FINAL PROJECT

1) The Shooting Method

- The file shooting_method.m contains the code that solves the problem by the shooting method.
- The file func-shorthy-nethod.m contains the code that solves the ivp in the shorthy method by AB2 method.
- There are the step sizes are corresponding maximum errors that are formed by absolute value of difference between three solution (vexet in ode) one numerical solution (vappl in the code)

$$\frac{h(hstep)}{20} \xrightarrow{max-error}$$

$$\frac{1}{20} \longrightarrow 0.1153$$

$$\frac{1}{40} \longrightarrow 0.1416$$

$$\frac{1}{80} \longrightarrow 0.0926$$

$$\frac{1}{160} \longrightarrow 0.0363$$

$$\frac{1}{160} \longrightarrow 0.0119$$

We observe that, when we divide the step-size by 2, maximum error is divide by 24, after $h=\frac{1}{80}$. This result is consistent with the fact that AB2 is of order 2.

Also, we know that the IVP we solve in the shooting method is unstable, that might be the reason that max-error is increased between $h=\frac{1}{20}$ as $h=\frac{1}{40}$.

2) The Symmetric Finite Difference Method

- The file symmetric_fam.m contains the code that solves the problem by the symmetric finite difference method.
- There are the step sizes and corresponding maximum errors that are found by absolve value of difference between the true solvation (vexact in the code) and the numerical solution (vapp in the code)

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h (hstep in	Max-error	
	125		0.4353
	40		0.1932
	80		7.0557
	160		0.0121

We observe that, from $h=\frac{1}{80}$ to $h=\frac{1}{160}$, when the his divided by 2, the maximum error is divided by 24, which is consistent with the feet that the symmetric FDM is of order 2.

(3) Also, we observe that for $h=\frac{1}{20}$ and $h=\frac{1}{40}$, small the problem is stiff, there are oscillations in the stiff region, as expected in the implementation of the symmetric FDM for stiff problems

3) The Upward Finit Difforme Method

The fite upmine-fam.m contains the code that solves the problem by the upmine finite difference method.

A the precious application

h (hs	tep in t	he code)	Max-crisc
	120	\longrightarrow	0.1599
	<u>L</u>	>	0.2036
	L 80	<i>—</i>	0.1579
	160		0.0922
	320		0.0517

We observe that, when h is divided by 2, the maximum error is divided by 22, which is consistent with the fact that the upwine FDM is of order 1.

- Also, unlike the symmetric FDM, we observe that the numerical solution does not display oscillations for any value of h in the staff region, which is consistent with the fact that upware FDM is absolutely stable for any h.
- 4) Error Estimation and Adoptive Mesh Regimenent
 - B The file nonuniform—adaptive—fdm.m contains the code that solves the problem by FDM employed in error estimation and adaptive mesh refinement.
 - The file function adoptie-fam. In contains the code that solves the problem by FDM by nonuniform mesh. This function is used in the process of error estimation and adoptive mesh refrement
 - When we run the code for all the values of h= \$20,\$40,\$50,\$160, we observe that maxarror=0.0030 in each case, when is expected because during the process of error estimation one adoptive nesh refinement, the tree neties in non-uniform mesh are created to be more donse in stiff region, when results a very good approximation companed to the previous methods. Also, we should not that, the final nonuniform mesh for all values of h are same.
 - Also, we can express that when maxerror's of all the nothers are companed, we an observe that error estimation as adjusted much refinement gives a very strong tool to get a nice numerical solution.
 - Finally, we should emphasize that max-error values above one obtained when ETOL = 0.01 However, if we take ETOL smaller (ETOL = 0.001 for example), we see that max-error values are much more smaller are we obtain a much better numerical approximation,