

Large scale clustering and nearest neighbor search

Yannis Avrithis

Inria Rennes-Bretagne Atlantique

Prague, March 2016

Problem

ANN search

- Given query point \mathbf{q} , find its nearest neighbor with respect to Euclidean distance within data set \mathcal{X} in a d -dimensional space
- Encode (compress) vectors, speed up distance computations
- Fit underlying distribution with little space & time overhead

Vector quantization

- Given data set \mathcal{X} , map it to discrete codebook \mathcal{C} such that distortion is minimized
- Use ANN search to assign points to centroids
- Use vector quantization to improve ANN search

Problem

ANN search

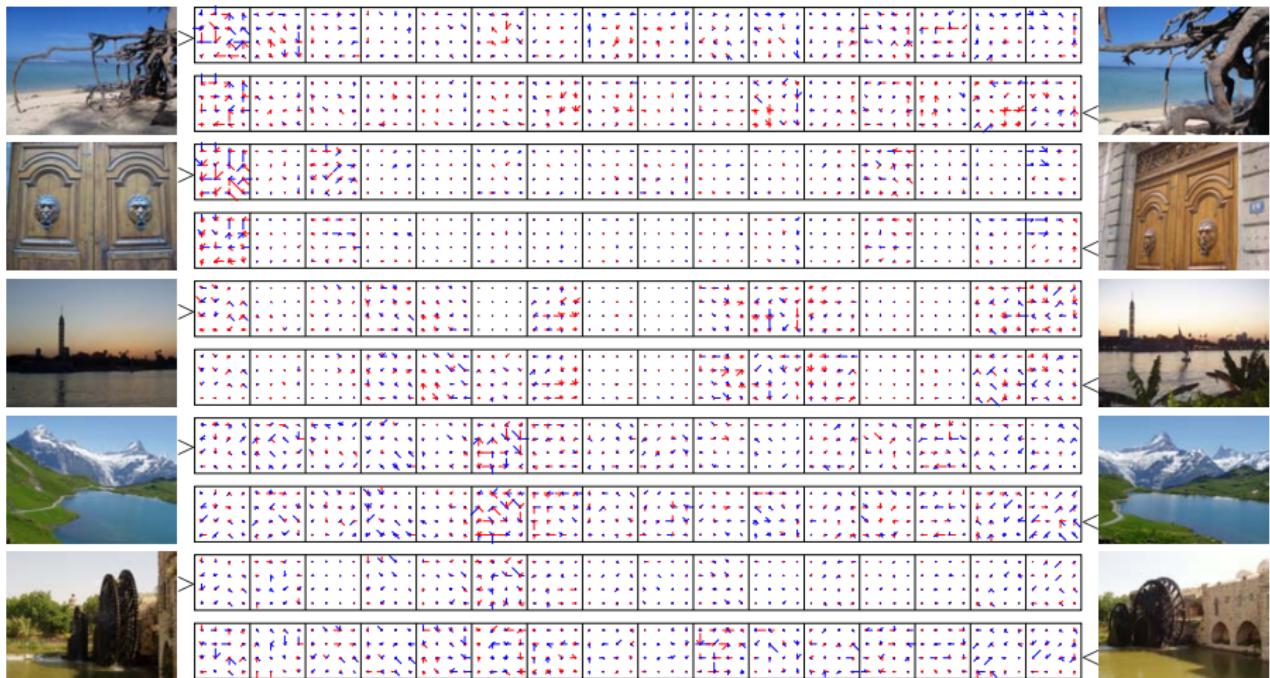
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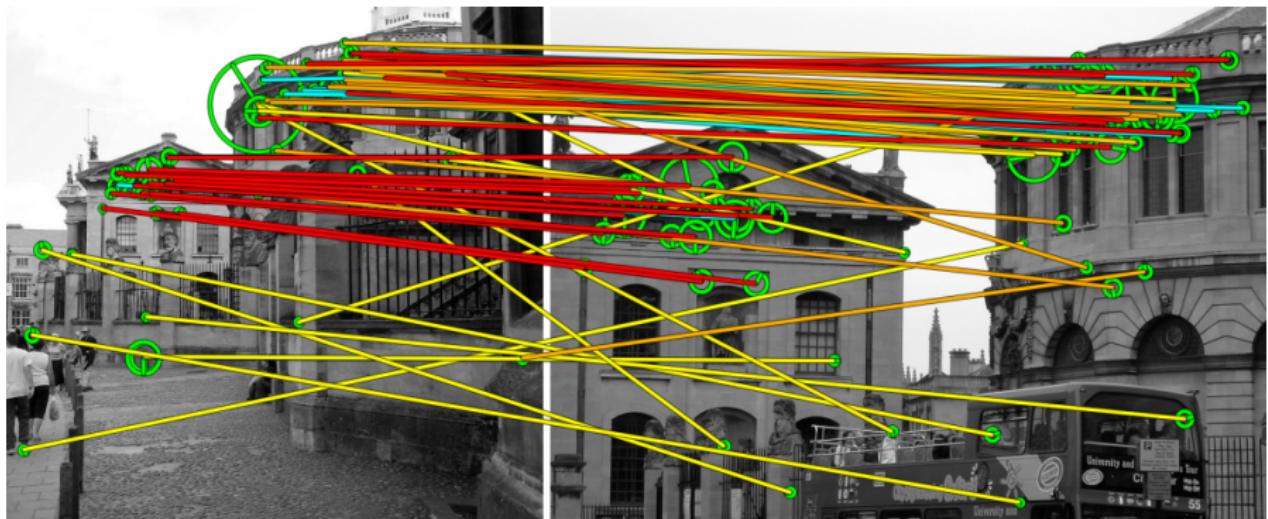
Applications in vision

Retrieval (image as point) [Jégou et al. '10][Perronnin et al. '10]



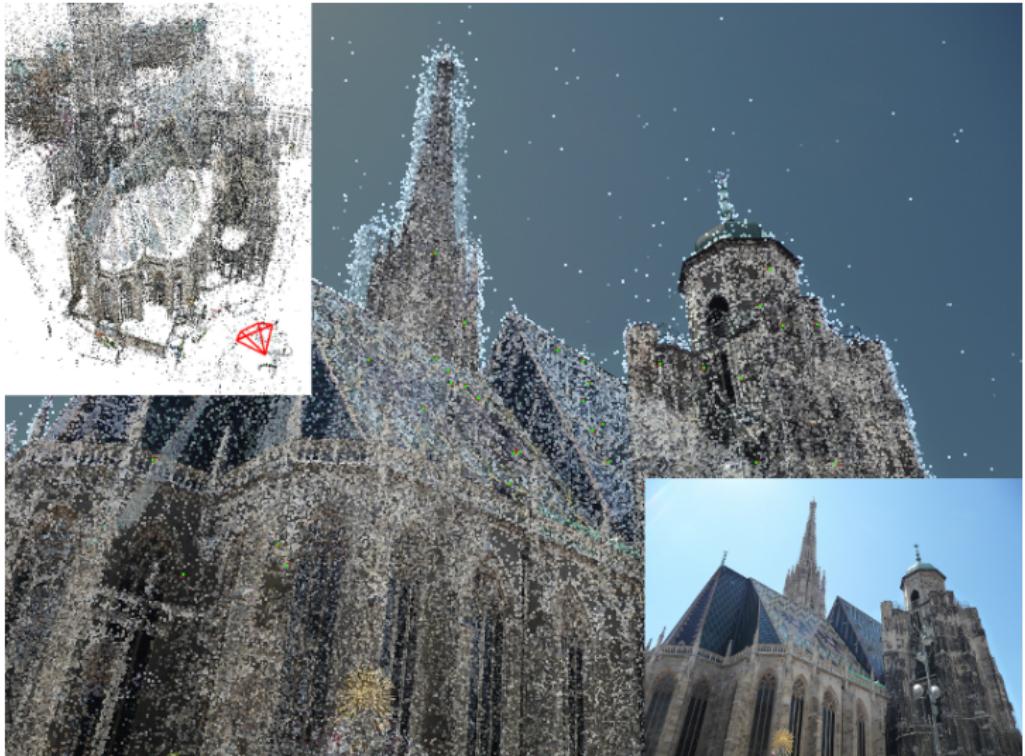
Applications in vision

Retrieval (patch as point) [Tolias et al. '13][Qin et al. '13]



Applications in vision

Localization, pose estimation [Sattler et al. '12][Li et al. '12]



Applications in vision

Classification [Boiman et al. '08][McCann & Lowe '12]

