



Elektrobit



UDACITY

Technical Safety Concept Lane Assistance

Document Version: 1.0

Template Version 1.0, Released on 2017-06-21



Document history

Date	Version	Editor	Description
11/10/2017	1.0	Ibis Prevedello	First draft

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Purpose of the Technical Safety Concept

The purpose of the functional safety concept is to avoid accidents by reducing risks to acceptable levels.

Inputs to the Technical Safety Concept

Functional Safety Requirements

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	The Electronic Power Steering ECU shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude.	C	50 ms	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Functional Safety Requirement 01-02	The Electronic Power Steering ECU shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Amplitude.	C	50 ms	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Functional Safety Requirement 02-01	The Electronic Power Steering ECU shall ensure that the lane assistance torque is applied for a maximum of Max_Duration.	B	50 ms	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.

Refined System Architecture from Functional Safety Concept

Figure 2 presents a refined system architecture including all the ASIL labels of each subsystem of the systems used.

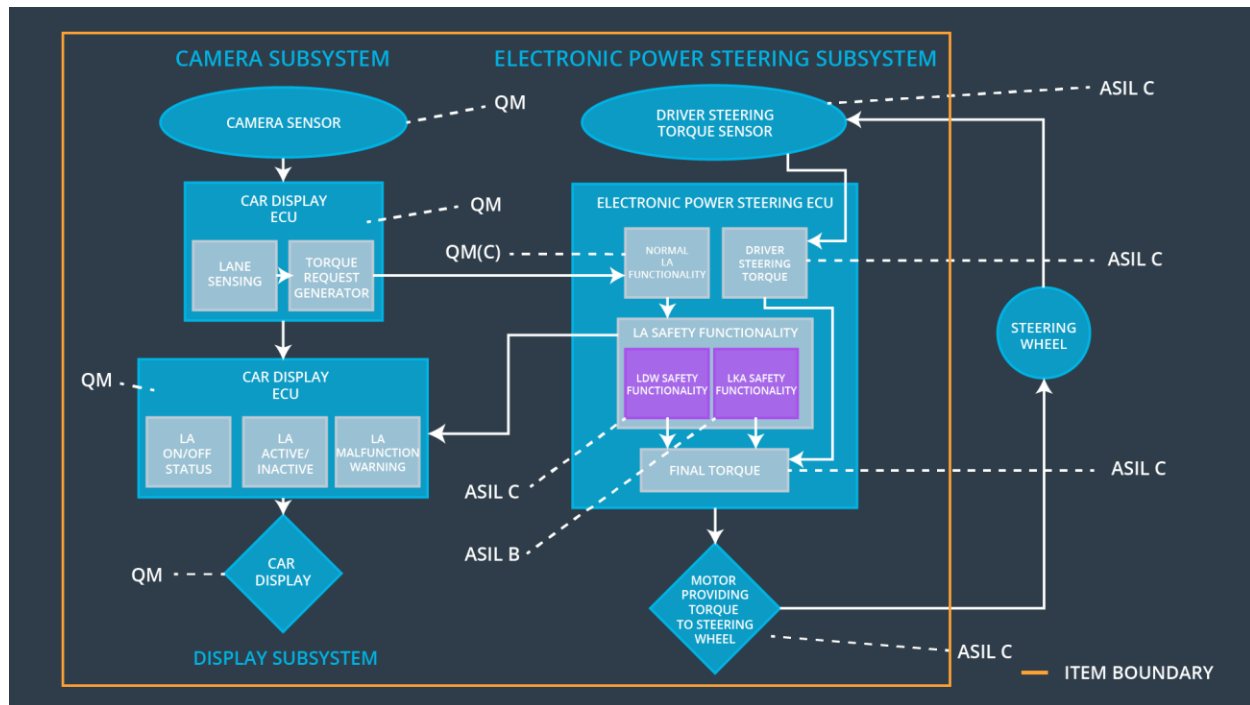


Figure 1 - Refined System Architecture

Functional overview of architecture elements

Element	Description
Camera Sensor	A sensor positioned in the front of the car which will capture images and sends to the Camera Sensor ECU.
Camera Sensor ECU - Lane Sensing	The Camera Sensor ECU receives the images from the Camera Sensor, process it to determine Lane Sensing and outputs information for the Car Display ECU.
Camera Sensor ECU - Torque request generator	The Camera Sensor ECU receives the images from the Camera Sensor, process it to determine the torque necessary to steer the vehicle and send it to the Electronic Power Steering.
Car Display	Display that takes data from the Car Display ECU and shows to the driver in form of lighted icons and audio warnings.
Car Display ECU - Lane Assistance On/Off Status	This function determines if Lane Assistance is On/Off, it illuminates if function is activated. For this function the driver has autonomy to switch it on or

	off.
Car Display ECU - Lane Assistant Active/Inactive	This function determines if Lane Assistance is Active/Inactive, it illuminates if function is activated; if it is inactive, the driver cannot turn it on.
Car Display ECU - Lane Assistance malfunction warning	If any problem happen, a malfunction warning will be presented for the driver, it illuminates if warning is presented.
Driver Steering Torque Sensor	Sensor that measures the steering torque that the driver is applying on the steering wheel.
Electronic Power Steering (EPS) ECU - Driver Steering Torque	EPS ECU takes an input from the Driver Steering Torque Sensor and process the data.
EPS ECU - Normal Lane Assistance Functionality	EPS ECU sends the output to the Motor. It also limits to the torque do not exceed Max_torque.
EPS ECU - Lane Departure Warning Safety Functionality	EPS ECU assures that the amplitude and frequency are below Max_Torque_Frequency and Max_torque_Amplitude and sends the output to the Motor.
EPS ECU - Lane Keeping Assistant Safety Functionality	EPS ECU assures that the duration of the applied torque is below Max_Duration.
EPS ECU - Final Torque	After all the safety requirements satisfied, the final torque will be calculated and send to the Motor.
Motor	Receives the command from the Electronic Power Steering ECU and converts to torque on the steering wheel.

Technical Safety Concept

Technical Safety Requirements

Lane Departure Warning (LDW) Requirements:

Functional Safety Requirement 01-01 with its associated system elements
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude	X		

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude'.	C	50 ms	Electronic Power Steering ECU (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 02	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	50 ms	Data Transmission Integrity Test (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement	As soon as a failure is detected by the LDW function, it shall	C	50 ms	Electronic Power Steering ECU	LDW is turned off with a lighted icon

ent 03	deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero.			(Includes the LDW safety block)	on the car display and/or sound warning to the driver.
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50 ms	Electronic Power Steering ECU (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 05	Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory.	A	Ignition Cycle	Separate External Block of Memory (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.

Functional Safety Requirement 01-2 with its associated system elements
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-02	The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency	X		

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the frequency of the 'LDW_Torque_Request' sent to the 'Final electronic	C	50 ms	Electronic Power Steering ECU (Includes the	LDW is turned off with a lighted icon on the car display and/or sound

	power steering Torque' component is below 'Max_Torque_Frequency.			LDW safety block)	warning to the driver.
Technical Safety Requirement 02	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	50 ms	Data Transmission Integrity Test (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero.	C	50 ms	Electronic Power Steering ECU (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50 ms	Electronic Power Steering ECU (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 05	Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory.	A	Ignition Cycle	Separate External Block of Memory (Includes the LDW safety block)	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.

Lane Keeping Assistance (LKA) Requirements:

Functional Safety Requirement 02-1 with its associated system elements
(derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety	The lane keeping item shall ensure that the lane keeping	X		

Requirement 02-01	assistance torque is applied for only Max_Duration			
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Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01	The LKA safety component shall ensure that the lane assistance torque is applied for only Max_Duration.	C	500 ms	Electronic Power Steering ECU (Includes the LKA safety block)	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 02	As soon as the LKA function deactivates the LKA feature, the 'LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light.	C	500 ms	Data Transmission Integrity Test (Includes the LKA safety block)	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 03	As soon as a failure is detected by the LKA function, it shall deactivate the LDW feature and the 'LKA_Torque_Request' shall be set to zero.	C	500 ms	Electronic Power Steering ECU (Includes the LKA safety block)	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'LKA_Torque_Request' signal shall be ensured.	C	500 ms	Electronic Power Steering ECU (Includes the LKA safety block)	LKA is turned off with a lighted icon on the car display and/or

					sound warning to the driver.
Technical Safety Requirement 05	Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory.	A	Ignition Cycle	Separate External Block of Memory (Includes the LKA safety block)	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.

