



Operating System Concepts

Che-Wei Chang

chewei@mail.cgu.edu.tw

Department of Computer Science and Information Engineering, Chang Gung University



Homework 4– An Real–Time OS: μ C/OS–II Quick Overview

Introduction of μ C/OS-II (1 / 2)

- ▶ The name is from micro-controller operating system, version 2
- ▶ μ C/OS-II is certified in an avionics product by FAA in July 2000 and is also used in the Mars Curiosity Rover
- ▶ It is a very small real-time kernel
 - Memory footprint is about 20KB for a fully functional kernel
 - Source code is about 5,500 lines, mostly in ANSI C
 - It's source is open but not free for commercial usages
- ▶ Preemptible priority-driven real-time scheduling
 - 64 priority levels (max 64 tasks)
 - 8 reserved for μ C/OS-II
 - Each task is an infinite loop

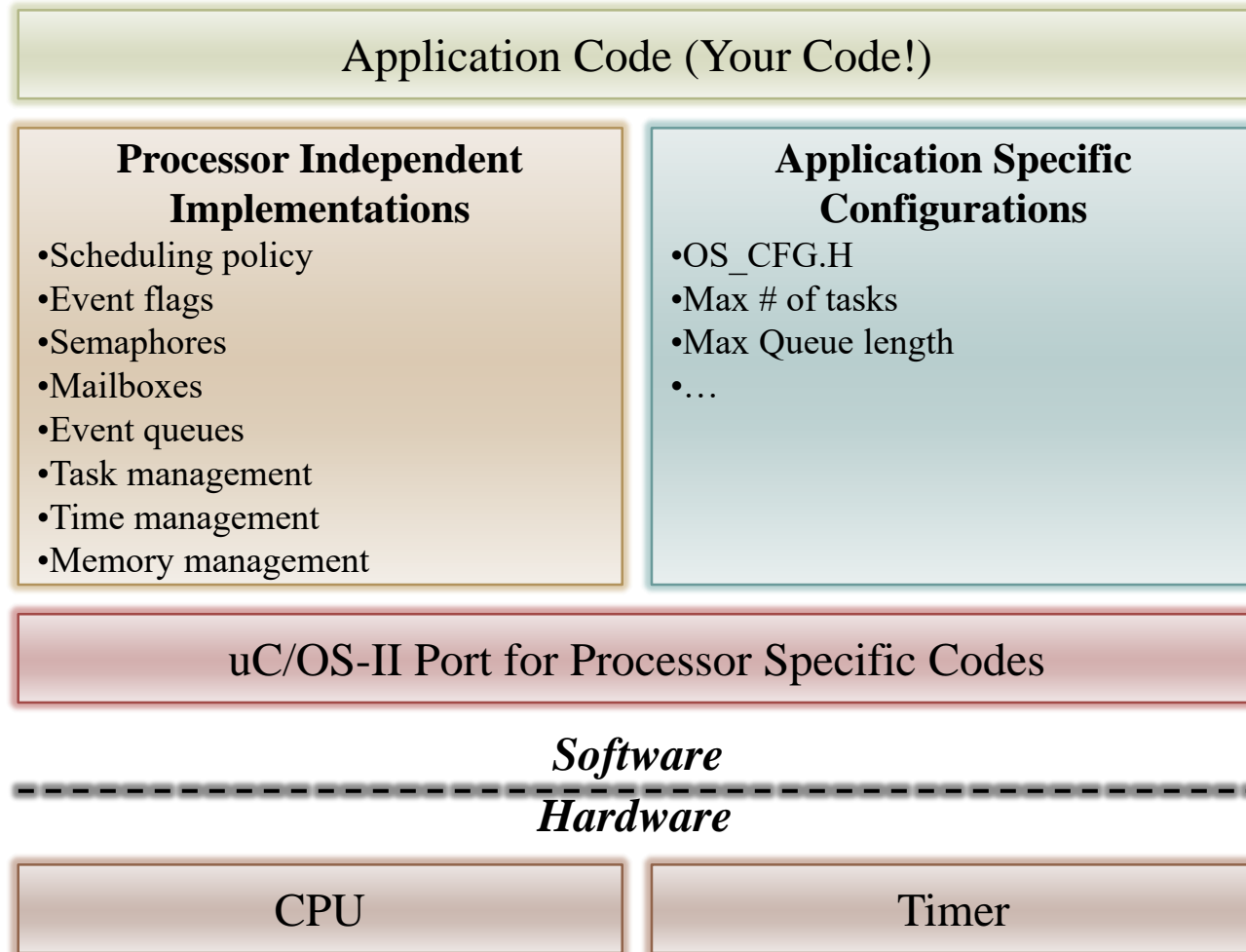


Introduction of $\mu\text{C}/\text{OS-II}$ (2 / 2)

