view frames Result Recorded at time: 25.006 \_(world)\_\_\_\_ Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /gazebo Average rate: 10000.0 Average rate: 10000.0 Average rate: 10.204 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 25.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 20.1 camera\_link world\_interface logical\_camera1\_frame Broadcaster: /robot state publisher Broadcaster: /gazebo Broadcaster: /robot state publisher Broadcaster: /gazebo Broadcaster: /gazebo Average rate:  $1000\overline{0}.0$ Average rate: 10.204 Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate: 10000.0 Average rate: 10.204 Average rate: 10.204 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 25.0 Most recent transform: 0.0 Most recent transform: 25.0 Most recent transform: 25.0 Oldest transform: 20.1 Oldest transform: 0.0 Oldest transform: 20.1 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 20.1 festo\_straight\_1festo\_module festo\_bypass\_1festo\_module logical\_camera1\_robot\_frame bin\_1\_base\_link bin\_4\_base\_link bin\_5\_base\_link festo\_straight\_2festo\_module festo\_t\_1festo\_module fib14 robot1\_pedestal\_link logical\_camera1\_ground\_plane\_frame logical\_camera1\_box\_01\_frame festo robot 1festo module festo\_straight\_3festo\_module festo\_straight\_4festo\_module camera\_link\_optical Broadcaster: /robot\_state\_publisher Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 bin\_1\_drop\_point panda\_link0 bin\_5\_drop\_point bin\_4\_drop\_point Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link1 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link2 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link3 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link4 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link5 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link6 Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 24.987 Oldest transform: 20.007 panda\_link7 Broadcaster: /robot\_state\_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda\_link8 Broadcaster: /robot state publisher Average rate:  $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda\_hand Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate:  $50.\overline{201}$ Average rate:  $50.\overline{201}$ Buffer length: 4.98 Buffer length: 4.98 Most recent transform: 24.987 Most recent transform: 24.987 Oldest transform: 20.007 Oldest transform: 20.007 panda\_leftfinger panda\_rightfinger