

# Operating System Practice

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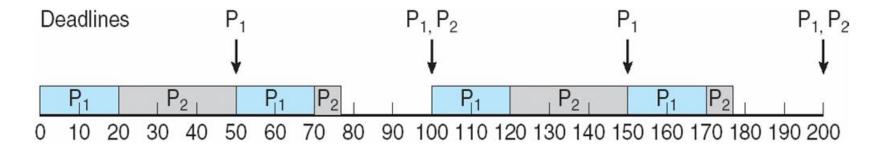
# Worst-Case Execution Time (WCET) Analysis

### Recall the Rate Monotonic Real-Time Scheduling

- A static priority is assigned to each task based on the inverse of its period
  - A task with shorter period → higher priority
  - A task with longer period 

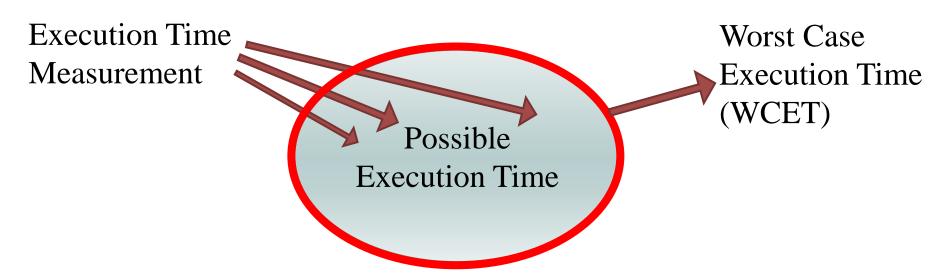
     lower priority
  - For example:
    - P<sub>1</sub> has its period 50 and execution time 20
    - P<sub>2</sub> has its period 100 and execution time 37
      - $\rightarrow$  P<sub>1</sub> is assigned a higher priority than P<sub>2</sub>

How can we get the **EXECUTION TIME** 



# Execution Time of a Program

▶ The execution time of a program might not be a constant



WCETs are most essential assumptions for schedulability analysis

How to get the WCET of a program!?

### Factors for WCET Analysis

- Input parameters
  - Algorithm parameters
  - Problem size
- States of the system
  - Cache configuration, cache replacement policies
  - Pipeline configuration
  - Speculations
- Interferences from the environment
  - Scheduling policies
  - Interrupts



### **WCET Analysis**

- ▶ Can we always get the WCET of a program?
  - Halting Problem tells us that we can not use an algorithm to decide whether another algorithm *m* halts on a specific input *x*.
  - Thus, WCET is also undecidable
- Most of industry's best practice
  - Measure it: determine WCET directly by running or simulating a set of inputs.
  - Exhaustive execution: by considering the set of all the possible inputs
- Another approach: compute an upper bound of the WCET
  - It should be no less than the WCET
  - It should be close to the WCET
  - It can not always be tight



## Research of WCET Analysis

**Execution Time** Worst Case Measurement **Execution Time** (WCET) Possible **Execution Time** Better **WCET** Upper WCET Bound Upper Bound

## Challenges of Analyzing WCET

- $\blacktriangleright$  Execution time e(i) of machine instruction i
  - e(i) is not a constant
  - The (architectural) execution state s should be considered
  - Thus, e(i) is within the following range

```
\min\{e(i, s)|s \in S\} \le e(i) \le \max\{e(i, s)|s \in S\},\ where S is the set of all states
```

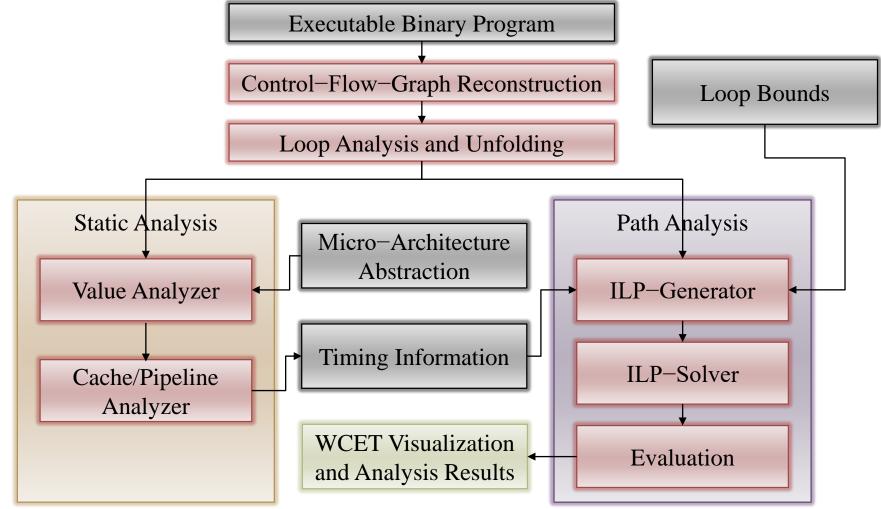
- ▶ Using  $\max\{e(i, s)|s \in S\}$  as the upper bound of WCET
  - It is safe
  - But it might be not tight

## Timing Accidents and Penalties

- Timing Accident: cause for an increase of the execution time of an instruction
- ▶ Timing Penalty: the associated increase
- Types of timing accidents
  - Cache misses
  - TLB misses
  - Page faults
  - Pipeline stalls
  - Branch prediction errors
  - Bus collisions