- ▶ Deterministic execution times for most $\mu\text{C}/\text{OS-II}$ functions and services
- ▶ Nested interrupts could go up to 256 levels
- ▶ Supports of various 8-bit to 64-bit platforms: x86, ARM, MIPS, 8051, etc.
- ▶ Easy for development: Borland C++ compiler and DOS (optional)
- ▶ However, $\mu\text{C}/\text{OS-II}$ still lacks of the following features:
 - Resource synchronization protocol
 - Soft-real-time support



The μ C/OS-II File Structure



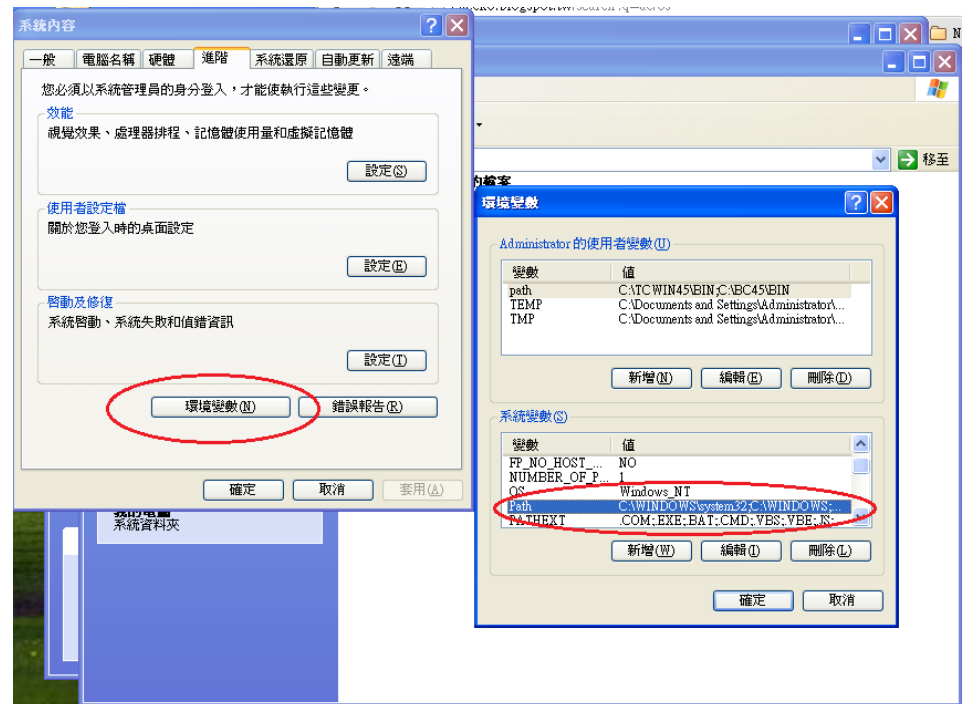
Requirements of μ C/OS-II Emulator

- ▶ Operating System
 - Windows XP 32bits
 - Use virtual machine to install the OS
 - Install “Guest Additions” for Virtualbox
- ▶ Tools
 - Borland C++ compiler (V4.5)
 - BC45 is the compiler
 - Turbo Assembler
 - The assembler is in tasm
 - The source code and the emulation environment of μ C/OS-II
 - SOFTWARE is the package
- ▶ Full Package
 - Download it from the course website with password: csie2020
 - https://www.csie.cgu.edu.tw/~chewei/files/ucOSII_ProjectPackage.zip
 - <https://www.csie.cgu.edu.tw/~chewei/files/Files.zip>



Borland C++ Compiler

- ▶ Download Borland C++ and install it on your windows XP environment
 - Double click the “INSTALL.EXE”
- ▶ Add “;C:\BC45\BIN” to your system Path



