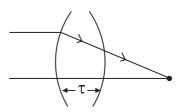
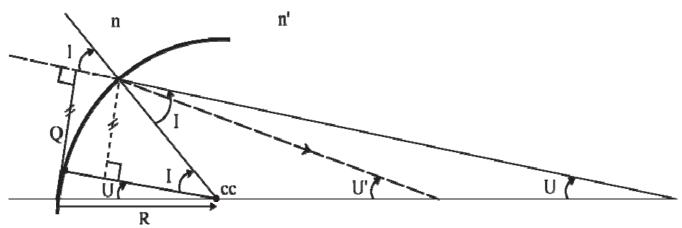
Exact Ray Trace

Analytical/exact ray tracing





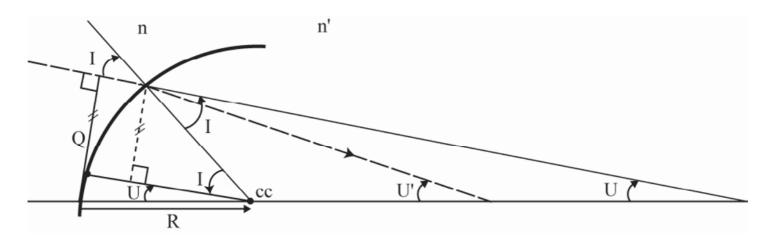
Q – U Method

- ray has height Q and \angle U

Givens:

- 1. Surface radius R
- 2. n′
- 3. n
- 4. Q,U ray description

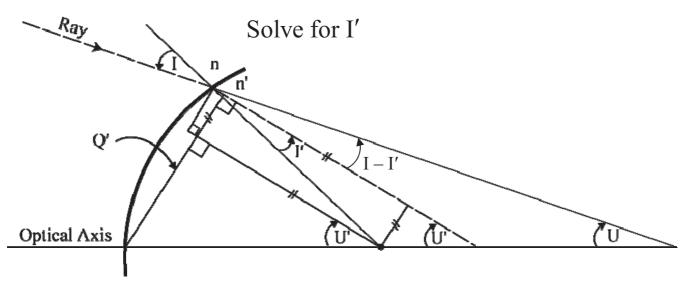
^{*} O'Shea, Elements of Modern Optics Design, Wiley (1985)



 $Q = R \sin I + R \sin(-U) = R \sin I - R \sin U$

solve for I;

 $n' \sin I' = n \sin I$



We know I, I', and U. From the geometry we can derive

$$Q' = R \sin(-U') + R \sin I'$$

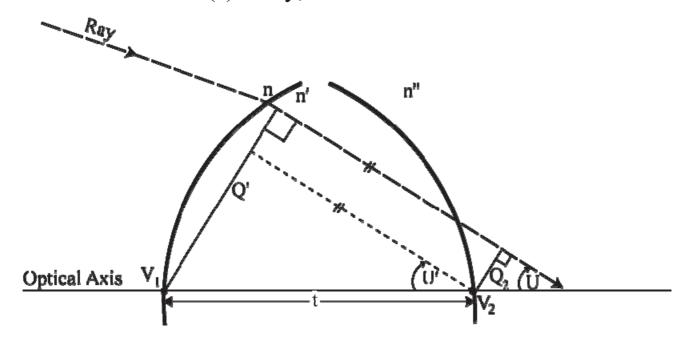
$$Q' = R(\sin I' - \sin U')$$

Recall that U' = U - I + I'

Therefore we now have a new ray, characterized by Q' - U' of refracted ray just inside surface in space n' angle

Axial Transfer

Axial transfer of an exact ray to next surface, thickness (τ) away, where τ is vertex distances.



$$Surface_1 \rightarrow Q_1, Q_1'$$

Surface₂
$$\rightarrow$$
 Q₂, Q₂'

$$Q_2 = Q' - t \sin(-U')$$

U' is negative in sign convention

$$Q_2 = Q' + t \sin U'$$

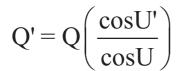
Now we have Q_2U_2 at surface₂, since $U_2 = U'$

