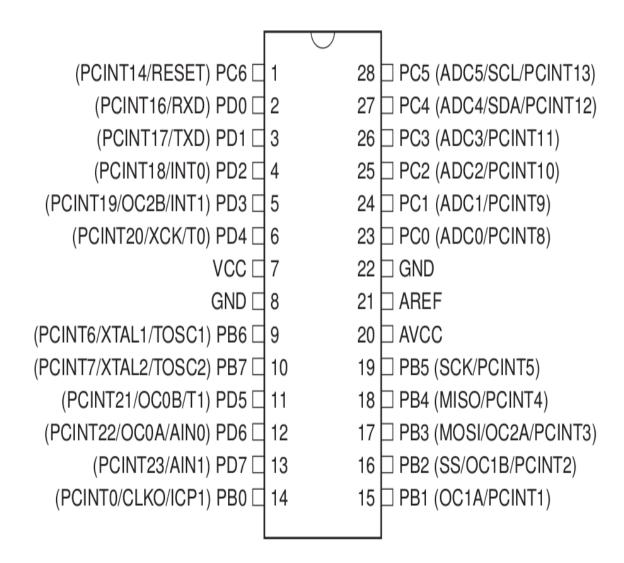
### CSE3023.1

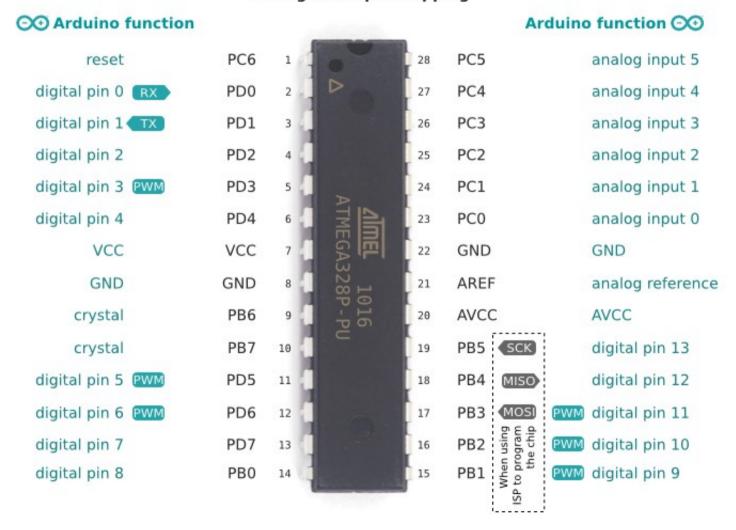
# Lecture 2 Digital I/O Port Operations in AVR

# Pin Configuration

- Pins are organized into 8-bit "Ports"
- PORTB 8 bit "Ports"
- PORTC 7 bits / Ports
- PORTD 8 bit "Ports"

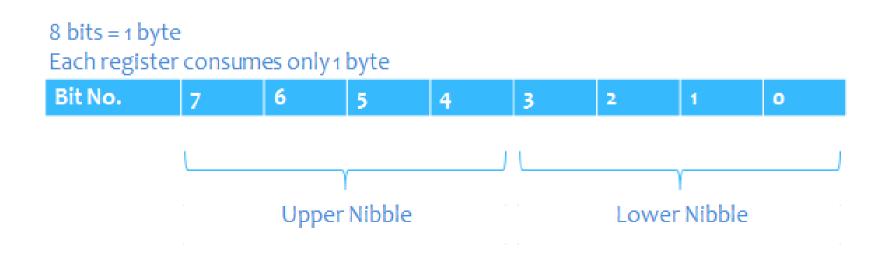


#### ATmega328P pin mapping



# Register

- A processor register is a memory space within the CPU itself so that they can be accessed very frequently and fast.
- These registers are linked with the operation of the MCU.



## Port Operation Registers

- DDRx Data Direction Register
- PORTx Pin Output Register
- PINx Pin Input Register
- where x = GPIO port name (B, C or D)



## DDRx - Data Direction Register

- The GPIO pins are the digital I/O pins i.e. they can act as both input and output.
- Now, how do we know that the pin is an output pin or input?
- The DDRx (Data Direction Register) controls one pin with each bit.
- 1 stands for output and 0 stands for input.