Turbo Assembler

- ▶ Download Turbo assembler and unzip the file
- ▶ Copy “\tasm\BIN\TASM.EXE” to your “C:\BC45\BIN”
 - Include the missing assembler which is going to be used during we compile the source code of μ C/OS-II



Compile μ C/OS-II Example Code

- ▶ Download the source code and emulator μ C/OS-II
 - It is recommended to put the source code package “SOFTWARE” directly in C:\
- ▶ Test the first example
 - Execute C:\SOFTWARE\uCOS-II\EX1_x86L\BC45\TEST\TEST.EXE
 - Press ECS to leave
- ▶ Rename or remove the executable file
 - Rename TEST.EXE
- ▶ Compile the μ C/OS-II and the source code of the first example
 - Run C:\SOFTWARE\uCOS-II\EX1_x86L\BC45\TEST\MAKETEST.BAT
 - A new “TEST.EXE” will be created if we compile it successfully



Common Mistakes

- ▶ Did you directly put the package “SOFTWARE” in C:\ ?
- ▶ Have you copied the correct file “TASM.EXE” to your “C:\BC45\BIN” directory?
- ▶ Did you set the Path correctly?
 - See the picture in Page 7
 - There is no space



An Example on μ C/OS-II: Multitasking

```
C:\uCOS-II\EX1_x86L\BC45\TEST\TEST.EXE
uC/OS-II, The Real-Time Kernel
Jean J. Labrosse

EXAMPLE #1

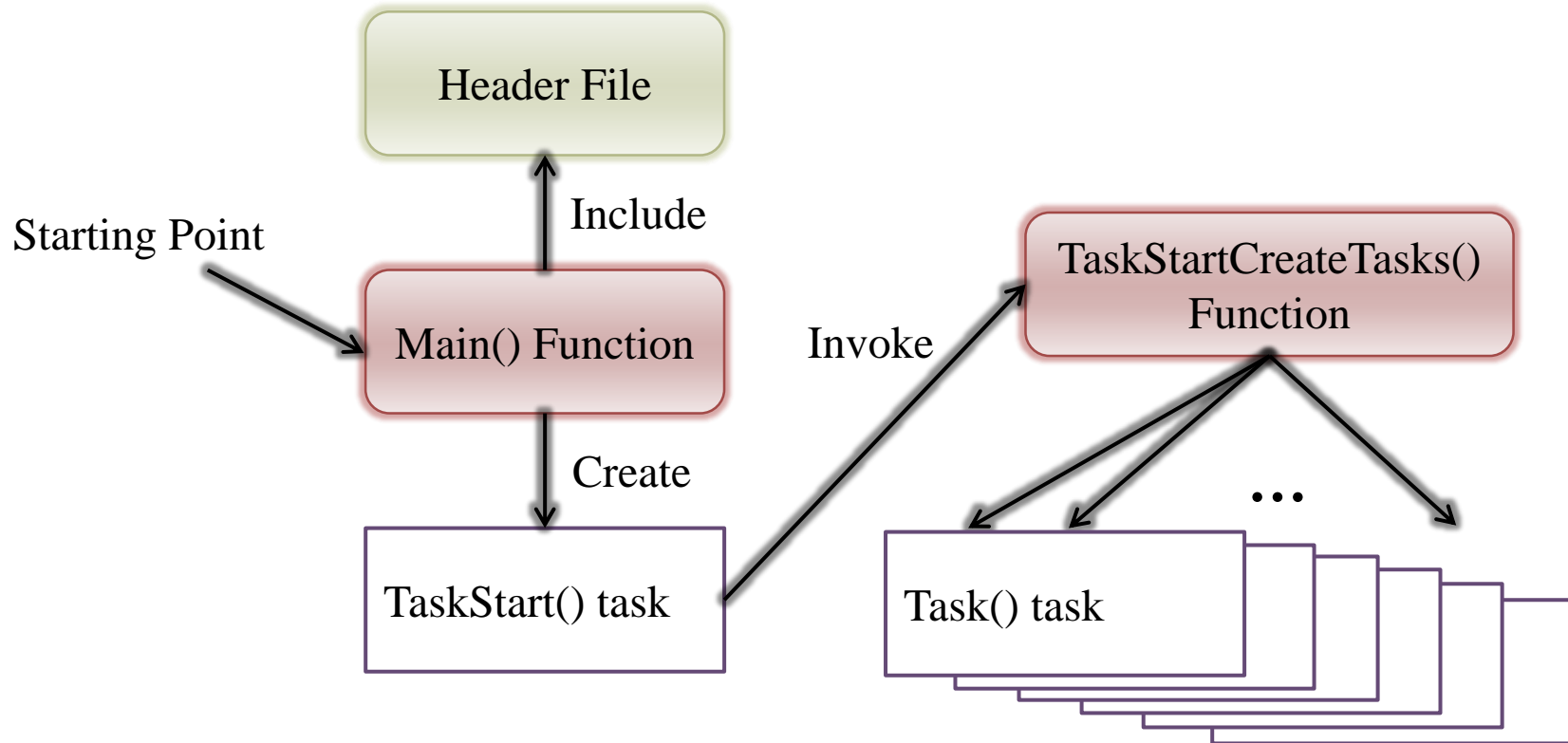
89116946172338525924079161200809680987546685223383412430562925283669250986343296
98422567751237719507656726175432412646318347491404672986312193962508036750506500
04198306651530328553114431544122365187318809730898007032272399672715650027363877
57693215933181639000816383274172546796339696111557231414036618916971167518052446
87167977628059531803062385498234324352909549230869288780517833713356812324910844
96076151657952095287797253242289346735963213862384059119369240826117079207048124
50287066314799080679735361291095736391568112369038700652374490934441706826730486
61653657628409302678221532201608795402893009143966646754749821505618818172743185
69560935200252403260849523760678265258404164088907314547748669211659483772199335
93691897099525014271788073000297334093355784200017645649344251375360001363268941
18413755595752132896946275817959024606461504024548855195345717704064029146502579
39135305037668501128487345021325236456554775525487387983679011227017745698622484
30331999915088898309710170652257536915600865755306746584310036105462443846286550
39453956761639757584971051539474995717314131408143522623578458454231281632586097
18641620203503855873907334096429674516982716819162572865737179140288485548441608
97238519699005928503612250283693854016620169262553618397402481204447485872954996

#Tasks      : 13 CPU Usage: 0 % 80387 FPU
#Task switch/sec: 2191
<-PRESS 'ESC' TO QUIT-> V2.52
```

