

Snake-AI

Project Documentation

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Contents

1	How we started	4
2	Introduction	5
2.1	General Topic	5
2.2	Similar problems in practice (References every time, look for actual ones)	6
3	Team Work	7
3.1	Work Participation	7
3.2	work structure (communication, decisions, bug tracking, repository, engineering, ...)	7
3.3	ideas (brainstorming)	7
4	Problem Description	8
4.1	Formal description: definitions, examples,	8
5	Related Work	8
5.1	Related Algorithms, Applications	8
6	Proposed Approaches	8
6.1	Input/Output Format, Benchmarks (Generation, Examples)	8
6.2	Algorithms in Pseudocode	8
7	Implementation Details	8
7.1	Application Structure	9
7.2	GUI Details	9
7.3	UML Diagram	9
7.4	Used Libraries	9
7.5	Code Snippets	9
8	Evolution of Bots	9
8.1	Bot1	9
8.2	Bot2	13
8.3	Bot3	13
9	Experimental Results and Statistical Tests	13
9.1	Simulations (Play with the Parameters!)	13
9.2	Use Benchmarks	13
9.3	Tables: input data details, results of different algorithms	13
9.4	Charts	13

9.5	Evaluations	13
10	Conclusions and Future Work	13
10.1	How the team work went	13
10.2	What we have learned	13
10.3	Ideas for the future development of your application, new al- gorithms	14

1 How we started

This chapter describes how we started with the project.

As we all know the hardest part of a journey is the start. But once started it is a easy on going. It is like the impact on the first domino stone, which brings the whole project in rolling.

As usual in any task of life we need to understand what the problem is and which requirements are necessary to solve the problem. To do so, we read the description from the organizers carefully. In addition to that we watched a few videos about our topic to get a better understanding.

After gaining knowledge about the problem we felt ready to start working with the Snake-AI framework, provided by the organizers on a GitHub repository. The framework was written in the Java programming language. To get familiar we looked into the UML class diagram. Besides that we followed a YouTube Tutorial which was also provided by the organizers, where we implemented our first working version. A detailed introduction and our results will now be presented.

2 Introduction

Many people know the popular game "Snake" which appeared on a Nokia device back in 1997. This project focuses on reestablishing Snake but in a different way. The most special is that instead moving one single snake manually, we will have two intelligent Snake bots competing against each other. The aim of a bot is to be the last standing snake or have the highest score by eating apples in 3 minutes. *Survival of the fittest* is a great saying. This chapter focuses on the general overview of this project and comparison to similar problems in practice.

2.1 General Topic

Our main objective is to make two efficiently working Snake Bots. To create a working bot, all we have to do is to implement a class that implements the Bot interface. This interface has one method which is the *chooseDirection()* method. We can say that the method simulates the brain of the bot. The return value of this method is the direction in which the snake should move to. For directions we have *up*, *down*, *left* or *right*. For example we could implement a first simple bot that just turns right one time. But this type of bot is really uninteresting. For our project we are aiming to implement a bot that uses algorithms from the fields of Artificial Intelligence. But for now let us look into the game rules.

The rules are described as follows: **Rule 1:** A bot controls only the direction (going either north, south, east, or west) to be taken by its own snake.

Rule 2: Snakes always move simultaneously and forward. Their size increases by one position (i.e. pixel) after taking an apple.

Rule 3: A Snake loses in any of these conditions:

1. If it leaves the board;
2. If it hits its own body;
3. If it hits the other snake's body;
4. If it takes more than one second to make a decision (i.e. which direction to take).

Rule 4: If snakes collide head to head, the longest snake wins the game.

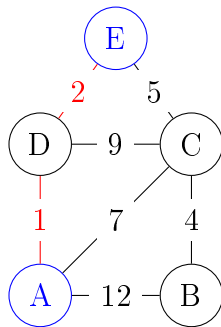
Rule 5: Apples appear randomly at an unoccupied position of the board, and there is only one apple available at any time.

Rule 6: An apple will disappear if it is not eaten by either snake in 10 seconds and reappear somewhere else on the map.

Rule 7: At the end of the tournament, players are ranked according to the number of victories; then the number of draws; then the result of

2.2 Similar problems in practice (References every time, look for actual ones)

Furthermore, since our bot should be smart then it definitely should use intelligent algorithms. What if we could implement a simple bot that just goes into the direction of the apple and gets closer and closer after every decision. But would this be enough to call it a smart bot? Of course not. Well it is a good behaviour that our snake goes for apples. But that's not enough. It should also take the shortest path to the apple. For this we want to use algorithm of dijkstra. Dijkstra algorithm is a graph based algorithm which calculates the shortest path from one node to every other node. Let us get a better understanding of this by looking into an example.



