

How to setup the Raspberry Pi to use the LPRF Driver

1. Download and unzip Raspbian image

```
$ wget [Link to download]
$ unzip file -d destination
```

2. Connect the SD-Card to the PC

3. Get the image to the SD-Card

```
$ df -h // determine the partition number
$ umount /dev/sdb1
$ umount /dev/sdb2
$ sudo dd bs=4M if=file.img of=/dev/sdb
$ pkill -USR1 -n -x dd // to get status
$ sync
```

4. Insert the SD-Card into the RPI and start the RPI

5. RPI configuration (first start config)

- Expand Filesystem
- Boot Options -> B1
- Change Timezone and Keyboard layout

6. Reboot

7. Change network settings

```
$ sudo nano /etc/network/interfaces
```

```
auto lo
iface lo inet loopback

auto eth0
iface eth0 inet dhsp
hwaddress 02:E4:73:03:BE:83
```

```
$ sudo reboot
```

8. Changing the Host

```
$ sudo nano /etc/hosts
```

Change “raspberrypi” into the name you want (RPI2)

```
$ sudo nano /etc/hostname
```

Replace “raspberrypi” with the name you choose above

```
$ sudo /etc/init.d/hostname.sh
$ sudo reboot
```

9. Now you can use ssh for remote to the RPI

```
$ ssh pi@137.226.200.211
```

10. Update the RPI

```
$ sudo apt-get update  
$ sudo apt-get upgrade
```

11. Download the linux source tree

```
$ mkdir kernel  
$ cd kernel  
$ git clone --depth=1 https://github.com/raspberrypi/linux.git  
$ cd linux
```

12. Prepare kernel compiling

```
$ sudo apt-get install bc libncurses5-dev libncursesw5-dev  
$ KERNEL=kernel  
$ make bcmrpi_defconfig  
$ make menuconfig
```

- Device Drivers -> Network device support -> Wireless LAN -> Realtek 8192C USB WiFi
- Device Drivers -> Network device support -> USB Network Adapters -> Multi-purpose USB Networking Framework -> SMSC LAN95XX based USB 2.0 10/100 ethernet devices
- Device Drivers -> SPI support -> BCM2835 SPI controller <*>
- Device Drivers -> USB support -> USB Mass Storage support <*>
- Device Drivers -> USB support -> DesignWare USB2 DRD Core Support <*>
- Networking support -> RF switch subsystem support <*>
- Networking support -> Wireless -> cfg80211 – wireless configuration API <*>
- Networking support -> Wireless -> Generic IEEE 802.11 Networking Stack (mac80211) <*>
- Networking support -> Networking Options -> TCP/IP networking -> The IPv6 protocol <*>
- Networking support -> Networking Options -> 6LoWPAN Support <*>
- Networking support -> Networking Options -> IEEE Std 802.15.4 Low-Rate Wireless Personal Area Networks support <*>
- Networking support -> Networking Options -> IEEE Std 802.15.4 Low-Rate Wireless Personal Area Networks support -> IEEE 802.15.4 socket interface <*>
- Networking support -> Networking Options -> IEEE Std 802.15.4 Low-Rate Wireless Personal Area Networks support -> 6lowpan support over IEEE 802.15.4 <*>
- Networking support -> Networking Options -> IEEE Std 802.15.4 Low-Rate Wireless Personal Area Networks support -> Generic IEEE 802.15.4 Soft Networking Stack (mac802154) <*>
- Networking support -> Networking Options -> NETLINK: mmaped IO <*>
- Networking support -> Networking Options -> NETLINK: socket monitoring interface <*>
- Device Drivers -> Network Device Support -> IEEE 802.15.4 drivers -> AT86RF230/231/233/212 transceiver driver <M>

13. Compiling the kernel

```
$ make zImage modules dtbs
```

Takes almost 12 hours

14. Install Modules and copy files in the boot folder

```
$ sudo make modules_install  
$ sudo cp arch/arm/boot/dts/*.dtb /boot/  
$ sudo cp arch/arm/boot/dts/overlays/*.dtb* /boot/overlays  
$ sudo cp arch/arm/boot/dts/overlays/README /boot/obverlays  
$ sudo scripts/mkknling arch/arm/boot/zImage /boot/kernel.img
```

15. Modify /boot/config.txt

Insert at the end of the file

```
dtoverlay=mmc
```

16. Reboot

Variant A: didn't work

1. Modify arch/arm/boot/dts/bcm2708-rpi-b-plus.dts

Delete the old spi0-node and insert

```
&spi0 {  
    status = "okay";  
    at86rf231@0 {  
        compatible = "atmel,at86rf231";  
        reg = <0>;  
        interrupts = <23 1>;  
        interrupt-parent = <&gpio>;  
        reset-gpio = <&gpio 24 1>;  
        sleep-tpio = <&gpio 25 1>;  
        spi-max-frequency = <500000>;  
    };  
};
```