- ▶ Three system tasks
- ▶ Ten application tasks randomly prints its number



Multitasking: Workflow



Multitasking: TEST.C

(\SOFTWARE\uCOS-II\EX1_x86L\BC45\SOURCE\TEST.C)

```
#include "includes.h"
```

```
/*
```

```
*****
```

```
CONSTANTS
```

```
*****
```

```
*/
```

```
#define TASK_STK_SIZE 512
```

```
#define N_TASKS 10
```

```
/*
```

```
*****
```

```
VARIABLES
```

```
*****
```

```
*/
```

```
OS_STK TaskStk[N_TASKS][TASK_STK_SIZE];
```

```
OS_STK TaskStartStk[TASK_STK_SIZE];
```

```
char TaskData[N_TASKS];
```

```
OS_EVENT *RandomSem;
```



Multitasking: Main()

```
void main (void)
```

```
{
```

```
    PC_DisPClrScr(DISP_FGND_WHITE + ISP_BGND_BLACK);
```

```
    OSInit();
```

```
    PC_DOSSaveReturn();
```

```
    PC_VectSet(uCOS, OSCtxSw);
```

```
    RandomSem = OSSemCreate(1);
```

```
    OSTaskCreate( TaskStart,
```

Top of stack

```
    (void *)0,
```

Entry point of the task
(a pointer to a function)

User-specified data

```
    (void *)&TaskStartStk[TASK_STK_SIZE-1],
```

Priority (0=highest)

```
    0);
```

```
    OSStart();
```

```
}
```



Multitasking: TaskStart()

```
void TaskStart (void *pdata)
```

```
{
```

```
    /*skip the details of setting*/
```

```
    OSStatInit();
```

```
    TaskStartCreateTasks();
```

```
    for (;;)
    {
```

```
        if (PC_GetKey(&key) == TRUE)
```

```
        {
```

```
            if (key == 0x1B) { PC_DOSReturn(); }
```

```
        }
```

```
        OSTimeDlyHMSM(0, 0, 1, 0);
```

```
    }
```

```
}
```

