Linear Regression

1. The Linear Model

Assume $Y_i = x_i^{\top} \beta + \epsilon_i$ or $Y = X\beta + \epsilon$ with $X \in \mathbb{R}^{n \times p}, \beta \in$ $\mathbb{R}^{p\times 1}$; $(n\geqslant p)$ and $\mathbb{E}[\epsilon_i]=0, Var(\epsilon_i)=\sigma^2$. X is often augmented with $(1_{N\times 1})$ to use β_1 as bias. df = n - p[-intercept]

2. Least Squares Method

LS estimator is $\hat{\beta} = \arg\min_{\beta} ||Y - X\beta||_2^2 = (X^{\top}X)^{-1}X^{\top}Y$ Estimate $\hat{\sigma}^2 = \frac{1}{n-n} \sum_{i=1}^n (y_i - \hat{\beta}^\top x_i)^2$ with $\mathbb{E}[\hat{\sigma}^2] = \sigma^2$

Assumptions for Linear Model

- i Linear regression equation is correct, i.e. $\mathbb{E}[\epsilon_i] = 0 \ \forall i$.
- ii We measure x_i 's exactly. Else, need correction (?).
- iii Error is homoscedastic, i.e. $Var(\epsilon_i) = \sigma^2 \ \forall i$. Else, use "Weighted LS".
- iv Errors are uncorrelated, i.e. $Cov(\epsilon_i, \epsilon_j) = 0 \ \forall i \neq j$. Else "Generalized LS"
- v Errors are jointly normally distributed. Else "Robust Methods".

Moments of least squares estimates

Assume $\mathbf{Y} = X\boldsymbol{\beta} + \epsilon$, $\mathbb{E}[\boldsymbol{\epsilon}] = \mathbf{0}$, $Cov(\boldsymbol{\epsilon}\boldsymbol{\epsilon}^{\top}) = \sigma^2 I$ (all assumptions satisfied). Then

- i $\mathbb{E}[\hat{\boldsymbol{\beta}}] = \boldsymbol{\beta} \ (\hat{\boldsymbol{\beta}} \text{ is unbiased}).$
- ii $\mathbb{E}[\hat{\mathbf{Y}}] = \mathbb{E}[\mathbf{Y}] = X\boldsymbol{\beta}$ and $\mathbb{E}[\mathbf{r}] = \mathbf{0}$.
- iii $Cov(\hat{\boldsymbol{\beta}}) = \sigma^2(X^\top X)^{-1}$.
- iv $Cov(\hat{\mathbf{Y}}) = \sigma^2 P$, $Cov(\mathbf{r}) = \sigma^2 (I P)$, $P = X(X^\top X)^{-1} X^\top$.
- If additionally $\epsilon_i, \ldots, \epsilon_n$ i.i.d. $\sim \mathcal{N}(0, \sigma^2)$, then
- $i \hat{\boldsymbol{\beta}} \sim \mathcal{N}_p(\boldsymbol{\beta}, \sigma^2(X^\top X)^{-1})$
- ii $\hat{\mathbf{Y}} \sim \mathcal{N}_n(X\boldsymbol{\beta}, \sigma^2), \ \mathbf{r} \sim \mathbb{N}_n(\mathbf{0}, \sigma^2(I-P))$

iii $\hat{\sigma}^2 \sim \frac{\sigma^2}{n-p} \chi^2_{n-p}$. Even when normality assumption doesn't hold, central limit theorem is a justification

3. Tests and Confidence Regions

Assume linear model with Gaussian errors (or "large enough" sample size), s.t. $\hat{\boldsymbol{\beta}} \sim \mathcal{N}_p \left(\boldsymbol{\beta}, \sigma^2 (\boldsymbol{X}^\top \boldsymbol{X})^{-1} \right)$ is normally distributed. Then we can test the null-hypothesis $H_{0,j}: \beta_j = 0$

$$\frac{\hat{\beta}_j}{\sqrt{\sigma^2(X^\top X)_{jj}^{-1}}} \sim \mathcal{N}(0,1) \Rightarrow T_j = \frac{\hat{\beta}_j}{\sqrt{\hat{\sigma}^2(X^\top X)_{jj}^{-1}}} \sim t_{n-p}$$

under the null-hypothesis $H_{0,j}$. Unknown σ^2 is replaced by $\hat{\sigma}^2$. Note that $t_{n-p} \approx \mathcal{N}$. An individual t-test for $H_{0,j}$ gives the effect of β_j after subtracting the linear effect of all $\beta_{i \neq j}$. Note that in summary.lm, the term Std. Error is $\sqrt{\hat{\sigma}^2(X^\top X)_{i,i}^{-1}} = \sqrt{\hat{Var}(\hat{\beta}_i)}$. Finally, we can also build a

confidence interval using $\hat{\beta}_j \pm \sqrt{\hat{\sigma}^2(X^\top X)_{ij}^{-1}} \cdot t_{n-p;1-\alpha/2}$

confint(fit,level=0.95)

Global null hypothesis and ANOVA

We can also check the global null-hypothesis $H_0: \beta_2 = \cdots =$ $\beta_n = 0$ using an analysis of variance<, which decomposes

$$||\mathbf{Y} - \bar{\mathbf{Y}}||_2^2 = ||\hat{\mathbf{Y}} - \bar{\mathbf{Y}}||_2^2 + ||\mathbf{Y} - \hat{\mathbf{Y}}||_2^2.$$