*query
image
 Q*



$$KL(p_Q \mid p_C) = 8.35$$



$$KL(p_Q \mid p_1) = 17.54$$



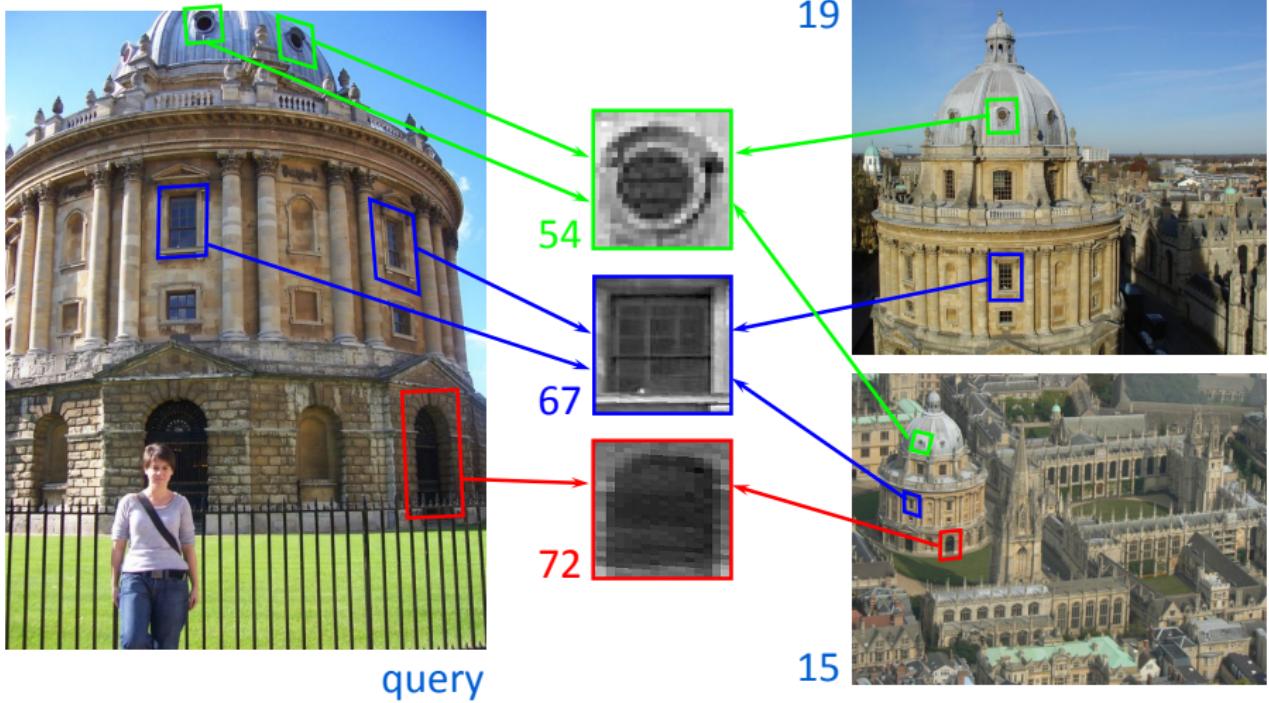
$$KL(p_Q \mid p_2) = 18.20$$



$$KL(p_Q \mid p_3) = 14.56$$

Applications in vision

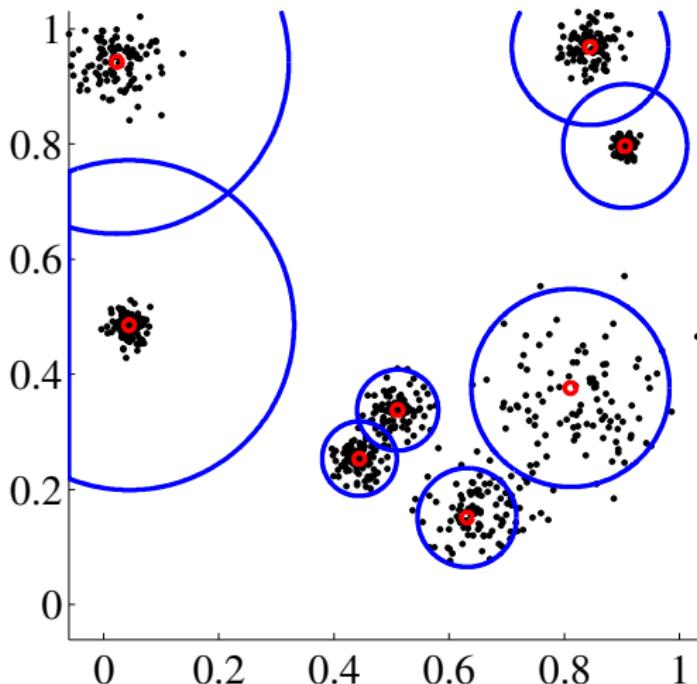
BoW (patch quantization) [Sivic et al. '03][Philbin et al. '07]



Applications in vision

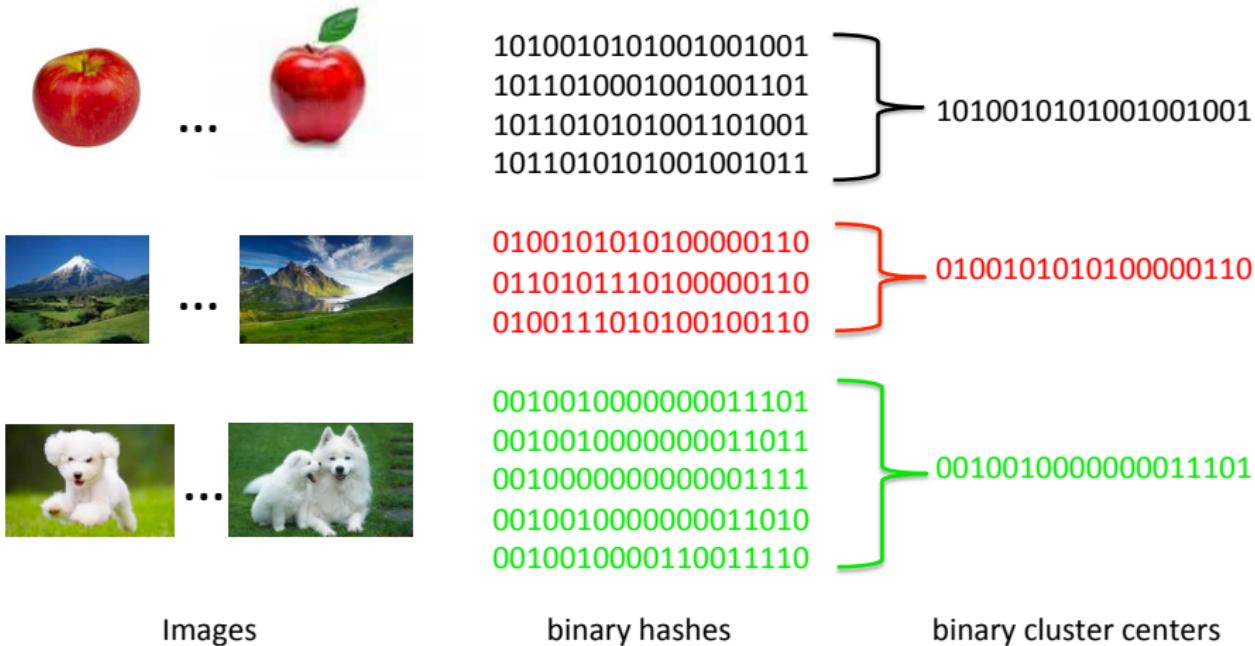
BoW (codebook construction) [Philbin et al. '07][Avrithis '12]

iteration=3, clusters=8



Applications in vision

Image clustering [Gong et al. '15][Avrithis '15]



Overview (1)

Binary codes

- spectral hashing [Weiss *et al.* '08]
- iterative quantization [Gong & Lazebnik '11]

Quantization

- vector quantization (VQ) [Gray '84]
- product quantization (PQ) [Jégou *et al.* '11]
- optimized product quantization (OPQ) [Ge *et al.* '13]
Cartesian k -means [Norouzi & Fleet '13]
- locally optimized product quantization (LOPQ) [Kalantidis & Avrithis '14]

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Overview (2)

Non-exhaustive search

- non-exhaustive PQ [Jégou *et al.* '11]
- inverted multi-index [Babenko & Lempitsky '12]
- multi-LOPQ [Kalantidis & Avrithis '14]

Clustering

- hierarchical k -means [Nister & Stewenius '06]
- approximate k -means [Philbin *et al.* '07]
- approximate Gaussian mixtures [Kalantidis & Avrithis '12]
- dimensionality-recursive vector quantization [Avrithis '13]
- ranked retrieval [Broder *et al.* '14]
- inverted-quantized k -means [Avrithis *et al.* '15]

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Binary codes

Spectral hashing

[Weiss et al. '08]

- Given a set of n data points $\mathbf{x}_i \in \mathbb{R}^d$, encode each by binary code \mathbf{y}_i
- Define **similarity matrix** S with $S_{ij} = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2/t^2)$
- Require binary codes to be **similarity preserving**, **balanced**, and **uncorrelated**:

$$\begin{aligned} & \text{minimize} && \sum_{ij} S_{ij} \|\mathbf{y}_i - \mathbf{y}_j\|^2 \\ & \text{subject to} && \mathbf{y}_i \in \{-1, 1\}^k \\ & && \sum_i \mathbf{y}_i = 0 \\ & && \frac{1}{n} \sum_i \mathbf{y}_i \mathbf{y}_i^\top = I. \end{aligned}$$

Spectral hashing

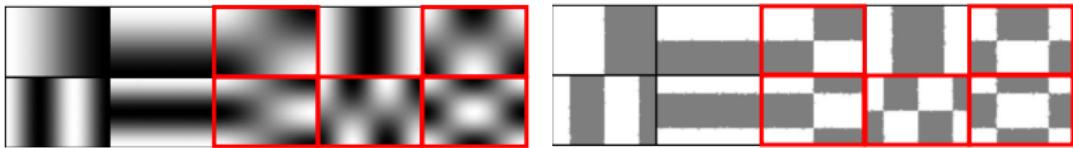
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Spectral hashing

