



Elektrobit



UDACITY

Technical Safety Concept Lane Assistance

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Document history

| Date | Version | Editor | Description |
|------------|---------|-----------------|--|
| 10/11/2017 | 1.0 | Ibis Prevedello | First draft |
| 10/18/2017 | 1.1 | Ibis Prevedello | Correction of Technical Safety Requirements related to lane departure warning amplitude malfunction, lane departure warning frequency malfunction and lane keeping assistance time malfunction |

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Purpose of the Technical Safety Concept

The purpose of the functional safety concept is to avoid accidents by reducing risks to acceptable levels.

Inputs to the Technical Safety Concept

Functional Safety Requirements

| ID | Functional Safety Requirement | ASIL | Fault Tolerant Time Interval | Safe State |
|-------------------------------------|--|------|------------------------------|--|
| Functional Safety Requirement 01-01 | The Electronic Power Steering ECU shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude. | C | 50 ms | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Functional Safety Requirement 01-02 | The Electronic Power Steering ECU shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Amplitude. | C | 50 ms | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Functional Safety Requirement 02-01 | The Electronic Power Steering ECU shall ensure that the lane assistance torque is applied for a maximum of Max_Duration. | B | 500 ms | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. |

Refined System Architecture from Functional Safety Concept

Figure 2 presents a refined system architecture including all the ASIL labels of each subsystem of the systems used.

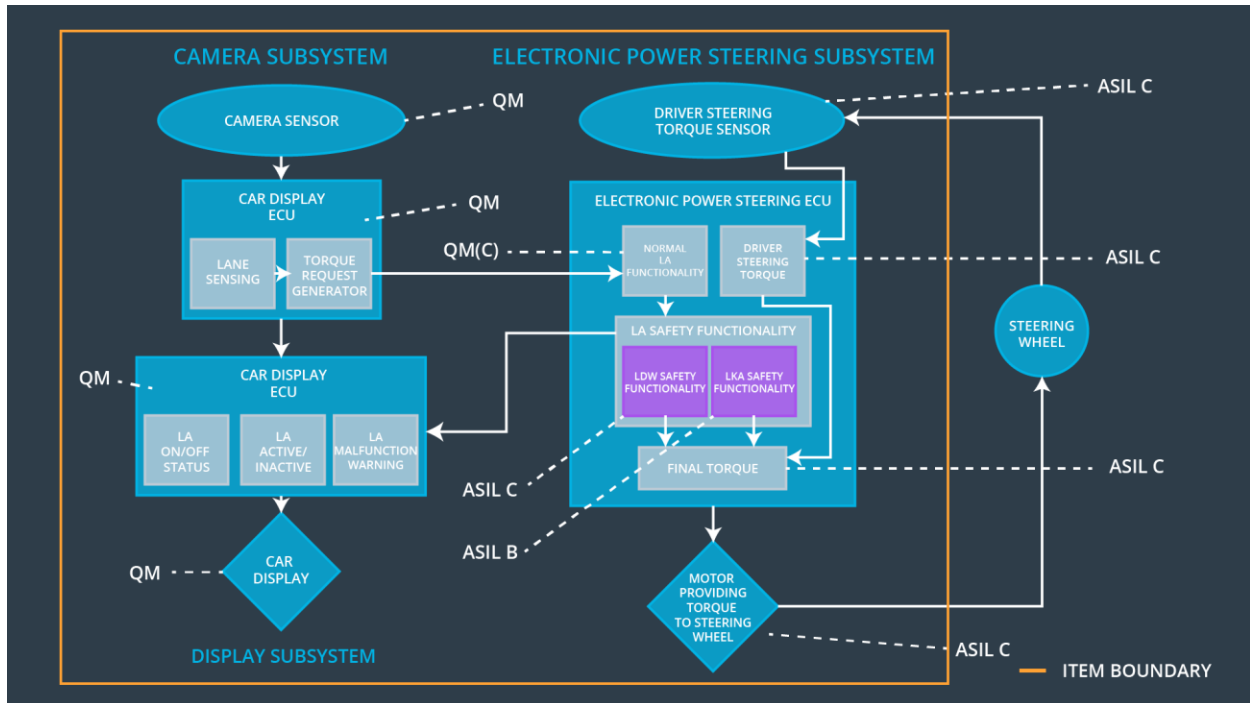


Figure 1 - Refined System Architecture

Functional overview of architecture elements

| Element | Description |
|---|---|
| Camera Sensor | A sensor positioned in the front of the car which will capture images and sends to the Camera Sensor ECU. |
| Camera Sensor ECU - Lane Sensing | The Camera Sensor ECU receives the images from the Camera Sensor, process it to determine Lane Sensing and outputs information for the Car Display ECU. |
| Camera Sensor ECU - Torque request generator | The Camera Sensor ECU receives the images from the Camera Sensor, process it to determine the torque necessary to steer the vehicle and send it to the Electronic Power Steering. |
| Car Display | Display that takes data from the Car Display ECU and shows to the driver in form of lighted icons and audio warnings. |
| Car Display ECU - Lane Assistance On/Off Status | This function determines if Lane Assistance is On/Off, it illuminates if function is activated. For this function the driver has autonomy to switch it on or |

