

Pathways of light and colour

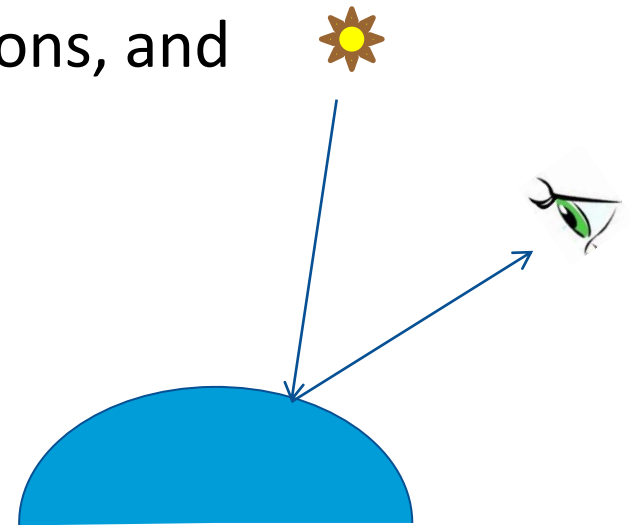
8 Ray Tracing



Department of Computer Science and Software Engineering
University of Canterbury, New Zealand.

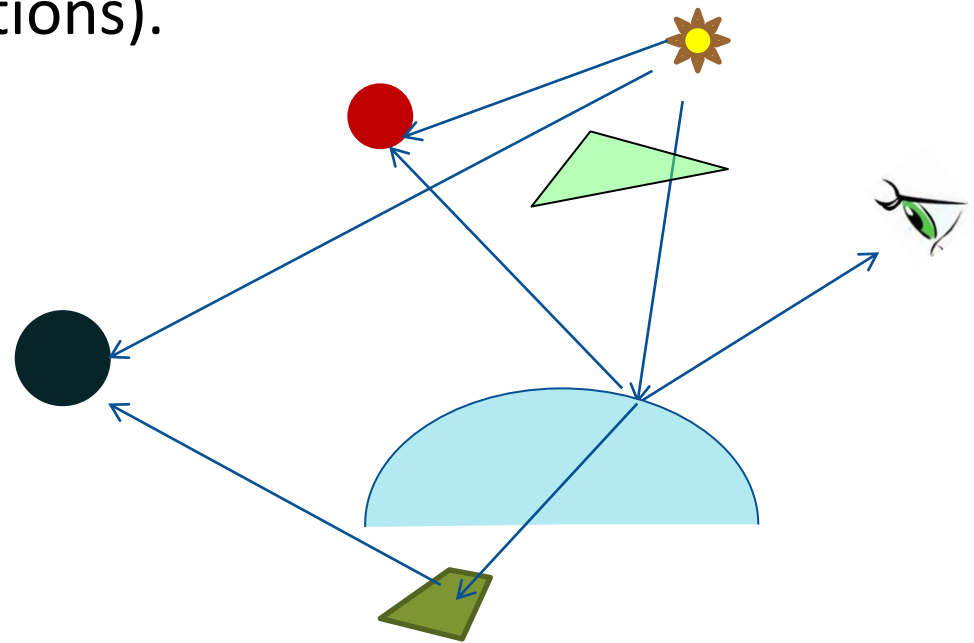
Local Illumination Model

- A local illumination model considers only light travelling from a light source to a surface and then reflected off the surface to the eye.
 - Requires only the light source coordinates, local surface geometry and the material characteristics at a vertex.
 - Suitable for the hardware pipeline (OpenGL, Direct3D)
- Does not consider occlusions, reflections, and transmittance of light.



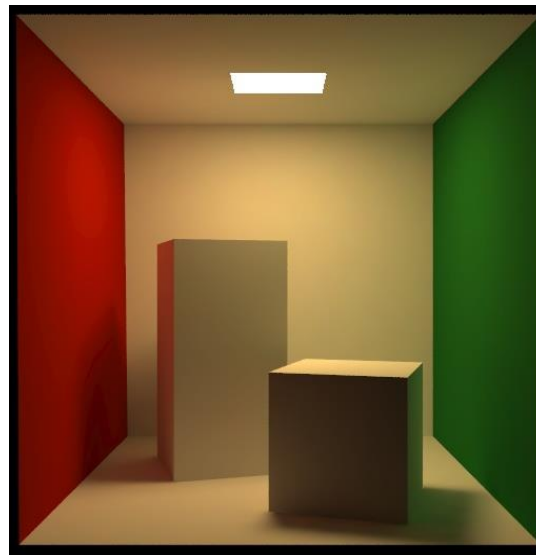
Global Illumination

- The illumination at a given point is a combination of the light received from a source and the light reflected from other surfaces in the scene.
- Considers the effects of occlusions (shadows) surface reflections, light transmission through a medium (direct transmittance and refractions).



