Python For Data Science Cheat Sheet SciPy - Linear Algebra

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SciPv

The **SciPv** library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPv extension of Pvthon.



Interacting With NumPv

Also see NumPv

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])
>>> c = np.array([[(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)]])
```

Index Tricks

>>>	np.mgrid[0:5,0:5]
>>>	np.ogrid[0:2,0:2]
>>>	np.r_[[3,[0]*5,-1:1:10j]
>>>	np.c [b,c]

Create a dense meshgrid Create an open meshgrid Stack arrays vertically (row-wise) Create stacked column-wise arrays

Shape Manipulation

>>>	np.transpose(b)	Permute array dimensions
>>>	b.flatten()	Flatten the array
>>>	np.hstack((b,c))	Stack arrays horizontally (column-wise)
>>>	np.vstack((a,b))	Stack arrays vertically (row-wise)
>>>	np.hsplit(c,2)	Split the array horizontally at the 2nd index
>>>	np.vpslit(d,2)	Split the array vertically at the 2nd index

Polvnomials

>>>	from	numpy	import	poly1d
>>>	p = p	ooly1d	([3,4,5])

Create a polynomial object

Vectorizing Functions

```
>>> def myfunc(a):
         if a < 0:
           return a*2
         else.
           return a/2
>>> np.vectorize(myfunc)
```

Vectorize functions

Type Handling

>>>	np.real(c)	Ret
>>>	np.imag(c)	Ret
>>>	np.real if close(c,tol=1000)	Ret
>>>	np.cast['f'](np.pi)	Cas

eturn the real part of the array elements eturn the imaginary part of the array elements eturn a real array if complex parts close to o ast object to a data type

Other Useful Functions

>>> np.angle(b,deg=True) >>> g = np.linspace(0,np.pi,num=5)	Return the angle of the complex argument Create an array of evenly spaced values
>>> g [3:] += np.pi	(number of samples)
>>> np.unwrap(g)	Unwrap
>>> np.logspace(0,10,3)	Create an array of evenly spaced values (log scale)
>>> np.select([c<4],[c*2])	Return values from a list of arrays depending on
	conditions
>>> misc.factorial(a)	Factorial
>>> misc.comb(10,3,exact=True)	Combine N things taken at k time
>>> misc.central_diff_weights(3)	Weights for Np-point central derivative
>>> misc.derivative(myfunc,1.0)	Find the n-th derivative of a function at a point

Linear Algebra Also see NumP۱

You'll use the linalg and sparse modules. Note that scipy.linalg contains and expands on numpy.linalg.

>>> from scipy import linalg, sparse

Creating Matrices

>>>	Α	=	np.matrix(np.random.random((2,2)))
>>>	В	=	np.asmatrix(b)
>>>	С	=	np.mat(np.random.random((10,5)))
>>>	D	=	np.mat([[3,4], [5,6]])

Basic Matrix Routines

Inverse

>>>	A.I
>>>	linalg.inv(A)
>>>	A.T
>>>	A.H
>>>	np.trace(A)

Norm

Rank	
>>>	<pre>linalg.norm(A,np.inf)</pre>
>>>	linalg.norm(A,1)
>>>	linalg.norm(A)

>>> np.linalg.matrix rank(C)

Determinant

>>> linalg.det(A)

Solving linear problems

,b)
T
,E)

Generalized inverse

>>>	linalg.pinv(C)

>>> linalg.pinv2(C)

Inverse

Inverse Tranpose matrix

Conjugate transposition

Trace

Frobenius norm L1 norm (max column sum) L inf norm (max row sum)

Matrix rank

Determinant

Solver for dense matrices Solver for dense matrices Least-squares solution to linear matrix

equation

Compute the pseudo-inverse of a matrix (least-squares solver) Compute the pseudo-inverse of a matrix (SVD)

Creating Sparse Matrices

>>> F = np.eye(3, k=1)	Create
>>> G = np.mat(np.identity(2))	Create
>>> C[C > 0.5] = 0	
>>> H = sparse.csr_matrix(C)	Compre
>>> I = sparse.csc_matrix(D)	Compre
>>> J = sparse.dok_matrix(A)	Diction
\\ E +odongo()	Snarca

a 2X2 identity matrix a 2x2 identity matrix

ressed Sparse Row matrix ressed Sparse Column matrix nary Of Keys matrix Sparse matrix to full matrix Identify sparse matrix

>>> sparse.isspmatrix csc(A) Sparse Matrix Routines

>>> sparse.linalg.inv(I)

Norm

>>> sparse.linalg.norm(I) Solving linear problems

>>> sparse.linalg.spsolve(H,I)

Inverse

Norm

Solver for sparse matrices

Sparse matrix exponential

Sparse Matrix Functions

>>>	sparse.linalg.expm(1)	

Asking For Help >> help(scipy.linalg.diagsvd) >>> np.info(np.matrix)

Matrix Functions

Addition

>>> np.add(A,D)

Subtraction

>>> np.subtract(A,D)

Division

>>> np.divide(A,D)

Multiplication

```
>>> np.multiply(D,A)
>>> np.dot(A,D)
>>> np.vdot(A,D)
>>> np.inner(A,D)
>>> np.outer(A,D)
>>> np.tensordot(A.D)
>>> np.kron(A,D)
```

Exponential Functions

```
>>> linalq.expm(A)
>>> linalg.expm2(A)
>>> linalg.expm3(D)
```

Logarithm Function

>>> linalg.logm(A)

Trigonometric Tunctions

>>>	linalg.sinm(D)
>>>	linalg.cosm(D)
>>>	linalg.tanm(A)

Hyperbolic Trigonometric Functions

```
>>> linalg.sinhm(D)
>>> linalg.coshm(D)
>>> linalg.tanhm(A)
```

Matrix Sign Function

>>> np.sigm(A)

Matrix Square Root >>> linalg.sqrtm(A)

Arbitrary Functions >>> linalg.funm(A, lambda x: x*x)

Matrix logarithm

decomposition)

Addition

Division

Subtraction

Multiplication

Inner product

Outer product

Vector dot product

Tensor dot product

Kronecker product

Matrix exponential

Matrix exponential (Taylor Series)

Matrix exponential (eigenvalue

Dot product

Matrix sine Matrix cosine Matrix tangent

Hypberbolic matrix sine Hyperbolic matrix cosine Hyperbolic matrix tangent

Matrix sign function

Matrix square root

Evaluate matrix function

Decompositions

Eigenvalues and Eigenvectors >>> la, v = linalg.eig(A)

```
>>> 11, 12 = la
>>> v[:,0]
>>> v[:,1]
>>> linalg.eigvals(A)
```

Singular Value Decomposition

>>> U,s,Vh = linalg.svd(B) >>> M,N = B.shape

LU Decomposition

>>> Sig = linalg.diagsvd(s,M,N) Construct sigma matrix in SVD

>>> P,L,U = linalg.lu(C)

Solve ordinary or generalized eigenvalue problem for square matrix Unpack eigenvalues First eigenvector Second eigenvector

Singular Value Decomposition (SVD)

LU Decomposition

Unpack eigenvalues

Sparse Matrix Decompositions

>>> la, v = sparse.linalg.eigs(F,1) >>> sparse.linalg.svds(H, 2)

Eigenvalues and eigenvectors SVD

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