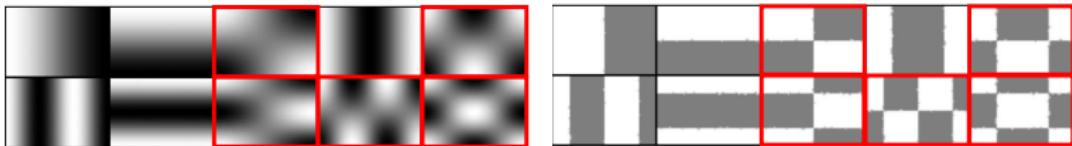
Example



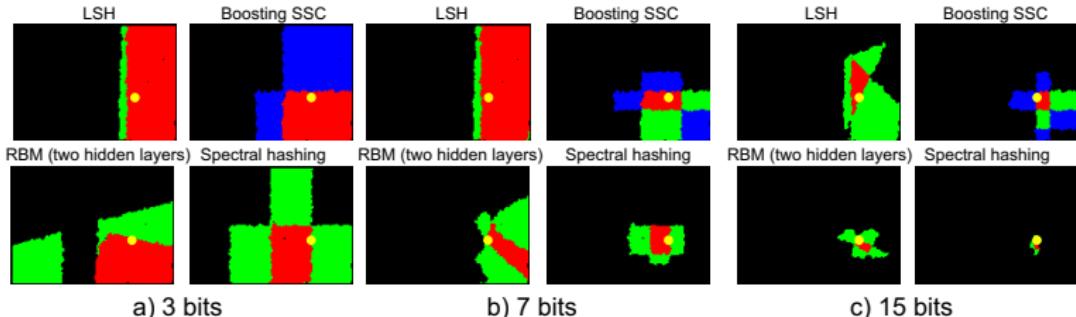
- Red: outer-product eigenfunctions: excluded
- Better to cut long dimension first
- Lower spatial frequencies are better than higher ones

Spectral hashing

Example



- Red: outer-product eigenfunctions: excluded
- Better to cut long dimension first
- Lower spatial frequencies are better than higher ones

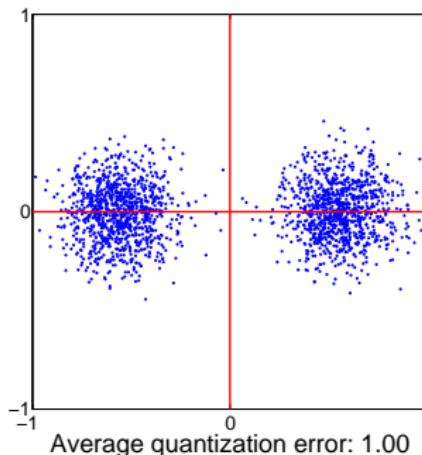


- Red: radius = 0; green: radius = 1; blue: radius = 2

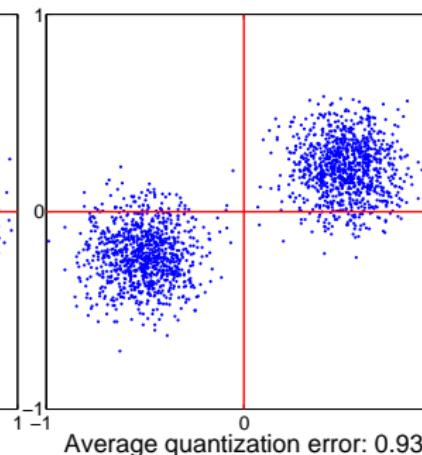
Iterative quantization

[Gong and Lazebnik '11]

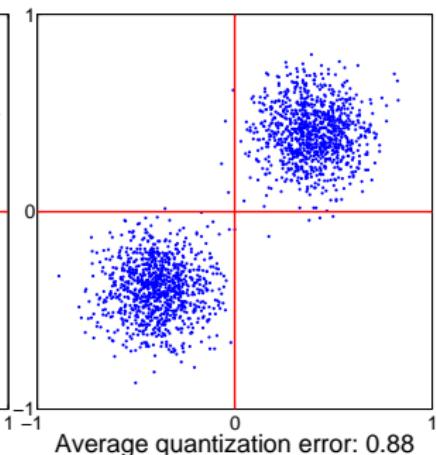
Quantize each data point to the closest vertex of the binary cube,
 $(\pm 1, \pm 1)$.



(a) PCA aligned.



(b) Random Rotation.

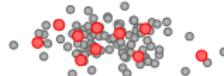
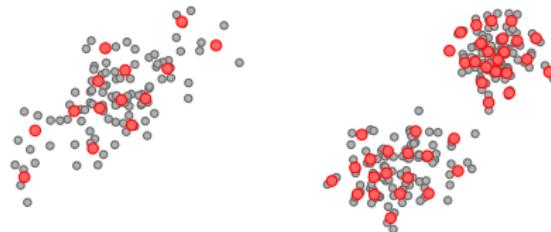


(c) Optimized Rotation.

Vector quantization

Vector quantization

[Gray '84]



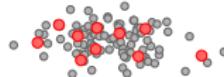
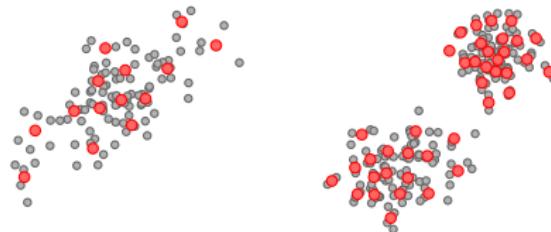
$$\text{minimize } E(\mathcal{C}) = \sum_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{c} \in \mathcal{C}} \|\mathbf{x} - \mathbf{c}\|^2 = \sum_{\mathbf{x} \in \mathcal{X}} \|\mathbf{x} - q(\mathbf{x})\|^2$$

distortion dataset codebook quantizer

The equation shows the minimization of distortion $E(\mathcal{C})$. Red arrows point from the labels "distortion", "dataset", and "codebook" to the corresponding terms in the equation. A pink arrow points from the label "quantizer" to the term $q(\mathbf{x})$.

Vector quantization

[Gray '84]

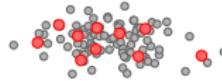
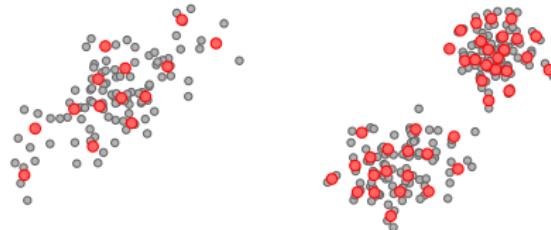


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distortion dataset codebook quantizer

Vector quantization

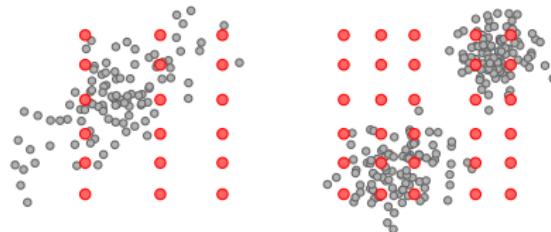
[Gray '84]



- For small distortion \rightarrow large $k = |\mathcal{C}|$:
 - hard to train
 - too large to store
 - too slow to search

Product quantization

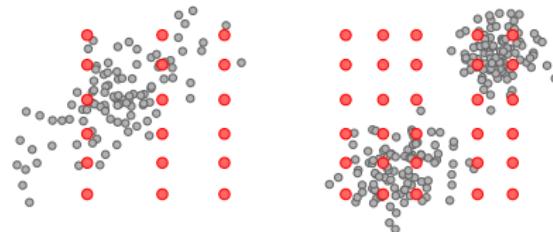
[Jégou et al. '11]



$$\begin{aligned} & \text{minimize} && \sum_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{c} \in \mathcal{C}} \|\mathbf{x} - \mathbf{c}\|^2 \\ & \text{subject to} && \mathcal{C} = \mathcal{C}^1 \times \cdots \times \mathcal{C}^m \end{aligned}$$

Product quantization

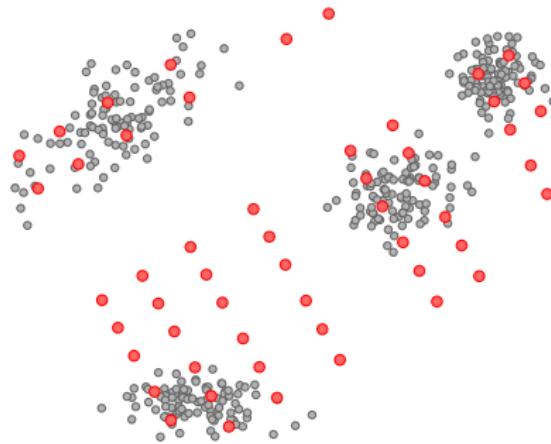
[Jégou et al. '11]



- train: $q = (q^1, \dots, q^m)$ where q^1, \dots, q^m obtained by VQ
- store: $|\mathcal{C}| = k^m$ with $|\mathcal{C}^1| = \dots = |\mathcal{C}^m| = k$
- search: $\|\mathbf{y} - q(\mathbf{x})\|^2 = \sum_{j=1}^m \|\mathbf{y}^j - q^j(\mathbf{x}^j)\|^2$ where $q^j(\mathbf{x}^j) \in \mathcal{C}^j$

