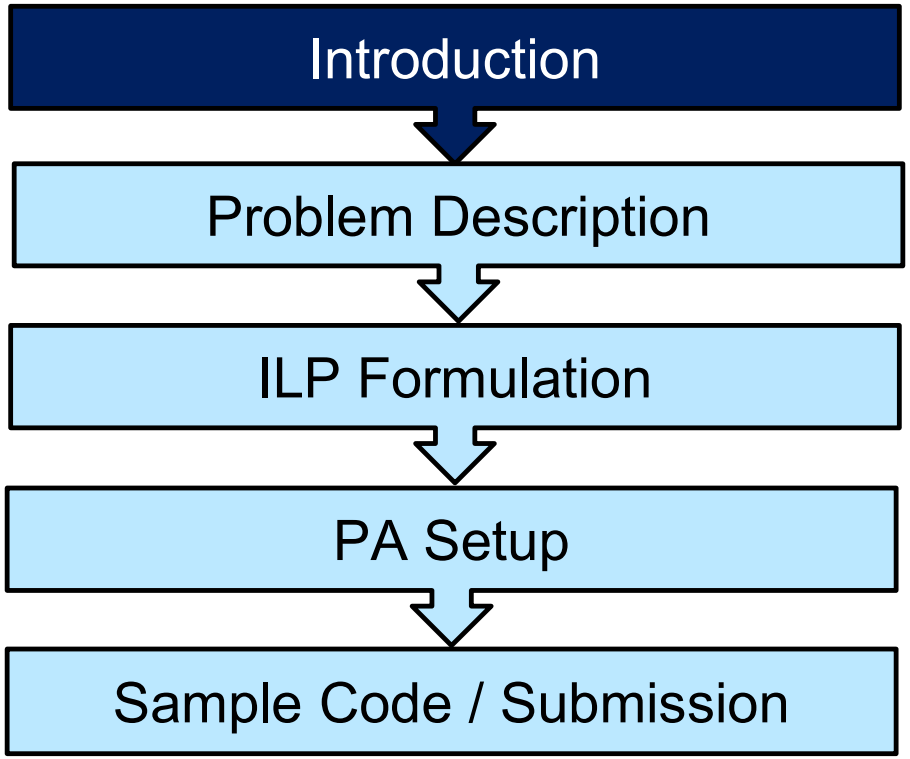
國立臺灣大學
National Taiwan University

Programming Assignment 2
Fixed-Outline Incremental ILP-Based Floorplanning

TA: Yu-Hsiang Huang (johnnyhuang1007@gmail.com)

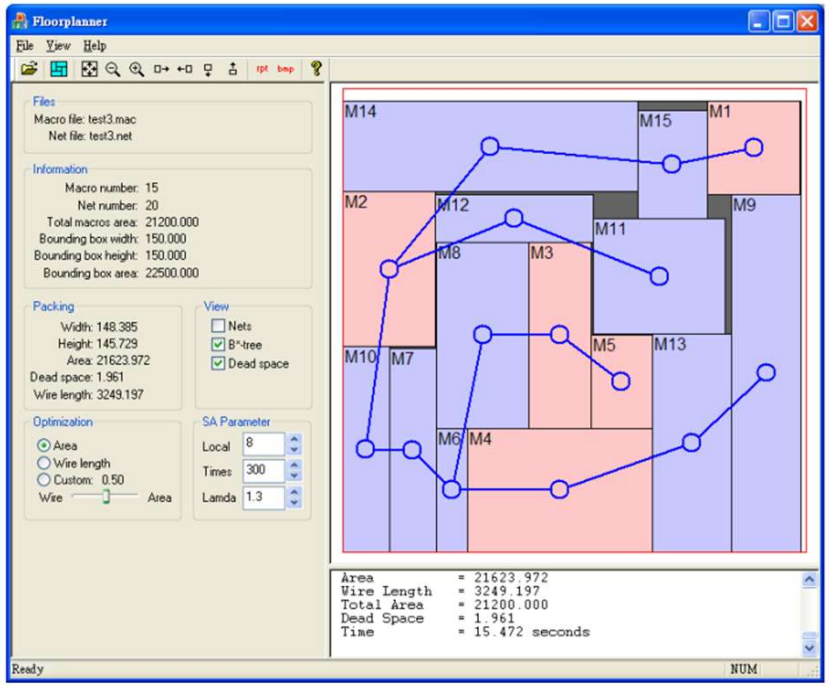
2025/10/15

Outline


Introduction
Problem Description
ILP Formulation
PA Setup
Sample Code / Submission

Introduction – Floorplanning

- Part of Physical Design flow that:
  - Decide the position of target macros
  - Minimize the dataflow between each macros
- Input:
  - A set of modules,
    - hard or soft
    - rectangle or rectilinear
  - Pin location of each modules
  - A set of netlist
- Output:
  - reduce wirelength, minimize area
- Methodology:
  - Heuristic Method, e.g., Simulated Annealing
  - Analytical Method, e.g., Gradient Descend
  - Mathematic Method, e.g., ILP Formulation



By Tung-Chieh Chen

Introduction – Integer Linear Programming

- An Optimization Problem with standard form is in the form of:

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \ldots, m \\ & h_i(x) = 0, \quad i = 1, \ldots, p \end{array}$$

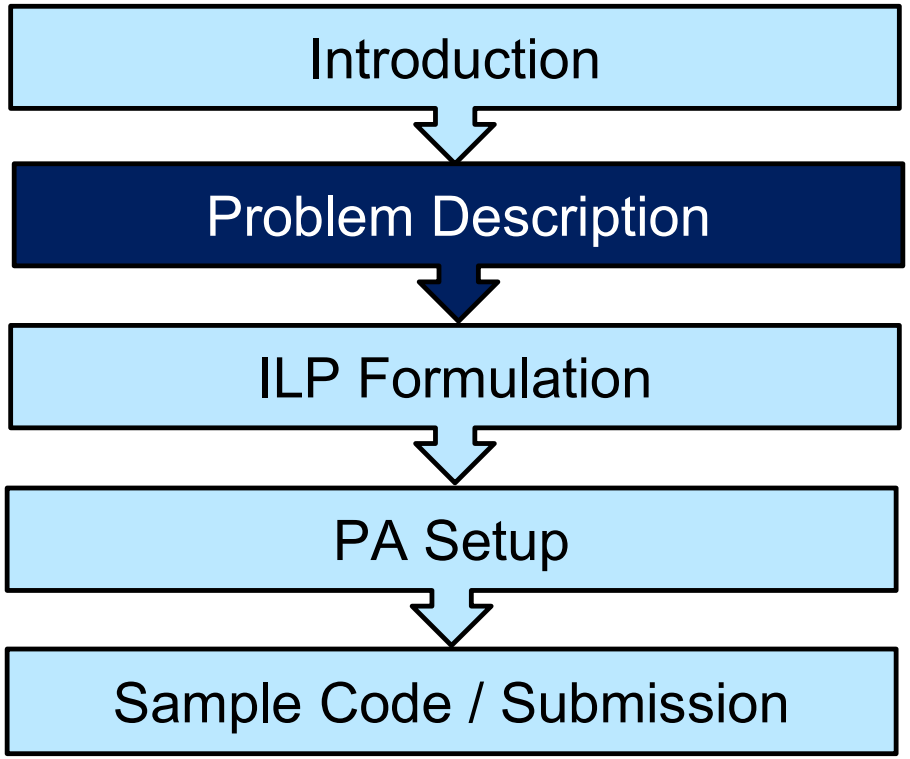
- Where $f_0(x)$ is objective function, $f_i(x)$ is in-equality constraint, $h_i(x)$ is equality constraint
- When the objective and constraint functions are linear functions, and the variables are all integer, then it's an Integer Linear Programming Problem

$$\begin{array}{ll} \text{minimize} & c^T x + d \\ \text{subject to} & Gx \preceq h \\ & Ax = b, \end{array} \qquad u \preceq v \ \text{means} \ u_i \leq v_i \ for \ i = 1, \ldots, m$$