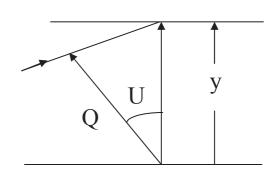
Plane Surface ($R = \infty$) problem

 $y = Exact ray height at surface, R = \infty$

$$y = \frac{Q}{\cos U} = \frac{Q'}{\cos U'}$$

$$\sin U' = \frac{n}{n'} \sin U$$



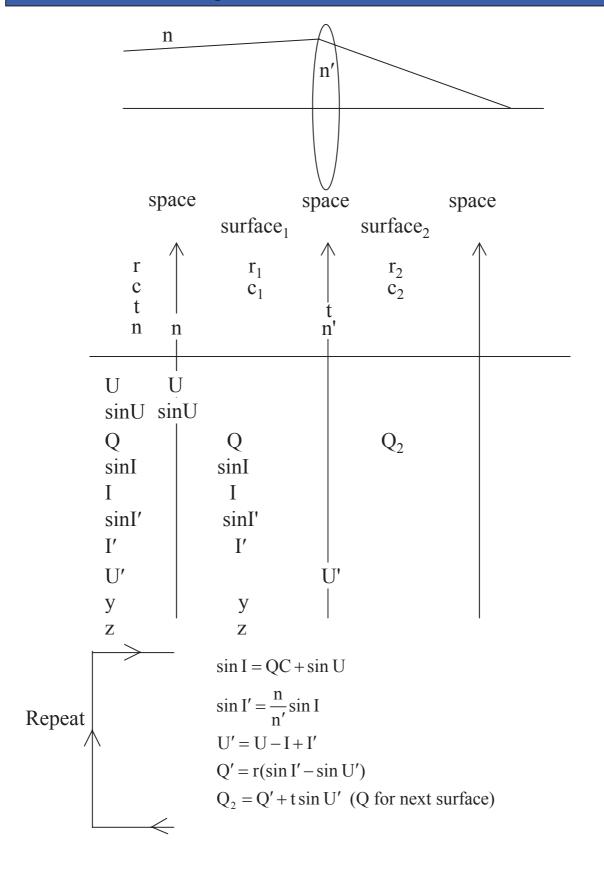


Q-U Ray Trace

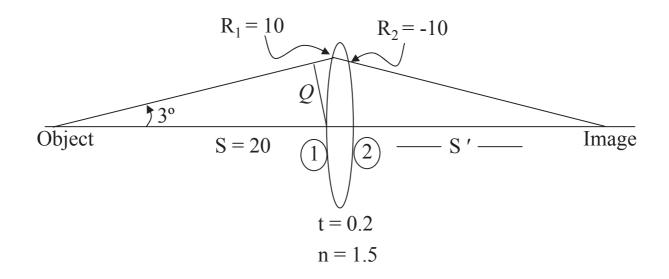
From geometry of Q - U at the surface of a known input ray:

- 1) $Q = R \sin(-U) + R \sin I$ find I from knowing Q and U $\sin I = \frac{Q}{R} - \sin(-U)$
- 2) $\sin I' = \frac{n}{n'} \sin I$ find I' from I via Snell's Law
- 3) U' = U + I' I [Geometry]
- 4) $Q' = R \left(\sin I' \sin U' \right)$ find Q'
- 5) $Q_2 = Q' + \tau \sin U'$ at next surface

Exact Ray Trace (Q U Trace)