Optimized product quantization

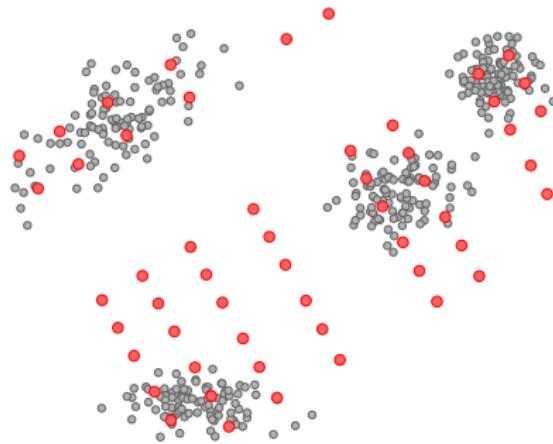
[Ge et al. '13]



$$\begin{aligned} & \text{minimize}_{\mathbf{x} \in \mathcal{X}} \sum_{\hat{\mathbf{c}} \in \hat{\mathcal{C}}} \|\mathbf{x} - R^\top \hat{\mathbf{c}}\|^2 \\ & \text{subject to} \quad \hat{\mathcal{C}} = \mathcal{C}^1 \times \cdots \times \mathcal{C}^m \\ & \quad R^\top R = I \end{aligned}$$

Optimized product quantization

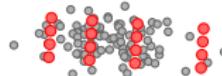
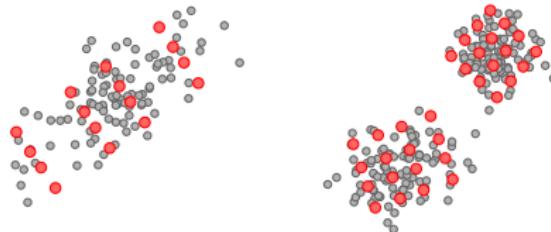
Parametric solution for $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \Sigma)$



- **independence:** PCA-align by diagonalizing Σ as $U\Lambda U^\top$
- **balanced variance:** permute Λ by π such that $\prod_i \lambda_i$ is constant in each subspace; $R \leftarrow UP_\pi^\top$
- find $\hat{\mathcal{C}}$ by PQ on rotated data $\hat{X} = RX$

Locally optimized product quantization

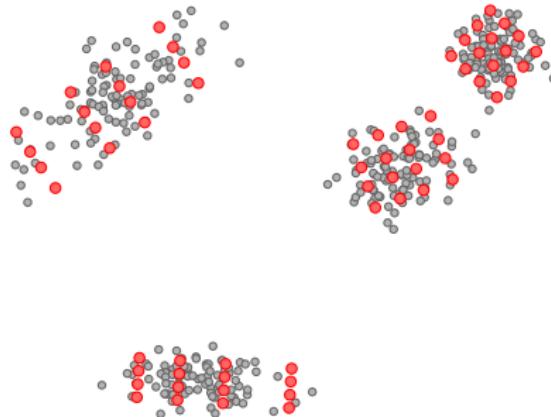
[Kalantidis & Avrithis '14]



- compute residuals $r(\mathbf{x}) = \mathbf{x} - Q(\mathbf{x})$ on coarse quantizer Q
- collect residuals $\mathcal{Z}_i = \{r(\mathbf{x}) : Q(\mathbf{x}) = \mathbf{c}_i\}$ per cell
- train $(R_i, q_i) \leftarrow \text{OPQ}(\mathcal{Z}_i)$ per cell

Locally optimized product quantization

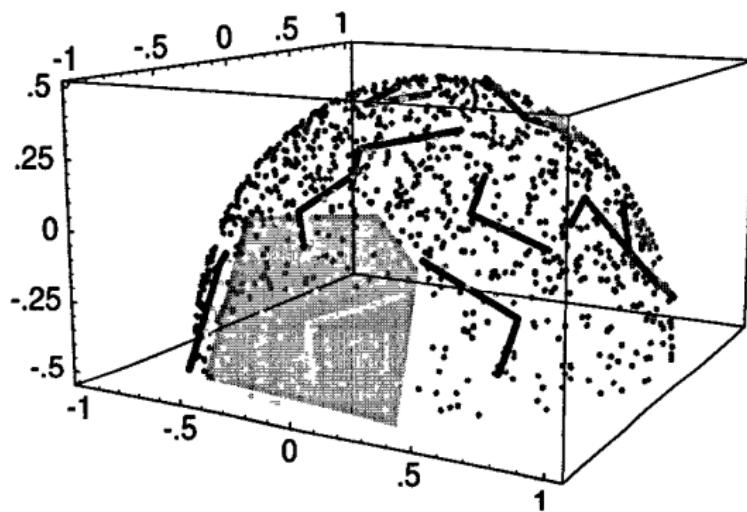
[Kalantidis & Avrithis '14]



- residual distributions closer to Gaussian assumption
- better captures the support of data distribution, like local PCA
 - multimodal (e.g. mixture) distributions
 - distributions on nonlinear manifolds

Local principal component analysis

[Kambhatla & Leen '97]

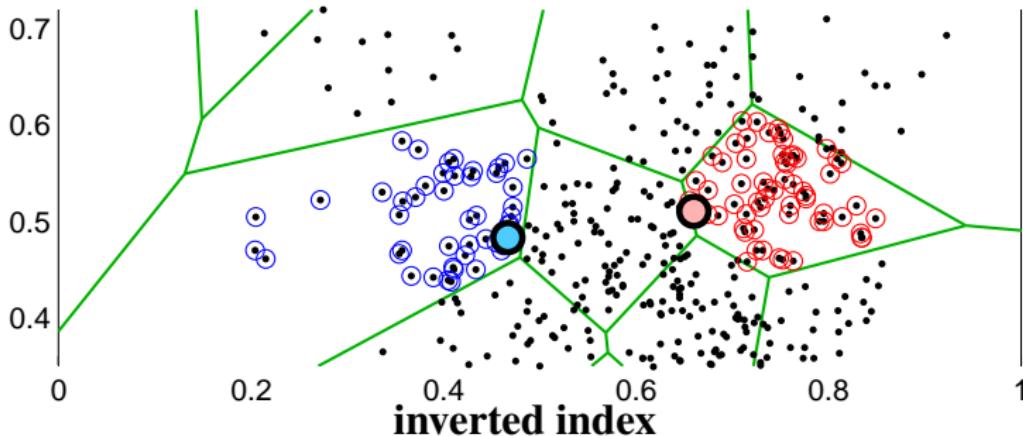


But, we are not doing dimensionality reduction!

Non-exhaustive search

Inverted multi-index

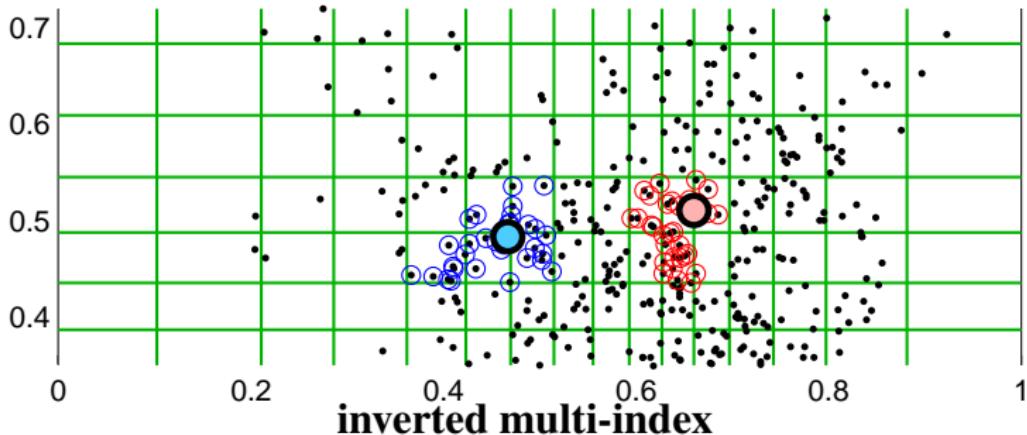
[Babenko & Lempitsky '12]



- train codebook \mathcal{C} from dataset $\{\mathbf{x}_n\}$, defining a **coarse** quantizer Q
- quantize each point \mathbf{x} to $Q(\mathbf{x})$ and encode its residual $r(\mathbf{x}) = \mathbf{x} - Q(\mathbf{x})$ by product quantizer q
- given query \mathbf{y} , visit w coarse cells closest to \mathbf{y}

Inverted multi-index

[Babenko & Lempitsky '12]

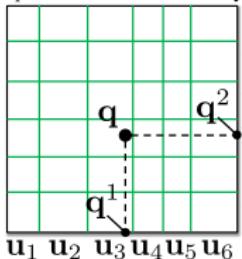


- decompose vectors as $\mathbf{x} = (\mathbf{x}^1, \mathbf{x}^2)$
- train codebooks $\mathcal{C}^1, \mathcal{C}^2$ from datasets $\{\mathbf{x}_n^1\}, \{\mathbf{x}_n^2\}$
- induced codebook $\mathcal{C}^1 \times \mathcal{C}^2$ gives a **finer** partition
- given query \mathbf{y} , visit cells $(\mathbf{c}^1, \mathbf{c}^2) \in \mathcal{C}^1 \times \mathcal{C}^2$ in ascending order of distance to \mathbf{y}