Global Illumination Methods

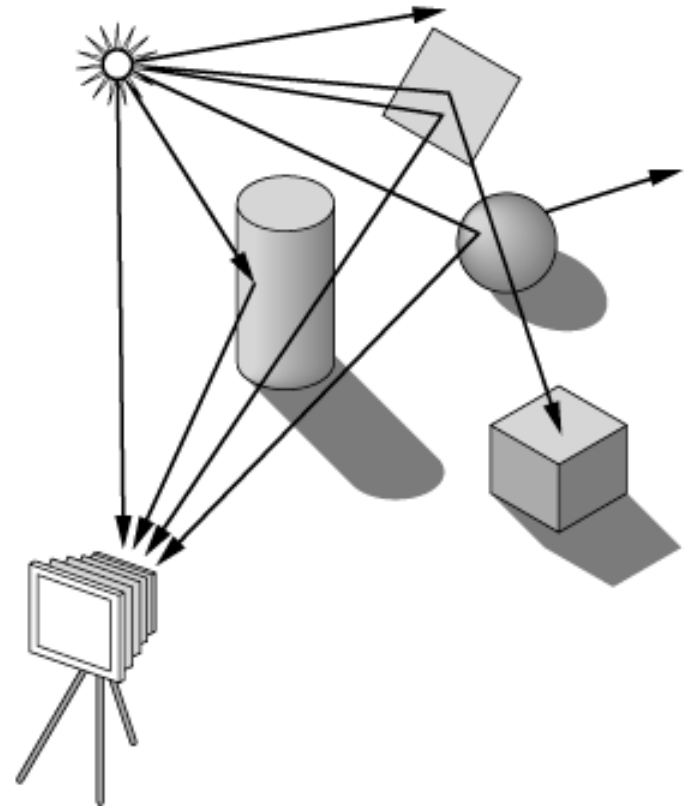
- Radiosity
 - A scene illumination can be considered as an equilibrium state for radiant energy transfers between surface elements.
 - Gives good results for diffuse illumination, but specularity is not handled.
 - Useful for modelling area light sources, colour bleeding, soft shadows.



'Forward' Ray Tracing

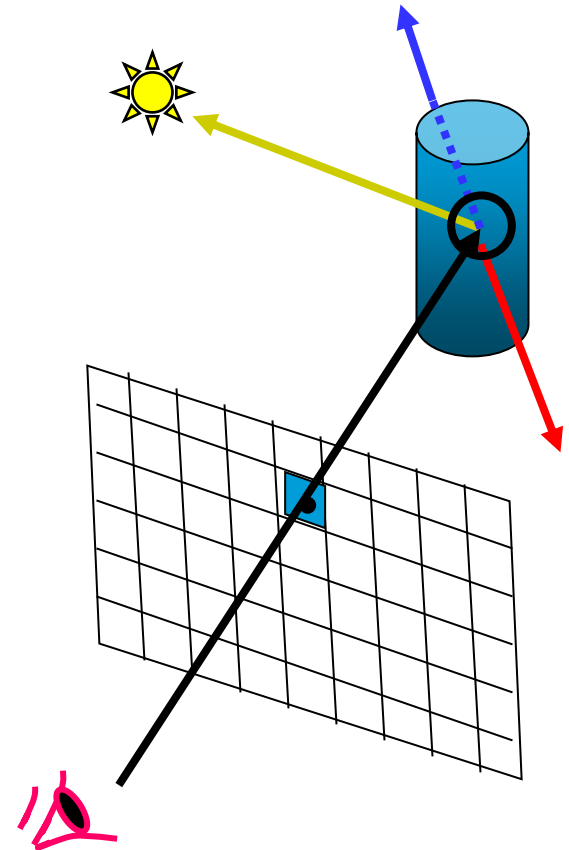
Trace rays from a light source.