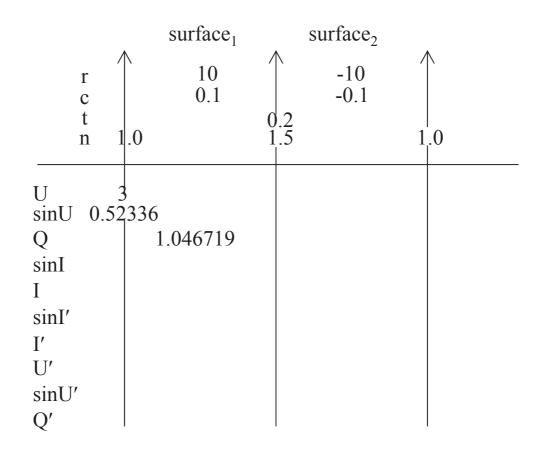
Example of Exact Ray Trace



Open/initial knowledge

$$Q = t \sin U = +20 \sin 3$$

 $Q = 1.046719$



Exact Ray Tracing Table

| Parameter | Object space | Surface ₁ | Lens space | Surface ₂ | Image space |
|-----------|--------------|----------------------|------------|----------------------|----------------|
| r | | | | | |
| С | | | | | |
| t | | | | | |
| n | | | | | |
| U | | | | | |
| sinU | | | | | |
| Q | | | | | |
| sinI | | | | | |
| I | | | | | |
| sinI' | | | | | |
| I' | | | | | |
| U' | | | | | |
| sinU' | | | | | |
| Q' | | | | | |
| Q_2 | | | | | |

Exact Ray Trace (Givens)

| Parameter | Object space | Surface ₁ | Lens space | Surface ₂ | Image space |
|-----------|--------------|----------------------|------------|----------------------|----------------|
| r | | 10 | | -10 | |
| С | | 0.1 | | -0.1 | |
| t | 20 | | 0.2 | | BFD = ?? |
| n | 1 | | 1.5 | | 1 |
| U | 3° | | | | |
| sinU | 0.52336 | | | | |
| Q | | 1.046719 | | | |
| sinI | | | | | |
| I | | | | | |
| sinI' | | | | | |
| I' | | | | | |
| U' | | | | | |
| sinU' | | | | | |
| Q' | | | | | 0 |
| Q_2 | | | | | |

Exact Ray Trace (Calculations)

| Parameter | Object space | Surface ₁ | Lens space | Surface ₂ | Image space |
|-----------|--------------|----------------------|------------|----------------------|----------------|
| r | | 10 | | -10 | |
| С | | 0.1 | | -0.1 | |
| t | 20 | | 0.2 | | BFD = ?? |
| n | 1 | | 1.5 | | 1 |
| U | 3° | | | | |
| sinU | 0.052336 | | | | |
| Q | | 1.046719 | | | |
| sinI | 0.157008 | | | | |
| I | 9.033258° | | | | |
| sinI' | | | 0.104672 | | |
| I' | | | 6.00826° | | |
| U' | | | -0.025001 | | |
| sinU' | | | -0.000436 | | |
| Q' | | 1.04235 | | | |
| Q_2 | | | | 1.050995 | |

Exact Ray Trace (Results)

| Parameter | Object space | Surface ₁ | Lens space | Surface ₂ | Image space |
|-----------|--------------|----------------------|------------|----------------------|----------------|
| r | | 1.0 | | -10 | |
| С | | 0.1 | | -0.1 | |
| t | 20 | | 0.2 | | 19.506692 |
| n | 1 | | 1.5 | | 1 |
| U | 3° | | V | | |
| sinU | 0.52336 | | V | | |
| Q | | 1.046719 | | √ | |
| sinI | 0.157008 | | | | -0.1055388 |
| Ι | 9.033258° | | | | -0.1057327 |
| sinI' | | | 0.104672 | | -0.1583037 |
| I' | | | 6.00826° | | -0.1589725 |
| U' | | | -0.025001 | | -0.0536761 |
| sinU' | | | -0.000436 | | -0.0536503 |
| Q' | | 1.04235 | | | 1.04653436 |
| Q_2 | | | | 1.05099523 | |

$$BFD = t = \frac{Q'}{\sin U'} = \frac{1.04653436}{-0.0536503}$$
$$BFD = 19.506692$$

Aberrations of the Rotationally Symmetric Optical System

- Paraxial systems are perfect.
- Aberrations describe the deviation of real systems from this perfection.
- An aberrated system will have image locations and magnifications approximately the same as those predicted by the paraxial or Gaussian analysis.
- The paraxial image is often used as a reference for the measurement of aberrations.
- In geometrical optics, the object is considered to be a collection of independently radiating point sources δ elta fn weighted by radiant flux.
- The image is the sum of the images of all of the point sources (independent irradiance patterns). There is no interference.