We want to know the shortest path from node A to node B. We as human can easily look into that graph and see that taking the route from A-D with cost of 1 is much lesser than rather taking A-C with cost of 7 or A-B with cost of 12. As next we would also see that we have a cost of 2 from D-E. So in total we see that the shortest path from A to D is A-D-E. But telling this to a computer which only knows 0's and 1's is nonsense. That's why we have algorithms like Dijkstra, which calculates and erases paths with higher costs and returns us the shortest path. Anyway there are many daily life problems where we are using algorithms to compute the shortest path. For example when you are using a navigation tool to drive from one city to another city. We all would have serious problems if the navigation would take any random path to our destination rather than taking the shortest path or

the path with less travel time. Or even when you are crossing over a street where cars are driving. You surely want to take the shortest and safest walkway to the other side.

Well that's not the only use case of Dijkstra in real life applications. When we talk about computer networks we will see a use case of Dijkstra too. Considering IP routing to find the shortest path between source and destination router. Dijkstra algorithm is commonly used in routing protocols for updating the forwarding tables.

Even many dating or social media applications are using Dijkstra to recommend you a person which you may know or be interested in. The users can be seen as nodes. The distance could be defined on different aspects like common friends, same interest or even living in the same city.

A really interesting real life application would be that we could use pathing algorithms in case of emergency calls. If there is a fire anywhere and an emergency call was sent out. The algorithm could calculate based on the location which firefighter department is the closest one. Based on this they could send out firefighters. The same could be used for police department and hospitals.

3 Team Work

to-do

3.1 Work Participation

to-do

3.2 work structure (communication, decisions, bug tracking, repository, engineering, ...)

to-do

3.3 ideas (brainstorming)

to-do

4 Problem Description

to-do

4.1 Formal description: definitions, examples, ...

to-do

5 Related Work

to-do

5.1 Related Algorithms, Applications

to-do

!for example: Fractals, Data Generation, Games, Evolutionary Algorithms (Genetic Algorithms; Collective Intelligence like Particle Swarm Optimization - PSO, Ant Colony Optimizaton - ACO; Evolutionary Multiobjective Optimization, ...)

6 Proposed Approaches

to-do

6.1 Input/Output Format, Benchmarks (Generation, Examples)

to-do

6.2 Algorithms in Pseudocode

to-do

7 Implementation Details

to-do

7.1 Application Structure

to-do

7.2 GUI Details

to-do

7.3 UML Diagram

to-do

7.4 Used Libraries

to-do

7.5 Code Snippets

to-do

8 Evolution of Bots

to-do

8.1 Bot1

Bot 1 (IntBot1.java):

After getting to know the framework of our task, one of our first objectives was implementing a basic bot by ourselves that does the following:

- Calculate all valid moves
- Exhibit a basic avoidance behavior regarding the opponent
- Go for the apple

This basic bot also served as an opponent for more advanced bots later on.

To keep things organized, we decided to create a package for each bot. The

packages were created in the „src“-folder of the given project. Each bot consists of a public class that implements the Interface „Bot“, which as previously described, consists of only one method: „chooseDirection“. Properly overriding this method turned this class into a bot that could be used in the game.

The basic idea for creating this bot was that a static array that contains all possible directions (Direction.RIGHT, Direction.DOWN, Direction.UP, Direction.LEFT) is created outside the method „chooseDirection“ and inside the method each element of this array is checked for its worth concerning the stated objectives.

Creating the static array:

```
public class IntBot1 implements Bot {
    private static final Direction[] DIRECTIONS = new Direction[]{Direction.RIGHT,
        Direction.DOWN, Direction.UP, Direction.LEFT};
    @Override
    public Direction chooseDirection(Snake snake, Snake opponent, Coordinate
        mazeSize, Coordinate apple) {
```

The first thing we did was to create an array of possible directions of the opponent's head and a set that contains the resulting coordinates, so that at the end of the method „chooseDirection“ the coordinates could be removed from the pool of possible directions of our bot's head. To create such an array, it was necessary to determine the coordinate of the second element of the opponent snake. We used an iterator to achieve this in the following way:

```
//Position of second Element of opponent
Coordinate afterHeadNotFinal2 = null;
if(opponent.body.size()>=2){
    Iterator<Coordinate> it = opponent.body.iterator();
    it.next();
    afterHeadNotFinal2 = it.next();
}
final Coordinate afterHead2 = afterHeadNotFinal2;
//second element of opponent snake
```

Note that the class „Snake“ featured a deque of elements of the „Coordinate“-class called „body“.

