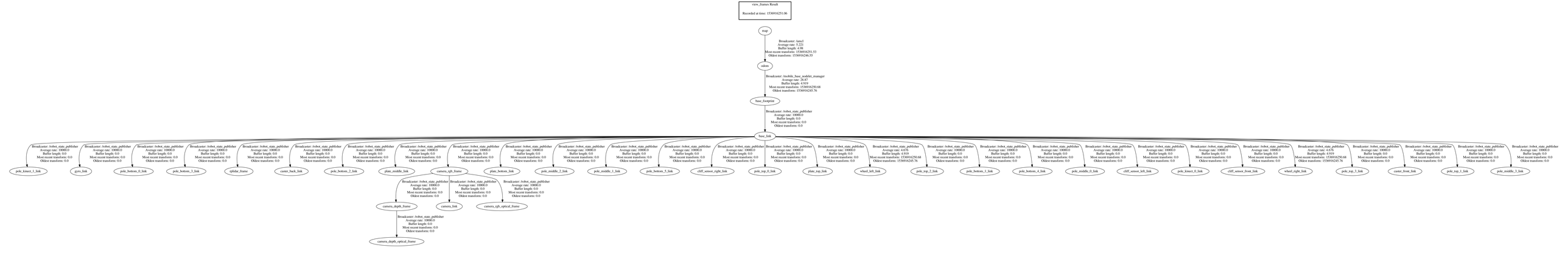
view_frames Result
Recorded at time: 1536916251.06
map
Broadcaster: /amcl
Average rate: 5.221
Buffer length: 4.98
Most recent transform: 1536916251.53
Oldest transform: 1536916246.55
odom
Broadcaster: /mobile_base_nodelet_manager
Average rate: 10000.0
Buffer length: 4.919
Most recent transform: 1536916250.68
Oldest transform: 1536916245.76
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
pole_kinect_1_link
gyro_link
pole_bottom_0_link
pole_bottom_3_link
rplidar_frame
caster_back_link
pole_bottom_2_link
plate_middle_link
camera_rgb_frame
plate_bottom_link
pole_middle_2_link
pole_middle_1_link
pole_bottom_5_link
cliff_sensor_right_link
pole_top_0_link
plate_top_link
wheel_left_link
pole_top_2_link
pole_bottom_1_link
pole_bottom_4_link
pole_middle_0_link
cliff_sensor_left_link
pole_kinect_0_link
cliff_sensor_front_link
wheel_right_link
pole_top_3_link
caster_front_link
pole_top_1_link
pole_middle_3_link
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
camera_depth_frame
camera_link
camera_rgb_optical_frame
camera_depth_optical_frame