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1 import tensorflow as tf
2 from tensorflow.keras.optimizers import RMSprop
3 from tensorflow.keras.preprocessing.image import
  ImageDataGenerator
4 import matplotlib.pyplot as plt
5 import os
6 import multiprocessing
7
8 import multiprocessing
9
10 def trainCNN( ):
11
12     base_dir = 'G:\GIEyA\TFG\
  MeteorClassificationProject\labeledData'
13     train_dir = os.path.join(base_dir, 'train_640x360
  ')
14     validation_dir = os.path.join(base_dir, '
  validation_640x360')
15
16     train_meteors_dir = os.path.join(train_dir, '
  meteors')
17     train_non_meteors_dir = os.path.join(train_dir, '
  non_meteors')
18     validation_meteors_dir = os.path.join(
  validation_dir, 'meteors')
19     validation_non_meteors_dir = os.path.join(
  validation_dir, 'non_meteors')
20
21     print('total training meteors images: ', len(os.
  listdir(train_meteors_dir)))
22     print('total training non-meteors images: ', len(
  os.listdir(train_non_meteors_dir)))
23     print('total validation meteors images: ', len(os
  .listdir(validation_meteors_dir)))
24     print('total validation non-meteors images: ',
  len(os.listdir(validation_non_meteors_dir)))
25
26
27     #Rescale all images by 1./255
28
29     train_datagen = ImageDataGenerator(rescale=1.0/
  255,
30                                     rotation_range
  =40, #Range from 0 to 180 degrees to randomly rotate

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30 images. In this case it's going to rotate between 0
   and 40 degrees
31
32   width_shift_range=0.2, #Move image in this fram (20%)
33   height_shift_range=0.2,
34   shear_range=0.
   2, #Girar la imagen un 20%
35   zoom_range=0.5
   , #Zoom up-to 20%
36   horizontal_flip=True, #Efecto cámara: girar la imagen
   con respecto al eje vertical
37   fill_mode='
   nearest') #Ckeck other options
38   test_datagen = ImageDataGenerator(rescale=1.0/255
   .)
39
40   train_generator = train_datagen.
   flow_from_directory(train_dir,
41
42     batch_size=8,
43
44     class_mode='binary',
45     color_mode='grayscale',
46
47     target_size=(300, 300))
48   validation_generator = test_datagen.
   flow_from_directory(validation_dir,
49
50     batch_size=4,
51
52     class_mode='binary',
53     color_mode='grayscale',
54
55     target_size=(300, 300))
56
57   model = tf.keras.models.Sequential([#Try Dropout
   after each Conv2D + MaxPôoling2D stage
58     tf.keras.layers.Conv2D(16, (3,3), activation=
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53 'relu', input_shape=(300, 300, 1)),
54     tf.keras.layers.MaxPooling2D(2,2),
55     tf.keras.layers.Dropout(0.2),
56     tf.keras.layers.Conv2D(64, (3,3), activation=
    'relu'),
57     tf.keras.layers.MaxPooling2D(2,2),
58     tf.keras.layers.Dropout(0.2),
59     tf.keras.layers.Flatten(),
60     tf.keras.layers.Dense(128, activation='relu'
    ),
61     tf.keras.layers.Dense(16, activation='relu'),
62     tf.keras.layers.Dense(4, activation='relu'),
63     tf.keras.layers.Dense(1, activation='sigmoid'
    )])
64
65     print(model.summary())
66
67     model.compile(optimizer=RMSprop(lr=0.001),
68                   loss='binary_crossentropy',
69                   metrics=['accuracy'])
70
71     #53.079 -> Training
72     #13.271 -> Validation
73     #53.079/batch_size =
74     #13.271/batch_size =
75
76     history = model.fit_generator(train_generator,
77                                   validation_data=
    validation_generator,
78                                   steps_per_epoch=6000,
79                                   epochs=20, #Later train with
    more epochs if neccessary
80                                   validation_steps=3000,
81                                   verbose=2)
82
83     acc      = history.history['accuracy']
84     val_acc  = history.history['val_accuracy']
85     loss     = history.history['loss']
86     val_loss = history.history['val_loss']
87     epochs = range(len(acc)) #Get number of epochs
88
89     plt.plot(epochs, acc)
90     plt.plot(epochs, val_acc)
91     plt.title('Meteor detection training and

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91 validation accuracy')
92     plt.figure()
93
94     plt.plot(epochs, loss)
95     plt.plot(epochs, val_loss)
96     plt.title('Meteor detection training and
validation loss')
97
98     plt.show()
99
100 if __name__ == '__main__':
101     p = multiprocessing.Process(target=trainCNN)
102     p.start()
103     p.join()
```