Introduction – Integer Linear Programming

- Objective and constraints are linear functions of the variables.
- The Problem is NP-hard
  - Runtime grows exponentially as the number of variable increases
- Popular solvers: Gurobi, CPLEX, OR-Tools
- For this assignment, we expect students to solve a floorplanning problem using ILP method

Outline

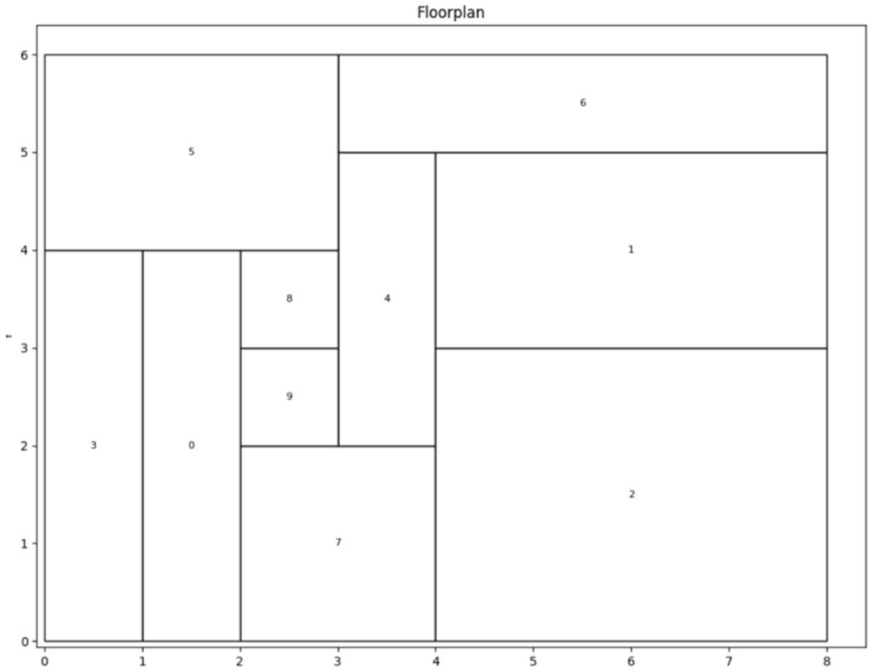

Introduction
Problem Description
ILP Formulation
PA Setup
Sample Code / Submission

Problem Statement

- Input:
  - Set of rotatable hard modules, fixed-outline [W,H], problem category
- Objective:
  - minimize the bounding area of a floorplan, Bounding area: $A = \left(\max_{i \in \mathcal{M}} (x_i + w_i')\right) \cdot \left(\max_{i \in \mathcal{M}} (y_i + h_i')\right).$
- Constraint:
  - Every modules should be placed inside given outline
  - No overlaps between each modules
- Two problem category:
  - 0: Find an optimal result (minimum bounding area) of the target module set
  - 1: Find a feasible floorplan that minimizes the bounding area as much as possible
- Outputs:
  - coordinates and rotation for all modules

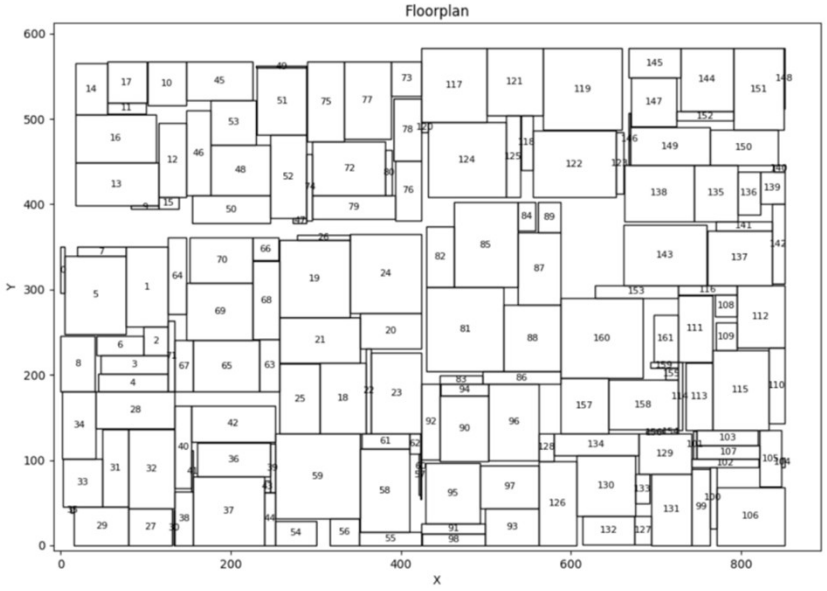
Problem Category 0

- The covered area of a given outline is equal to the total area of modules
  - W * H = Area(modules)
- In other word, every floorplanning result should achieve 100% utilization
- Let M be the set of input modules: $4 \leq |M| \leq 11$
- Runtime Limit: 1 hour
- Example result:



Problem Category 1

- The given outline is larger than the optimal solution
  - W * H > Area(bounding area)
- Let M be the set of input modules: $20 \leq |M| \leq 500$
- Runtime Limit: 1 hour
  - It is impossible to solve this problem by only by a single ILP formulation
- Example result:

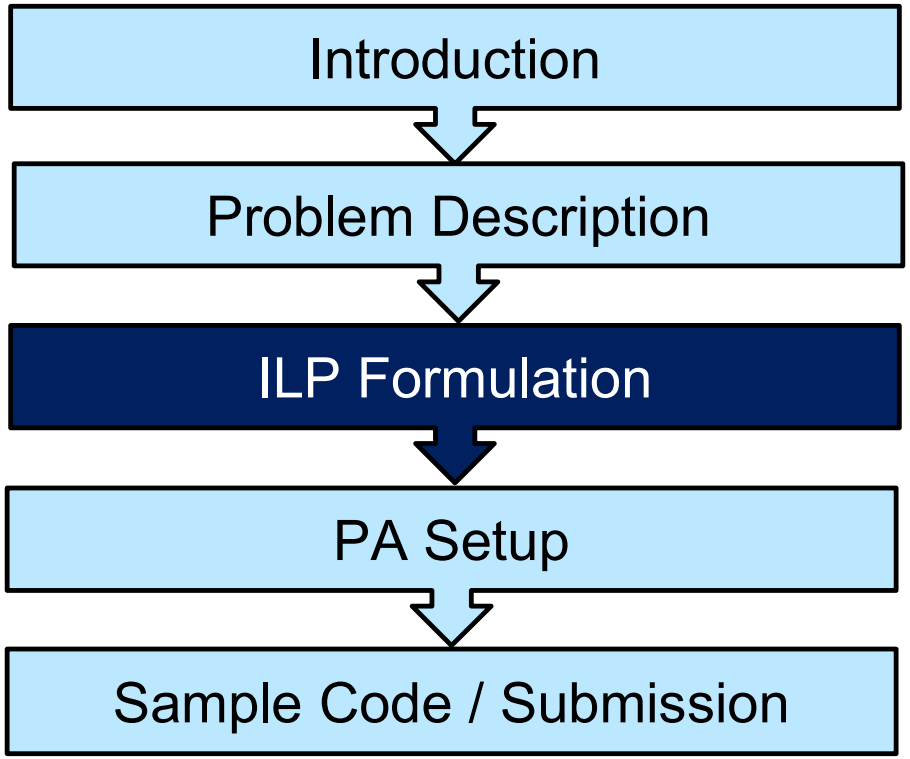


Input/Output Format

- .in: List of all modules
  - First line: MODULE_SIZE [num]
  - Second line: column headers
  - Following Lines: module information
    - ID always starts from 0 and increases by 1
    - W and H are always integers
- .spec:
  - First line: problem category (0 or 1)
  - Second line: given outline size W, H
- .out: placement result (ID pos.x pos.y rotatation)
  - (pos.x, pos.y): coordinates of the lower-left corner
  - rotatation = 0 → no rotation, rotatation = 1 → rotated 90° counterclockwise
- Execution command example:
  - bin/fp ./input/sample.in ./spec/sample.spec ./sample.out

sample.in	sample.spec	sample.out
MODULE_SIZE 10	0	0 0 4 1
ID W H	8 6	1 4 4 0
0 1 4		2 0 0 1
1 4 2		3 3 3 1
2 4 3		4 1 5 0
3 1 4		5 3 1 0
4 3 1		6 3 0 0
5 3 2		7 6 1 0
6 5 1		8 0 5 0
7 2 2		9 7 3 0
8 1 1		
9 1 1		

