```
% Zachary Linkletter
% ECE 498 HW 8
% 4/9/18
clear
clc
Q1 = dsolve('Dy = x^2/y','x')
Q2 = dsolve('Dy + y^2 * sin(x) = 0', 'x')
Q3 = dsolve('x * Dy = sqrt(1 - y^2)','x')
f = @(x,y) (-x*y)/sqrt(2 - y^2);
[x,y] = ode45(f, [0 5], 1);
figure(1);
plot(x,y)
grid on;
title('Q4');
function dy = ode(t,y)
dy = zeros(3,1);
dy(1) = 2*y(1) + y(2) + 5*y(3) + exp(-2*t);
dy(2) = -3*y(1) - 2*y(2) - 8*y(3) + 2*exp(-2*t) - cos(3*t);
%dy(3) = 3*y(1) + 3*y(2) + 2*y(3) + cos(3*t);
%end
[x1,y1] = ode23('ode',[0 pi/2], [1 -1 1])
figure(2);
plot(x1,y1)
grid on;
title('Q5');
Q1 =
  2^{(1/2)*}(x^{3/3} + C2)^{(1/2)}
 -2^{(1/2)*}(x^{3/3} + C2)^{(1/2)}
Q2 =
 -1/(C5 + cos(x))
Q3 =
                1
                -1
```

```
sin(C8 + log(x))
x1 =
         0
    0.0100
    0.0600
    0.1455
    0.2370
    0.3369
    0.4479
    0.5706
    0.7023
    0.8075
    0.9127
    0.9789
    1.0283
    1.0777
    1.1378
    1.2106
    1.2946
    1.3893
    1.4963
    1.5708
y1 =
    1.0000
            -1.0000
                        1.0000
             -1.0816
    1.0710
                        1.0301
    1.4550
             -1.5393
                        1.1838
    2.2286
             -2.5075
                        1.4451
             -3.7854
                        1.6960
    3.2227
             -5.4157
                        1.8992
    4.4903
    6.0906
             -7.4337
                        1.9987
   8.0208
             -9.7722
                        1.9156
   10.1700 -12.2140
                        1.5808
   11.8542
            -13.9738
                        1.1408
   13.4408 -15.4686
                        0.5748
   14.3658 -16.2454
                        0.1725
   15.0127
            -16.7367
                       -0.1423
   15.6200 -17.1513
                       -0.4631
   16.3043 -17.5543
                       -0.8527
   17.0554 -17.9035
                       -1.3084
   17.8256
            -18.1442
                       -1.7855
```

18.6031 -18.2693

19.4316 -18.3435

20.0321 -18.4420

-2.2262

-2.5520

-2.6492