2. Change directory and remake dtbs files

```
$ cd ~/kernel/linux  
$ make dtbs  
$ sudo cp arch/arm/boot/dts/*.dtb /boot
```

3. Reboot and go to step 17.

Variant B: use the at86rf233 overlay file

1. Edit arch/arm/boot/dts/overlays/at86rf233-overlay.dts

```
spi-max-frequency = <2000000>;
```

2. Change directory and remake dtbs files

```
$ cd ~/kernel/linux  
$ make dtbs  
$ sudo cp arch/arm/boot/dts/overlays/*.dtb* /boot/overlays
```

3. Insert at the end of /boot/config.txt

```
dtoverly=at86rf233
```

4. Reboot and go to step 17.

Variant C: use a lprf overlay file

1. Change directory to the kernel overlays and create a new overlay for the LPRF Driver

```
$ cd arch/arm/boot/dts/overlays  
$ nano lprf-overlay.dts
```

2. Insert

```
/dts-v1/  
/plugin/  
  
/* Overlay for LPRF Transceiver Chip spi0.0 */  
  
/{  
    compatible = "brcm,bcm2835", "brcm,bcm2836", "brcm,bcm2708",  
    "brcm,bcm2709";  
  
    fragment@0 {  
        target = <&spi0>;  
        __overlay__ {  
            #address-cells = <1>;  
            #size-cells = <0>;  
  
            status = "okay";  
  
            lowpan0: lprf@0 {  
                compatible = "ias,lprf";  
                reg = <0>;  
                interrupt-parent = <&gpio>;  
                interrupts = <23 4>; /* active high */  
                reset-gpio = <&gpio 24 1>;  
                sleep-gpio = <&gpio 25 1>;  
                spi-max-frequency = <2000000>;  
                xtal-trim = /bits/ 8 <0xf>;  
            };  
        };  
    };  
};
```

```

fragment@1 {
    target = <&spidev0>;
    __overlay__ {
        status = "disabled";
    };
};

fragment@2 {
    target = <&gpio>;
    __overlay__ {
        lowpan0_pins: lowpan0_pins {
            brcm,pins = <23 24 25>;
            brcm,function = <0 1 1>; /* in out out */
        };
    };
};

__overrides__ {
    interrupt = <&lowpan0>, "interrupts:0",
                <&lowpan0_pins>, "brcm,pins:0";
    reset      = <&lowpan0>, "reset-gpio:4",
                <&lowpan0_pins>, "brcm,pins:4";
    sleep      = <&lowpan0>, "sleep-gpio:4",
                <&lowpan0_pins>, "brcm,pins:8";
    speed      = <&lowpan0>, "spi-max-frequency:0";
    trim       = <&lowpan0>, "xtal-trim:0";
};
};

```

3. Create the *.dtbo file and copy it into the /boot-folder

```

$ dtc -O dtb -o lprf.dtbo -b 0 -@ lprf-overlay.dts
$ sudo cp arch/arm/boot/dts/overlays/lprf.dtbo /boot/overlays

```

4. Modify the /boot/config.txt and insert at the end

```
dtoverlay=lprf
```

5. Reboot and go to step 17.

17. Build and install the WPAN tools

```

$ cd
$ sudo apt-get install libnl-3-dev libnl-genl-3-dev
$ sudo apt-get install dh-autoreconf

$ git clone https://github.com/linux-wpan/wpan-tools
$ cd wpan-tools

```

```
$ ./autogen.sh
$ ./configure CFLAGS='-g -O0' --prefix=/usr --sysconfdir=/etc --libdir=/usr/lib
$ make

$ sudo make install
```

18. Copy lprf-files to RPI

19. Create file linux/include/linux/spi/lprf.h and insert

```
#ifndef LPRF_H
#define LPRF_H

struct lprf_platform_data {
    int rstn;
    int slp_tr;
    int dig2;
    u8 xtal_trim;
};

#endif
```

20. Everything is ready and the driver can be loaded.

```
$ sudo ./load_driver.sh
```

If you downloaded the linux source tree in a different folder, you have to change *load_driver.sh* (line 15) and the *Makefile* (line 6).

21. If you want to unload the driver manually, you have to set down the wpan device first.

```
$ sudo ip link set wpan0 down
$ sudo rmmod lprf_tx
```