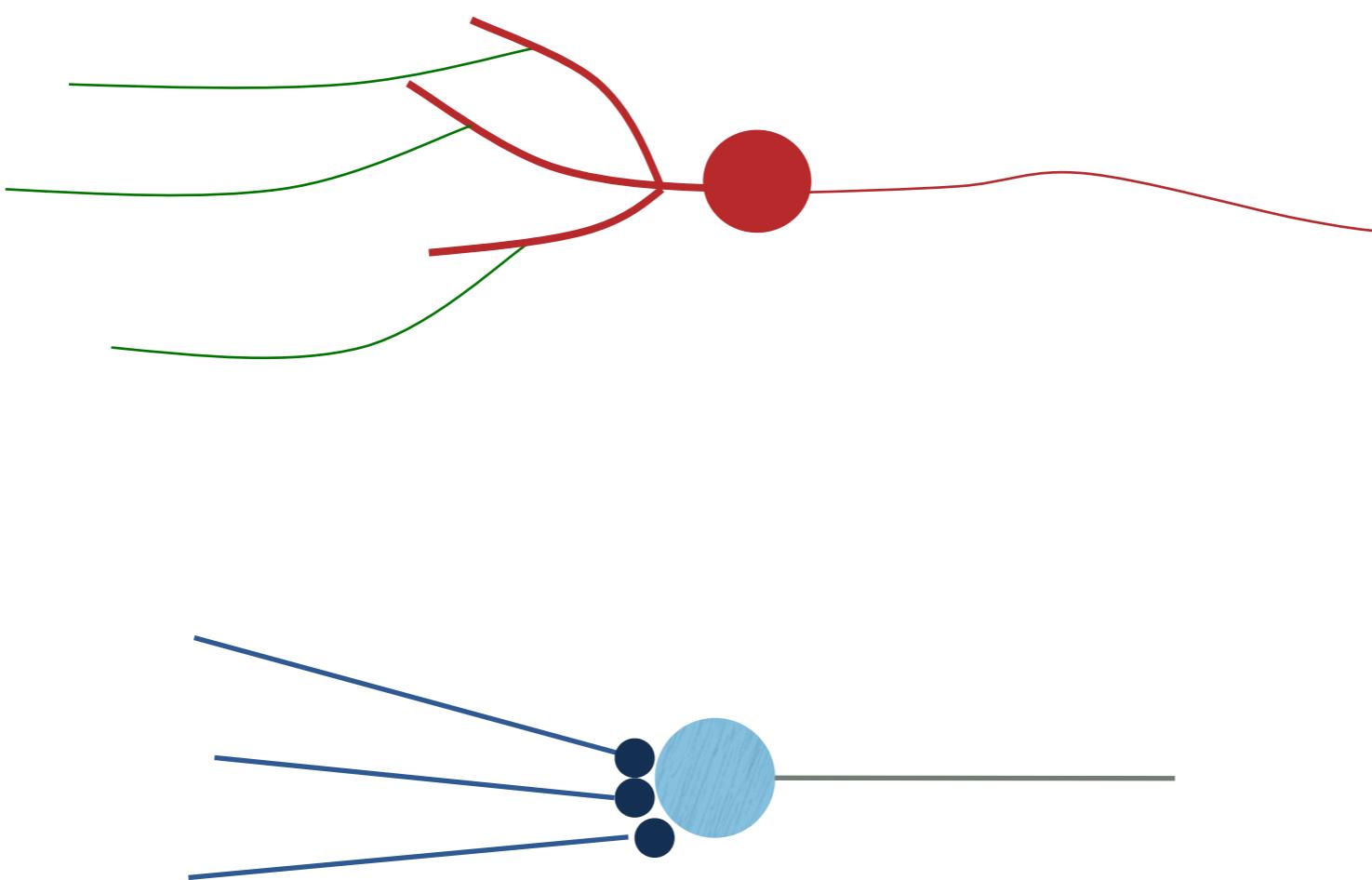


# Reinforcement Learning

$$\{ (x^1, a^1, r^{11}) (x^1, a^2, r^{12}) (x^2, a^1, r^{21}) \dots \}$$

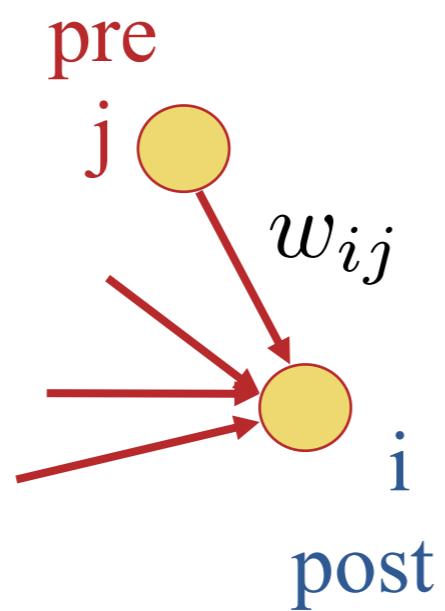
- An agent receives an input/stimulus.
- Choice of actions.
- Reward upon correct action (or actions - it may not be immediate!).
- Parameters are updated so that the total Reward is maximised.

# Artificial Neurons



$$\nu_i = g \left( \sum_j w_{ij} \nu_j \right)$$

# The Hebbian rule



Correlations

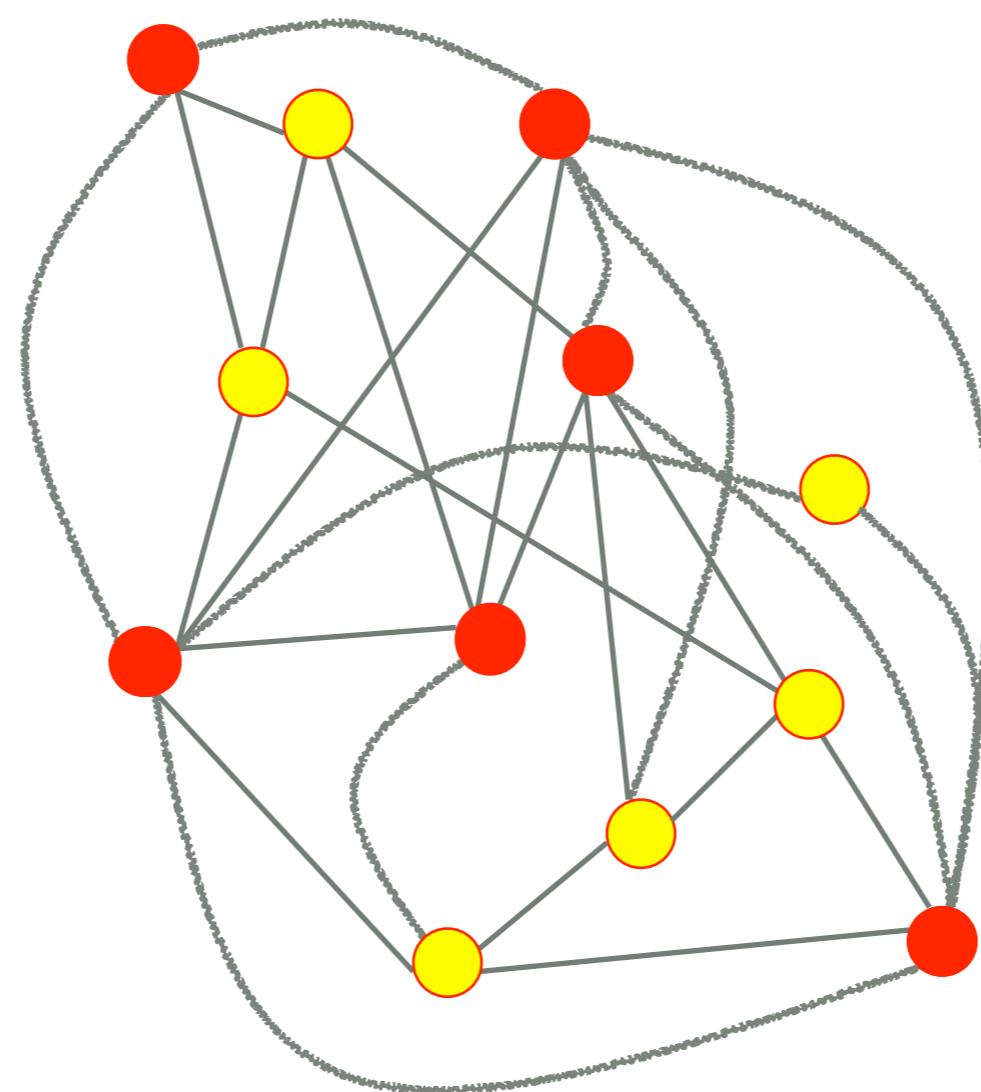


Donald Hebb

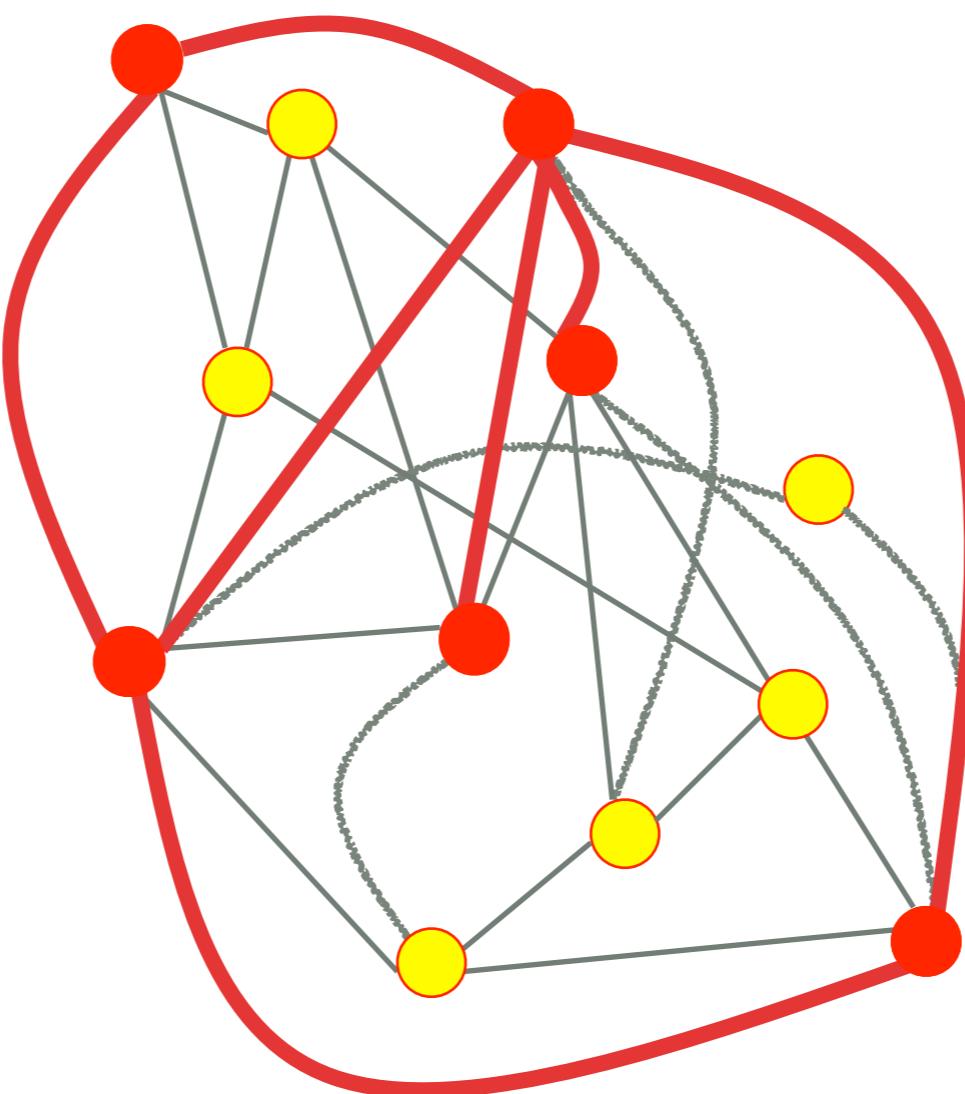
**“Neurons that fire together wire together.”**

