

# Modelagem e Análise de Sistemas Lineares

## Roteiro 4

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EC-14.1.80P3

$$a) J_m \ddot{\theta}_m + D_m \dot{\theta}_m = T_m$$

$$T_m(s) = (J_m s^2 + D_m s) \theta_m(s)$$

$$b) \frac{(R_a + L_a s) T_m}{K_t} + K_{ce} s \theta_m = E_a(s) \quad \text{Equação (P.)}$$

$$\frac{(R_a + L_a s)}{K_t} (J_m s^2 + D_m s) \theta_m + K_{ce} s \theta_m = E_a(s)$$

$$c) L_a = 0$$

$$\left[ \frac{R_a}{K_t} (J_m s + D_m) + K_{ce} \right] s \theta_m(s) = E_a(s)$$

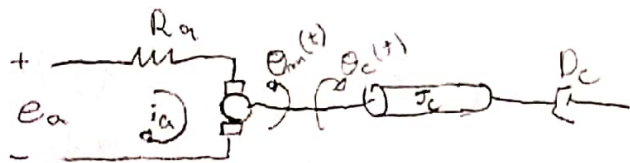
$$\frac{\theta_m(s)}{E_a(s)} = \frac{1}{s \left[ \frac{R_a}{K_t} (J_m s + D_m) + K_{ce} \right]} \rightarrow \frac{\frac{K_t}{R_a J_m}}{s \left[ s + \frac{1}{J_m} \left( D_m + \frac{K_t K_{ce}}{R_a} \right) \right]}$$

d) Refletindo  $J_c$  e  $D_c$  p/ armadura

$$J_{ceq} = J_a + J_c \left( \frac{N_L}{N_p} \right)^2$$

$$D_{ceq} = D_a + D_c \left( \frac{N_L}{N_p} \right)^2$$

①  $\frac{\Theta_c(s)}{E_a(s)} = ?$  ; refletindo  $J_c$  e  $D_c$  p/ armadura



Pelo gráfico:

$$\begin{cases} e_a = 100 \text{ V} \\ \omega_m = 50 \text{ rad/s} \\ T_m = 500 \text{ N-m} \end{cases}$$

$$J_e = J_a + J_c \left( \frac{N_1}{N_2} \right)^2 \approx 5 + 700 \left( \frac{100}{1000} \right)^2 \approx \boxed{J_m = 12}$$

$$D_e = D_a + D_c \left( \frac{N_1}{N_2} \right)^2 \approx 2 + 800 \left( \frac{1}{10} \right)^2 \approx \boxed{D_m = 10}$$

$$\Theta_c = \frac{N_1}{N_2} \Theta_m \approx \Theta_c = \frac{1}{10} \Theta_m \approx \boxed{\Theta_m = 10 \Theta_c}$$

$$\frac{K_T}{R_a} = \frac{T_m}{e_a} \approx \frac{500}{100} = 5$$

$$K_{ce} = \frac{e_a}{\omega_m} \approx \frac{100}{50} = 2$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{\frac{K_T}{R_a J_m}}{s \left[ s + \frac{1}{J_m} \left( D_m + \frac{K_T K_{ce}}{R_a} \right) \right]}$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{5/12}{s \left[ s + \frac{1}{12} (10 + 5 \cdot 2) \right]}$$

$$\approx \frac{5/12}{s \left[ s + 20/12 \right]}$$

$$\frac{10 \Theta_c(s)}{E_a} = \frac{5/12}{s \left[ s + 20/12 \right]}$$

$$\approx \boxed{\frac{\Theta_c(s)}{E_a(s)} = \frac{5/120}{s(s + 20/12)}}$$

$$\textcircled{2} \frac{\Theta_c(s)}{E_a(s)} ; \quad t_m = -\delta \omega_m + 200, \quad e_a = 100 \text{ V}$$

$$J_m = J_a + J_c \left( \frac{N_1}{N_2} \right)^2 \approx 1 + 400 \left( \frac{25}{1000} \right)^2 \approx \boxed{2}$$

$$D_m = D_a + D_c \left( \frac{N_1}{N_2} \right)^2 \approx 5 + 800 \left( \frac{25}{1000} \right)^2 \approx \boxed{7}$$

$$\frac{K_T}{R_a} = \frac{t_m}{e_a} \approx \frac{200}{200} = \boxed{2}$$

$$K_{ce} = \frac{e_a}{\omega_{vazio}} \approx \frac{100}{\frac{100}{8}} = \boxed{4}$$

$$\Theta_c = \frac{N_1 N_3}{N_2 N_4} \Theta_m \approx \boxed{\Theta_m = 20 \Theta_c}$$

$$\frac{\Theta_m(s)}{E_a(s)} = \frac{\frac{K_T}{R_a} \cdot \frac{1}{J_m}}{s \left[ s + \frac{1}{J_m} \left( D_m + \frac{K_T}{K_a} K_{ce} \right) \right]} \approx \frac{2/2}{s \left[ s + \frac{1}{2} (7 + 2 \cdot 4) \right]}$$

$$\frac{20 \Theta_c(s)}{E_a(s)} = \frac{1}{s \left[ s + \frac{15}{2} \right]} \Rightarrow \boxed{\frac{\Theta_c(s)}{E_a(s)} = \frac{1/20}{s \left[ s + \frac{15}{2} \right]}}$$