Under the global null-hypothesis $\mathbb{E}[\mathbf{Y}] = \mathbb{E}[\mathbf{\tilde{Y}}] = const.$ (no effect of predictor variables). $\sigma^2/\hat{\sigma}^2$ yields F-statistic: $F = \frac{||\hat{\mathbf{Y}} - \bar{\mathbf{Y}}||^2/(p-1)}{||\mathbf{Y} - \hat{\mathbf{Y}}||^2/(n-p)} \sim F_{p-1,n-p}$

$$F = \frac{||\mathbf{Y} - \mathbf{Y}||^2/(p-1)}{||\mathbf{Y} - \hat{\mathbf{Y}}||^2/(n-p)} \sim F_{p-1, n-p}$$

under the global null-hypothesis H_0 . ANOVA also yields goodness of fit $R^2 = \frac{||\hat{\mathbf{Y}} - \bar{\mathbf{Y}}||^2}{||\mathbf{Y} - \bar{\mathbf{Y}}||^2}$, which should be close to 1.

anova(fit) # global F test # partial F test - sig. of predictors in .full but not .part anova(fit.part, fit.full)

ANalysis Of VAriance (ANOVA) Table

	sum sq.	df	i msq: sum sq./df
Reg.	$\ \hat{Y} - \bar{Y}\ ^2$		ii RSE: \sqrt{MSE}
Error	$ Y - \hat{Y} ^2$	n-p	iii Adjusted R^2 : $R^2 \cdot (n-1)/df$
Total	$ Y - \bar{Y} ^2$	n-1	_

4. Checking Model Assumptions

Tukey-Anscombe Plot

Error should fluctuate randomly. Error increases linearly: logtransform $\mathbf{Y} \mapsto \log \mathbf{Y}$. Error increases with \sqrt{Y} : squareroot-transform $Y \mapsto \sqrt{Y}$. Error has parabolic shape: add quadratic term. Error is groups: they have different Variance. plot(fit, which=1) # Tukey-Anscombe plot

QQ-Plot/Normal-Plot

Plot empirical quantiles of residuals on y versus the theoretical quantiles of $\mathcal{N}(0,1)$ on x. If assumption holds, get straight line with intercept μ and slope σ . Z-shape: long-tailed distr. Curved: skewed distr.

plot(fit, which=2) # QQ-plot (qqnorm, qqline)

- i Scale Location (which=3): should look random ii Cook dist (which=4): impact of sample on fit
- 5. Model Selection

Assume again $\mathbb{E}[\epsilon_i] = 0$, $Var(\epsilon_i = \sigma^2)$. Address bias-variance trade-off. Bias $:= \mathbb{E}[\hat{f}(x)] - f(x)$, variance $:= q/n \cdot \sigma^2 \ (q \le p)$.

Mallows C_n statistic

Let SSE(d) be the residual sum of squares. Then $n^{-1}\sum_{i=1}^{n} \mathbb{E}\left[(f(x) - \hat{f}(x))^2 \right] \approx n^{-1}SSE(d) - \hat{\sigma}^2 + 2\hat{\sigma}^2 d/n$ Thus, we search for the model that minimizes $C_p(\mathcal{M})$ = $\frac{SSE(d)}{2} - n + 2d$. Alternatively, use AIC = $2d - 2\log \hat{L}$, where \hat{L} = maximal value of likelihood, or BIC. AIC is equivalent to C_p for linear Gaussian models.

All subsets regression require(leaps) fit.all = regsubsets(y~., data=data) p.regsubsets(fit.all)

Forwards and backwards selection

Forward selection: (i) Start with empty model. (ii) (Greedily) Keep adding variable that reduces the residual sum of squares the most. (iii) When done, pick submodel which min-

Backward selection: (i) Start with full model. (ii) (Greed ily) Keep excluding predictor that increases the residual sum of squares the least. (iii) When done, pick submodel which minimizes C_p . Backwards selection typically better but more expensive. When $p \ge n$, use forward selection. Both methods prone to overfitting - p-values (and similar values) are not valid anymore and effects look too significant.

Backward / forward selection fit.empty = lm(y~1, data=data)fit.full = lm(y~., data=data) fit.bw = step(fit.full, direction="backward") fit.fw = step(fit.empty, direction="forward", → scope=list(upper=fit.full,lower=fit.empty)

predict.lm(fit, newdata, interval=..) poly(formula, degree=d) # polynomial fits of the data in the → predictive variables up to degree d

Density Estimation

Kernel estimator

Estimate density $\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n w((x-X_i)/h)$. Kernels include (i) rectangular $(wx) = 0.5 \cdot 1_{|x| < 1}$, (ii) triangular, or (iii) Gaussian. We require $\int_{\mathbb{R}} K(x)dx = 1$. The bandwidth parameter h is crucial and determines the "smoothness" of the density estimate

Choosing a bandwidth h

A simple approach is using k-nearest neighbors, i.e. h(x) = $\max_{x_i \in KNN_L(x)} ||x - x_i||_2$ with tuning parameter k. Note that $\int_{\mathbb{D}} K(x)dx = 1$ might be violated. Naturally, the bandwidth also induces a bias-variance trade-off. Note that $MSE(x) = \mathbb{E}\left[\left(\hat{f}(x) - f(x)\right)^2\right] = \left(\mathbb{E}\left[\hat{f}(x)\right] - f(x)\right)^2 +$

 $Var(\hat{f}(x))$, so we can try to minimize the integrated MSEover all points to find the best bandwidth.