*–A compact form of Donald Hebb’s postulate*

# Hebbian Learning



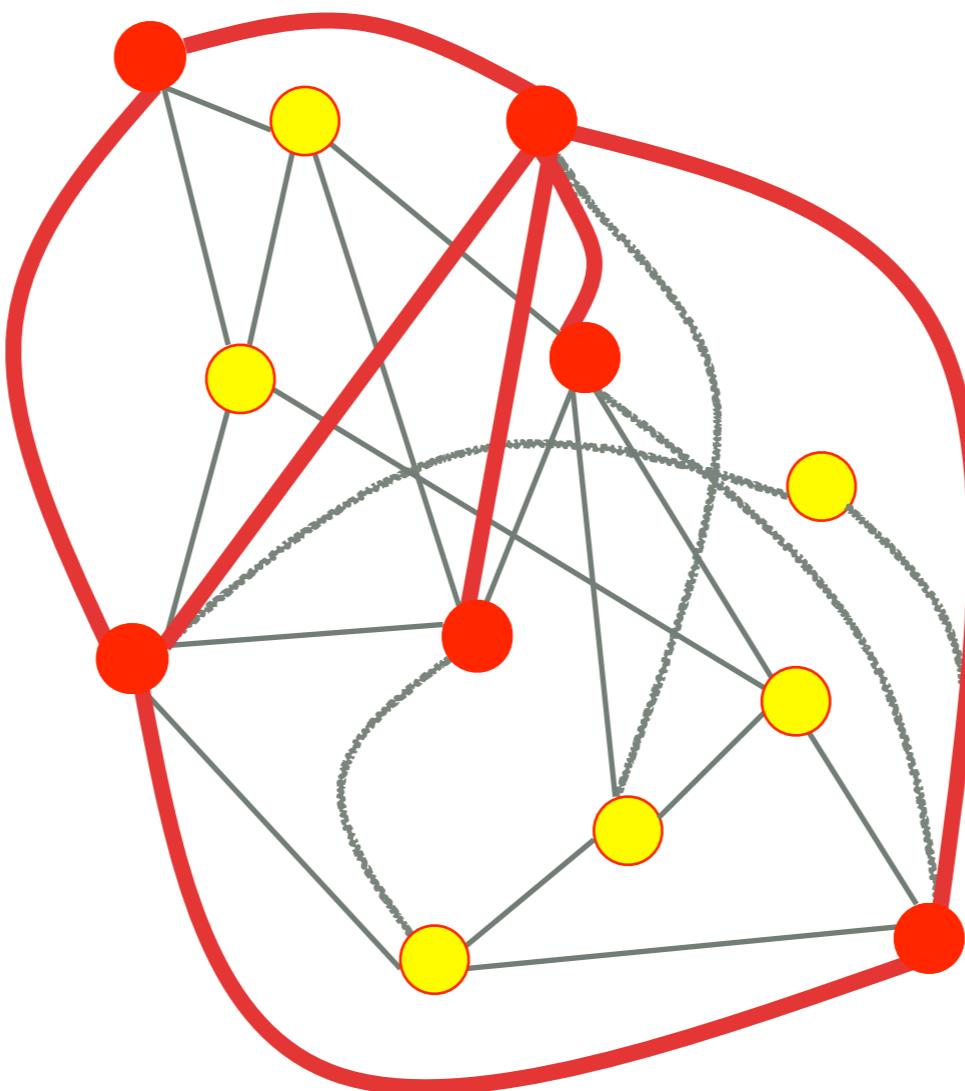
# Hebbian Learning



item memorized

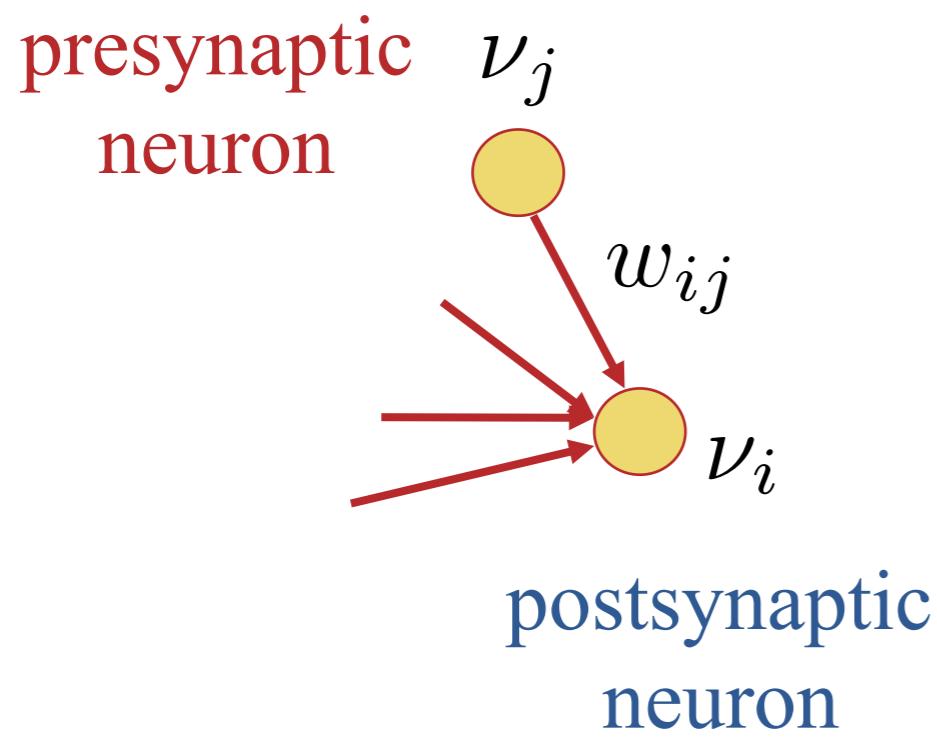
# Hebbian Learning

Recall:  
Partial info



item recalled

# The “minimal” Hebbian Rule



In equations

$$\Delta w_{ij} = w_{ij}^{new} - w_{ij}^{old} = \alpha \nu_i \nu_j$$

$w_{ij}$  : weight from neuron j to neuron i

$\Delta w_{ij}$  : weight change

$\alpha$  : learning rate,  $>0$

# Learning rule notation

**Discrete time**

$$\Delta w_{ij} = f(\nu_i, \nu_j, w_{ij})$$

$$w_{ij} \rightarrow w_{ij} + f(\nu_i, \nu_j, w_{ij})$$

**Continuous time**

$$\frac{dw_{ij}}{dt} = g(\nu_i, \nu_j, w_{ij})$$

# Hebbian rules

$$\Delta w_{ij} = \alpha \nu_i \nu_j$$

$$\Delta w_{ij} = \alpha \nu_i \nu_j - c$$

$$\Delta w_{ij} = \alpha(\nu_i - \theta)\nu_j$$

$$\Delta w_{ij} = \alpha(\nu_i - \theta)(\nu_j - \theta)$$

**Common “ingredient”**

$$\Delta w_{ij} = \alpha \nu_i \nu_j$$

# Which rules are Hebbian?

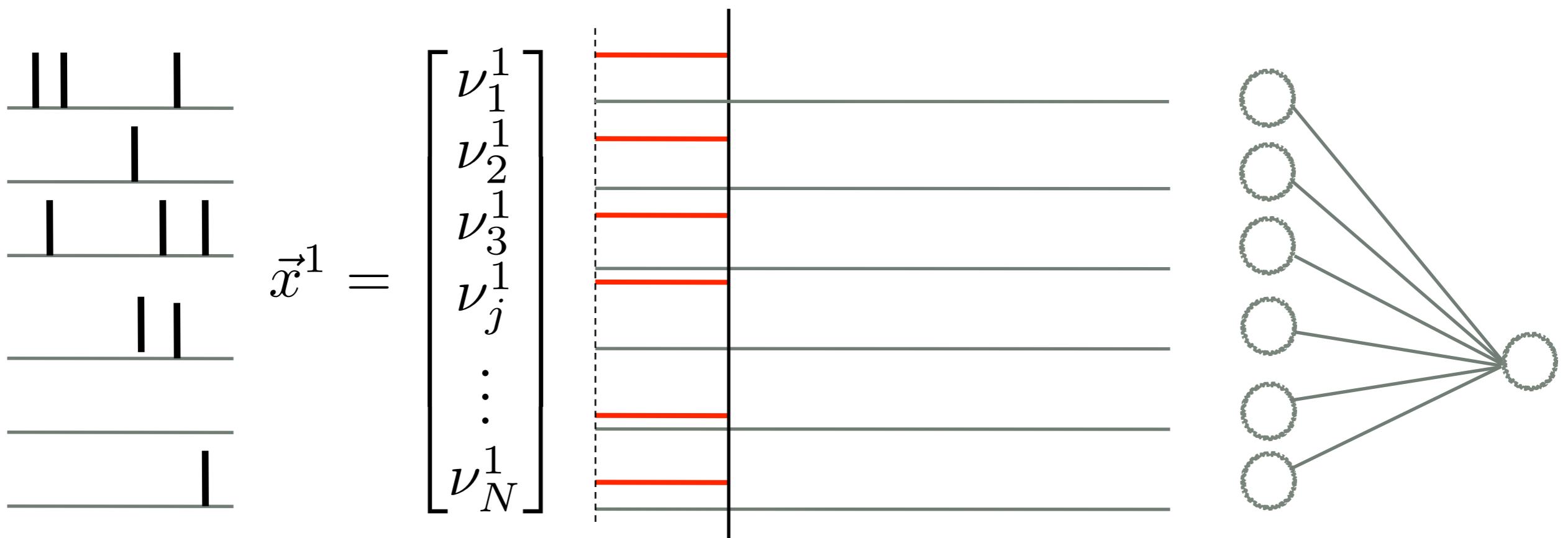
Variable definitions.  $x$ : stimulus (neuronal input),  $y$ : neuronal activity,  $w$ : synaptic weight,  $\epsilon$ : small positive number (learning rate),  $r$  : reward. Unless otherwise stated,  $x,y$  are mean firing rates.