| | |
|--|---|
| | off. |
| Car Display ECU - Lane Assistant Active/Inactive | This function determines if Lane Assistance is Active/Inactive, it illuminates if function is activated; if it is inactive, the driver cannot turn it on. |
| Car Display ECU - Lane Assistance malfunction warning | If any problem happen, a malfunction warning will be presented for the driver, it illuminates if warning is presented. |
| Driver Steering Torque Sensor | Sensor that measures the steering torque that the driver is applying on the steering wheel. |
| Electronic Power Steering (EPS) ECU - Driver Steering Torque | EPS ECU takes an input from the Driver Steering Torque Sensor and process the data. |
| EPS ECU - Normal Lane Assistance Functionality | EPS ECU sends the output to the Motor. It also limits to the torque do not exceed Max_torque. |
| EPS ECU - Lane Departure Warning Safety Functionality | EPS ECU assures that the amplitude and frequency are below Max_Torque_Frequency and Max_torque_Amplitude and sends the output to the Motor. |
| EPS ECU - Lane Keeping Assistant Safety Functionality | EPS ECU assures that the duration of the applied torque is below Max_Duration. |
| EPS ECU - Final Torque | After all the safety requirements satisfied, the final torque will be calculated and send to the Motor. |
| Motor | Receives the command from the Electronic Power Steering ECU and converts to torque on the steering wheel. |

Technical Safety Concept

Technical Safety Requirements

Lane Departure Warning (LDW) Requirements:

Functional Safety Requirement 01-01 with its associated system elements
(derived in the functional safety concept)

| ID | Functional Safety Requirement | Electronic Power Steering ECU | Camera ECU | Car Display ECU |
|-------------------------------------|---|-------------------------------|------------|-----------------|
| Functional Safety Requirement 01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude | X | | |

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

| ID | Technical Safety Requirement | ASIL | Fault Tolerant Time Interval | Architecture Allocation | Safe State |
|---------------------------------|--|------|------------------------------|---|--|
| Technical Safety Requirement 01 | The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude'. | C | 50 ms | Electronic Power Steering ECU (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50 ms | Electronic Power Steering ECU (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement | As soon as a failure is detected by the LDW function, it shall | C | 50 ms | Electronic Power Steering ECU | LDW is turned off with a lighted icon |

| | | | | | |
|---------------------------------|---|---|----------------|---|--|
| ent 03 | deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero. | | | (Includes the LDW safety block) | on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 04 | The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured. | C | 50 ms | Data Transmission Integrity Test (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 05 | Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory. | A | Ignition Cycle | Separate External Block of Memory (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |

Functional Safety Requirement 01-2 with its associated system elements
(derived in the functional safety concept)

| ID | Functional Safety Requirement | Electronic Power Steering ECU | Camera ECU | Car Display ECU |
|-------------------------------------|---|-------------------------------|------------|-----------------|
| Functional Safety Requirement 01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency | X | | |

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

| ID | Technical Safety Requirement | ASIL | Fault Tolerant Time Interval | Architecture Allocation | Safe State |
|---------------------------------|--|------|------------------------------|---|---|
| Technical Safety Requirement 01 | The LDW safety component shall ensure that the frequency of the 'LDW_Torque_Request' sent to the 'Final electronic | C | 50 ms | Electronic Power Steering ECU (Includes the | LDW is turned off with a lighted icon on the car display and/or sound |

| | | | | | |
|---------------------------------|---|---|----------------|---|--|
| | power steering Torque' component is below 'Max_Torque_Frequency. | | | LDW safety block) | warning to the driver. |
| Technical Safety Requirement 02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50 ms | Electronic Power Steering ECU (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero. | C | 50 ms | Electronic Power Steering ECU (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 04 | The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured. | C | 50 ms | Data Transmission Integrity Test (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 05 | Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory. | A | Ignition Cycle | Separate External Block of Memory (Includes the LDW safety block) | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. |

Lane Keeping Assistance (LKA) Requirements:

Functional Safety Requirement 02-1 with its associated system elements
(derived in the functional safety concept)

| ID | Functional Safety Requirement | Electronic Power Steering ECU | Camera ECU | Car Display ECU |
|-------------------------------|---|-------------------------------|------------|-----------------|
| Functional Safety Requirement | The lane keeping item shall ensure that the lane keeping assistance torque is applied for | X | | |

| | | | | |
|-------|-------------------|--|--|--|
| 02-01 | only Max_Duration | | | |
|-------|-------------------|--|--|--|

Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

| ID | Technical Safety Requirement | A S I L | Fault Tolerant Time Interval | Allocation to Architecture | Safe State |
|---------------------------------|---|------------------|---------------------------------------|--|--|
| Technical Safety Requirement 01 | The LKA safety component shall ensure that the lane assistance torque is applied for only Max_Duration. | B | 500 ms | Electronic Power Steering ECU (Includes the LKA safety block) | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 02 | As soon as the LKA function deactivates the LKA feature, the 'LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light. | B | 500 ms | Data Transmission Integrity Test (Includes the LKA safety block) | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 03 | As soon as a failure is detected by the LKA function, it shall deactivate the LDW feature and the 'LKA _Torque_Request' shall be set to zero. | B | 500 ms | Electronic Power Steering ECU (Includes the LKA safety block) | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. |
| Technical Safety Requirement 04 | The validity and integrity of the data transmission for 'LKA _Torque_Request' signal shall be ensured. | B | 500 ms | Electronic Power Steering ECU (Includes the LKA safety block) | LKA is turned off with a lighted icon on the car display and/or sound |

| | | | | | |
|---------------------------------|---|---|----------------|---|--|
| | | | | | warning to the driver. |
| Technical Safety Requirement 05 | Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory. | A | Ignition Cycle | Separate External Block of Memory (Includes the LKA safety block) | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. |

Refinement of the System Architecture

Figure 2 shows the system architecture after the safety technical requirements are applied.

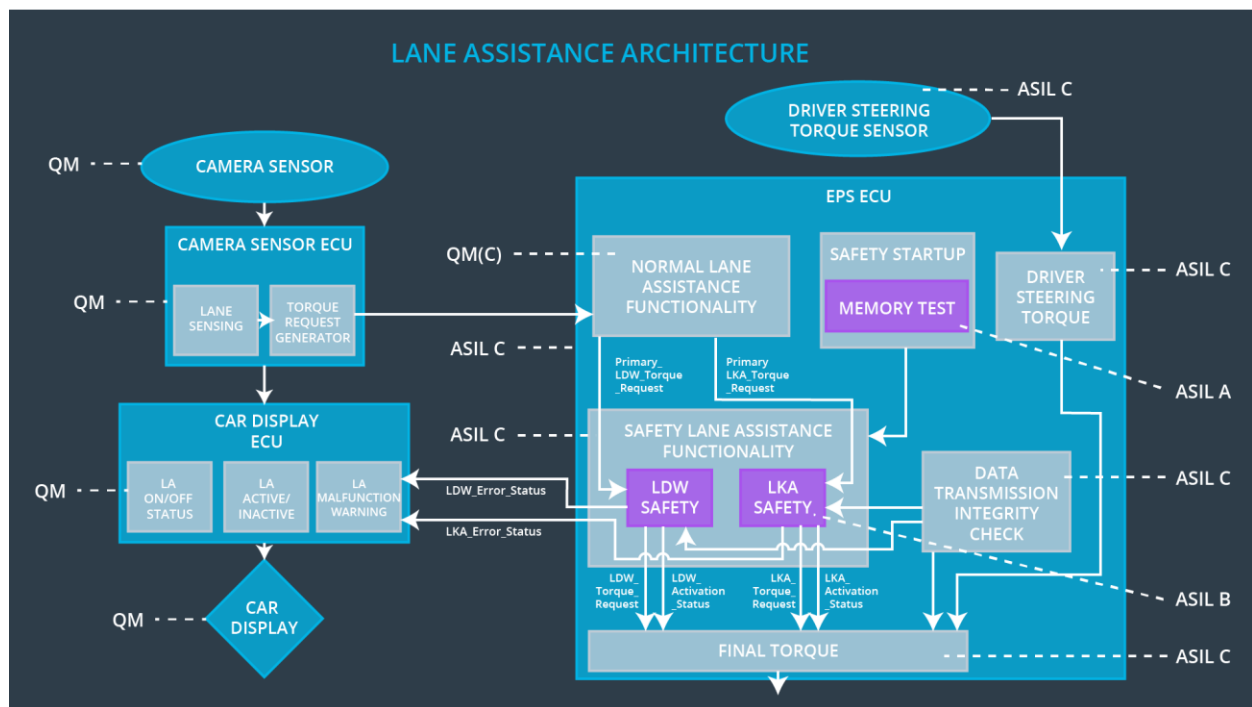


Figure 2 - Lane assistance architecture

Allocation of Technical Safety Requirements to Architecture Elements

All technical safety requirements are allocated to the Electronic Power Steering ECU.

Warning and Degradation Concept

| ID | Degradation Mode | Trigger for Degradation Mode | Safe State invoked? | Driver Warning |
|--------|--|---|---------------------|---|
| WDC-01 | LDW is turned off with a lighted icon on the car display and/or sound warning to the driver. | LDW torque exceeds Max_Torque_Amplitude or Max_Torque_Frequency | YES | Lighted icon on the car display and/or sound warning to the driver. |
| WDC-02 | LKA is turned off with a lighted icon on the car display and/or sound warning to the driver. | LKA torque is applied for a time longer than Max_Duration | YES | Lighted icon on the car display and/or sound warning to the driver. |