$$A = \begin{bmatrix} 2 & -4 & 6 & 1 & 7 & 117 \\ 1 & -2 & -1 & 1 & 9 & 12 \\ -1 & 2 & 1 & 3 & -5 & -16 \\ 4 & -8 & 1 & -1 & 6 & -2 \end{bmatrix}, B = \begin{bmatrix} 1 & -2 & 0 & 0 & 3 & 27 \\ 0 & 0 & 1 & 0 & -5 & -3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

A, B row equivalent.

(C) Basis for RS(A) is the same as basis for RS(B)

Basis RS(A) = & (1,-2,0,0,3,2), (0,0,1,0,-5,-3), (0,0,0,1,1,7)3

(6)1-2 CIA = CZ,A (ano CIA + az CZ,A + az CZ,A = 0 when a, =-2, az = +, az = 0

i. CIA, CZIA, CZIA linearly dependent.

Also, d.m CS(A) = dim(RC(A) = 3) -> NOT imports independent

(c) besis for CSCA = {(2,1,-1,4), (0,-1x 1,1), (1,1,3,-1).}

does NOT spen 184.

(d) 2C118 + (-3)C318 + 7C418 = ES18

: Cs,A = span & C1,A, C3,A, C4,A 3

(e) Nullspace (A) = Nullspace (B) = & FERE | BF = 03

2 1 - 2 1 + 3 5 + 2 5 = 0

- SUTS - 3VE = 0

Cet 52=6, 50=5, 5=5

J= [26-35-20]

$$\begin{cases}
-5\sqrt{4} = -\sqrt{5} - 7\sqrt{6} \\
-7\sqrt{5} = 5\sqrt{5} + 3\sqrt{6}
\end{cases}$$

$$\sqrt{5} = 2\sqrt{2} - 3\sqrt{5} - 2\sqrt{6}$$

$$\sqrt{5} = 2\sqrt{2} - 3\sqrt{5} - 2\sqrt{6}$$

(f) RCAK(A) + NO 11, +y(A) = 6 . Dollify (A) = 3

RONK (A) = OIN RS(A) = 3 - : RONK(A) = 3

$$\widehat{Z} = \widehat{\nabla}_{1} - \underbrace{(3,1)}_{4\widehat{M}^{2}} \widehat{G}_{1} = (0,1) - \frac{2}{12} (4,1) \\
\widehat{W}_{2} = \widehat{\nabla}_{2} - \underbrace{(3,3)}_{4\widehat{M}^{2}} \widehat{G}_{1} = (0,1) - \frac{2}{12} (4,1) \\
\widehat{W}_{3} = \widehat{\mathcal{C}}_{3} - \underbrace{(3,3)}_{4\widehat{M}^{2}} \widehat{G}_{1} - \underbrace{(3,2)}_{122_{1}} \widehat{G}_{2} \widehat{G}$$

## Scanned with CamScanner

Problem 3: 
$$T(f) = \int_{1}^{2} f(x) dx$$
  $T: CE-1,2J \rightarrow \mathbb{R}$ 

(a)  $T(f+g) = \int_{1}^{2} f(x) dx + \int_{1}^{2} g(x) dx + \int_{1}^{2} g(x) dx = T(f) + T(g)$ 
 $T(cf) = \int_{1}^{2} cf(x) dx = C\int_{1}^{2} f(x) dx = T(f) + T(g)$ 

i.  $T.$  Since transformation.

T(g) =  $\int_{1}^{2} cos \pi \times dx = \frac{sn\pi \times 1^{2}}{\pi} = O(: s.n2\pi = c, s.n.(-m))$ 
 $T(g) = \int_{1}^{2} r^{2} dx = \frac{1}{4} x^{4} \int_{1}^{2} = 4 - 1/4 = \frac{15}{4}$ 

i.  $T(f) = 0$ 

i.  $T(f) = 0$ 

i.  $T(g) = \frac{15}{4}$ 

T(o) = 0

T(o) =

on element other than a. aim (Range (T)) 21

.. dim (Range (TI) = 1 R.

aim (Range CTI) connet be >1 :: dim (TE)=1

Froblem III [2, w] 
$$= \begin{bmatrix} x_1 & y_1 \\ 2_1 & w_1 \end{bmatrix} = \begin{bmatrix} x_1 & y_2 \\ 2_2 & w_2 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \\ 2_3 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ 2_4 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_3 \\ 2_4 & x_4 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 + C \times S^{1/4} & S^{1/4} \\ x_1 & y_1 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 + C \times S^{1/4} & S^{1/4} \\ x_1 & y_2 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 + C \times S^{1/4} & S^{1/4} \\ x_1 & y_2 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_1 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_3 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_3 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_3 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_3 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_1 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & y_2 \\ x_3 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & y_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_3 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_2 & x_3 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2 \\ x_1 & x_2 \end{bmatrix} \times \begin{bmatrix} x_1 & x_2$$

## Scanned with CamScanner

roblem S. (a) dim (V)=n -> & it, it, -, it my must be linearly independent. Let dim(v)=3 , V=R3 E(1,2,3), (-1,-2,-3)3 set of 2 vectors but 3, + 32 =0 i. Falsc. Test for subspace: ( UEV - OEU, WEV -> OEW 2 u, JEUNW - Tirreuni DEUNW → i, feU → i+ reU

(b) U EV, W EV -> UNW EV ( < meas subspecce) 一つ ふっか とい 一つ ストテモい = it it EUNW (3) THEONW -> CREUNW WEU -3 CREU = caeunw JEW->cZEW TRUE : Unw =V. (C) W = \( \int \c/ \rangle (\rangle ) \tag{\int (\rangle ) \rangle (\ -> Test for subspace: OWER - DEW "x = 0, y = 0 - CO, O, O) = W.

② む、テモルータはよるとい

ecser method! Q= E1, 1,1) EW but 22=(2,2,2)&

: W not closed ander Scalar multiplication.

(x1, x141, 41) + (+2, 4242,42) ( (x,++2), x, 4,++242, (1+42)) but if x=x1+x2, y=11+42 -> (x1+72, cx1+72)(41+42), (4, 442) -> (x, +>2, (,x,y, + x, 122+224, + x232), (4,442) x141+x212 iff x142 = = x2131

Scanned with CamScanner

(d) 
$$A^{2}=0$$
,  $B\sim A \rightarrow B^{2}=0$   
 $B\sim A \rightarrow B=P^{-1}AP$   
 $\Rightarrow B^{2}=(P^{-1}AP)^{2}=(P^{-1}AP)(P^{-1}AP)$   
 $=P^{-1}A(PP^{-1})AP$   
 $=P^{-1}A^{2}P^{\frac{11}{2}}$   
 $=P^{-1}(O)P$   
 $=O$ 

120,3>1 < 11011 (Cauchy Showert 2.)

:. 120,0 > 1 2 1 :TRUE