1. Rescorla-Wanger (reward predicting) rule.  $w \rightarrow w + \epsilon \delta x$ , where  $\delta = r - y$ ,  $x \in \{0, 1\}$ .
2. Homeostatic rule.  $w \rightarrow w + \epsilon (y - \theta)$ , where  $\theta$  is the homeostatic threshold.
3. Node perturbation.  $w \rightarrow w + \epsilon ry\xi$ , where  $\xi$  represents noise (random variable drawn from a Gaussian distribution).

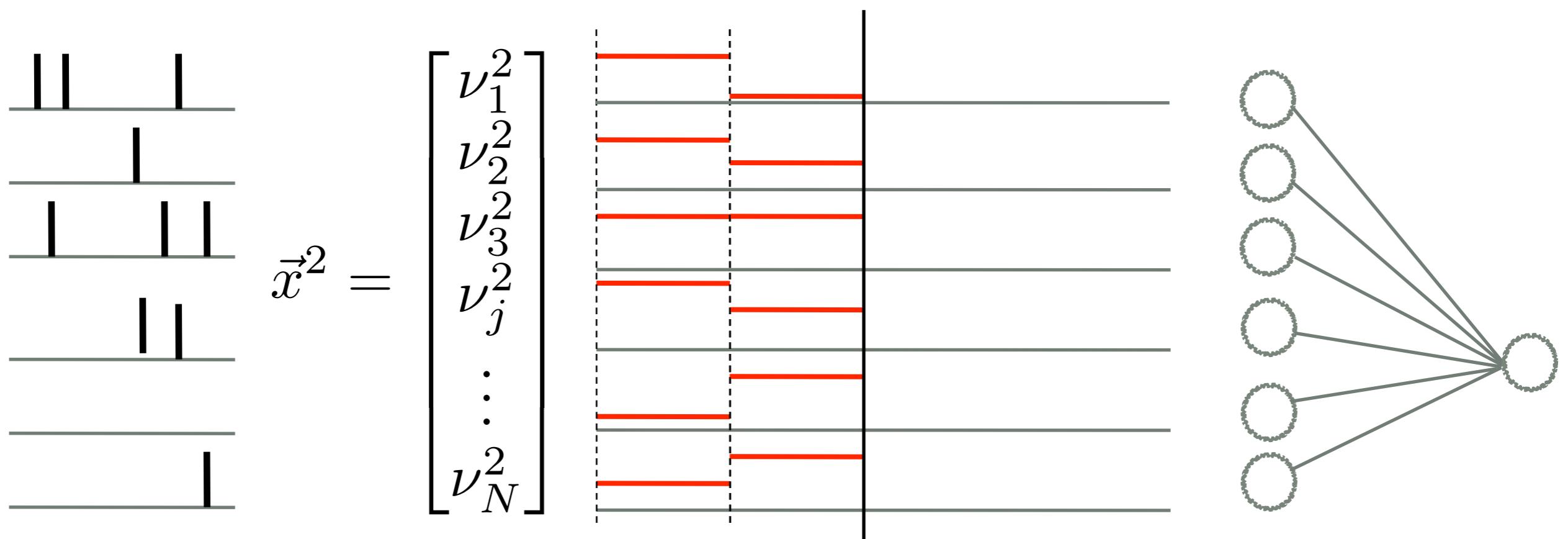
# Which rules are Hebbian?

5. Sejnowski rule.  $w \rightarrow w + \epsilon(y - \langle y \rangle)(x - \langle x \rangle)$ , with  $\langle . \rangle$  being the mean activity of the signals  $y$  and  $x$  across time.
6. Oja rule.  $w \rightarrow w + \epsilon y(x - yw)$ .
7. Learning in Hopfield networks.  $w \rightarrow w + \epsilon yx$ , with  $x, y \in \{-1, 1\}$ .
8. Delta rule.  $w \rightarrow w + \epsilon \delta x$ , where  $\delta = t - y$ , with  $t$  being the target for input  $x$ .
9. Associative Reward Inaction  $w \rightarrow w + \epsilon r(y - P(y))x$ , where  $P(y)$  the probability of  $y$  to be active,  $y \in \{0, 1\}$ .

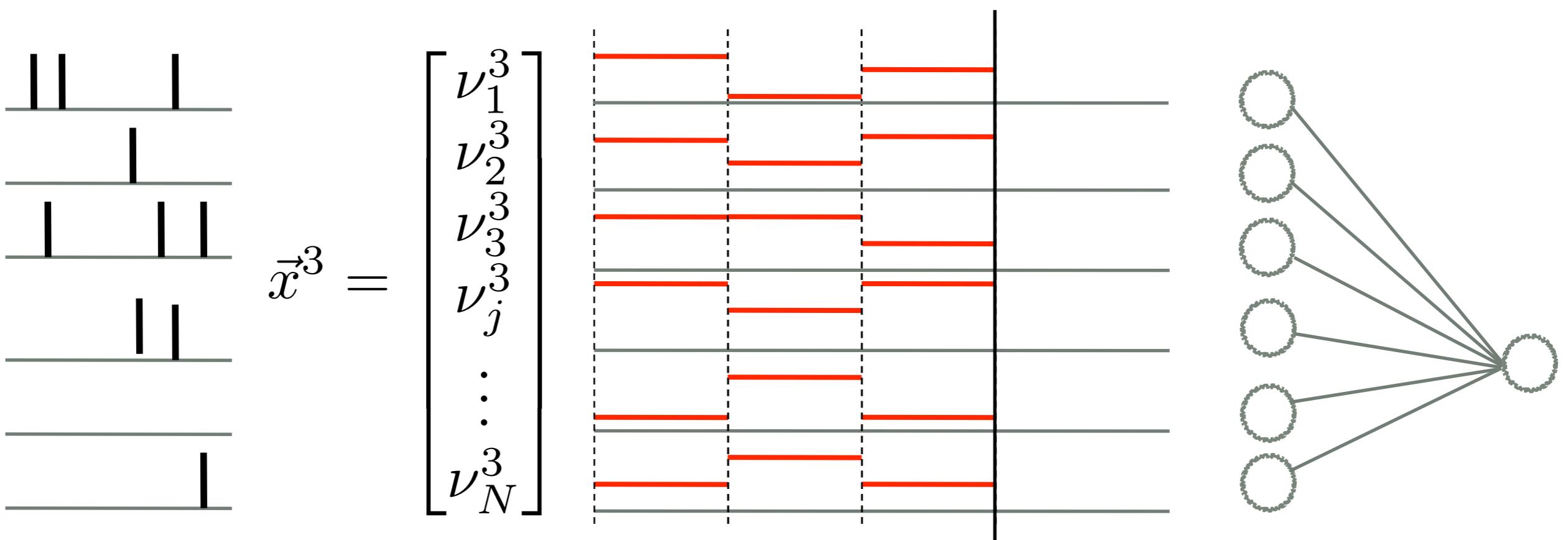
# Functional Consequences of Hebbian Learning



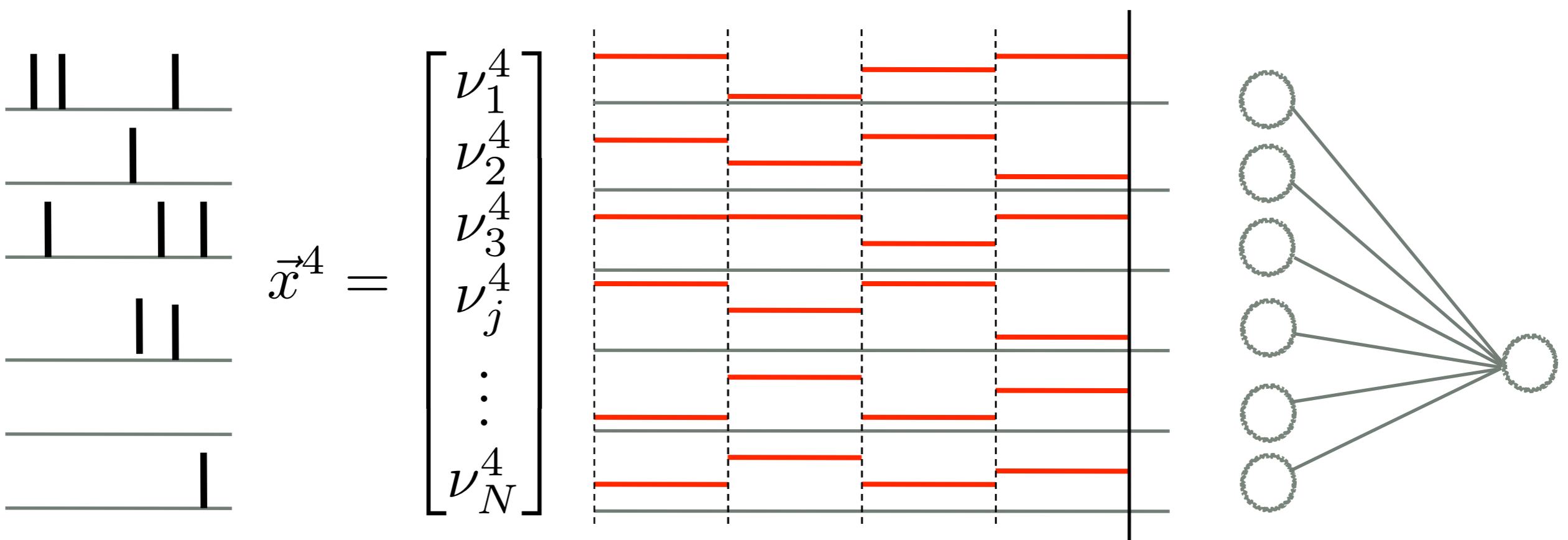
# Functional Consequences of Hebbian Learning