Refinement of the System Architecture

Figure 2 shows the system architecture after the safety technical requirements are applied.

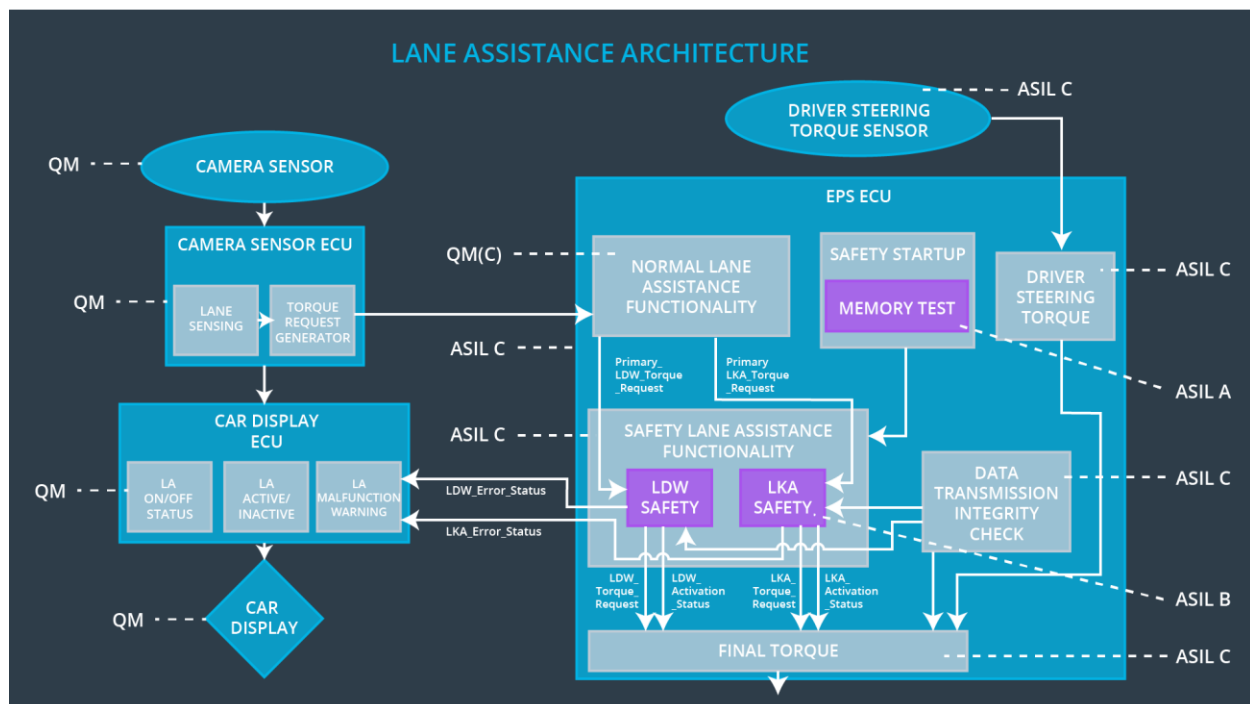


Figure 2 - Lane assistance architecture

Allocation of Technical Safety Requirements to Architecture Elements

All technical safety requirements are allocated to the Electronic Power Steering ECU.

Warning and Degradation Concept

ID	Degradation Mode	Trigger for Degradation Mode	Safe State invoked?	Driver Warning
WDC-01	LDW is turned off with a lighted icon on the car display and/or sound warning to the driver.	LDW torque exceeds Max_Torque_Amplitude or Max_Torque_Frequency	YES	Lighted icon on the car display and/or sound warning to the driver.
WDC-02	LKA is turned off with a lighted icon on the car display and/or sound warning to the driver.	LKA torque is applied for a time longer than Max_Duration	YES	Lighted icon on the car display and/or sound warning to the driver.