Density estimation in higher dimensions

Basically use $\hat{f}(\mathbf{x}) = \frac{1}{nh^d} \sum_{i=1}^n K((\mathbf{x} - \mathbf{X}_i)/h)$ with a Kernel that supports vectors. The Gaussian kernel is the only one that is radially symmetric. Note that in higher dimensions, density estimation becomes very hard, due to data points becoming very sparse.

Nonparametric Regression

Nonparametric regression with one predictor variable, i.e. Y_i $m(x_i) + \epsilon_i$ with $\epsilon_{1:n}$ i.i.d and $\mathbb{E}[\epsilon_i] = 0$. We want m(x) = $\mathbb{E}[Y|x]$ and "some" smoothness.

Kernel regression estimator

A "locally weighted" approach yields the NW kernel estimator $\hat{m}(x) = \frac{\sum_{i=1}^{n} \omega_i Y_i}{\sum_i \omega_i} = \underset{m_x \in \mathbb{R}}{\arg\min} \sum_{i=1}^{n} \omega_i (Y_i - m_x)^2 \qquad (3.1)$

with $\omega_i = K\left(\frac{x_i - x}{h}\right)$ a kernel centered at x_i and bandwidth h. As h small \rightarrow large then (high variance) \rightarrow (high bias) For x_i equidistant there exists $h_{opt} = f(\sigma_{\epsilon}^2, m''(x))$ which can be iteratively found.

ksmooth(x, y, kernel="normal", bandwidth=0.2, x.points=x)\$y fit.lo<-lokerns(X, Y, x.out=X, hetero=TRUE, is.rand=TRUE) fit.gl<-glkerns(X, Y, x.out=X, hetero=TRUE, is.rand=TRUE)</pre>

i Bias $(mean(\hat{y} - y_{true}))$: high \rightarrow under fitting ii Variance (measure of fluctuation): high → over fitting

Local polynomial regression estimator

Instead of finding a local constant m_x we can also find a local polynomial, i.e. we replace m_x with $\beta_1 + \sum_{i=2}^p \beta_i (x_i - x)^{i-1}$ (usually p = 2 or p = 4). Often better at edges and yields first derivative.

fit.loess <- loess(y ~ x, data=data.frame(x=x, y=y_pert), ⇒ span=0.2971339, surface='direct') fit.loess.pred <- predict(fit.loess, newdata=x)

The hat matrix S

We want to construct S with $\hat{Y} = SY$, i.e. the linear operator mapping the labels to the predictions. Given the regression (smoothing) function s, we compute $S_{ij} = s(\mathbf{x}, \mathbf{e}_j, h)$ with \mathbf{e}_{j} the j-th unit vector. Then $Cov(\hat{m}(\mathbf{x})) = Cov(S\mathbf{Y}) =$ $SCov(\mathbf{Y})S^{\top} = \sigma_{\epsilon}^{2}SS^{\top}$. Set $df = \mathbf{tr}S$ and estimate $\hat{\sigma}_{\epsilon}^{2} =$ $\sum_{i=1}^{n} (Y_i - \hat{m}(x_i))^2 / (n - df)$. Then

• $\widehat{s.e.}(\widehat{m}(x_i)) = \sqrt{\widehat{Var}(\widehat{m}(x_i))} = \widehat{\sigma}_{\epsilon} \sqrt{(SS^{\top})_{ii}}$

Construct S matrix (or hatMatrix() from sfsmics)

N <- length(x): Eve <- diag(N)

• $\hat{m}(x_i) \approx \mathcal{N}\left(\mathbb{E}[\hat{m}(x_i)], Var(\hat{m}(x_i))\right)$ • $I = \hat{m}(x_i) \pm 1.96 \cdot \widehat{s.e.}(\hat{m}(x_i)) \rightarrow \text{(pointwise) CI}$

S.nw <- matrix(0, nrow=N, ncol=N) for (j in 1:N) { y_ <- Eye[, j] S.nw[, j] <- ksmooth(x, y_, kernel="normal",</pre> bandwidth=0.2, x.points=x)\$y # Compute standard error est.nw <- ksmooth(x=x, y=y, kernel="normal", bandwidth=0.2, x.points=x)\$y sig_sq.nw <- sum((y - est.nw)^2) / (N - sum(diag(S.nw))) se.nw <- sqrt(sig_sq.nw * diag(S.nw \%*\% t(S.nw)))