Outline


Introduction
Problem Description
ILP Formulation
PA Setup
Sample Code / Submission

ILP Formulation

- Area objective is non-linear
  - Alternative way: fix the floorplan's width and minimize floorplan's height instead

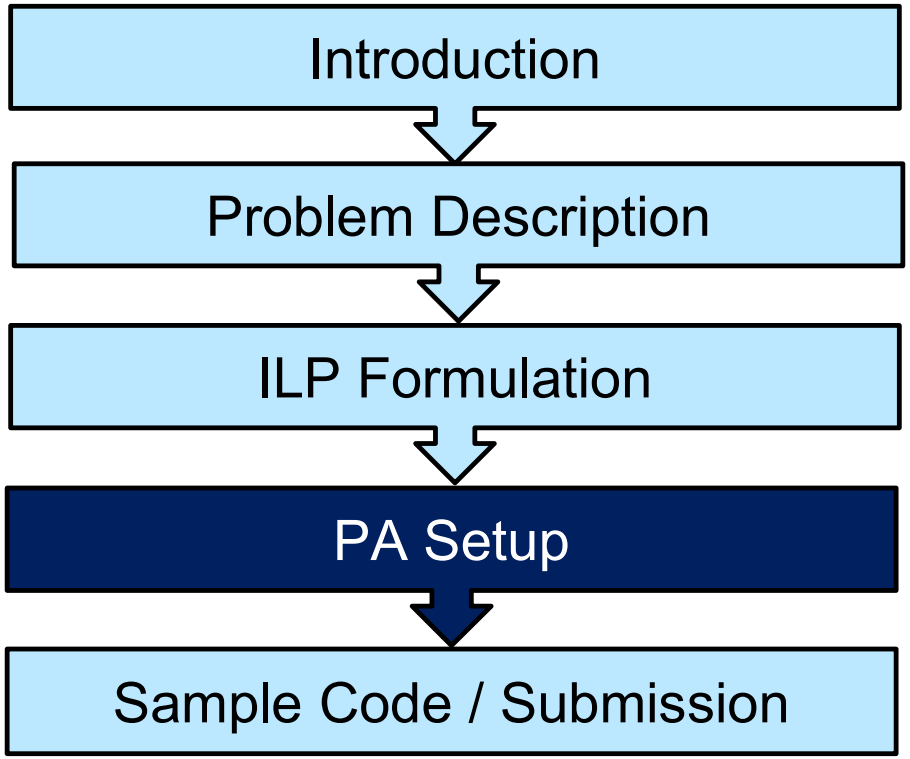
Objective $\min\ y_{\max}.$

Constraints

Inside outline:	$0 \le x_i, \quad 0 \le y_i,$	$\forall i \in \mathcal{M},$ (4)
	$x_i + w'_i \le W,$	$\forall i \in \mathcal{M},$ (5)
	$y_i + h'_i \le Y,$	$\forall i \in \mathcal{M},$ (6)
Optional height cap:	$Y \le \mathrm{H},$	(7)
Non-overlap:	$x_i + w'_i \le x_j + M\,(p_{ij} + q_{ij}),$	$\forall i < j,$ (8)
	$y_i + h'_i \le y_j + M\,(1 + p_{ij} - q_{ij}),$	$\forall i < j,$ (9)
	$x_i \ge x_j + w'_j - M\,(1 - p_{ij} + q_{ij}),$	$\forall i < j,$ (10)
	$y_i \ge y_j + h'_j - M\,(2 - p_{ij} - q_{ij}),$	$\forall i < j,$ (11)
Domains:	$x_i, y_i \in \mathbb{R}_+, \ r_i \in \{0,1\}, \ p_{ij}, q_{ij} \in \{0,1\}, \ Y \in \mathbb{R}_+.$	(12)