- No specific limit for ray directions.
- Hardly any rays reach the eye.
- Computationally infeasible
- But a hybrid scheme called *photon mapping* can be used
 - Forward ray trace from light source
 - Record photon hits
 - Then, to render image:
 - Backward trace from eye
 - Get colour from photon hit density



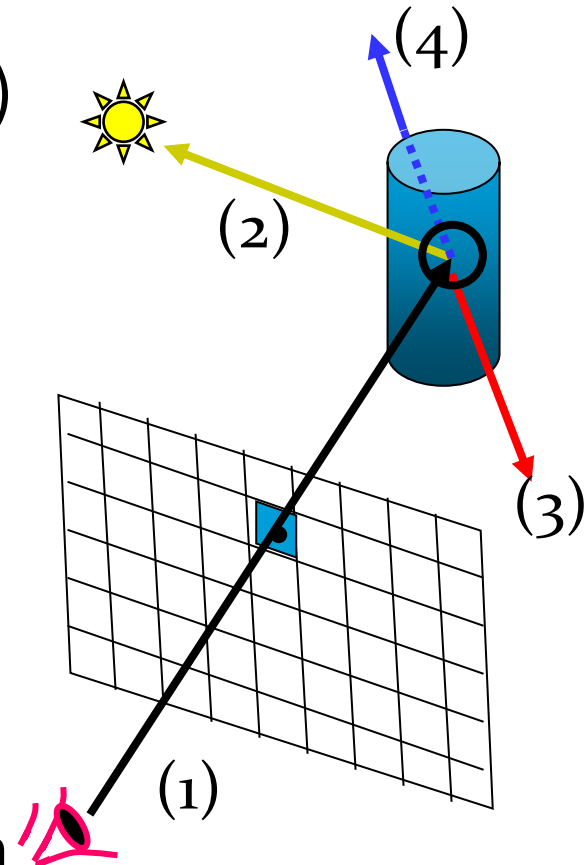
Ray Tracing (Backward Ray Tracing)

- Traces ray outwards from the eye to objects and light sources. The opposite of reality.
- Use secondary rays to determine shadows and to model mirror reflection and refraction
- Easy way to get many global illumination effects
- But:
 - Doesn't handle diffuse inter-reflections
 - e.g. “colour bleed” from red wall to adjacent white wall
 - Computationally expensive



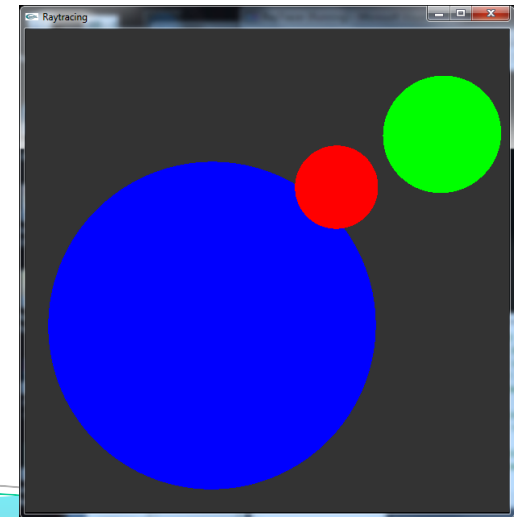
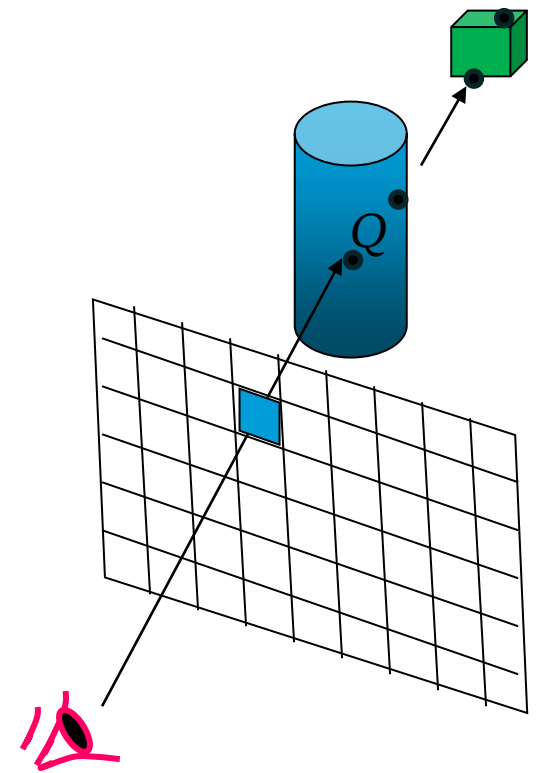
Ray Tracing: Basic Steps

- Define a “virtual screen” and eye position
- Trace rays from eye through each “pixel” (1)
- Compute the closest point of intersection (Ray casting)
- Apply an illumination model at the point of intersection.
- Trace a shadow ray to determine if the point is in shadow (2)
- If the surface is reflective, trace a reflected ray (3)
- If the surface is refractive, trace a refraction ray (4)
- Add contributions from (3) and (4).