Inverted multi-index

Multi-sequence algorithm

space subdivision via PQ



71
72
73
74
75
76

product antization

q^1 vs. \mathcal{U}

i	$\mathbf{u}_{\alpha(i)}$	r
1	\mathbf{u}_3	0.5
2	\mathbf{u}_4	0.7
3	\mathbf{u}_5	4
4	\mathbf{u}_2	6
5	\mathbf{u}_1	8
6	\mathbf{u}_6	9

q^2 vs. ν

j	$\mathbf{v}_{\beta(j)}$	s
1	\mathbf{v}_4	0.1
2	\mathbf{v}_3	2
3	\mathbf{v}_5	3
4	\mathbf{v}_2	6
5	\mathbf{v}_6	7
6	\mathbf{v}_1	11

multi-sequence algorithm

$[u_{\alpha(i)} \ v_{\beta(j)}]$	(i, j)	$r(i) + s(j)$
$[u_3 \ v_4]$	(1,1)	0.6 (0.5+0.1)
$[u_4 \ v_4]$	(2,1)	0.8 (0.7+0.1)
$[u_3 \ v_3]$	(1,2)	2.5 (0.5+2)
$[u_4 \ v_3]$	(2,2)	2.7 (0.7+2)
$[u_3 \ v_5]$	(1,3)	3.5 (0.5+3)
$[u_4 \ v_5]$	(2,3)	3.7 (0.7+3)
$[u_5 \ v_4]$	(3,1)	4.1 (4+0.1)
$[u_5 \ v_3]$	(3,2)	6 (4+2)
$[u_3 \ v_2]$	(1,4)	6.5 (0.5+6)
	...	

	1	2	3	4	5	6
1	0.6	0.8	4.1	6.1	8.1	9.1
2	2.5	2.7	6	8	10	11
3	3.5	3.7	7	9	11	12
4	6.5	6.7	10	12	14	15
5	7.5	7.7	11	13	15	16
6	11.5	11.7	15	17	19	20

1	2	3	4	5	6
0.6	0.8	4.1	6.1	8.1	9.1
2.5	2.7	6	8	10	11
3.5	3.7	7	9	11	12
6.5	6.7	10	12	14	15
7.5	7.7	11	13	15	16
11.5	11.7	15	17	19	20

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6.5	6.7	10	12	14	15
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1	2	3	4	5
0.6	0.8	4.1	6.1	8.1
2.5	2.7	6	8	10
3.5	3.7	7	9	11
6.5	6.7	10	12	14
7.5	7.7	11	13	15
11.5	11.7	15	17	19

1	2	3	4	5
0.6	0.8	4.1	6.1	8.1
2.5	2.7	6	8	10
3.5	3.7	7	9	11
6.5	6.7	10	12	14
7.5	7.7	11	13	15
11.5	11.7	15	17	19

	1	2	3	4	5	6
1	0.6	0.8	4.1	6.1	8.1	9.1
1	2.5	2.7	6	8	10	11
2	3.5	3.7	7	9	11	12
5	6.5	6.7	10	12	14	15
6	7.5	7.7	11	13	15	16
0	11.5	11.7	15	17	19	20
1						

OUTPUT:

$$(1, 1) \rightarrow \mathbf{W}_{3,4}$$

$$(2,1) \rightarrow \mathbf{W}_{4,4}$$

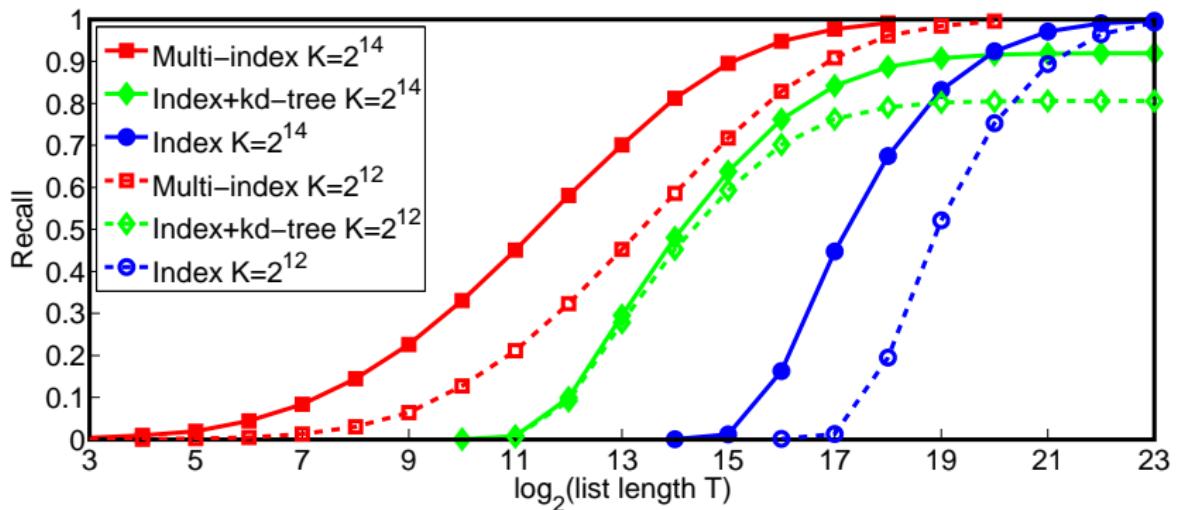
$$(1, 2) \rightarrow W_{3,3}$$

$$(2,2) \rightarrow \mathbf{W}_{4,3}$$

$$(1, 3) \rightarrow \mathbf{W}_{3,5}$$

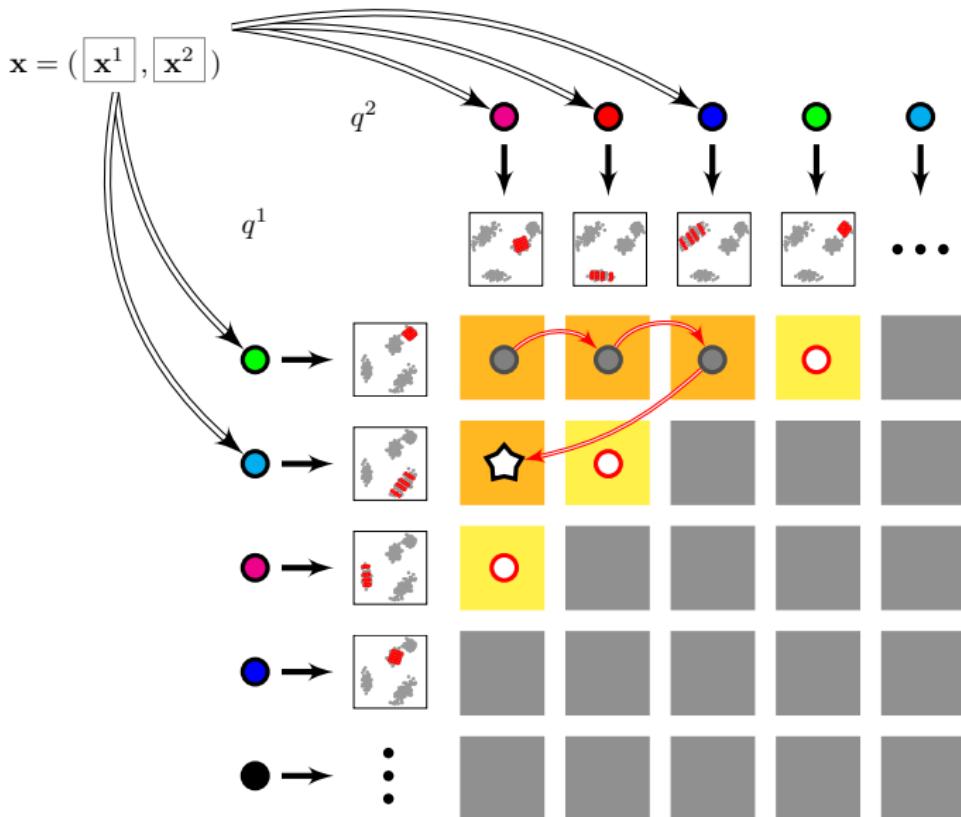
Inverted multi-index

Result on SIFT1B: are NN in candidate lists?