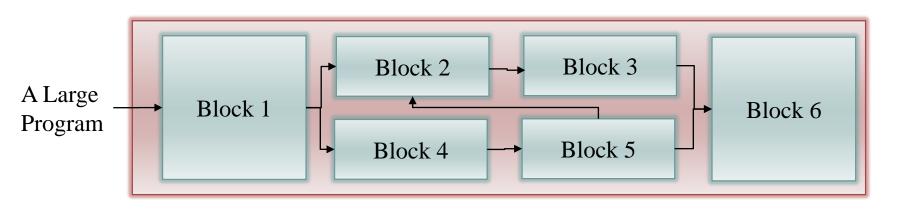


### Overall Structure of WCET Analisis



### **Basic Blocks**

- Beginning of Basic Blocks
  - The first instruction
  - The targets of un/conditional jumps
- Ending of Basic Block
  - The basic block consists of the block beginning and runs until the next block beginning (exclusive) or until the program ends



## Value Analysis

#### Motivation

- Provide access information to data-cache/pipeline analysis
- Detect infeasible paths
- Derive loop bounds

#### Method

- Calculate intervals at all program points
- Consider addresses, register contents, local/global variables

### Abstract Interpretation

 Perform the program's computation using value descriptions or abstract values in place of the concrete values

### **Abstract Interpretation**

#### Abstract Domain

- Replace an integer/double operator by using intervals
- For example, L = [3,5] stands for L is a value between 3 and 5

#### Abstract Transfer

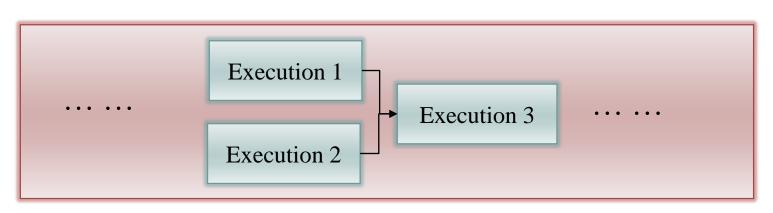
- For example, operator +: [3, 5] + [2, 6] = [5, 11]
- For example, operator -: [3, 5] [2, 6] = [-3, 3]

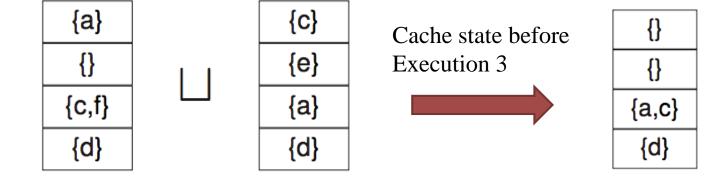
### Join Combining

- For example, [a, b] join [c, d] becomes  $[\min\{a, c\}, \max\{b, d\}]$
- That is, [3, 5] join [2, 4] becomes [2, 5]

# A Case Study with LRU: Join Management

Program
Execution





### **Pipelines**

- An instruction execution consists of several sequential phases, e.g.,
  - Fetch
  - Decode
  - Execute
  - Write Back

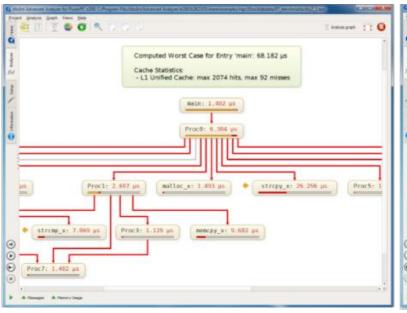
Inst 1	Inst 2	Inst 3	Inst 4
Fetch			
Decode	Fetch		
Execute	Decode	Fetch	
Write Back	Execute	Decode	Fetch
	Write Back	Execute	Decode
		Write Back	Execute
			Write Back

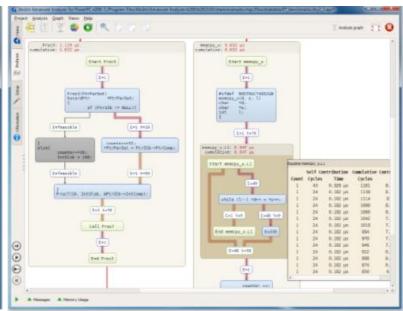
### Hardware Features of Pipelines

- Instruction execution is split into several stages
- Several instructions can be executed in parallel
- Some pipelines can start more than one instruction per cycle: VLIW, Superscalar
- ▶ Some CPUs can execute instructions out-of-order
- Practical Problems: Hazards and cache misses
  - Data Hazards: Operands not yet available (Data Dependences)
  - Control Hazards: Conditional branch
  - Resource Hazards: Consecutive instructions use same resource
  - Instruction-Cache Hazards: Instruction fetch causes cache miss

### WCET Analysis Tools (1/2)

aiT WCET Analyzers

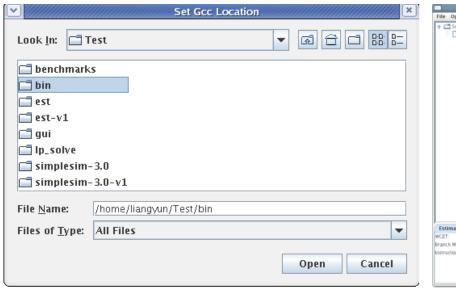


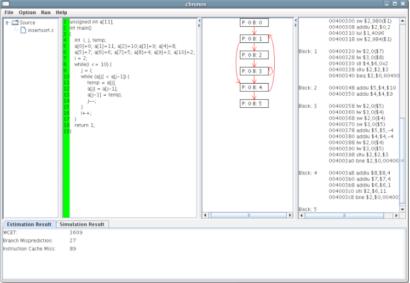


- ▶ It is not free
- https://www.absint.com/ait/

### WCET Analysis Tools (2/2)

Chronos





- ▶ It is free and open-source for academic
- But it is not stable
- http://www.comp.nus.edu.sg/~rpembed/chronos/