Ray Casting

- Ray tracing without secondary rays.
- Trace a ray from the view point (called the primary ray) through each “pixel” on the image plane
 - Test each surface to determine if it is intersected by the ray.
 - Compute the points of intersection on each primary ray.
 - Get the point of intersection Q that is closest to the eye.
 - Use the colour of the object on which Q lies as pixel colour.



Ray Casting + Phong Lighting

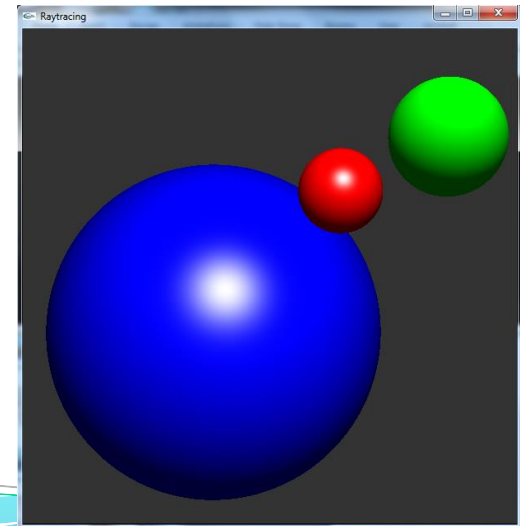
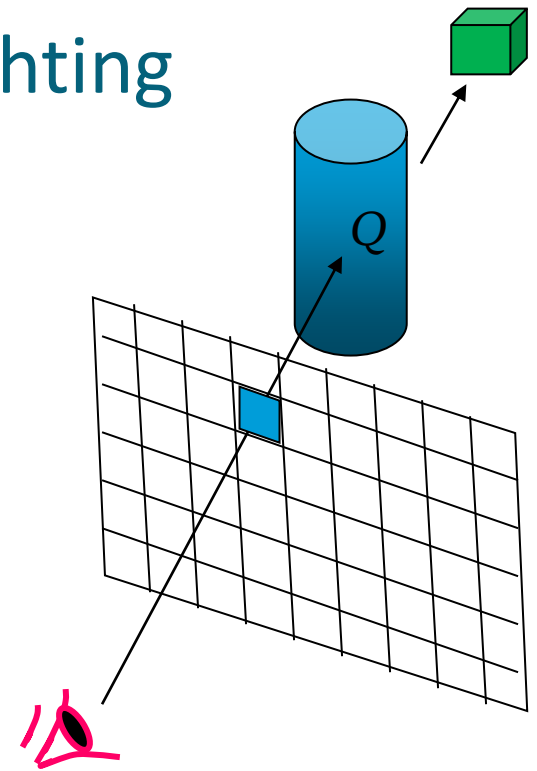
- Still without secondary rays.
- At the point of intersection Q , recompute the colour value using an illumination model.
- Simplified Phong Illumination:

B = Background Color = (0.2, 0.2, 0.2)

M = Material Color (ambient and diffuse)

Light's diffuse color = Light's specular color = Material's specular color = (1, 1, 1)

$$\text{Col} = BM + M (L \bullet N) + (1, 1, 1) (R \bullet V)^f$$



Shadow Ray

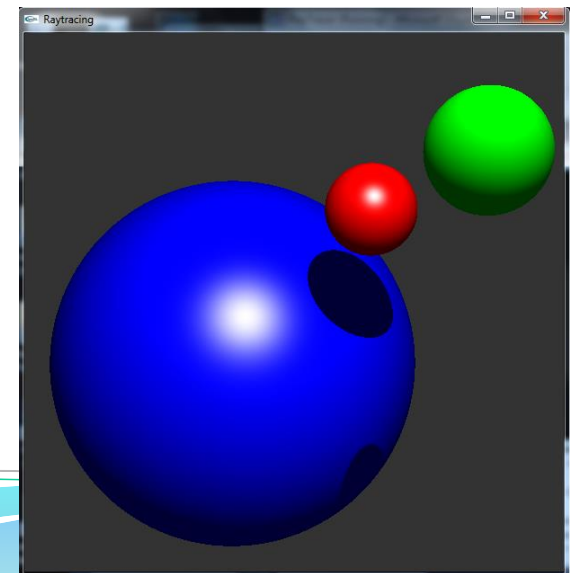
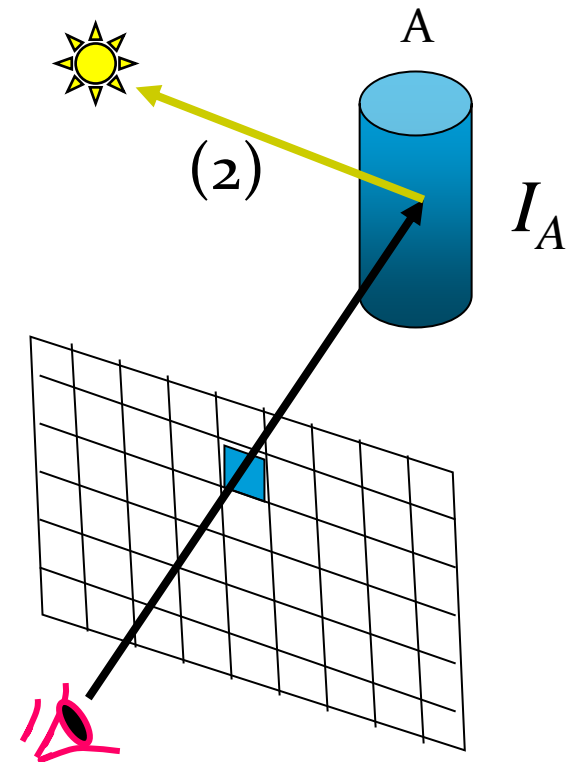
- Trace a ray from the point of intersection towards the light source (2)
- Colour I_A of object A determined using Phong model (previous slide)
- If the shadow ray hits an object, and if the point of intersection is between the light source and the object A, then apply only the ambient contribution of light to Q.