#### DDRx Register

Bit No.	7	6	5	4	3	2	1	О
Name	DDx7	DDx6	DDx5	DDx4	DDx3	DDx2	DDx1	DDxo
Initial Value	O	О	О	O	O	O	О	0

# PORTx - Pin Output Register

- Also one pin per bit
- If configured as an output:
  - 0 -> the pin is held at 0 V
  - 1 -> the pin is held at +5 V

#### **PORTx Register**

Bit No.	7	6	5	4	3	2	1	0
Name	Px7	Px6	Px5	Px4	Px3	Px2	Px1	Pxo
Initial Value	0	0	0	0	O	0	0	0

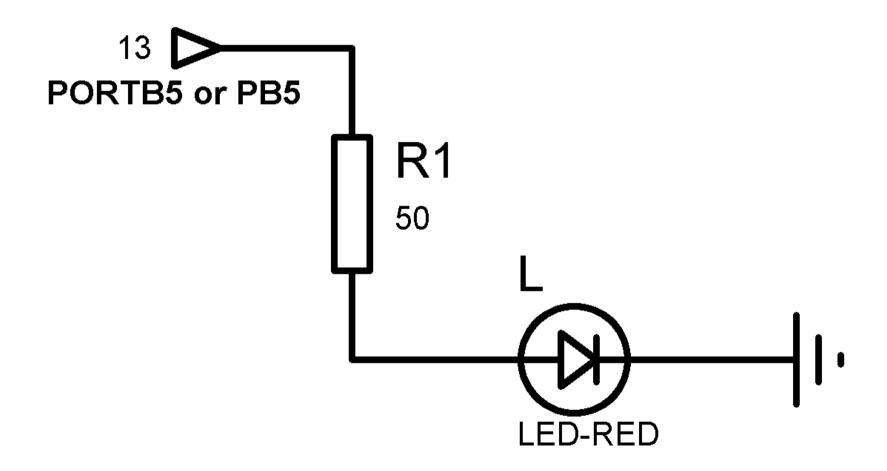
# PINx - Pin Input Register

- One pin per bit
- Reading from the register:
  - 0 -> the voltage of the pin is near 0 V
  - 1 -> the voltage of the pin is near +5 V
- If nothing is connected to the pin, then the pin will appear to be in a random state

### Hello World

- It's customary to write hello world whenever we are learning something new.
- In case of embedded system.. BLINK a Light Emitting Diode (L.E.D.)...

### The Circuit



### Blink v. 1.00

```
#include <avr/io.h> // for register name
#include <util/delay.h> //for delay ms built-in
function
int main(void)
  DDRB = 0b00100000; // Set PB5 as <u>ouput</u>
  PORTB = 0x00; //clear PortB
  while(1) //Run for-ever
     PORTB = 0b00100000; // Turn on
      delay ms(1000); //wait for 1 second
     PORTB = 0b00000000; // Turn off
     delay ms(1000);//wait for 1 second
```

### Blink v. 1.10

```
#include <avr/io.h>
#include <util/delay.h>
int main(void)
   DDRB |= 1<<DDB5;//PB5 as output
   PORTB = 0 \times 00;
   while(1)
      PORTB|=1<<PORTB5; //turn on
      delay ms(5000);
      PORTB\&=\sim(1<< PORTB5);//turn off
     _delay_ ms(5000);
//Good tutorial on bit shift operations
http://www.robotplatform.com/howto/blinker/blinker 8
.html
```

### Blink v. 1.20

```
#include <avr/io.h>
#include <util/delay.h>
int main(void)
  DDRB |= BV(DDB5)//PB5 as output
  PORTB = 0 \times 00;
  while(1)
     PORTB = BV(PORTB5); //turn on
      delay ms(5000);
     PORTB&=~ BV(PORTB5);//turn off
     _delay ms(5000);
```

# Blink in Arduino Processing

```
// Pin 13 has an LED connected on most Arduino boards.
// give it a name:
int led = 13:
// the setup routine runs once when you press reset:
void setup() {
 pinMode(led, OUTPUT); // initialize the digital pin as an output.
// the loop routine runs over and over again forever:
void loop() {
 digitalWrite(led, HIGH); // turn the LED on (HIGH is the voltage level)
 delay(1000);
               // wait for a second
 digitalWrite(led, LOW); // turn the LED off by making the voltage LOW
 delay(1000);
               // wait for a second
```