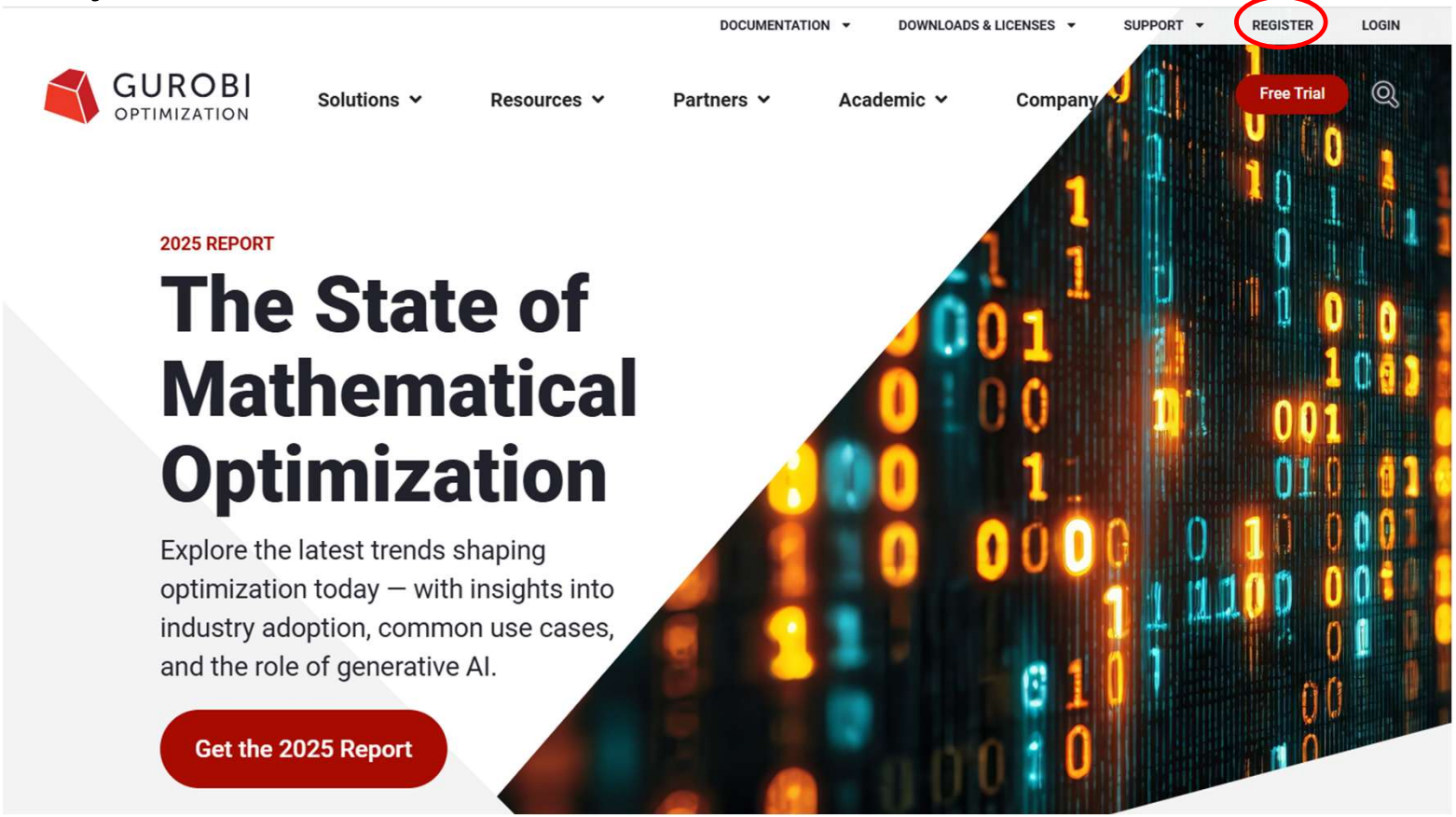
M is a sufficiently large number

Outline

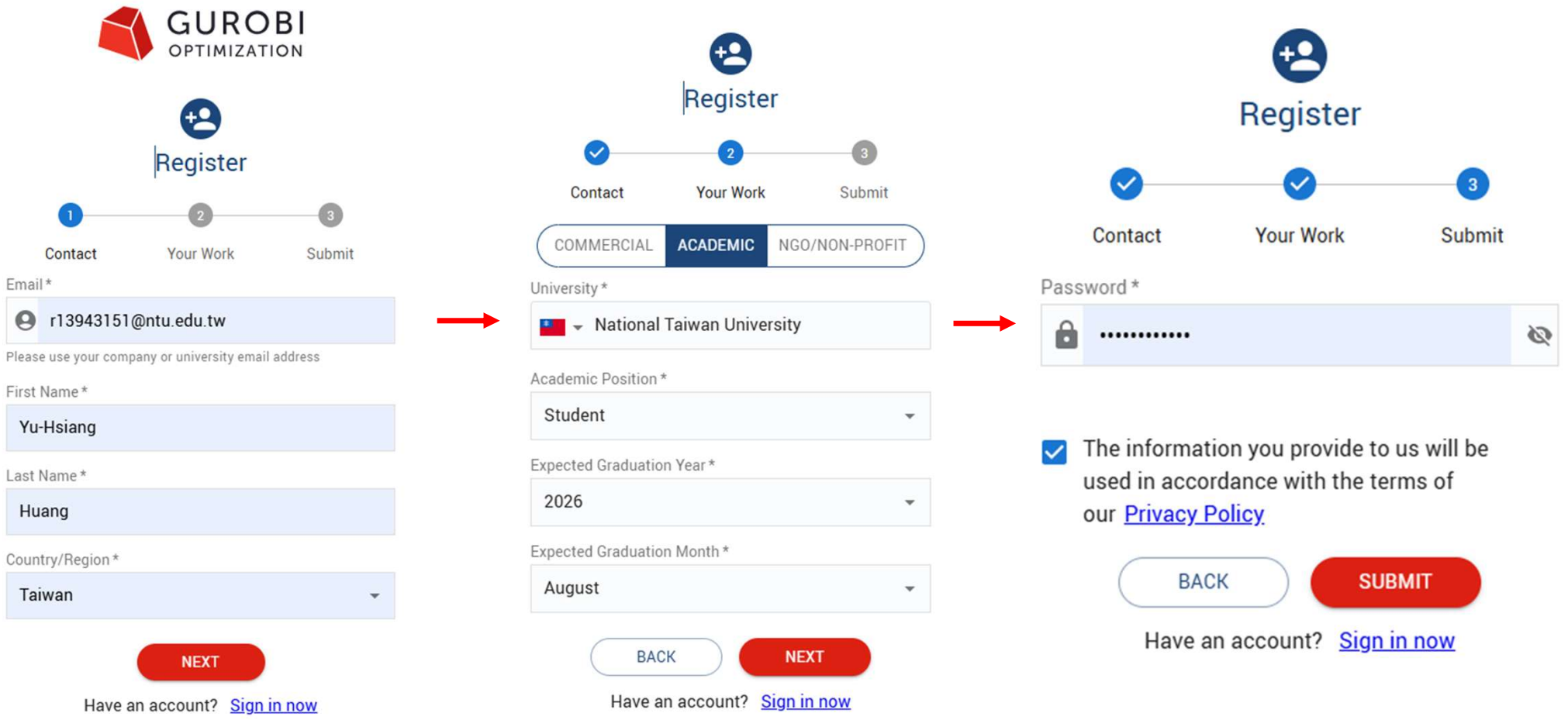

Introduction
Problem Description
ILP Formulation
PA Setup
Sample Code / Submission

