

Designing optimal cell factories: integer programming couples elementary mode analysis with regulation

Molecular Networks B SS13

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METHODOLOGY ARTICLE

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Designing optimal cell factories: integer programming couples elementary mode analysis with regulation

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Overview

- 1 Background and Motivation
- 2 Theory
- 3 Illustrative example
- 4 Including regulation
- 5 (Optimizing metabolic functionality)
- 6 Results of realistic example
- 7 Discussion
- 8 Summary and conclusions

Background and Motivation

- microbes can be used for metabolic engineering e.g. ethanol production in *E. coli*
- Metabolic networks are available for some model organisms

Gaol

Gene deletion strategie to optimize the production efficiency of strains.

Metabolic network and steady state assumption

Model of metabolic network with

- m internal metabolites
- n reactions
- $S \in \mathbb{R}^{m \times n}$ stoichiometric matrix
- $\hat{v} \in \mathbb{R}^n$ flux vector

fig?

Steady state assumption

Assume metabolite concentrations and reaction rates are constant.

$$S \cdot \hat{v} = 0 \quad (1)$$

Elementary mode analysis

Definition

An elementary mode (EM) is a minimal and indivisible set of reactions that operates under steady state conditions, while obeying all (ir-)reversibility constraints.

Network of minimal functionality (NMF)

Theory: Elementary mode analysis

$e = e(\hat{e})$ is the binary representation of a EM e .

$$e_i := e(\hat{e}_i) = \begin{cases} 1 & \text{if } \hat{e}_i \neq 0 \\ 0 & \text{if } \hat{e}_i = 0 \end{cases} \quad (2)$$

$$e^T v \leq e^T e = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n e_i =: \|e\|$$

Binary integer program

Group all q elementary modes:

$$G := (e_1, \dots, e_r)^T$$

goal matrix with desirable EM

$$H := (e_{r+1}, \dots, e_{r+s})^T$$

helper matrix tolerated EM

$$K := (e_{r+s+1}, \dots, e_{r+s+t})^T$$

kill matrix unwanted EM

$$\max ||x||$$

s.t.

$$e_g^T x = ||e_g||$$

$$g \in \{1, \dots, r\}$$

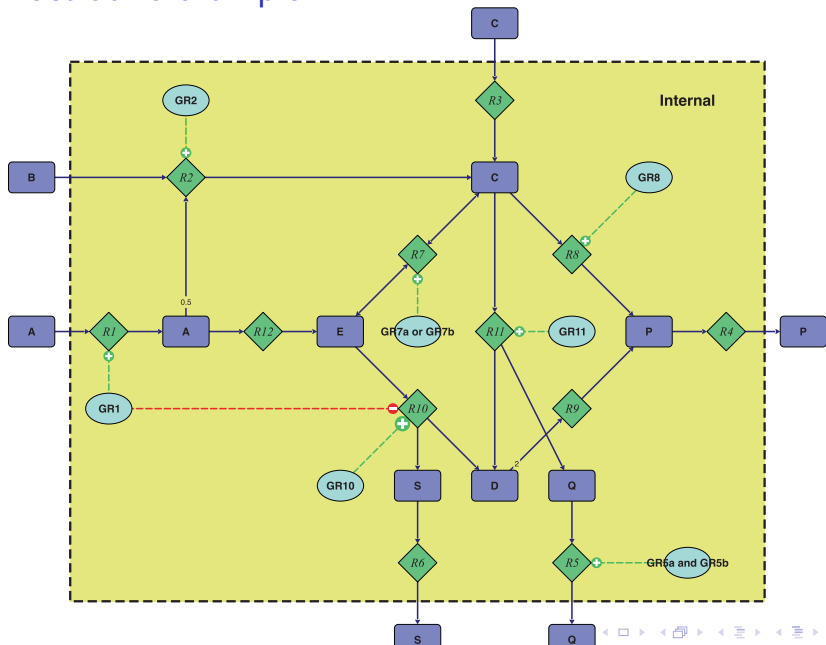
$$e_h^T x \leq ||e_h||$$

$$h \in \{r+1, \dots, r+s\}$$

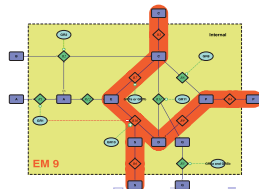
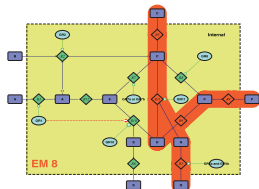
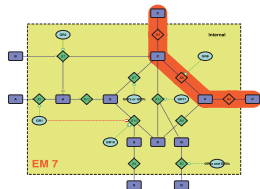
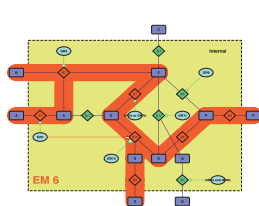
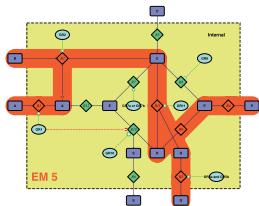
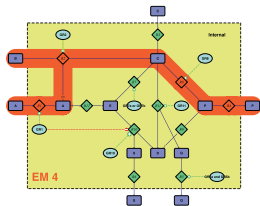
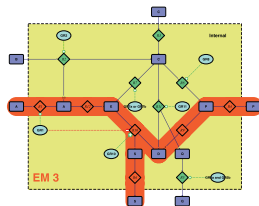
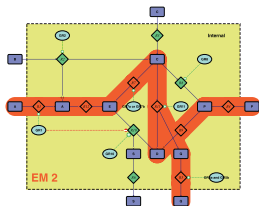
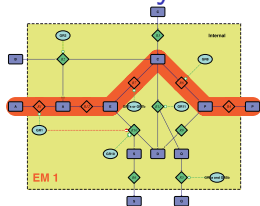
$$e_k^T x \leq ||e_k|| - 1$$

$$k \in \{r+s+1, \dots, r+s+t\}$$

Illustrative example



Elementary Modes



Introduction: Fixed Point Analysis

Given the system of differential equations:

$$y' = f(y)$$

Definition

A *fixed point* y^* is defined by $f(y^*) = 0$.

- Solve the equation $f(y) = 0$
- Analyse eigenvalues of the Jacobian at fixed points.

Now: System with *control parameter* μ .

$$y' = f(y, \mu)$$

How does μ influence the number, location and stability of fixed points?

Elementary flux mode

For $v \in R$