Smoothing splines and penalized regression

High-order polynomials do not work, so splines are used. We discuss splines without having to specify the knots. Find $\arg\min_{m\in C^0(\mathbb{R})}\sum_{i=1}^n (Y_i-m(x_i))^2 + \lambda \int_{\mathbb{R}} m''(z)^2 dz$. Note that the minimizer is finite dimensional — it is a cubic spline that can be computed using a set of basis functions $m_{\lambda}(x) = \sum_{j=1}^{n} \beta_{j} B_{j}(x) \text{ or } ||\mathbf{Y} - B\boldsymbol{\beta}||^{2} + \lambda \boldsymbol{\beta}^{\top} \Omega \boldsymbol{\beta} \Rightarrow \hat{\boldsymbol{\beta}} =$ $(B^{\top}B + \lambda\Omega)^{-1}B^{\top}\mathbf{Y}$. Choose λ on the scale of $df = \mathbf{tr}(\mathcal{S}_{\lambda})$ Note that this is Ridge-type regression, which saves us from being overparametrized (n points, n parameters). In the exam, this is not considered "standard" least squares.

```
fit.ss = smooth.spline(x, y, df=df)
ss.preds = predict(fit.ss, newdata=x)$y
```

Cross Validation

Let $(X_1, Y_1), \ldots, (X_n, Y_n)$ i.i.d $\sim P$. We would like to compute $\mathbb{E}_{(X_{\text{new}}, Y_{\text{new}})}[\rho(\mathbf{Y}_{\text{new}}, \hat{m}_{\text{train}}(X_{\text{new}}))].$

Constructing cross-validation datasets

Approaches include Validation set: -

Leave-one-out CV: $n^{-1} \sum_{i=1}^{n} \rho\left(Y_i, \hat{m}_{n-1}^{(-i)}(X_i)\right)$ ca. unbiased.

k-fold CV: $K^{-1}\sum_{i=1}^{K}|\mathcal{B}_k|^{-1}\sum_{i\in\mathcal{B}_k}\rho\left(Y_i,\hat{m}_{n-|\mathcal{B}_k|}^{(-\mathcal{B}_k)}(X_i)\right)$

Random division: Like k-fold, but build \mathcal{B}_k by sampling without replacement (≈ 10%). Usually fastest.

Tricks using hat matrix

For linear fitting operators and the loss $\rho(y,x) = (y-x)^2$ we can exploit the hat matrix and get the full LOOCV result in

$$n^{-1} \sum_{i=1}^n \left(Y_i - \hat{m}_{n-1}^{(-i)}(X_i) \right)^2 = n^{-1} \sum_{i=1}^n \left(\frac{Y_i - \hat{m}(X_i)}{1 - S_{ii}} \right)^2.$$

It can be cheaper to just compute $\mathbf{tr}(\mathcal{S})$ (instead of all \mathcal{S}_{ii}) which leads to the *generalized cross-validation*

$$GCV = \frac{n^{-1} \sum_{i=1}^{n} (Y_i - \hat{m}(X_i))^2}{(1 - n^{-1} \mathbf{tr}(S))^2}$$

The two equations coincide if $S_{ii} = c$

Bootstrap

Efron's parametric and nonparametric bootstrap can be described as "simulating from an estimated model" and can be used for statistical inference (confidence intervals and testing) and estimating the predictive power of a model or algorithm.

Nonparametric Bootstrap

Let $Z_{1:n}$ i.i.d $\sim P$ with $Z_i = (X_i, Y_i), X_i \in \mathbb{R}^p, Y_i \in \mathbb{R}$, and let $\hat{\theta}_n = g(Z_{1:n})$ be an estimator. We would like to know the distribution of $\hat{\theta}_n$. We approximate **P** by the empirical distribution \hat{P}_n . Then we can repeatedly sample $Z_{1:n}^* \sim \hat{P}_n$ independently and compute $\hat{\theta}_n^* = g(Z_{1:n}^*)$. The histogram (or any density estimator) then describes the distribution of $\hat{\theta}_{-}^{*}$. The algorithm reads

- a) Sample (with replacement) $Z_{1:n}^*$ i.i.d $\sim \hat{P}_n$.
- b) Compute the bootstrapped estimator $\hat{\theta}_n^* = g(Z_{1:n}^*)$.
- c) Repeat B times to obtain $\hat{\theta}_{n}^{*1:B}$.
- d) Approximate $\mathbb{E}^*[\hat{\theta}_n^*] \approx B^{-1} \sum_{i=1}^B \hat{\theta}_n^{*i}$ and $Var^*(\hat{\theta}_n^*) \approx$ $(B-1)^{-1} \sum_{i=1}^{B} \left(\hat{\theta}_{n}^{*i} - B^{-1} \sum_{j=1}^{B} \hat{\theta}_{n}^{*j} \right)^{2}$. Then α -quantile of $\hat{\theta}_n^* \approx \text{empirical } \alpha\text{-quantile of } \hat{\theta}_n^{*1:B}$.

Central limit theorem

Let X_i be a random variable with $\mathbb{E}[X_i] = \mu$ and $Var(X_i) =$ σ^2 . Then $n^{-1} \sum_{i=1}^n X_i \overset{n \to \infty}{\to} \mathcal{N}(\mu, \sigma^2/n)$.

