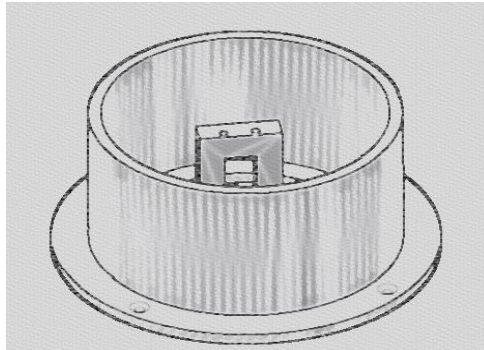
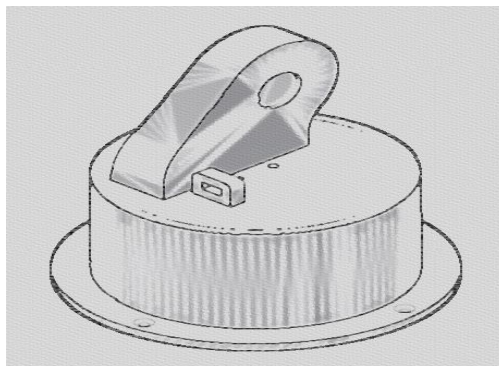


This is an assembly instruction on how to build the robotic arm.

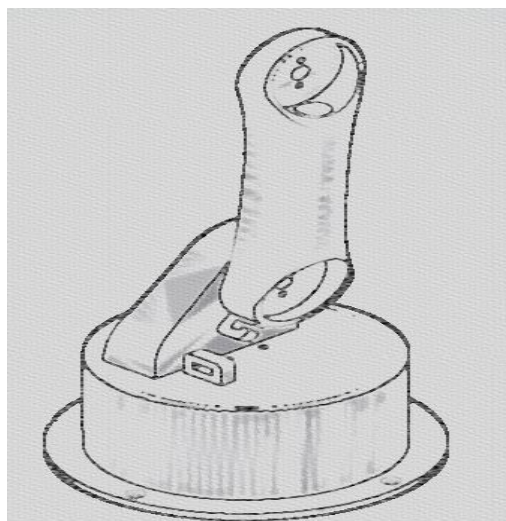
1. Put the base on a table or a horizontal surface as shown in the figure below.



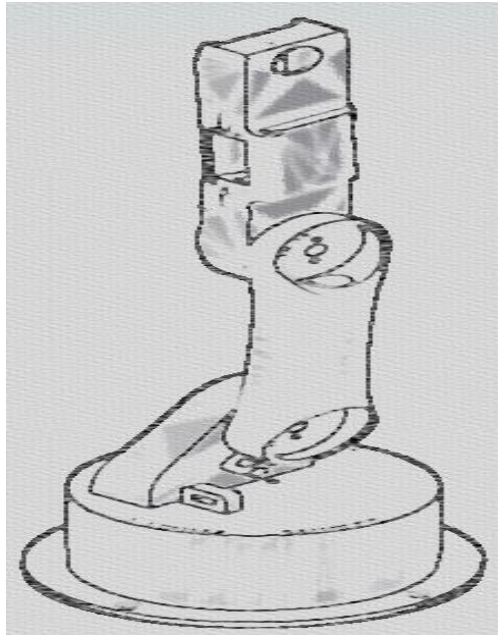
2. Put the waist above the base as shown in the figure below and make sure that it is fixed in its place.



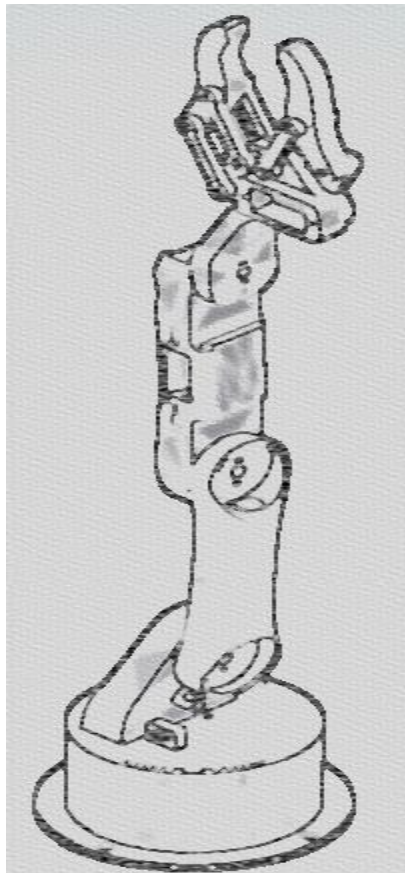
3. Take the symmetrical arm and put it in its place as shown in figure below, make sure that the arm is secured correctly.



4. Take the other arm and put it together with the symmetrical arm as shown in the figure below, make sure that the arm is secured correctly.



5. Take the gripper and put together with the arm as shown in the figure below.



6. Now you have to put the servo motors in its place as shown below.

