

view_frames Result

Recorded at time: 25.006

world

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /gazebo
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 25.0
Oldest transform: 20.1

world_interface

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

bin_1_base_link

bin_4_base_link

bin_5_base_link

festo_bypass_1festo_module

festo_robot_1festo_module

festo_straight_1festo_module

festo_straight_2festo_module

festo_straight_3festo_module

festo_straight_4festo_module

festo_t_1festo_module

fib14

robot1_pedestal_link

camera_link_optical

logical_camera1_ground_plane_frame

logical_camera1_box_01_frame

logical_camera1_robot_frame

bin_1_drop_point

bin_4_drop_point

bin_5_drop_point

camera_link

logical_camera1_frame

robot1_pedestal_link

panda_link0

panda_link1

panda_link2

panda_link3

panda_link4

panda_link5

panda_link6

panda_link7

panda_link8

panda_hand

panda_leftfinger

panda_rightfinger

panda_link0

panda_link1

panda_link2

panda_link3

panda_link4

panda_link5

panda_link6

panda_link7

panda_link8

panda_hand

panda_leftfinger

panda_rightfinger

panda_link0

panda_link1

panda_link2

panda_link3

panda_link4

panda_link5

panda_link6

panda_link7

panda_link8

panda_hand

panda_leftfinger

panda_rightfinger