Gurobi Account Registration

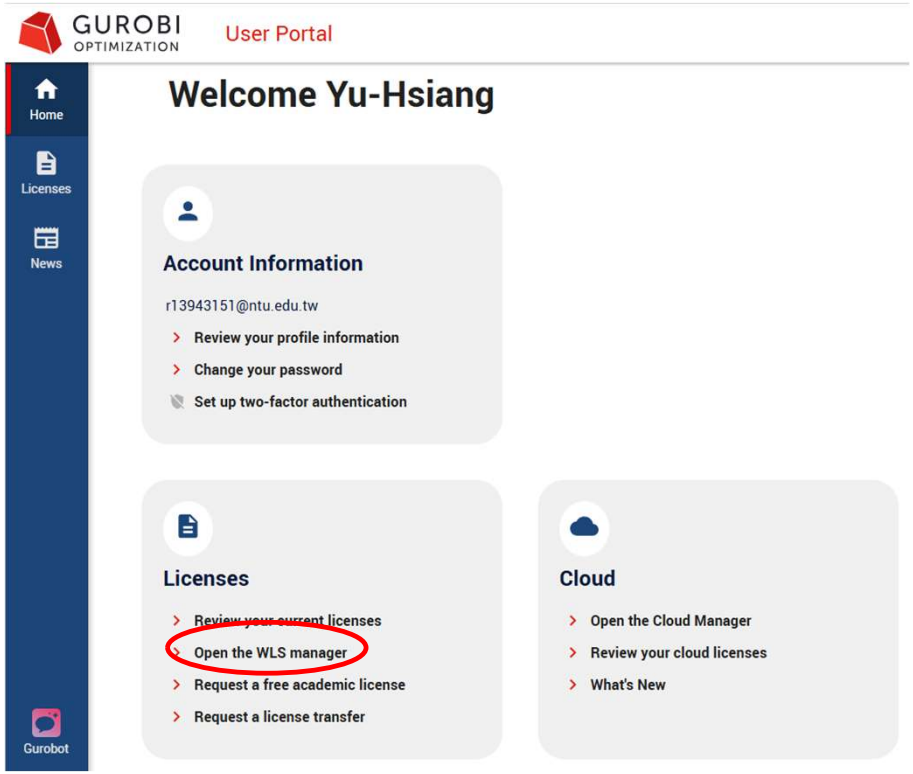
- Register your account: website

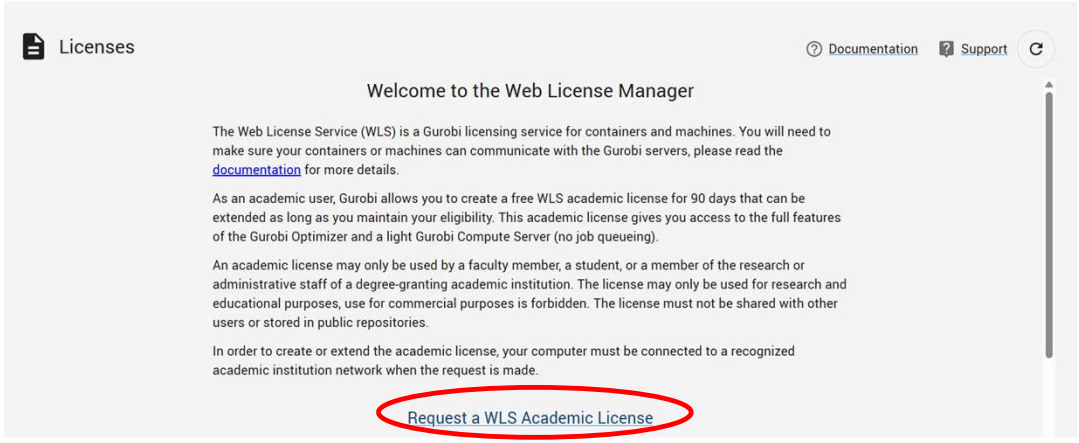


Gurobi Account Registration



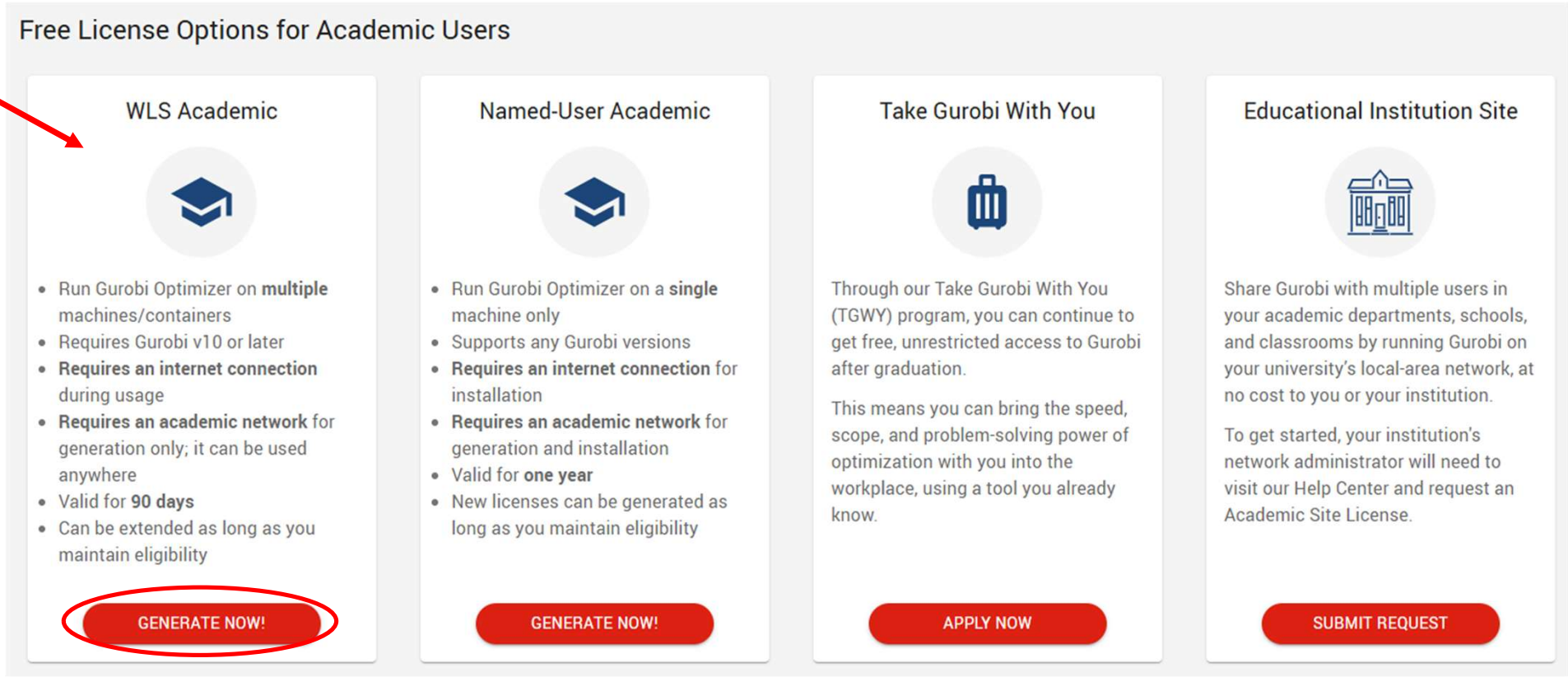
License Request





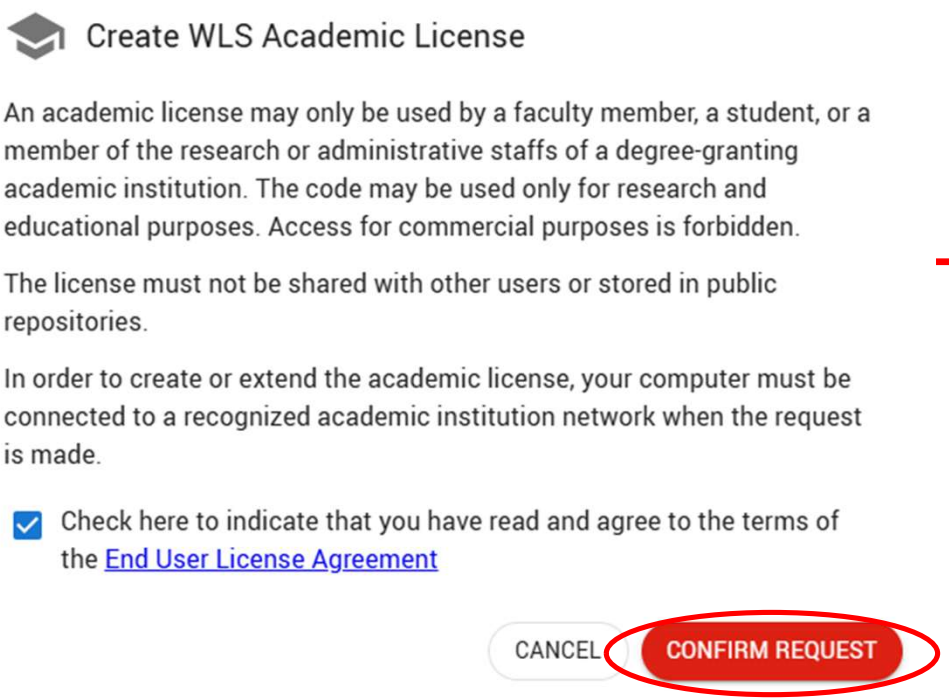
License Request

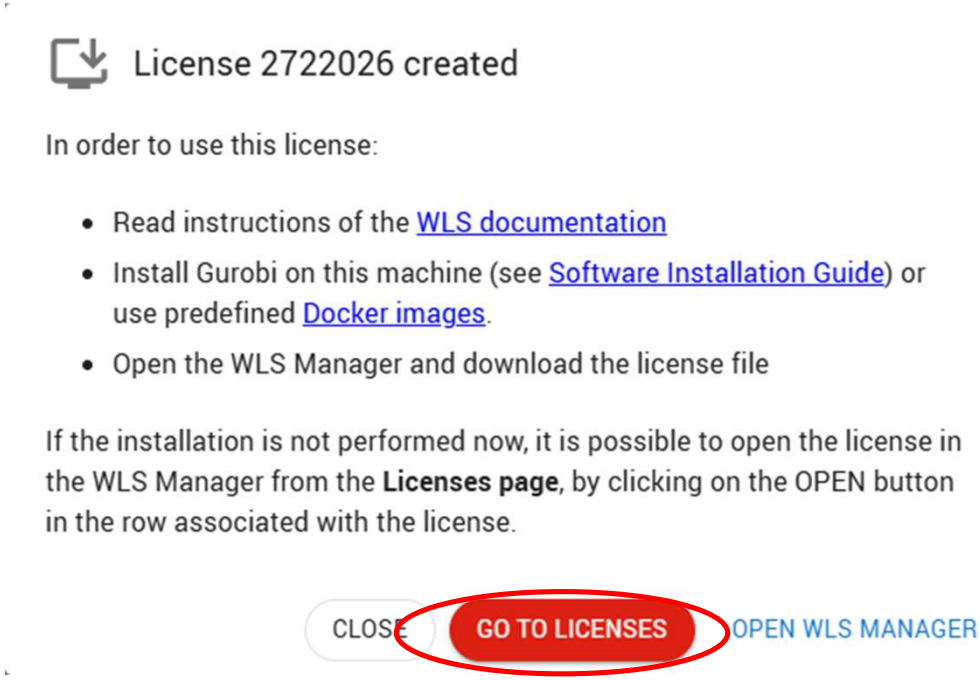
Choose WLS Academic License instead of Named-User Academic License