After that, we used a stream method to get a sequential stream of the elements from the array „DIRECTIONS“ to create a new array of directions

called „validMovesOpponent“. The direction whose result would equal the second element of the opponent snake was filtered out using the “equals”-method on coordinate objects. Finally, a Set of coordinates called “possiblePositionsOpponent” was created by simply using the “moveTo” method on the head of the opponent snake and having all elements of “validMovesOpponent” as parameters.

```
Direction[] validMovesOpponent = Arrays.stream(DIRECTIONS)
    .filter(d -> !head2.moveTo(d).equals(afterHead2))
    .sorted()
    .toArray(Direction[]::new);
Set<Coordinate> possiblePositionsOpponent = new HashSet<>();
for(int i=0; i< validMovesOpponent.length; i++){
    possiblePositionsOpponent.add(head2.moveTo(validMovesOpponent[i]));
}
```

Since no other restrictions were made, the set „possiblePositionsOpponent“ always contained three elements, even if they were to be outside the maze.

Analogous to the array „validMovesOpponent“ we created an array of directions called „validMoves“ for our bot’s snake that excluded the possibility of backwards movement of the snake. This array „validMoves“ was subsequently used as a parameter of the stream method to create a new array of directions called „notLosing“, that with the use of the filter method excluded some unfavorable outcomes.

```
Direction[] notLosing = Arrays.stream(validMoves)
    .filter(d -> head.moveTo(d).inBounds(mazeSize))
    .filter(d -> !opponent.elements.contains(head.moveTo(d)))
    .filter(d -> !snake.elements.contains(head.moveTo(d)))
    .filter(d -> !possiblePositionsOpponent.contains(head.moveTo(d)))
    .sorted()
    .toArray(Direction[]::new);
```

Using the filter method, we checked the following: Is the resulting coordinate outside the maze? Is the resulting coordinate part of the opponent’s body? Is the resulting coordinate part of our snake’s body? And finally, does the set „possiblePositionsOpponent“ contain the resulting coordinate? If the answer to each of these question was „no“ the streamed element was added to the array.

Finally, we used the bubble sort algorithm to sort the elements of „notLosing“ based upon the distance to the apple. „chooseDirection“ returns the first element of „notLosing“ provided that this array is not empty. If this array happens to be empty, the first element of „validMoves“ is returned which, is never empty.

```
//Bubble Sort; Sorting Elements of "NotLosing"
double distance1, distance2;
int a1, a2, h11, h12, h21, h22, d1, d2;
Coordinate test1, test2;
Direction temp;
if (notLosing.length > 0){
    a1=apple.x;
    a2=apple.y;
    for(int i=0; i< notLosing.length; i++){
        for(int a= i+1; a< notLosing.length; a++){
            test1 = head.moveTo(notLosing[i]);
            test2 = head.moveTo(notLosing[a]);
            h11= test1.x;
            h12 = test1.y;
            d1 = (h11-a1)*(h11-a1)+(h12-a2)*(h12-a2);
            distance1=Math.sqrt((double)d1);
            h21= test2.x;
            h22 = test2.y;
            d2 = (h21-a1)*(h21-a1)+(h22-a2)*(h22-a2);
            distance2=Math.sqrt((double)d2);
            if(distance2<distance1){
                temp=notLosing[i];
                notLosing[i]=notLosing[a];
                notLosing[a]=temp;
            }
        }
    }
    return notLosing[0];
}
else{
    return validMoves[0];
}
}
```

8.2 Bot2

8.3 Bot3

9 Experimental Results and Statistical Tests

to-do

9.1 Simulations (Play with the Parameters!)

to-do

9.2 Use Benchmarks

to-do

9.3 Tables: input data details, results of different algorithms

to-do

9.4 Charts

to-do

9.5 Evaluations

to-do

10 Conclusions and Future Work

to-do

10.1 How the team work went

to-do

10.2 What we have learned

to-do

10.3 Ideas for the future development of your application, new algorithms

to-do