Bootstrap consistence

Consistency of the bootstrap typically holds if the limiting Given $(X_1,Y_1),\ldots,(X_n,Y_n)$ i.i.d. with $Y_i\in\{0,\ldots,J-1\}$ matically, for an increasing sequence a_n and $\forall x$, $\mathbb{P}[a_n(\hat{\theta}_n Op^*(\hat{\theta}_n^*)/Op(\hat{\theta}_n) \stackrel{P}{\to} 1 \text{ with } Op \in \{Var, \mathbb{E}\}.$

Bootstrap confidence intervals

Given bootstrap consistence, we can compute confidence in-

i quantile / quantile: $[q_{\hat{\square}*}(\alpha/2), q_{\hat{\square}*}(1-\alpha/2)]$

ii rev. quantile:
$$[\hat{\Theta} - q_{\hat{\Theta} - \hat{\Theta}} (1 - \alpha/2), \hat{\Theta} - q_{\hat{\Theta} - \hat{\Theta}} (\alpha/2)]$$

iii normal:
$$2\hat{\Theta} - \overline{\hat{\Theta}^*} \pm q_X (1 - \alpha/2) \cdot \hat{sd}(\hat{\Theta})$$

($X \sim \mathcal{N}(0, 1)$; corrects for bias $\hat{\Theta} - \hat{\Theta}^*$)

Note $\hat{q}_{\alpha} = q_{\alpha}^* - \hat{\theta}_n$ with $q_{\alpha}^* = \alpha$ -bootstrap quantile of $\hat{\theta}_n^*$ Thus $[\hat{\theta}_n - \hat{q}_{1-\alpha/2}, \hat{\theta}_n - \hat{q}_{\alpha/2}] = [2\hat{\theta}_n - q_{1-\alpha/2}^*, 2\hat{\theta}_n - q_{\alpha/2}^*]$

require("boot") tm = function(x, ind) {mean(x[ind], trim = 0.1)} res.boot = boot(data=sample, statistic=tm, R=1000) boot.ci(res.boot, conf=0.95, type=c("basic","norm","perc")) # "basic"=reverse quantile, "norm"=normal, "perc"=quantile

```
require(MASS); mle = fitdistr(boogg, "gamma")$estimate
boot.est = matrix(NA, nrow=R, ncol=1)
for (i in 1:R) {
 boogg.s = rgamma(N, shape=mle[1], rate=mle[2])
 # boogg.s = sample(boogg, N, replace=T) # NP
 boot.est[i] = quantile(boogg.s, probs=0.75)
rac{1}{3}; a = 0.05
# Quantile / Percentile
quantile(boot.est, probs=c(a/2, 1-a/2))
# Normal.
mean.est = mean(boot.est)
sd.hat = sqrt(1/(R-1)*sum((boot.est - mean.est)^2))
2*est-mean.est + c(-1,1)*qnorm(1-a/2)*sd.hat
# Reverse quantile / Basic quantile
est - quantile(boot.est-est, probs=c(1-a/2, a/2))
```

Double bootstrap

Idea: Find α' s.t. actual coverage of bootstrap CI $I^*(1-\alpha')$ is equal to α .

- i Draw BS sample Z^* . Sample from Z^* to obtain Z^{**} Compute CI $I^{**}(1-\alpha)$ for $\hat{\Theta}^*$ based on B draws Z^{**} Compute coverage of $\hat{\Theta}$ by I^{**} (1 or 0).
- mean to obtain actual coverage of I^{**} .
- coverage $(I^{**}(1-\alpha')) = 1 \alpha$. Use CI $I^*(1-\alpha')$.

Parametric Bootstrap

Assume $Z=(Z_1,\ldots,Z_n)$ $i.i.d.\sim P_\Theta$. Fit $\hat{\Theta}=$ MLE and generate samples Z^* $i.i.d.\sim P_{\hat{\Theta}}$. Usually better than nonparametric version when $P_{\hat{\Theta}}$ is a good fit (e.g. known model structure P) and few data points available.

```
require(MASS); fit.gamma = fitdistr(boogg, "gamma")
fun.theta = function(x) {quantile(x, probs=0.75)}
fun.gen = function(x, mle) {rgamma(length(x), shape=mle[1],
\rightarrow rate=mle[2])}
res.boot = boot(data, fun.theta, R=1000, sim="parametric",
→ ran.gen=fun.gen, mle=fit.gamma$estimate);
```

Bootstrap error estimate

Generalization error (loss $\rho(y, m(x))$) of model m (fitted to full data set) can be estimated by fitting models $m^{*,i}$ to bootstrap samples and computing errors on full data set $e^{*,i} = n^{-1} \sum_{i=1}^{n} \rho(y, m^{*,i}(x_i))$

- OOB errors $e_{ob}^{*,i} = n_{ob,i}^{-1} \sum_{i=1}^{n_{ob,i}} \rho(y_{ob,i}, m^{*,i}(x_{ob,i}))$
- The error of m is then approximated by $R^{-1} \sum_{i=1}^{R} e^{*,i}$.

Classification

Consistency of the bootstrap typically are i.i.d. Mathedistribution of $\hat{\theta}_n$ is Normal and if $Z_{1:n}$ are i.i.d. Mathedistribution of $\hat{\theta}_n$ is Normal and if $Z_{1:n}$ are i.i.d. Mathedistribution of $\hat{\theta}_n$ is Normal and if $Z_{1:n}$ are i.i.d. Mathedistribution of $\hat{\theta}_n$ is Normal and if $Z_{1:n}$ are i.i.d. Mathedistribution of $\hat{\theta}_n$ is Normal and if $Z_{1:n}$ are i.i.d. $Z_{1:n}$ are i.i matically, for an increasing sequence a_n and $\forall x$, $\mathbb{P}[a_n(\theta_n - \text{The optimal classifier is } C_{\text{Bayes}}(x) = \text{arg max}_{0 \neq j \neq l-1} T_{ij}(x)]$. θ) $\leq x$] $-\mathbb{P}^*[a_n(\hat{\theta}_n^* - \hat{\theta}_n)] \leq x$] $\to 0$ as $n \to \infty$. Then Then Bayes risk for the 0-1-loss is $\mathbb{P}[C_{\text{Bayes}}(X_{\text{new}}) \neq Y_{\text{new}}]$. Discriminant analysis