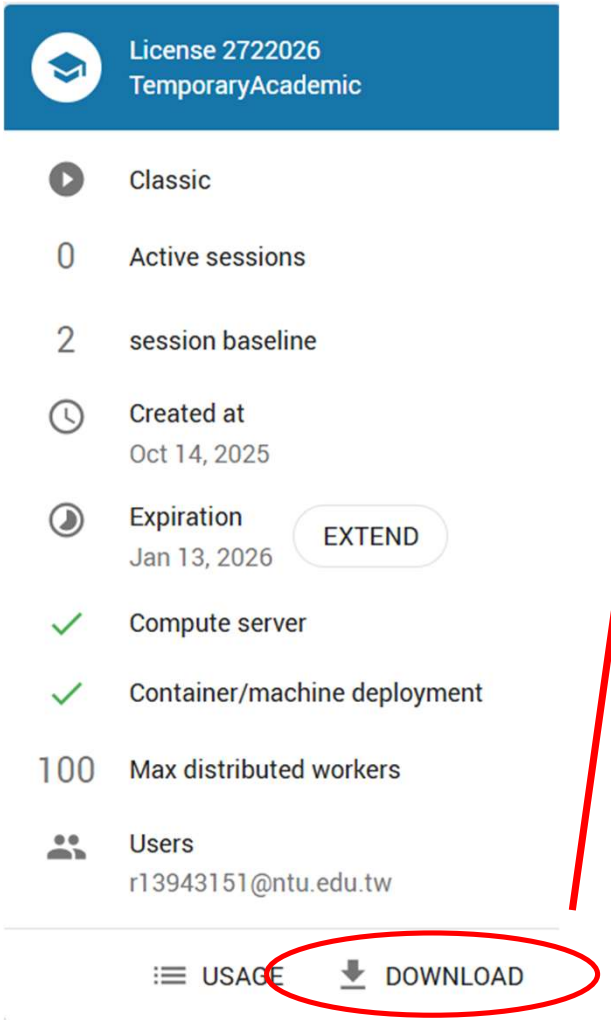
License Request

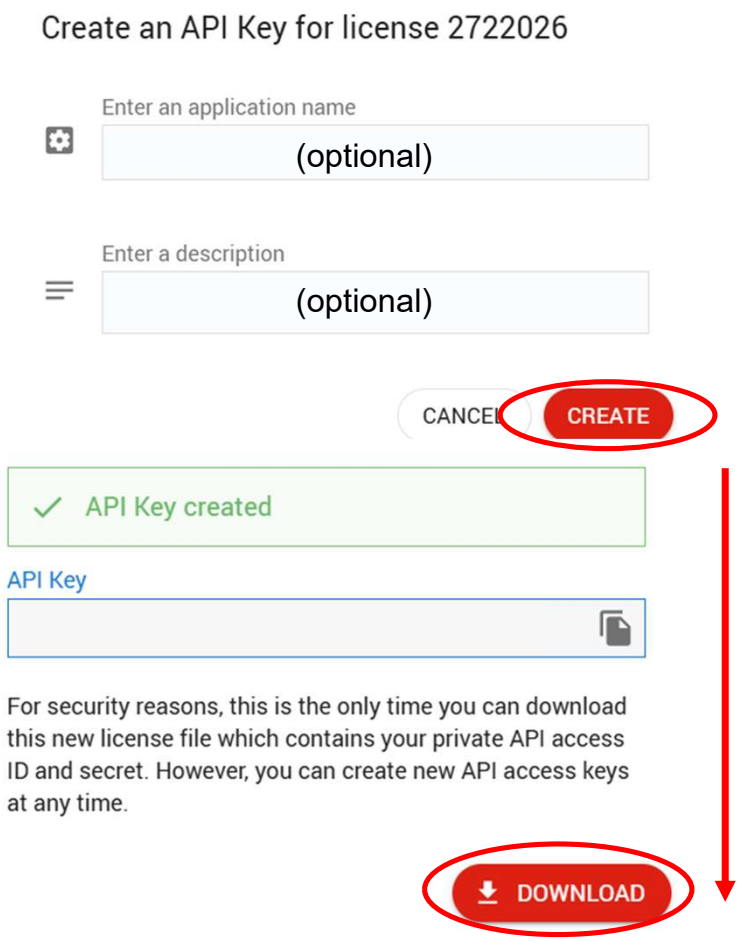
- Connect to NTU VPN before confirming request





License Request





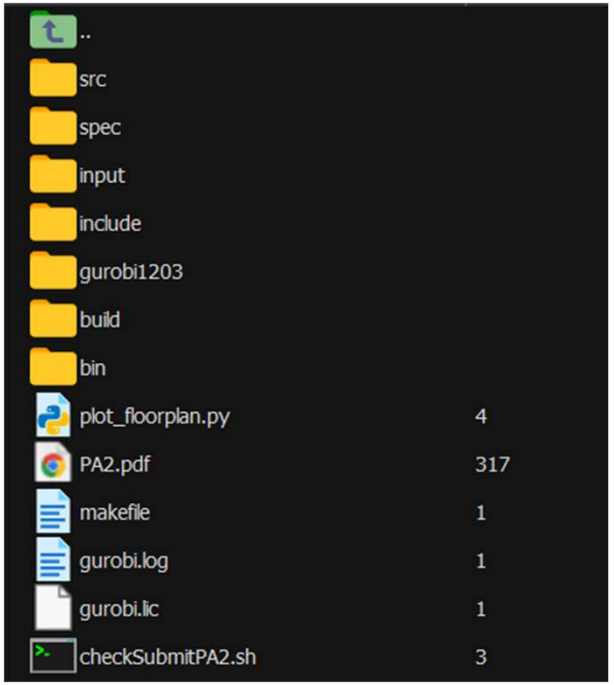
At this point, you should find the file “gurobi.lic” in your Downloads folder

Programming Assignment Setup

- Download “PA2.tar” from NTU COOL
- Upload the file to the EDA union server and unzip it:
  - eda25fXX@edaU12:~$ tar –xvf ./PA2.tar
- Upload “gurobi.lic” to the PA2 folder
- Check if you can compile the sample code:
  - eda25fXX@edaU12:~/PA2$ make

```
eda25f01@edaU12:~/PA2$ make
g++ -O3 -std=c++17 -Iinclude -Igurobi1203/linux64/include -MMD -MP -c src/cluster.cpp -o build/cluster.o
g++ -O3 -std=c++17 -Iinclude -Igurobi1203/linux64/include -MMD -MP -c src/floorplanner.cpp -o build/floorplanner.o
g++ -O3 -std=c++17 -Iinclude -Igurobi1203/linux64/include -MMD -MP -c src/main.cpp -o build/main.o
g++ -O3 -std=c++17 -Iinclude -Igurobi1203/linux64/include -MMD -MP -c src/parser.cpp -o build/parser.o
g++ -O3 -std=c++17 -Iinclude -Igurobi1203/linux64/include -MMD -MP -c src/solver.cpp -o build/solver.o
g++ -o bin/fp build/cluster.o build/floorplanner.o build/main.o build/parser.o build/solver.o -Lgurobi1203/linux64/lib -Wl,-rpath,'
$ORIGIN/../gurobi1203/linux64/lib' -lgurobi_c++ -lgurobi120 -lpthread -lm
```

Though some of the function is not completed,
the sample code is still compliable