Multi-LOPQ

[Kalantidis & Avrithis '14]



Multi-LOPQ

Result on SIFT1B, 128-bit codes

T	Method	$R = 1$	10	100
20K	IVFADC+R [Jégou <i>et al.</i> '11]	0.262	0.701	0.962
	LOPQ+R [Kalantidis & Avrithis '14]	0.350	0.820	0.978
10K	Multi-D-ADC [Babenko & Lempitsky '12]	0.304	0.665	0.740
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.345	0.725	0.794
	Multi-LOPQ [Kalantidis & Avrithis '14]	0.430	0.761	0.782
30K	Multi-D-ADC [Babenko & Lempitsky '12]	0.328	0.757	0.885
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.366	0.807	0.913
	Multi-LOPQ [Kalantidis & Avrithis '14]	0.463	0.865	0.905
100K	Multi-D-ADC [Babenko & Lempitsky '12]	0.334	0.793	0.959
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.373	0.841	0.973
	Multi-LOPQ [Kalantidis & Avrithis '14]	0.476	0.919	0.973

Application: image search

Deep learned image features

[Krizhevsky et al. '12] [Babenko et al. '14]

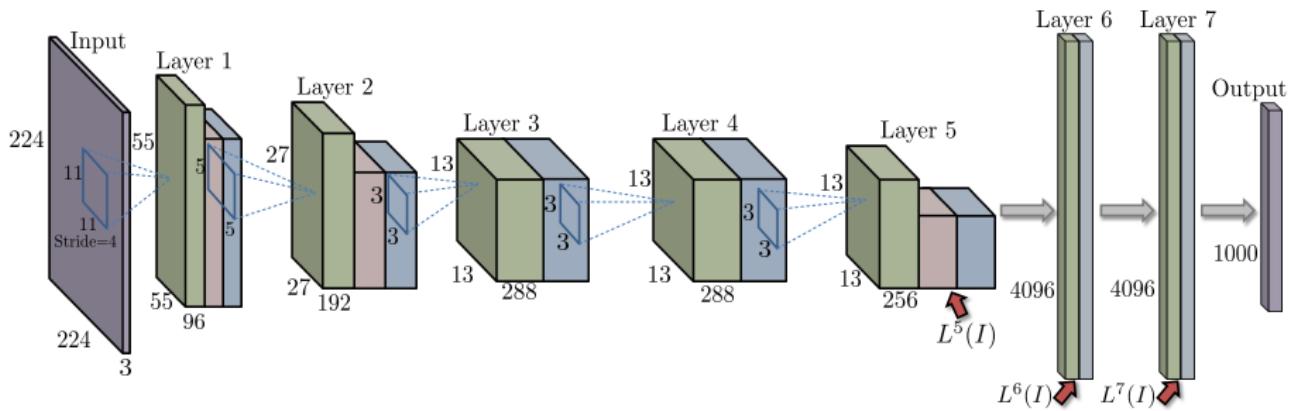
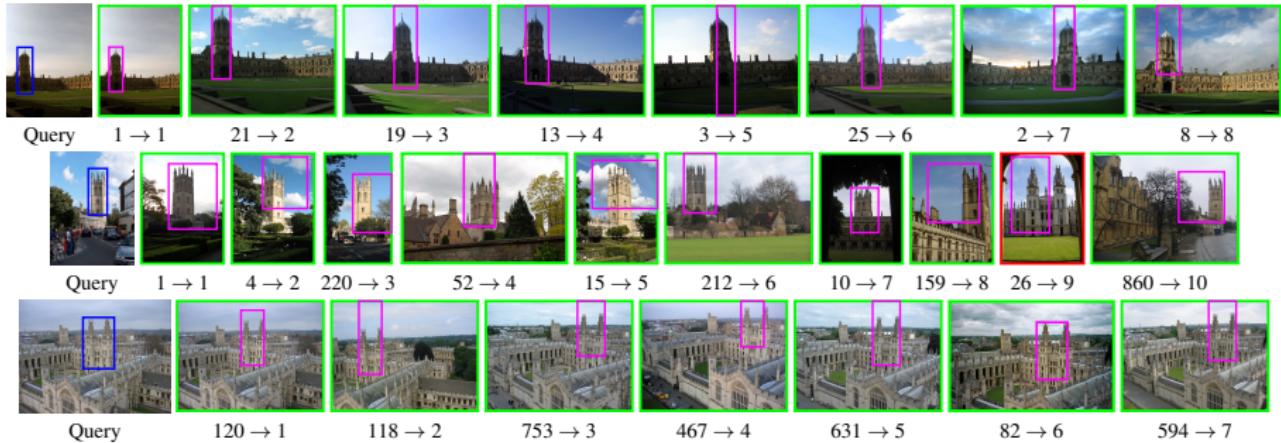


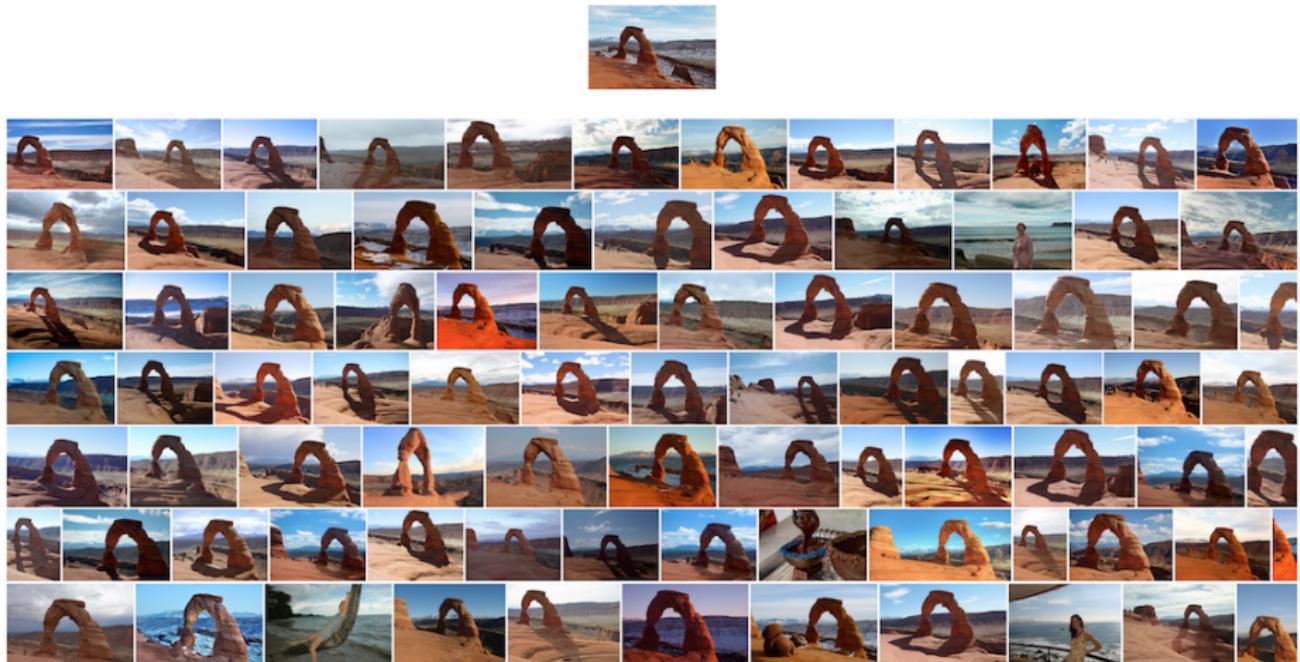
Image search on CNN activations

[Razavian '14, Babenko '15, Kalantidis '15, Tolias '16]



Multi-LOPQ on CNN activations

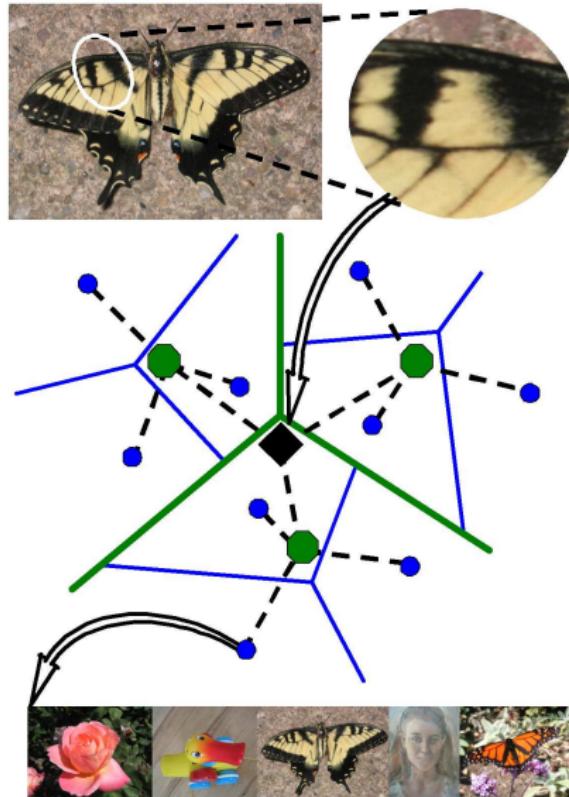
Image query on Flickr 100M ($4k \rightarrow 128$ dimensions)



Clustering

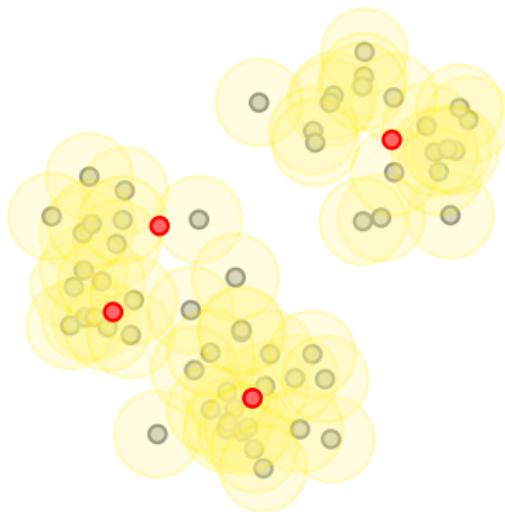
Hierarchical k -means

[Nister & Stewenius '06]



Approximate k -means

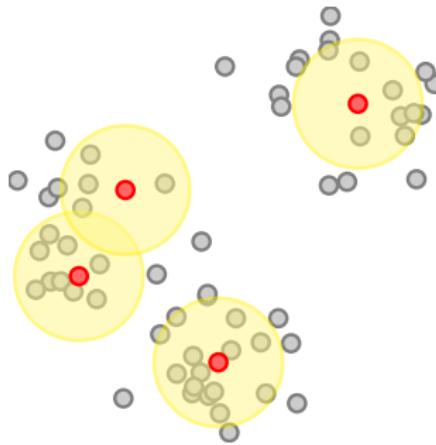
[Philbin et al. '07][Gong et al. '15]