> **LDA:** Assume $X \mid Y = j \sim \mathcal{N}(\mu_j, \Sigma), \mathbb{P}[Y = j] = p_j$. Then by Bayes formula

$$\pi_{j}(x) = \frac{f_{X|Y=j}(x) \cdot p_{j}}{\sum_{k=0}^{J-1} f_{X|Y=k}(x) \cdot p_{k}}$$

with each $f_{X|Y=j}$ a Gaussian $\mathcal{N}(\mu_j, \Sigma)$. We can estimate μ_j and Σ by the (closed-form) MLEs, and we also need a prior for Y, which often is fixed as $\hat{p}_i = n_i/n$. This results in $\hat{\delta}_i(x) = (x - \hat{\mu}_i/2)^\top \Sigma^{-1} \hat{\mu}_i + \log(\hat{p}_i)$ with linear (in x) decision boundaries $\hat{\delta}_{i}(x) = \hat{\delta}_{i'}(x)$ and $C(x) = \arg \max_{i} \hat{\delta}_{i}(x)$. **QDA:** Now we assume different Σ_i for each class and obtain quadratic decision boundaries $\hat{\delta}_i(x) = -\log(\det(\hat{\Sigma}_i))/2 - (x - \det(\hat{\Sigma}_i))/2$ $(\hat{\mu}_i)^{\top} \hat{\Sigma}_i^{-1} (x - \hat{\mu}_i)/2 + \log(\hat{p}_i)$. The price: $J \cdot p(p+1)/2$ parameters (for all Σ_i) vs. p(p+1)/2 (symmetry of Σ) for a single Σ (μ ($J \cdot p$) and priors (J - 1) are the same), require(MASS)

class_lda = lda(x=df[, c("x1", "x2")], grouping=df[, "y"])

Logistic regression for binary classification

Given some model $g: \mathbb{R}^p \to \mathbb{R}$ (e.g. a linear model) we can use the logistic transform $\pi \mapsto \log(\pi/(1-\pi))$ to get probabilities: $\log(\pi(x)/(1-\pi(x))) = g(x)$ and $\pi(x) = 1/(1+\exp(-g(x)))$. This implies $Y_i \sim \text{Bernoulli}(\pi(x_i))$ (e.g. weighted coin flip). The likelihood is thus $\prod_{i=1}^{n} \pi(x_i)^{Y_i} (1 - \pi(x_i))^{1-Y_i}$. We typically estimate β using gradient descent. As $n \to \infty$ we can asymptotically compute the standard errors $\widehat{s.e.}(\hat{\beta}_i)$ and ttest statistics $\hat{\beta}_i/\widehat{s.e.}(\hat{\beta}_i) \sim \mathcal{N}(0,1)$ (under $H_{0,i}: \beta_i = 0$).

fit = glm(Y~., data=data, family="binomial") mean((predict(fit, type="response") > 0.5) == data\$Y)

Linear predictors

Note that both LDA and Logistic regression are linear in the prediction variables. For LDA that comes from the Gaussian assumption (i.e. "linearization" of the true distribution), for Logistic regression it comes from the linear log-odds function.

Multiclass case (J > 2)

- Compute coverage of Θ by I^{rw} (1 or 0). in Repeat i) M times to obtain M coverage values. Compute mean to obtain actual coverage of I^{**} and I^{**} and I^{**} and I^{**} are the coverage of I^{**} .
- iii Vary lpha' and repeat previous steps to find lpha' with b) Using multinomial distribution (parametric linear logistic)
 - c) "Reference class" $\log(\pi_i(x)/\pi_0(x)) = g_i(x)$
 - d) Pairwise 1-vs-1, fitting $\binom{J}{2} \cdot p$ parameters
 - e) Exploiting "ordered" classes with proportional odds

Manually Calculating Predicted Class

- i Predict class for x: $\arg\min_{k\in[1,J]}\sum_{j=1}^J L(j,k)\cdot\pi_j(x)$ ii E.g loss for predicting class $c:\sum_{j=1}^J L(j,c)\cdot\pi_j(x)$

Flexible regression and classification methods

We fight the curse of dimensionality by making some structural assumptions (although staying with methods $g(\cdot): \mathbb{R}^p \to \mathbb{R}$ of nonparametric nature).

1. Additive models

Decompose multivariate function as $g_{add}: \mathbb{R}^p \to \mathbb{R}, x \mapsto$ $\mu + \sum_{j=1}^p g_j(x_j)$ with $g_j(\cdot) : \mathbb{R} \to \mathbb{R}, \mathbb{E}[g_j(X_j)] = 0$. The zero-mean requirement for each $g_i(\cdot)$ makes the problem well posed. This approach is a generalization of linear models, and similarly can not model interaction terms $g_{j,k}(x_j,x_k)$. Due to the way they are constructed, additive linear models avoid the curse of dimensionality.