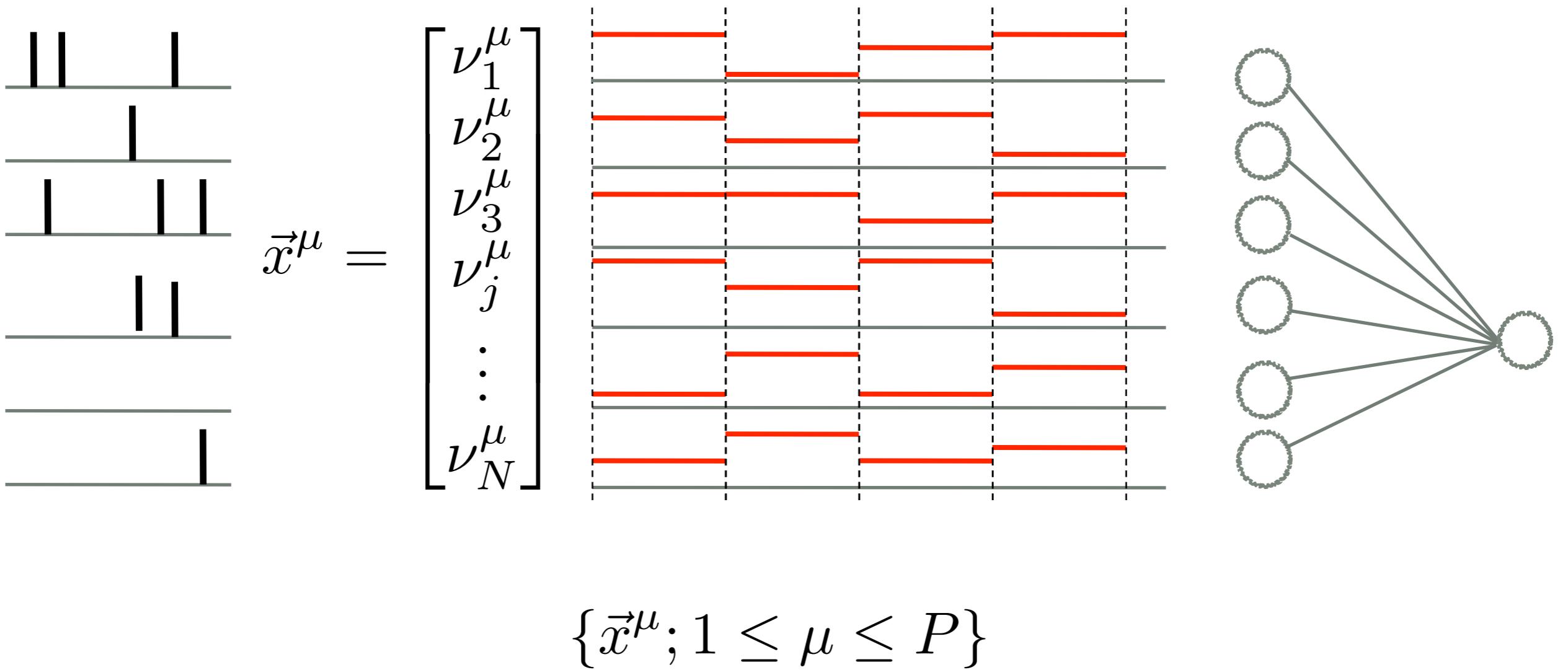
# Functional Consequences of Hebbian Learning



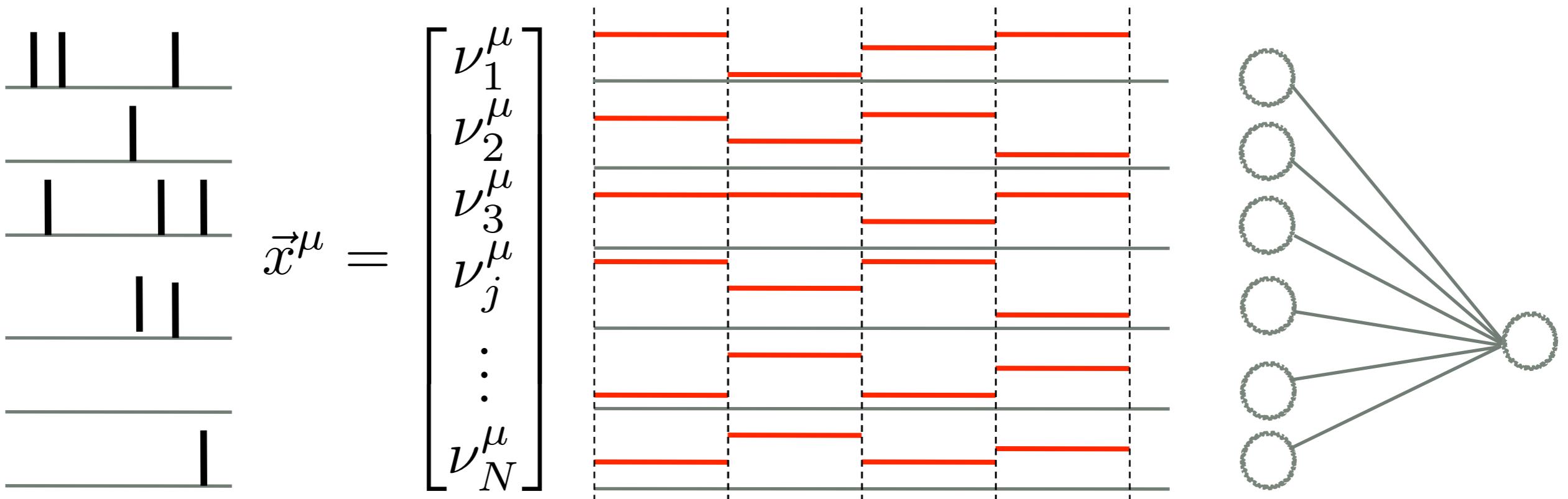
# Functional Consequences of Hebbian Learning



# Functional Consequences of Hebbian Learning



# Functional Consequences of Hebbian Learning



**Correlation:**  $C_{kj} = \langle \nu_k \nu_j \rangle = \frac{1}{P} \sum_{\mu=1}^P \nu_k^\mu \nu_j^\mu$

# Calculate the Correlation Matrix

$$C_{kj} = \langle \nu_k \nu_j \rangle = \frac{1}{P} \sum_{\mu=1}^P \nu_k^\mu \nu_j^\mu$$

**Neurons 1 and 2 exhibit the following pattern:**

$\nu_1$	1	-1	-1	1
$\nu_2$	1	-1	-1	1

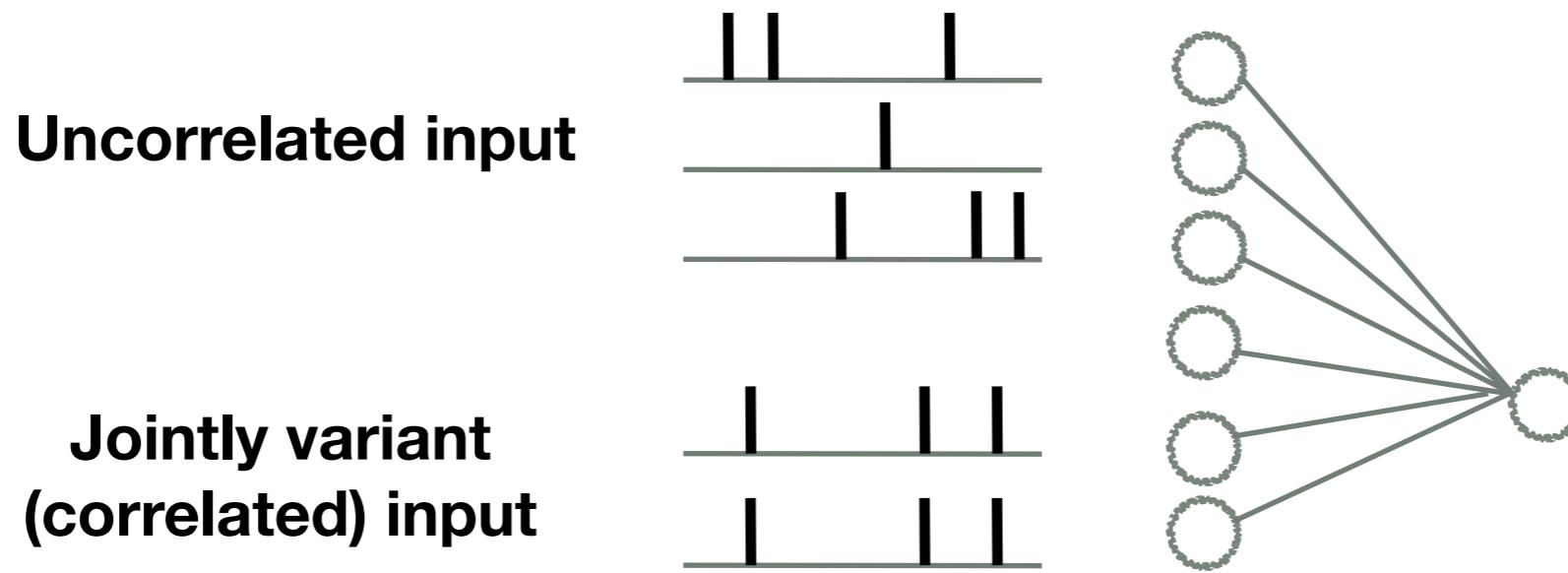
# Calculate the Correlation Matrix

$$C_{kj} = \langle \nu_k \nu_j \rangle = \frac{1}{P} \sum_{\mu=1}^P \nu_k^\mu \nu_j^\mu$$