After “make”, you should find the files above under your PA2 folder

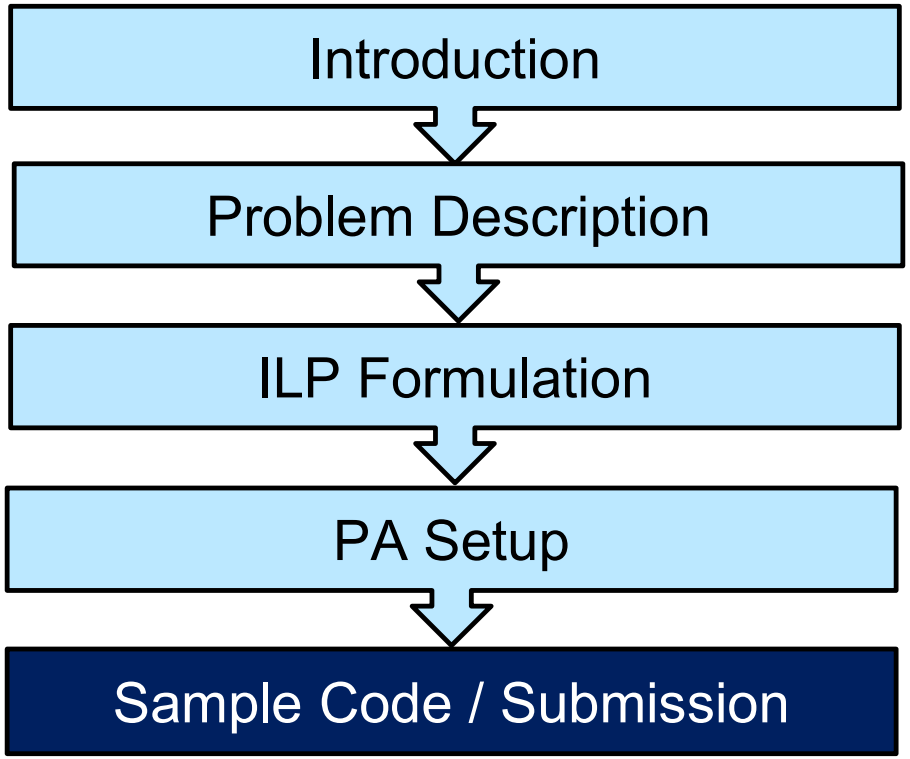
Programming Assignment Setup

- Type the following command and check if the terminal outputs the following lines:
  - eda25fXX@edaU12:~/PA2$ ./bin/fp ./input/sample.in ./spec/sample.spec ./sample.out

```
Initializing Gurobi model...
Set parameter WLSAccessID
Set parameter WLSSecret
Set parameter LicenseID to value 2722026
Set parameter LogFile to value "gurobi.log"
Academic license 2722026 - for non-commercial use only - registered to r1___@ntu.edu.tw
Gurobi model initialized.
Reading input file: ./input/sample.in
Gurobi Optimizer version 12.0.3 build v12.0.3rc0 (linux64 - "Ubuntu 22.04.5 LTS")

CPU model: Intel(R) Xeon(R) Silver 4314 CPU @ 2.40GHz, instruction set [SSE2|AVX|AVX2|AVX512]
Thread count: 32 physical cores, 64 logical processors, using up to 32 threads

Academic license 2722026 - for non-commercial use only - registered to r1___@ntu.edu.tw
Optimize a model with 0 rows, 0 columns and 0 nonzeros
Model fingerprint: 0xf9715da1
Coefficient statistics:
  Matrix range     [0e+00, 0e+00]
  Objective range  [0e+00, 0e+00]
  Bounds range     [0e+00, 0e+00]
  RHS range        [0e+00, 0e+00]
Presolve time: 0.08s
Presolve: All rows and columns removed
Iteration    Objective       Primal Inf.    Dual Inf.      Time
       0    0.0000000e+00   0.000000e+00   0.000000e+00      0s

Solved in 0 iterations and 0.09 seconds (0.00 work units)
Optimal objective  0.000000000e+00
Resetting the solver...
Module 0 and Module 1 overlap!
Writing output file: ./sample.out
```

If you see the same output, you're ready to start your assignment.
If you get a different result, please briefly describe your setup process and email the TA (johnnyhuang1007@gmail.com)

Outline


Introduction
Problem Description
ILP Formulation
PA Setup
Sample Code / Submission

Sample Code

- For this assignment, we have prepared a sample code which contain:
  - Input / Output Parser
  - Result Plotter
  - Basic Data structure (floorplanner/solver/module/etc…)
- There are three parts of function you need to complete (marked as TODO):
  - bool Floorplanner:: solveCluster(Cluster*, float, float)
    - a function for you to complete ILP formulation and result write back
  - float Floorplanner:: category1Opt()
    - a function for you to develop your framework for Problem Category 1
  - void Cluster::rotate() //This function is optional but strongly recommend to complete
    - A function to rotate a super module (Cluster)

- You are free to adjust any part of the code as long as it produce a valid result

Class Cluster

- An inherent class of a module
  - It extends Module and represents a group of sub-modules
- Submodules member: std::vector<Module*> leaf
  - You can actually use the member to save an “cluster” member (an inherent class of module)
  - Accessor: std::vector<Module*>& getSubModules()
  - Constructor will initialize the leaf member: Cluster(std::vector<Module*>)

- To check if the item in leaf is module/cluster use:
  - bool isCluster(Module* m)

- The rotate() function of cluster is not written (leave as TODO)

bool Floorplanner:: solveCluster(Cluster*, float, float)

- Determine positions and rotations for the target cluster's sub-modules so they fit within the W×H outline

- Main function for you to complete ILP framework:
  - Add VAR: solver_.addVariable("X", 0.0, 2.0, GRB_INTEGER);
  - Add Constraint: solver_.addConstraint("c1", {{"Y", 1.0}, {"X", -1.0}}, '<', 100.0); //Y-X < 100
  - Add Objective: solver_.setObjective({{"X", 1.0}, {"Y", 1.0}}, 'M'); //min X+Y

- Also need to complete a write back feature to update positions/rotations of your modules