- centroids updated as in k -means
- points assigned to centroids by approximate search
- index rebuilt in every k -means iteration

Ranked retrieval

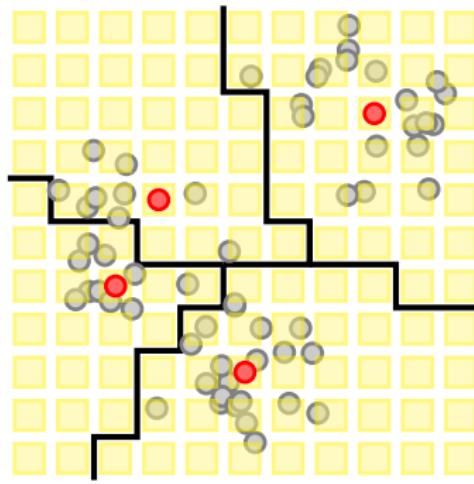
[Broder et al. '14]



- points assigned by inverse search from **centroids** to points
- needs conflict resolution; points may remain unassigned
- index built only once; resembles mean shift [Cheng et al. '95]

Dimensionality-recursive vector quantization

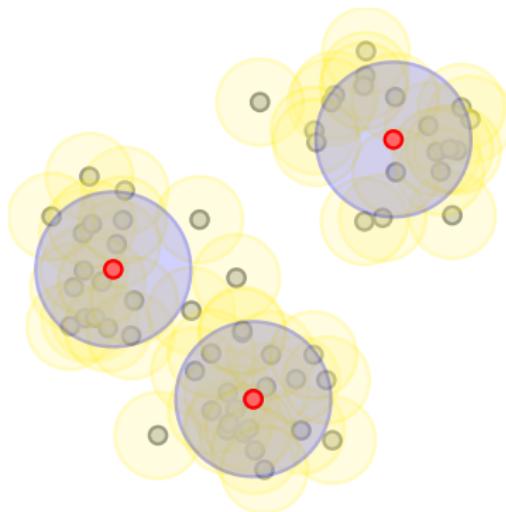
[Avrithis '13]



- points quantized as in multi-index
 - cells assigned exhaustively by distance map from centroids
 - points assigned by lookup

Approximate Gaussian mixtures

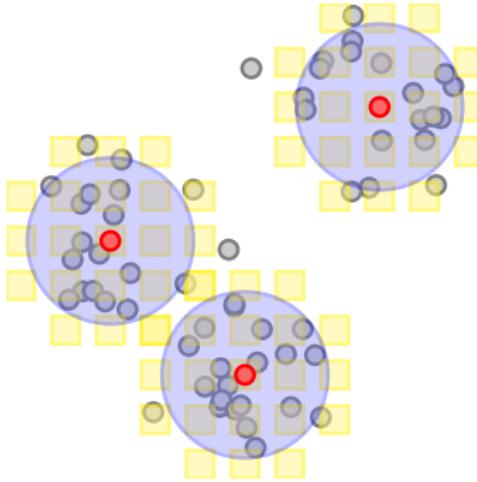
[Kalantidis & Avrithis '12]



- centroids & variances updated as in EM
- points soft-assigned by approximate search
- k dynamically estimated

Inverted-quantized k -means

[Avrithis et al. '15]



- inverse search as in RR
- points quantized as in DRVQ; search as in multi-index
- k dynamically estimated as in AGM

Inverted-quantized k -means

representation: for each cell u_α , with $X_\alpha = \{x \in X : q(x) = u_\alpha\}$

- probability $p_\alpha = |X_\alpha|/n$
- mean $\mu_\alpha = \frac{1}{|X_\alpha|} \sum_{x \in X_\alpha} x$ of all points in X_α

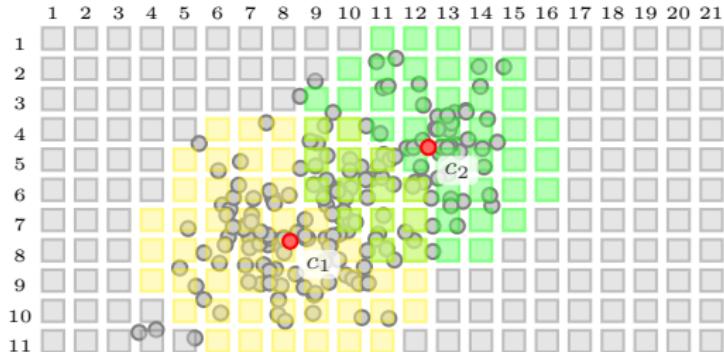
update: for each centroid c_m , with $A_m = \{\alpha \in I : a(u_\alpha) = m\}$

$$c_m \leftarrow \frac{1}{\sum_{\alpha \in A_m} p_\alpha} \sum_{\alpha \in A_m} p_\alpha \mu_\alpha,$$

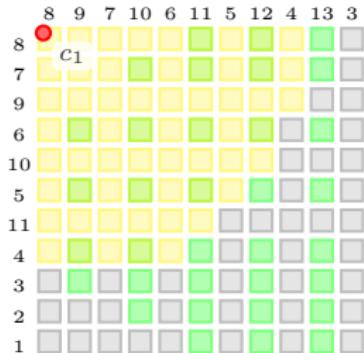
assignment: for each centroid c_m ,

- find the w nearest sub-codewords in each of two sub-codebooks
- run multi-sequence independently in $w \times w$ search block
- assign visited cells $m \leftarrow a(u_\alpha)$; resolve conflicts