Call the function to
create the other tasks

See if the ESCAPE
key has been pressed

Wait one second



Multitasking:

TaskStartCreateTasks()

```
static void TaskStartCreateTasks (void)
```

```
{
```

```
    INT8U i;
```

```
    for (i = 0; i < N_TASKS; i++)
```

```
    {
```

```
        TaskData[i] = '0' + i;
```

```
        OSTaskCreate(
```

```
            Task,
```

```
            (void *)&TaskData[i],
```

```
            &TaskStk[i][TASK_STK_SIZE - 1],
```

```
            i + 1 );
```

```
    }
```

```
}
```

Entry point of the task
(a pointer to function)

Argument:
character to print

Top of stack

Priority



Multitasking: Task()

```
void Task (void *pdata)
```

```
{
```

```
    INT8U x;
```

```
    INT8U y;
```

```
    INT8U err;
```

```
    for (;;)
    {
```

```
        OSSemPend(RandomSem, 0, &err);
```

```
        /* Acquire semaphore to perform random numbers */
```

```
        x = random(80);
```

```
        /* Find X position where task number will appear */
```

```
        y = random(16);
```

```
        /* Find Y position where task number will appear */
```

```
        OSSemPost(RandomSem);
```

```
        /* Release semaphore */
```

```
        PC_DisgChar(x, y + 5, *(char *)pdata, DISP_FGND_BLACK +DISP_BGND_LIGHT_GRAY);
```

```
        /* Display the task number on the screen */
```

```
        OSTimeDly(1);
```

```
        /* Delay 1 clock tick */
```

```
    }
```

```
}
```

Randomly pick up the position to print its data

Print & delay



OSinit()

(\SOFTWARE\uCOS-II\SOURCE\OS_CORE.C)

- ▶ Initialize the internal structures of μ C/OS-II and MUST be called before any services
- ▶ Internal structures of μ C/OS-2
 - Task ready list
 - Priority table
 - Task control blocks (TCB)
 - Free pool
- ▶ Create housekeeping tasks
 - The idle task
 - The statistics task



PC_DOSSaveReturn()

(\SOFTWARE\BLOCKS\PC\BC45\PC.C)

- ▶ Save the current status of DOS for the future restoration
 - Interrupt vectors and the RTC tick rate
- ▶ Set a global returning point by calling setjump()
 - μ C/OS-II can come back here when it terminates.
 - PC_DOSReturn()



PC_VectSet(uCOS,OSCtxSw)

(\SOFTWARE\BLOCKS\PC\BC45\PC.C)

- ▶ Install the context switch handler
- ▶ Interrupt 0x08 (timer) under 80x86 family
 - Invoked by INT instruction



OSStart()

(SOFTWARE\uCOS-II\EX1_x86L\BC45\SOURCE\CORE.C)

- ▶ Start multitasking of μ C/OS-II
- ▶ It never returns to main()
- ▶ μ C/OS-II is terminated if PC_DOSReturn() is called



Report

1. The steps for your implementation
 2. The problem you met, and how you solved it
 3. **The reference of this homework**
- The report is limited within 4 pages in PDF



Extra Exercise

- ▶ Read the e-book of μ C/OS-II
 - Try to read and understand the first chapter
- ▶ Read the source code to understand the application
 - The application source code is in C:\SOFTWARE\uCOS-II\EX1_x86L\BC45\SOURCE
- ▶ Browse the source code of μ C/OS-II
 - The source code of μ C/OS-II is in C:\SOFTWARE\uCOS-II\SOURCE
- ▶ 準時繳交且實作完成第九頁的內容，提供截圖或相關說明 ➔ 標準分數為80正負10分
- ▶ 有做Extra Exercise，並寫入報告心得且說明精確者最多加20分



Grading

- ▶ Implementation
 - Install the environment for running $\mu\text{C}/\text{OS-II}$ 30%
 - Compile and run the first example 30%
- ▶ Report
 - 20%
- ▶ Bonus
 - Extra exercise 20%
- ▶ Demo Q&A
 - 20%



Submission

- ▶ Homework 4 deadline: at 20:00 on 2022-12-13
➔NO DELAY!
- ▶ Upload to e-learning system
- ▶ The title of the report: OSHomework4StudentID
- ▶ **Point deduction for wrong format: 10%**

➔DEMO will be arranged!