**Neurons 1, 2 and 3 exhibit the following pattern:**

$\nu_1$	1	-1	-1	1
$\nu_2$	1	-1	-1	1
$\nu_3$	-1	1	1	-1

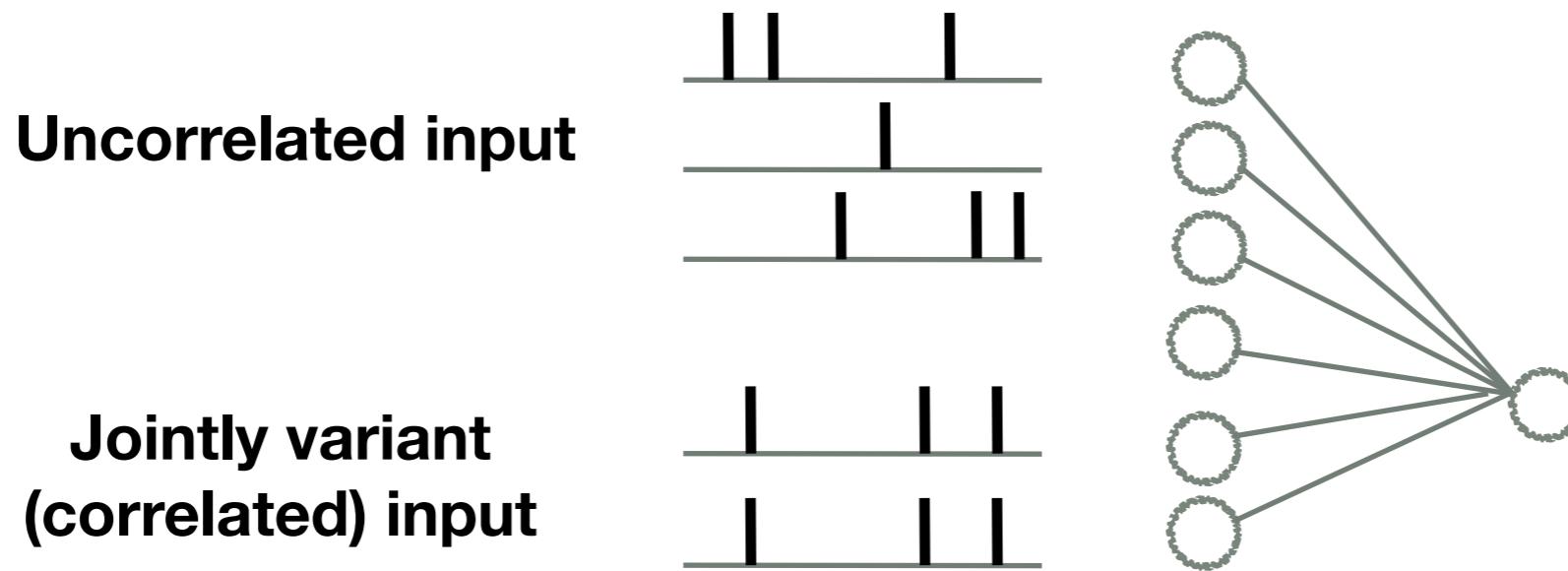
# Functional Consequences of Hebbian Learning



$$\Delta w_{ij} = \alpha \nu_i \nu_j$$

**Claim: Detects correlations in the inputs**

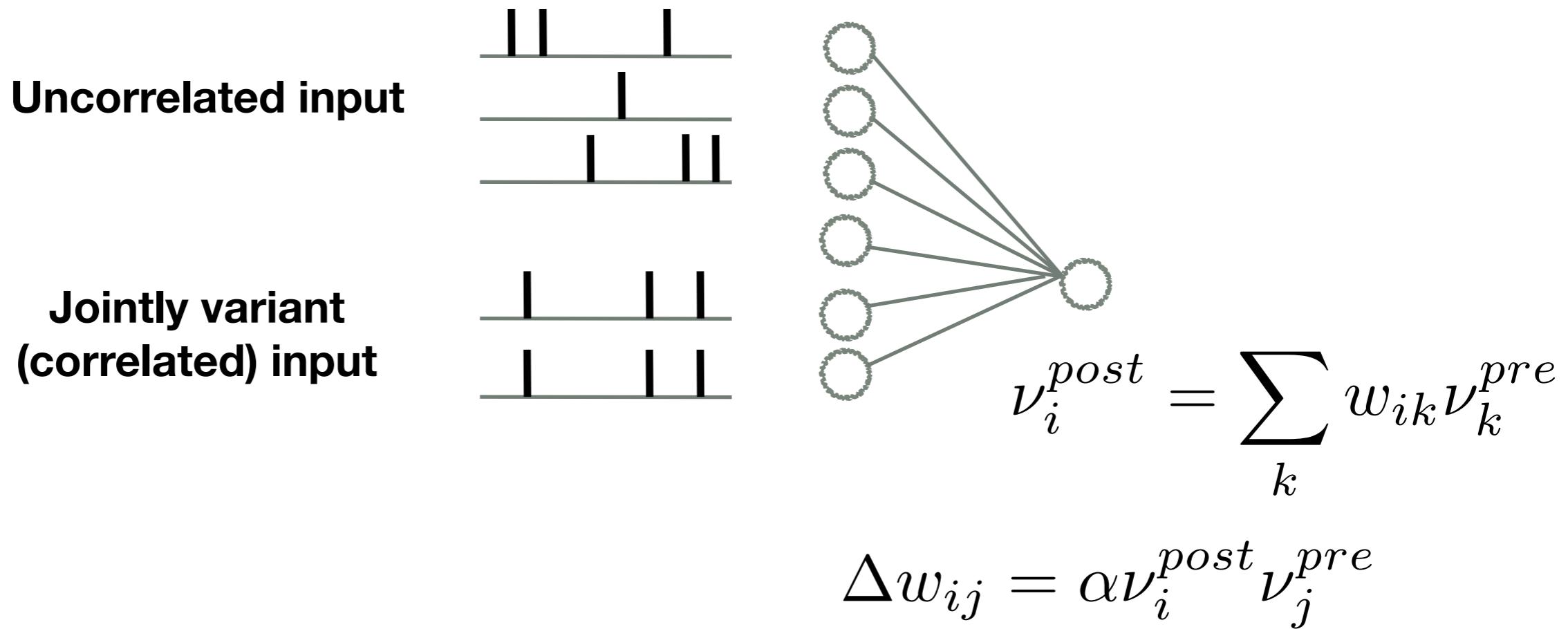
# Functional Consequences of Hebbian Learning



$$\Delta w_{ij} = \alpha \nu_i^{post} \nu_j^{pre}$$

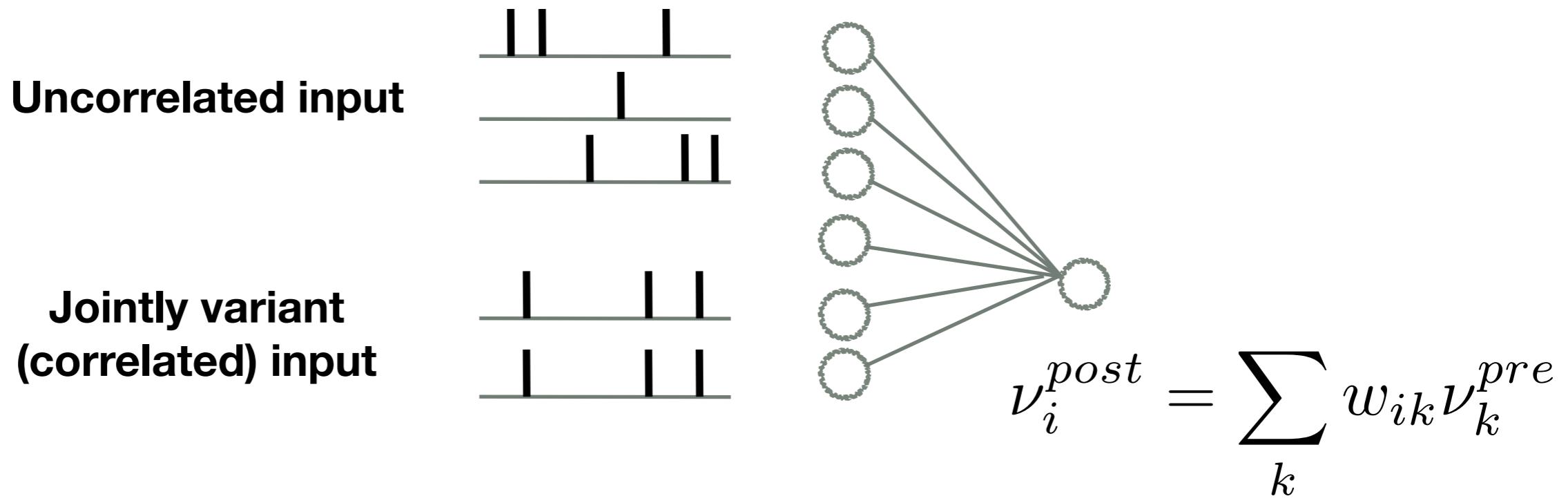
**Claim: Detects correlations in the inputs**

# Functional Consequences of Hebbian Learning



**Claim: Detects correlations in the inputs**

# Functional Consequences of Hebbian Learning



$$C_{kj} = \langle \nu_k \nu_j \rangle = \frac{1}{P} \sum_{\mu=1}^P \nu_k^\mu \nu_j^\mu$$

# Functional Consequences of Hebbian Learning

**Learning rule**

$$\Delta w_{ij} = \alpha \nu_i^{post} \nu_j^{pre}$$

$$\Delta w_{ij} = \alpha \left( \sum_k w_{ik} \nu_k^{pre} \right) \nu_j^{pre}$$

$$\frac{1}{P} \sum_{\mu=1}^P \Delta w_{ij}^\mu = \frac{1}{P} \sum_{\mu=1}^P \alpha \left( \sum_k w_{ik} \nu_k^\mu \right) \nu_j^\mu$$

$$\langle \Delta w_{ij} \rangle = \alpha \sum_k w_{ik} \langle \nu_k \nu_j \rangle$$