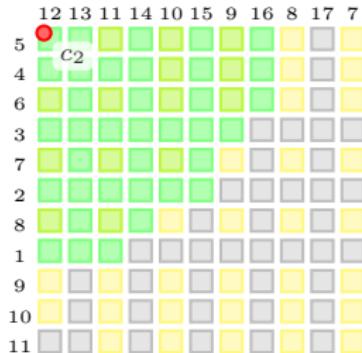
Centroid-to-cell search



(a) visited cells on original grid

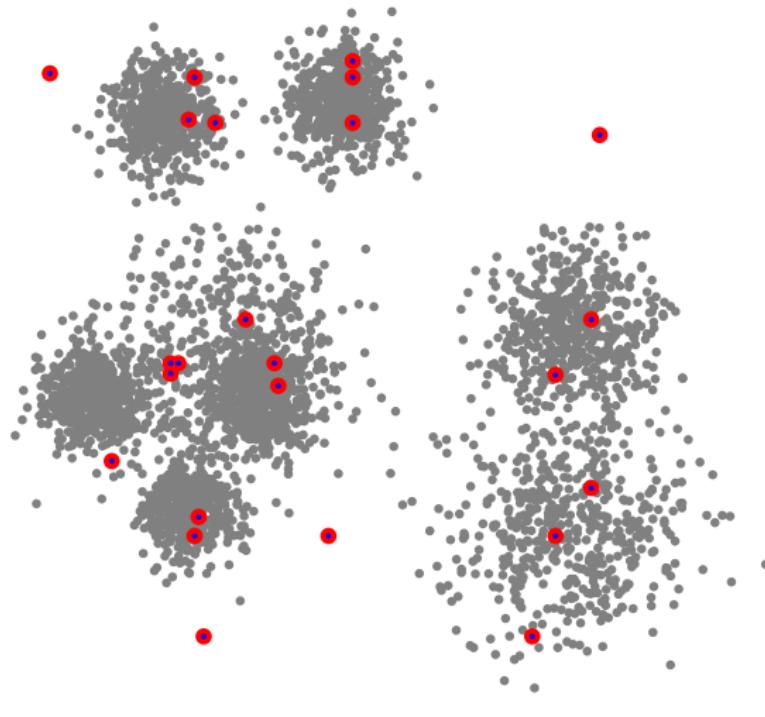


(b) search block of c_1

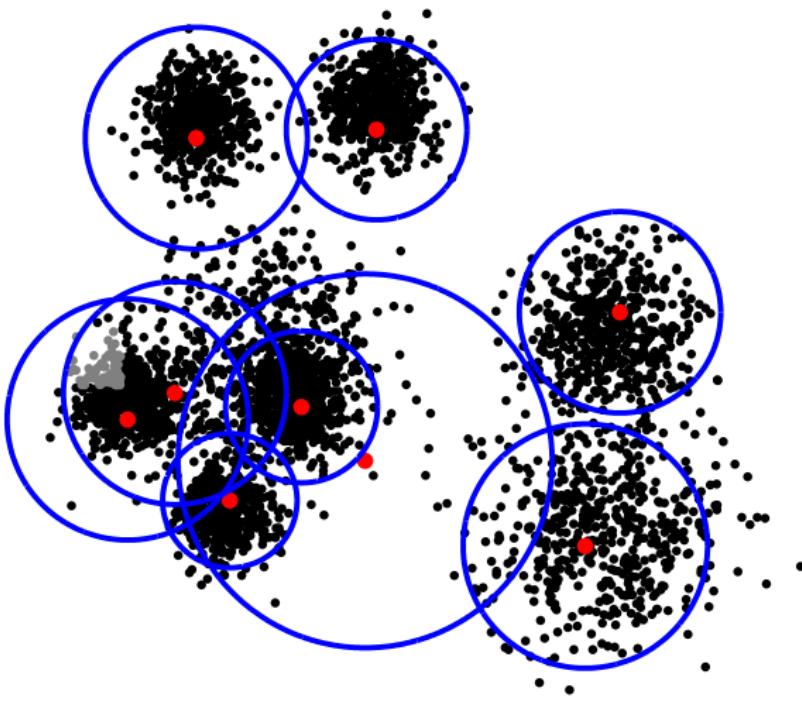


(c) search block of c_2

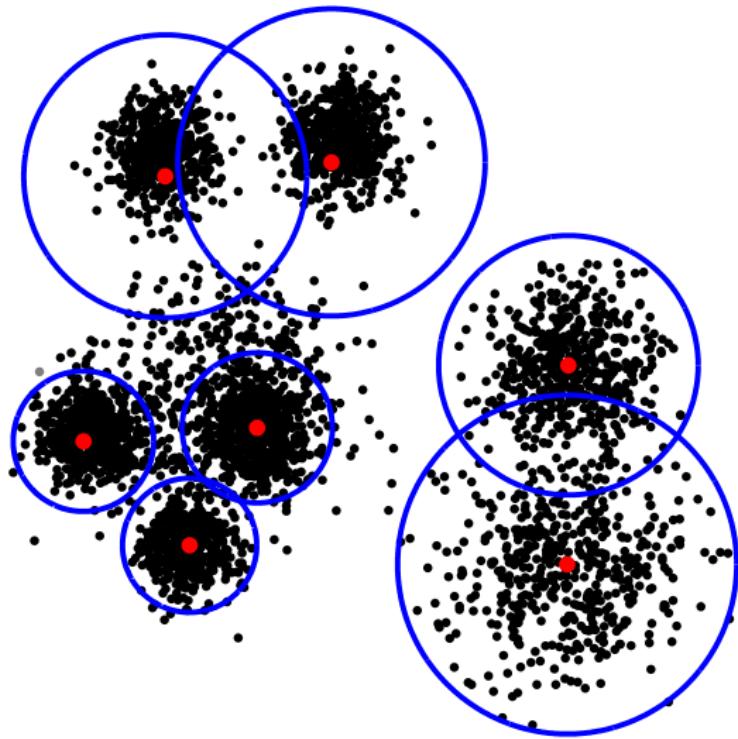
Dynamic IQ-means



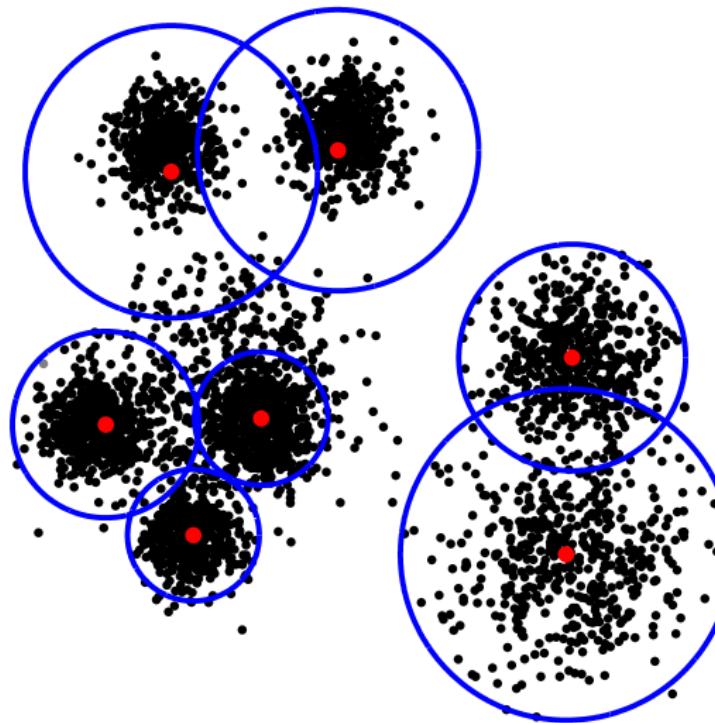
Dynamic IQ-means



Dynamic IQ-means



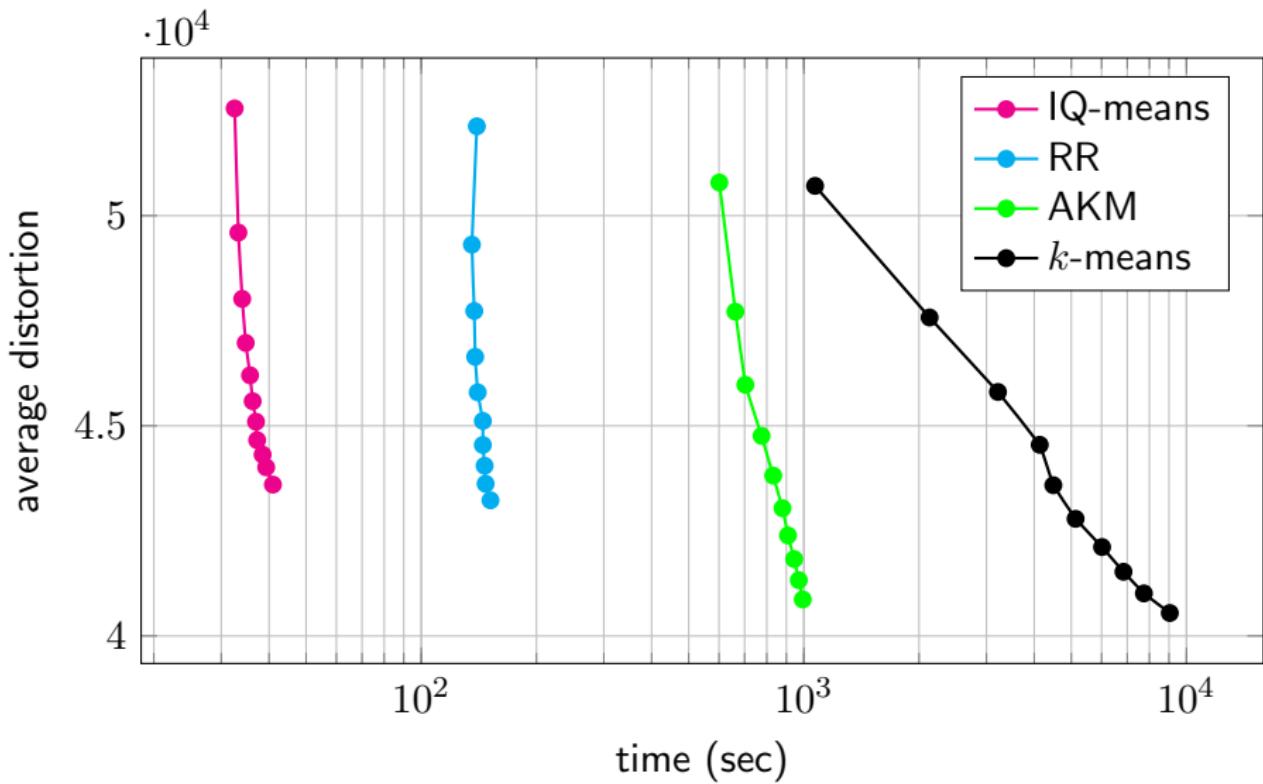
Dynamic IQ-means



Dynamic IQ-means

- quantize each centroid to closest cell just before search
- get **centroid-to-centroid** search at no extra cost
- greedily delete centroids as in EGM [Avrithis & Kalantidis '12]

Comparison on SIFT1M with $k \in \{10^3, \dots, 10^4\}$



Comparison on YFCC100M, initial $k = 10^5$

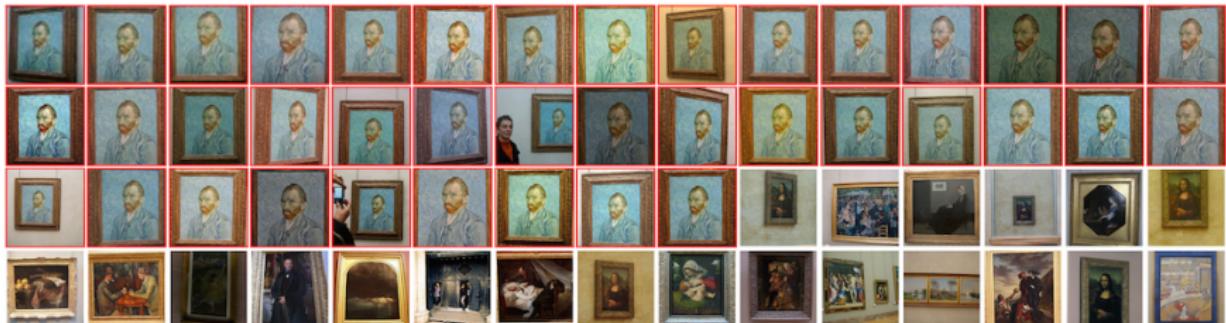
AlexNet fc7 features, 128 dimensions, optimized decomposition

	Cell-KM	DKM ($\times 300$)	D-IQ-Means
k/k'	100000	100000	85742
time (s)	13068.1	7920.0	140.6
precision	0.474	0.616	0.550

Cell-KM k -means on points quantized to cell

DKM distributed k -means on 300 machines

Mining on YFCC100M



Paris500k



Paris500k + YFCC100M

Y. Avrithis, Y. Kalantidis, E. Anagnostopoulos, I. Z. Emiris.
Web-scale image clustering revisited. ICCV 2015.

<http://image.ntua.gr/iva/research/>



Thank you!