To fit a model, let S_i be a smoothing technique (e.g. Nadaraya-Watson kernel estimators). Then, the backfitting algorithm works as follows:

- Compute $\hat{\mu}=n^{-1}\sum_{i=1}^nY_i$ and initialize $\hat{g}_j(\cdot):=0$. Cycle through the indices $j=1,2,\ldots,p,1,2,\ldots$ and update $\hat{g}_j = S_j(\mathbf{Y} - \hat{\mu}\mathbf{1} - \sum_{k \neq j} \hat{g}_k)$. Stop each function at
- Normalize the functions: $\tilde{g}_j(\cdot) = \hat{g}_j(\cdot) n^{-1} \sum_{i=1}^n \hat{g}_j(X_{ij})$ This basically makes the algorithm repeatedly solve the 1dimensional fitting problem. The algorithm may be slow but often works and can use any 1-dimensional fitting technique.

When fitting Additive models in R with the function gam, the smoothers S_i are penalized regression splines, and the degrees of freedom for each spline (i.e. each variable) will be determined through cross-validation.

```
fit <-gam(Y~s(x1)+s(x2)+..., data=data) # wrapFormula()
plot(fit, pages=1, shade=TRUE) # show effect predictor
sfsmisc::TA.plot(fit, labels="o")
```

2. Multivariate adaptive regression splines

 $g(\mathbf{x}) = \mu + \sum_{m=1}^{M} \beta_m h_m(\mathbf{x}) = \sum_{m=0}^{M} \beta_m h_m(\mathbf{x})$ Find $h \in \mathcal{M}$ functions by foward selection and pruning:

- i Initialize $\mathcal{M} = \{h_0 = 1\}, \beta_0 = \overline{Y}$
- ii For r = 1, 2, ... Find best pair (most reduction of RSS) $h_{2r-1} = h_l(\cdot)(x_j - x_{i,j})_+, h_{2r} = h_l(\cdot)(x_{i,j} - x_j)_+,$ where $h_l \in \mathcal{M}$ does not already depend on x_i . Estimate β_{2r-1}, β_{2r} by LS. Add h_{2r-1}, h_{2r} to \mathcal{M} .
- iii Repeat until \mathcal{M} large enough. Prune by repeatedly removing one function from pairs h_{2r-1}, h_{2r} (least increase in RSS). Stop when GCV score is optimized.

require("earth"): fit <- earth(formula=y~.,data=data, degree=2)</pre> plotmo(fit, degree2=FALSE, caption="main effects")

3. Neural Networks

 $g(\mathbf{x})_k = f_0(\alpha_k + \sum_{h=1}^q w_{hk}\sigma(\tilde{\alpha_h} + \sum_{j=1}^p \tilde{w}_{jh}x_j))\forall k = 1..J,$ q hidden nodes, J output dim. Activation $\sigma(t) = \frac{\exp t}{1 + \exp t}$ For regression, f_0 identity, for classification $f_0 = \sigma$ and $C_{NN} = \arg \max_{i} g_{i}(\mathbf{x})$. Many other architectures possible, e.g. including a component directly connecting input to output by linear regression.

library(nnet); ?nnet ?ppr

Classification and Regression Trees

Let $g_{tree}(\mathbf{x}) = \sum_{r=1}^{M} \beta_r 1_{[\mathbf{x} \in \mathcal{R}_r]}$, where $\{\mathcal{R}_1, \dots, \mathcal{R}_M\}$ is a partition of \mathbb{R}^p . The function is piecewise constant. When a partition is given, we can estimate $\hat{\beta}_r$ $\sum_{i=1}^n Y_i 1_{[\mathbf{x} \in \mathcal{R}_T]} / \sum_{i=1}^n 1_{[\mathbf{x} \in \mathcal{R}_T]}$. For multiclass classification $\hat{\pi}_{j}(\mathbf{x}) = \sum_{i=1}^{n} 1_{[Y_{i}=j]} 1_{[\mathbf{x} \in \mathcal{R}_{r}]} / \sum_{i=1}^{n} 1_{[\mathbf{x} \in \mathcal{R}_{r}]} \text{ for } \mathbf{x} \in \mathcal{R}_{r}.$ Greddy algorithm to find axes parallel partition:

- i Initialize M = 1 subset $\mathcal{P} = \{\mathcal{R} = \mathbb{R}^p\}$
- ii Split R at d in dimension j, where d is from the set of midpoints of observed values. Select j, d s.t. neg. loglikelihood decrease is maximized by refinement.
- ii Apply ii) to one cell of the current partition (select like above). Add the resulting two cells and remove the refined
- iv Iterate iii) until until specified max. partition size is achieved.
- v Prune tree by removing leaves resulting in smalles increase in some (CV) metric.