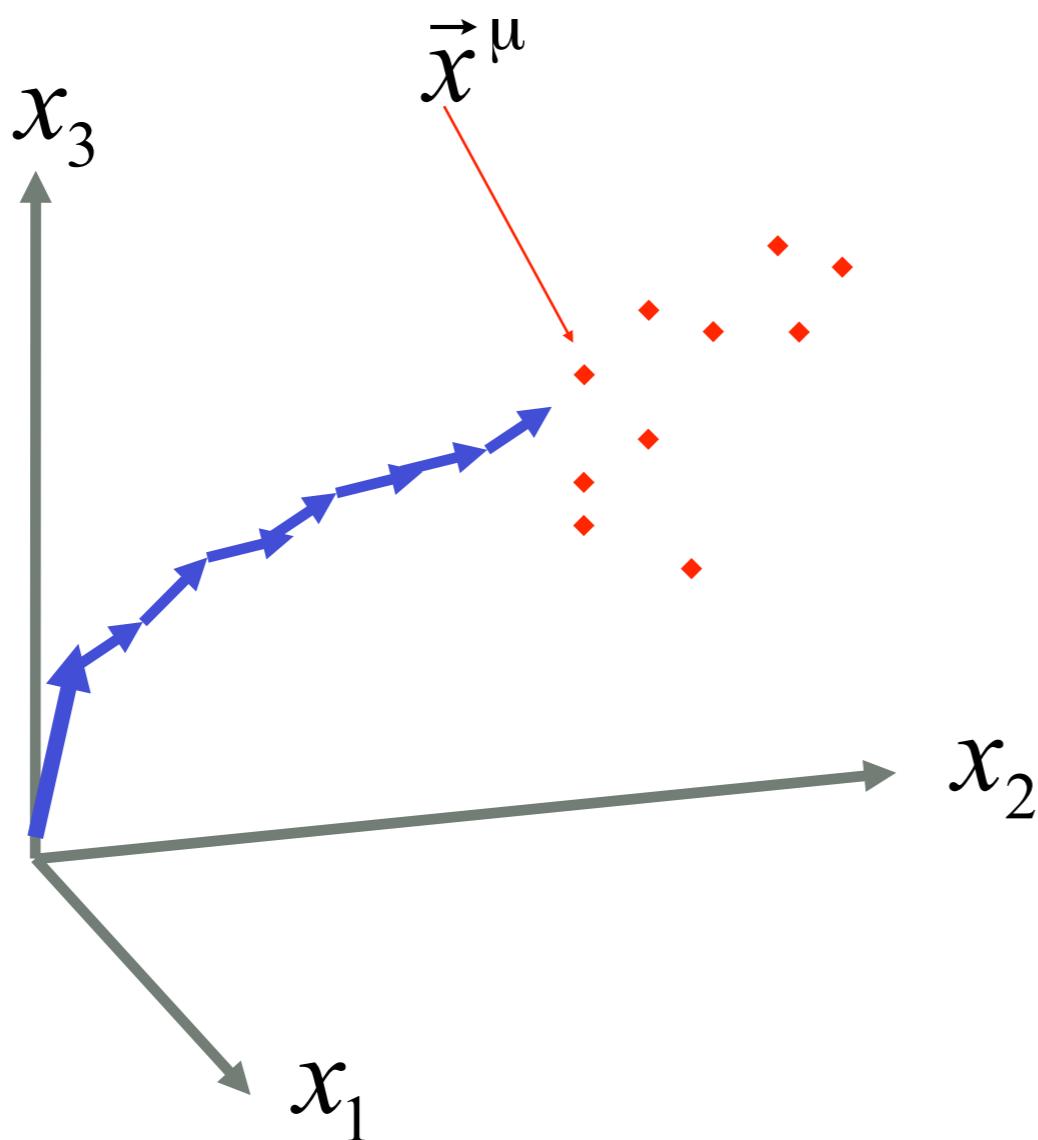
**Neuron model**

$$\nu_i^{post} = \sum_k w_{ik} \nu_k^{pre}$$

$$C_{kj} = \langle \nu_k \nu_j \rangle = \frac{1}{P} \sum_{\mu=1}^P \nu_k^\mu \nu_j^\mu$$

**Detects correlations in the inputs**

# The minimal Hebbian rule



$$\Delta w_{ij} = \alpha \nu_i^{post} \nu_j^{pre}$$

**Unstable!**

# The BCM rule

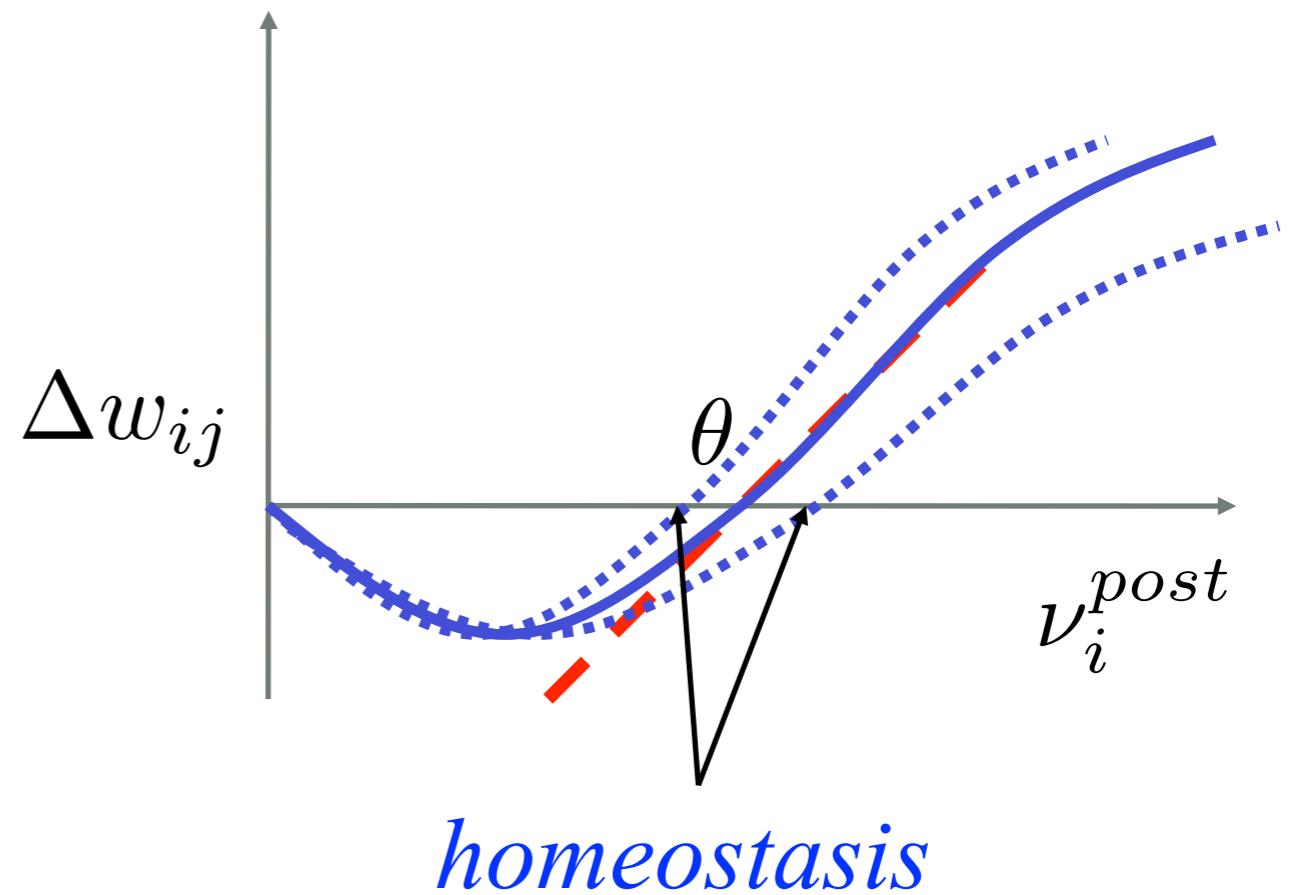
$$\Delta w_{ij} = \alpha \Phi(\nu_i^{post} - \theta) \nu_j^{pre}$$

**Bienenstock, Cooper,  
Munro 1982**

$$\Delta w_{ij} = \alpha (\nu_i^{post} - \theta) \nu_j^{pre}$$

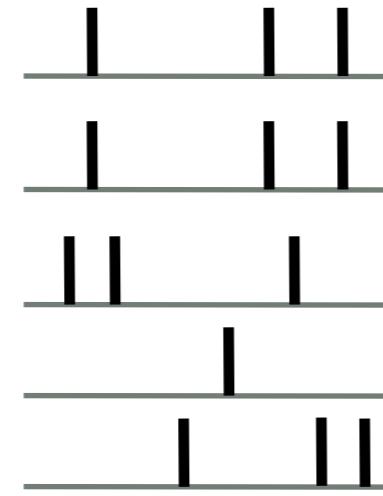
**presynaptically gated**

$$\theta = f(\langle \nu_i^{post} \rangle)$$

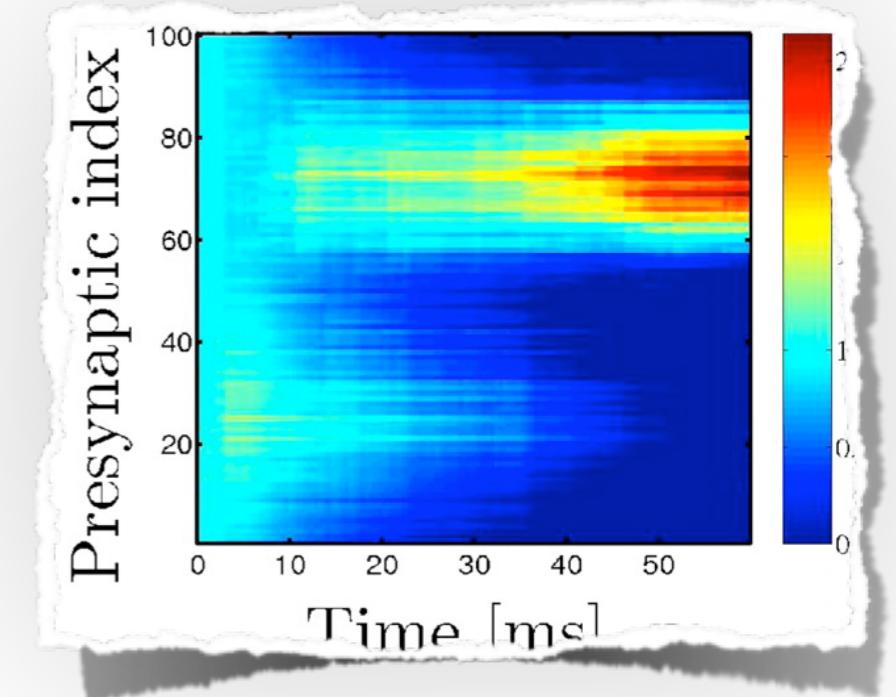
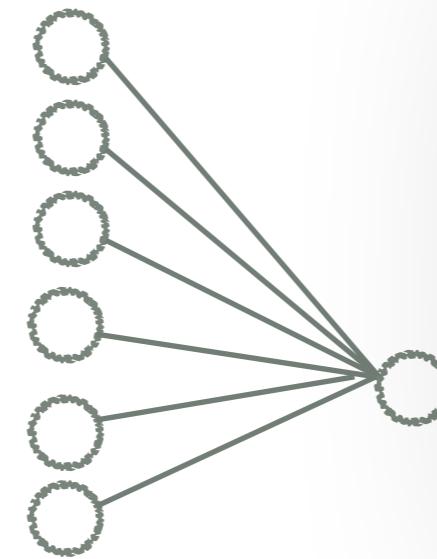