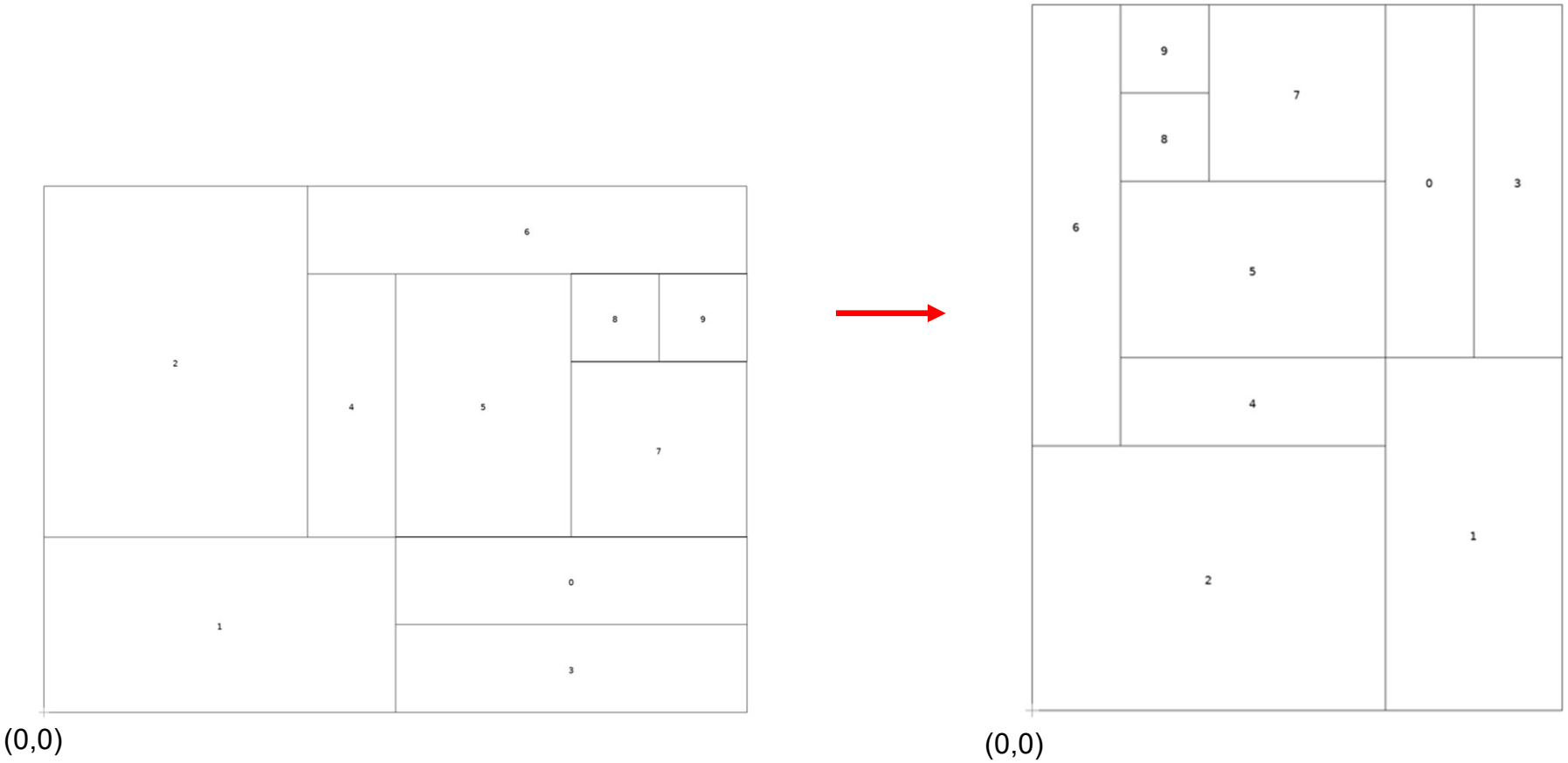
- We do not recommend removing the original solver-state update calls inside solveCluster()

void Cluster::rotate()

- Assume you have solved the sub-modules inside a Cluster and obtained the cluster's width and height
  - When the cluster is rotated, its lower-left coordinate remains unchanged
  - width/height change accordingly
  - every sub-module update its position and rotation
- "rotated" is the cluster's rotation flag
  - 0 → 1 rotates the internal modules 90° counterclockwise
  - 1 → 0 rotates them back to 0°
- Hint: Use collectAll() to gather all sub-modules and sub-clusters,
  - Compute each new coordinate independently to avoid recursive calls

void Cluster::rotate() - Example

Rotate 0 → 1

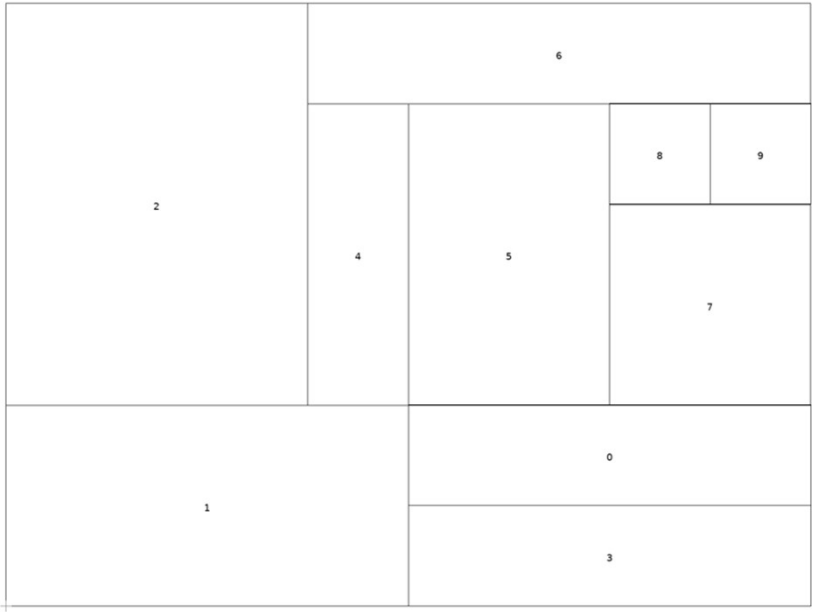


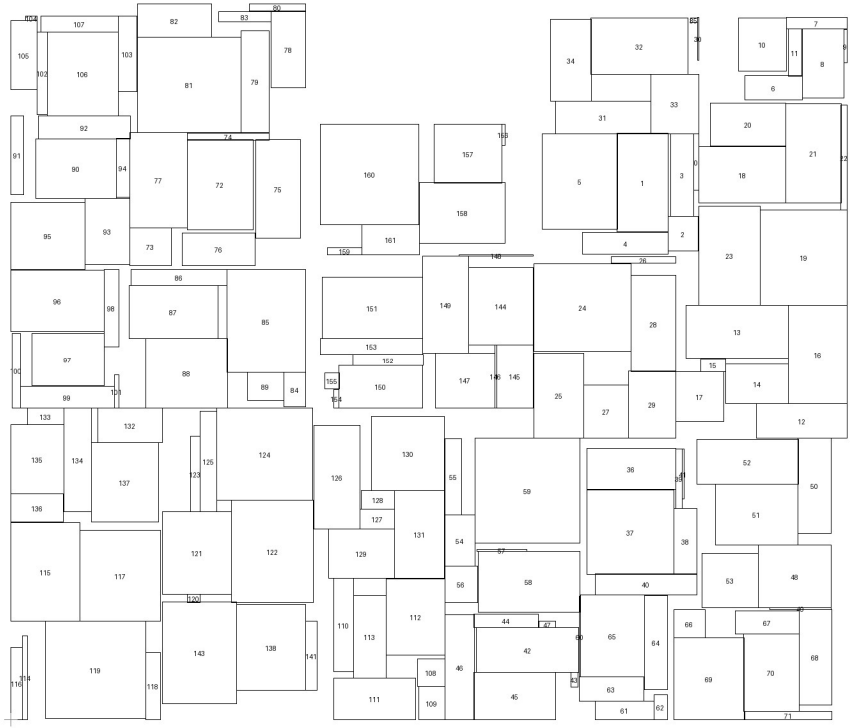
float Floorplanner:: category1Opt()

- We leave this function unimplemented
  - leverage solveCluster() to design an incremental/recursive flow.

Plotter

- Usage: python plot_floorplan.py ./input/sample.txt ./sample.out





Submission (I)

- Rename your working directory: mv PA2 [studentID]_pa2
- Include the following files inside [studentID]_pa2/
  - readme.txt
  - report.pdf
  - If you use Gurobi, include the package (gurobi1203)
- Do not include your gurobi license and input files
- you should have at least the following items in your directory

```
src/<all your source code>
include/<all your header files>
gurobi1203/
bin/fp
report.pdf
makefile
readme.txt
```

Submission (II)

- Compress your directory: tar zcvf [studentID]_pa2.tgz [studentID]_pa2
  - Do not add "./" prefix in the command
- Set execution permission for the checker script: chmod 755 ./checkSubmitPA2.sh
- Run submission checker: ./checkSubmitPA2.sh [studentID]_pa2.tgz
  - Do not add "./" prefix in the command

Submission (III)

- **No Plagiarism**
- Penalty for late submission: 20% per day
- Deadline: November 19, 2025, 23:59

- If you have any question, please contact:
  - Yu-Hsiang Huang (johnnyhuang1007@gmail.com)
  - Office Hours: Thu. 12:30~13:20 @ BL-407, by appointment

Thank you