The size of a tree T is the number of leaves (=1 + cuts) For some goodness-of-fit measure $\mathcal{R}(\mathcal{T})$ (e.g. SSE, NLL), the cost-complexity measure is $\mathcal{R}_{\alpha}(\mathcal{T}) = \mathcal{R}(\mathcal{T}) + \alpha \cdot \text{size}(\mathcal{T})$. For some α , we thus choose $\mathcal{T}(\alpha) = \arg\min_{\mathcal{T} \subset \mathcal{T}_M} \mathcal{R}_{\alpha}(\mathcal{T})$. The parameter α is chosen by CV. The 1 s.e. rule says: Choose smallest tree such that its performance is at most one standard error larger than the minimal one.

```
num leafs<-length(unique(tree$where))
depth <- trunc(log2(max(as,integer(row,names(tree$frame)))))
```

```
library(rpart); require(rpart.plot);
 tree = rpart(y~., data=data, control=rpart.control(cp=0.0,
 → minsplit=1)) # unregularized tree
 plotcp(tree); cps = tree$cptable # cp = \alpha/\mathcal{R}_{\Omega}(\mathcal{T}_{\alpha})
 idx.min = which.min(cps[, "xerror"])
 std.min = cps[idx.min, "xstd"]
 → cps[abs(cps[,"xerror"]-cps[idx.min,"xerror"])<std.min,]</p>
 pruned.tree = prune.rpart(tree, cp=cp.1se[1, "CP"])
rf <- randomForest(Boston.train, y.train, xtest=Boston.test,
 → ytest=y.test, ntree=ntree, mtry=ncol(Boston.train))
 rf$mse[ntree] # OOB error; rftestmse[ntree]
 tail(rf$err.rate) # cumulative error rate
5. Ridge and Lasso
Trade-off between ||\beta||_1 and ||\beta||_2 regularization, i.e. L(\lambda_1,\lambda_2,\beta)=||\mathbf{Y}-X\beta||_2^2+(1-\alpha)/2||\beta||_2^2+\alpha||\beta||_1. \alpha=
1 \Leftrightarrow \lambda_2 = 1 means full L_2-regularization, i.e. Ridge, otherwise
LASSO. Limited parameter size → reduced variance
ridge <- glmnet(x.train, y.train, lambda=100, alpha=1)
ridge$beta
 ridge.cv <- cv.glmnet(x.train, v.train, lambda=grid.lambda,
  → alpha=0, type.measure="mse")
 mean((predict(ridge.cv, newx=x.test, s="lambda.min") -
 → v.test)^2)
 lasso.cv <- cv.glmnet(x.train, y.train, lambda=grid.lambda
 → alpha=1, type.measure="mse")
 mean((predict(lasso.cv, newx=x.test, s="lambda.min") -
 → y.test)^2)
```

Bagging and Boosting

Bagging and Subbagging

Bootstrap aggregating (bagging) (mostly on trees), uses $\hat{g}(\cdot): \mathbb{R}^p \to \mathbb{R}$ and ensembles them (which comes at the loss of interpretability).

length(which(beta[2:..]!=0) # num non-zero predictors

- i Generate bootstrap sample $(X_1^{\bigstar},Y_1^{\bigstar}),\dots,(X_n^{\bigstar},Y_n^{\bigstar})$ and compute $\hat{g}_{i=1}^{*}(\cdot)$. Repeat B times.
- ii Aggregate bootstrap estimates with $\hat{g}_{\mathrm{B}ag}(\cdot)$ $B^{-1} \sum_{i=1}^{B} \hat{g}_{i}^{*}(\cdot) \approx \mathbb{E}^{*}[\hat{g}^{*}(\cdot)].$

Note that $\hat{g}_{Bag}(\cdot) = \hat{g}(\cdot) + (\mathbb{E}^*[\hat{g}^*(\cdot)] - \hat{g}(\cdot))$. We can

bootstrap bias estimate

reduce variance at price of higher bias (at least for trees) In fact, for many x, $Var(\hat{g}_{Bag}(x)) < Var(\hat{g}(x))$. We can use larger trees (higher variance) to balance the bias-variance

For Subsample aggregating (Subbagging), we draw $(X_1^*, Y_1^*), \dots, (X_m^*, Y_m^*)$ without replacement (e.g. with $m = \lfloor n/2 \rfloor$, which can be cheaper overall and is equivalent to Bagging in some simple settings.

L₂-Boosting

Similar to Bagging, iterates on a "base-learner" by continually adding a fit on the residuals.

- i Get first fit $\hat{g}_1(\cdot)$ by fitting on the full data. Compute residuals $U_i = Y_i - \hat{g}_1(X_i)$ and let $\hat{f}_1(\cdot) = \nu \hat{g}_1(\cdot)$ with $0 < \nu \le 1$ (typically $\nu = 0.1$).
- ii For m = 2, 3, ..., M fit $\hat{g}_m(\cdot)$ on residuals U_i and set $\hat{f}_m(\cdot) = \hat{f}_{m-1}(\cdot) + \nu \hat{g}_m(\cdot)$ (and update residuals using

The main tuning parameter is the stopping point M. Boosting increases the bias and can be used to ensemble trees to fit more complex data. See e.g.

```
?mboost; ?xgboost; ?gbm;
```

```
i RStudio: Tools → Global Options → Code → Display
ii ROC: FPR (x) vs TPR (y)
```

iii P[> |t|]: large (> 0.05) $\rightarrow \beta_i \approx 0 \rightarrow \beta_i$ not relevent; small $\rightarrow \beta_i! = 0 \rightarrow \beta_i$ relevant & reject $H_{i,0}$ (R: pt(...))

```
print(.., digits=..); table(df$Class, y.pred); residuals(..)
factor(Class) # for classification; optim(..); termplot(...
```