# BCM

**Jointly variant  
(correlated) input**



**Uncorrelated input**



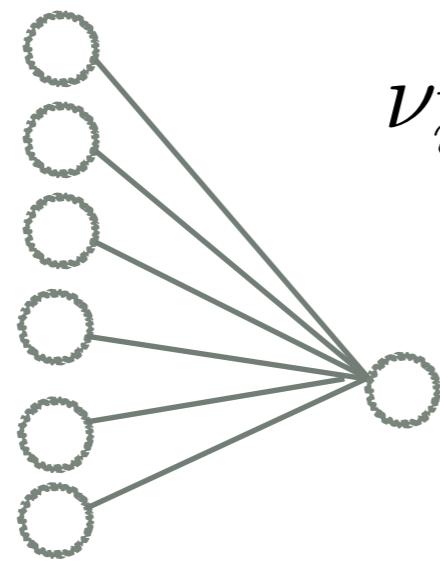
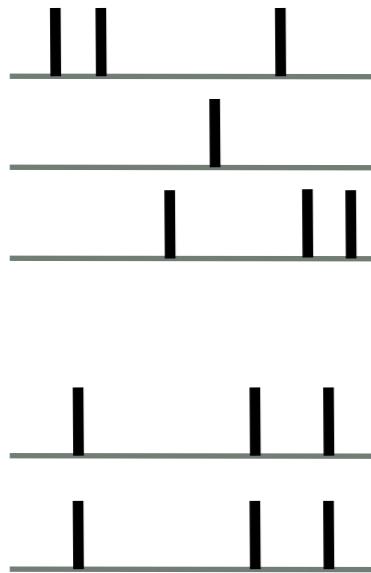
$$\Delta w_{ij} = \alpha \Phi(\nu_i^{post} - \theta) \nu_j^{pre}$$

**Weight evolution**

**Is this a hebbian rule?**

**Detects where the ‘interesting’ input occurs (correlations):  
some synapses strengthened at the expense of others**

# BCM Rule



**Neuron model**

$$\nu_i^{post} = \sum_k w_{ik} \nu_k^{pre}$$

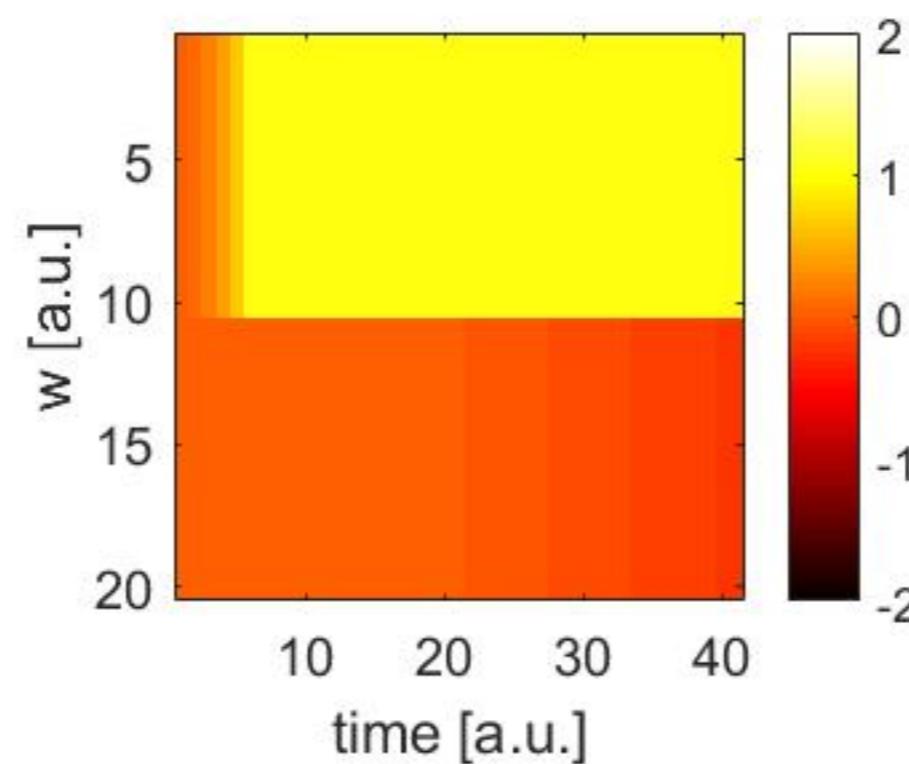
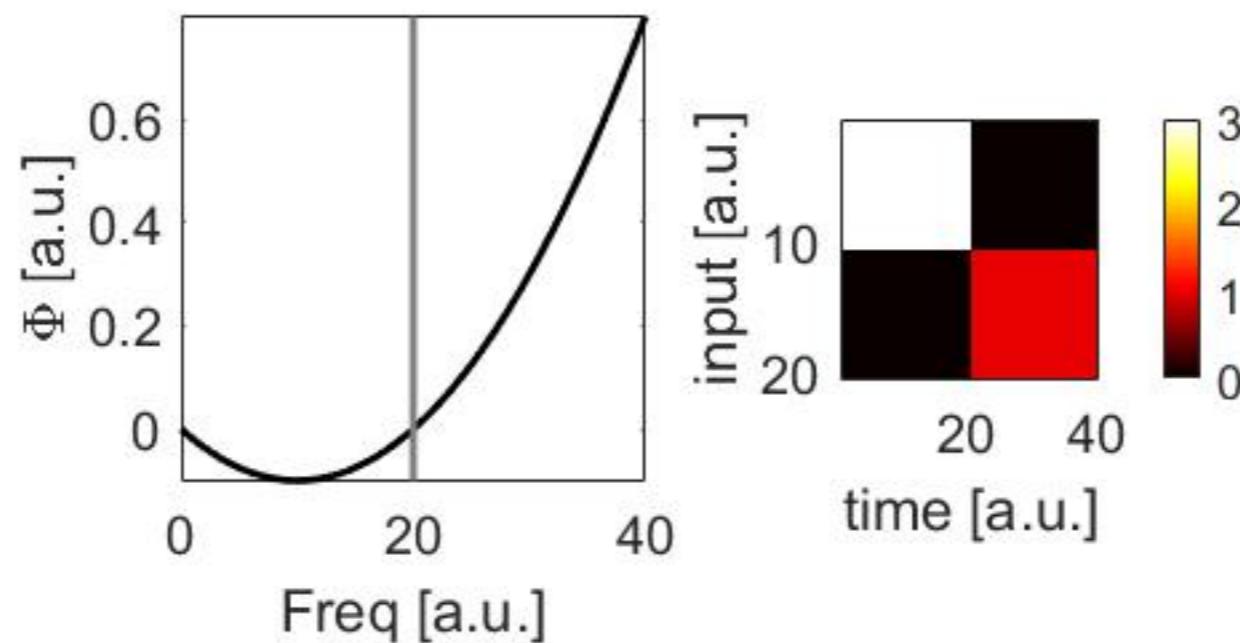
$$\Delta w_{ij} = \alpha \Phi(\nu_i^{post} - \theta) \nu_j^{pre}$$

**Assume two (presynaptic) groups of 10 neurons each. All weights = 1 and threshold  $\theta = 20\text{Hz}$ .**

1. Group 1 fires at 3 Hz, then group 2 at 1 Hz. What happens?
2. Group 1 fires at 3 Hz, then group 2 at 2.5 Hz. What happens?
3. As in 2, but make theta a function of the averaged rate. What happens?

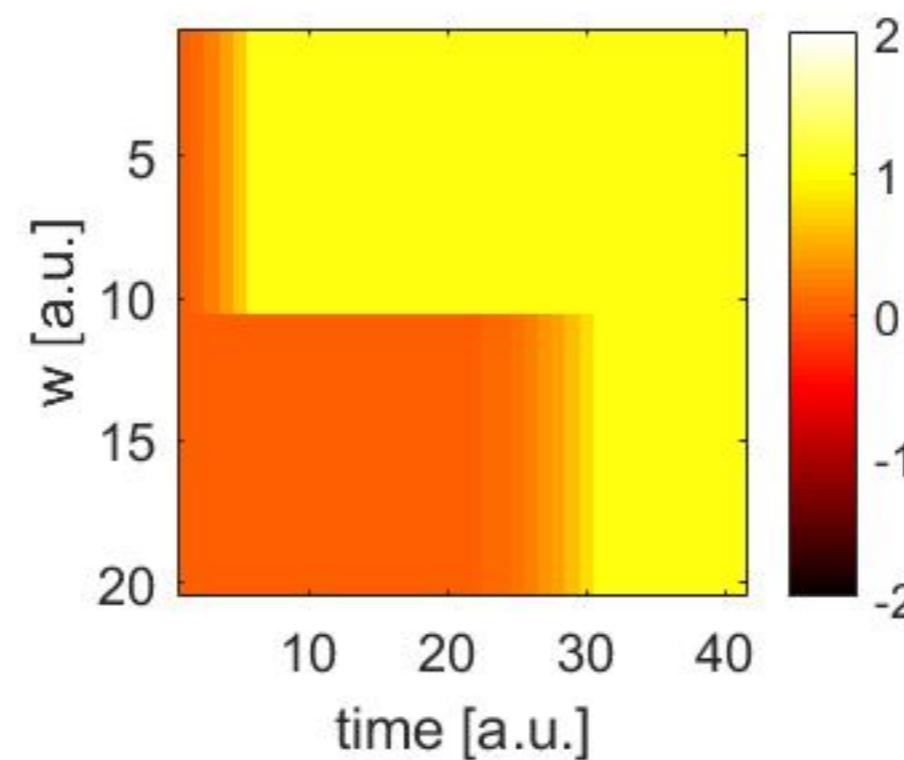
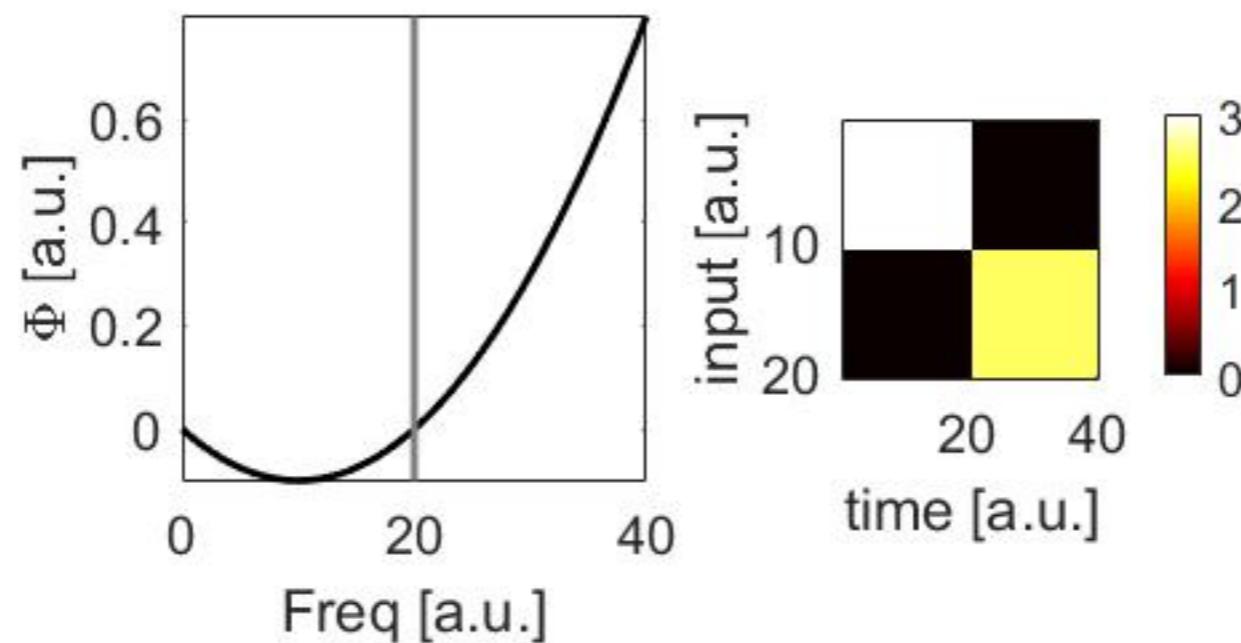
# BCM Rule

1.



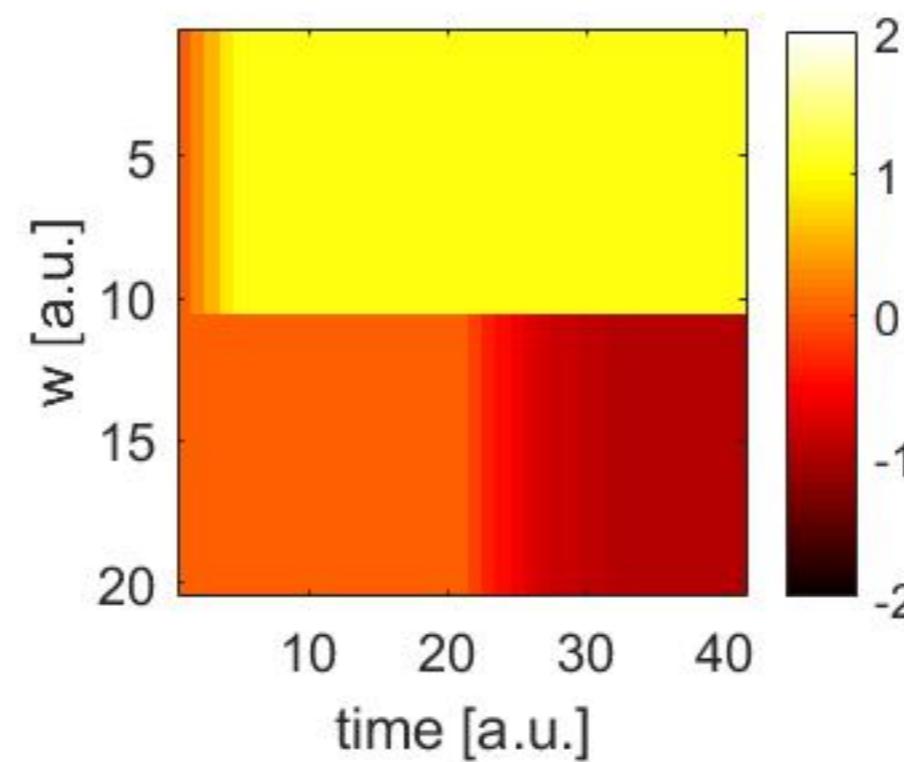
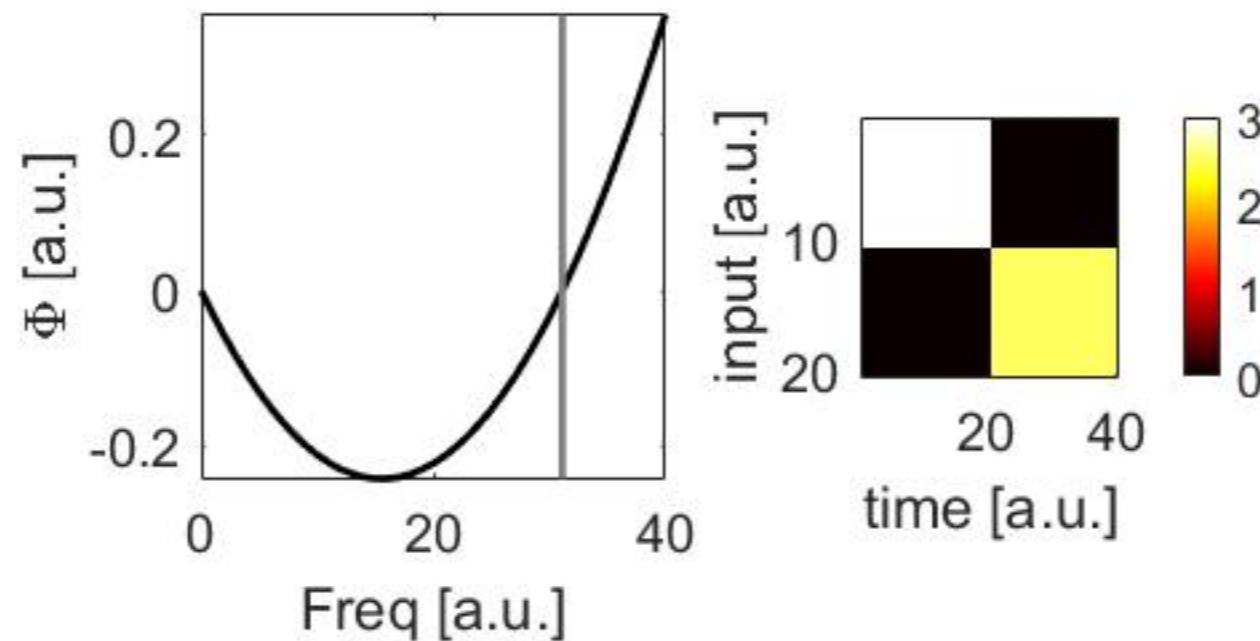
# BCM Rule

2.

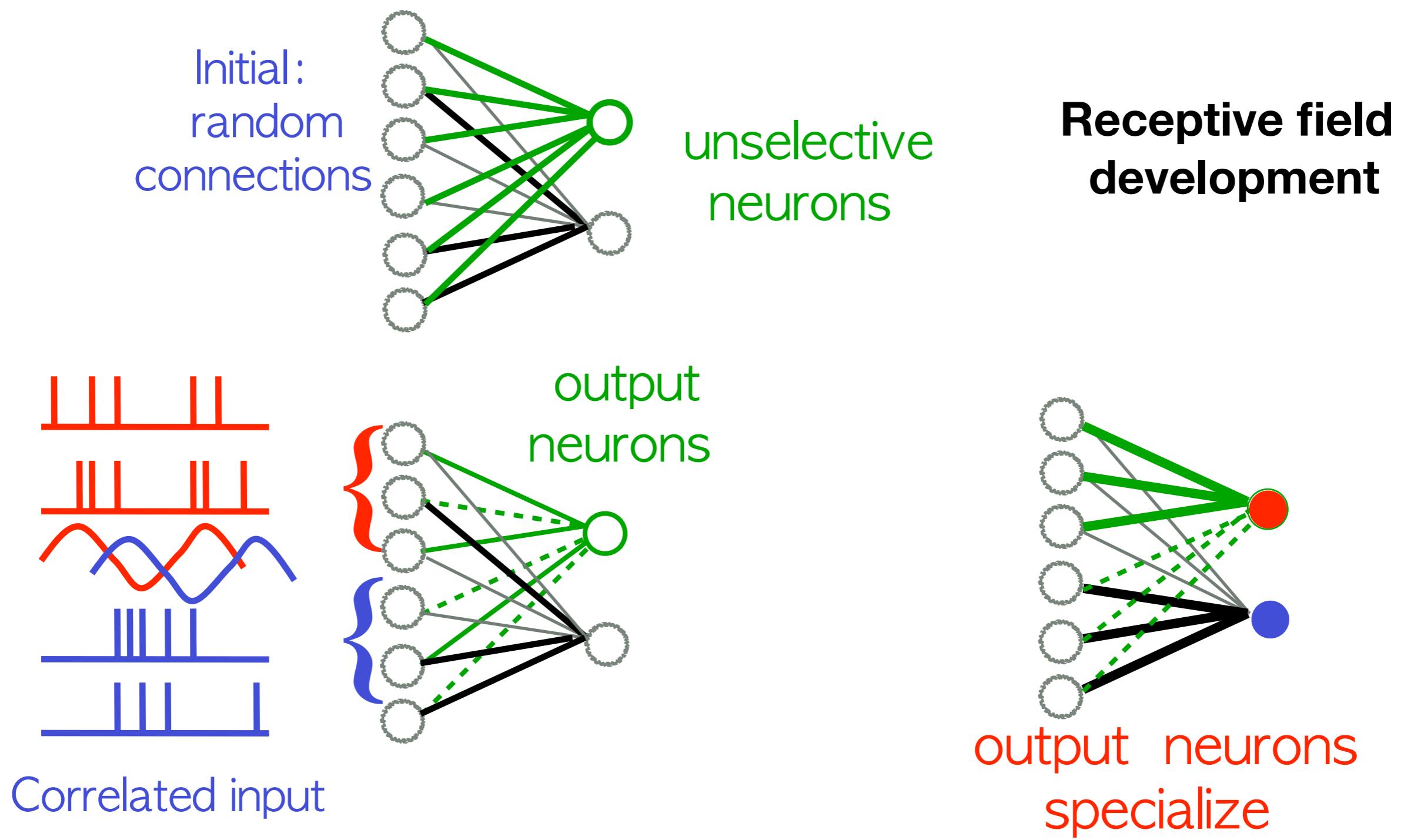


# BCM Rule

3.



# BCM leads to specialised neurons



# Summary

- Hebbian rules detect correlation in the input.
  - Mathematical proof.
  - True for all hebbian rules.
- The minimal hebbian rule is unstable.
- The BCM rule is a hebb rule with a homeostatic term.
  - Leads to specialised neurons.
  - Useful for receptive field development.

**Thank you!**

# Acknowledgements

- This module is an adaptation of the MSc module “Unsupervised and Reinforcement Learning in Neural Networks” by Prof. Wulfram Gerstner at EPFL, Switzerland.

# Bibliography

- Neuronal Dynamics, by Gerstner et al.
- "Introduction to the Theory of Neural Computation" by Hertz, Krogh & Palmer
- "Reinforcement Learning: An Introduction" by Sutton & Barto
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