If Q is in shadow

$$I_A = \text{BM}$$

Else

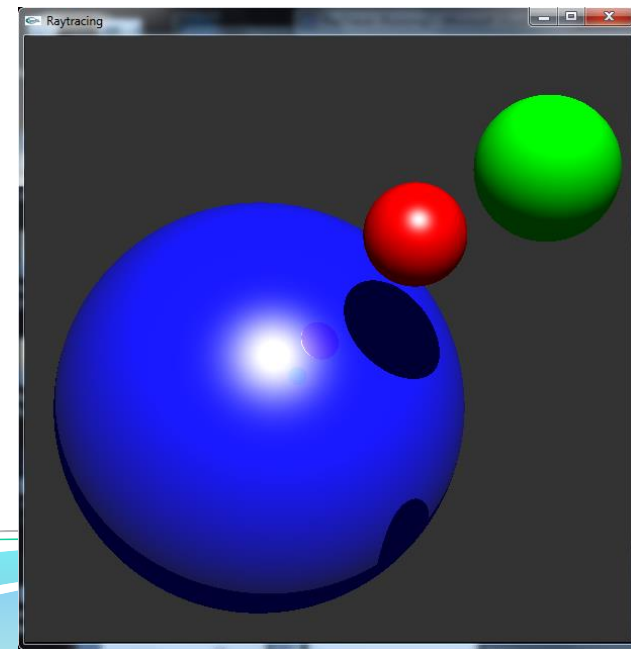
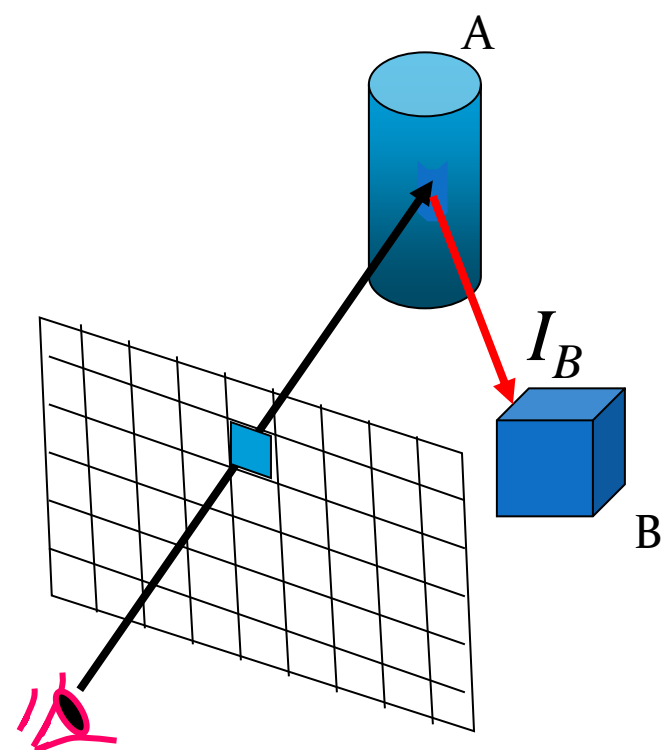
$$I_A = \text{BM} + M (\mathbf{L} \cdot \mathbf{N}) + (1, 1, 1) (\mathbf{R} \cdot \mathbf{V})^f$$



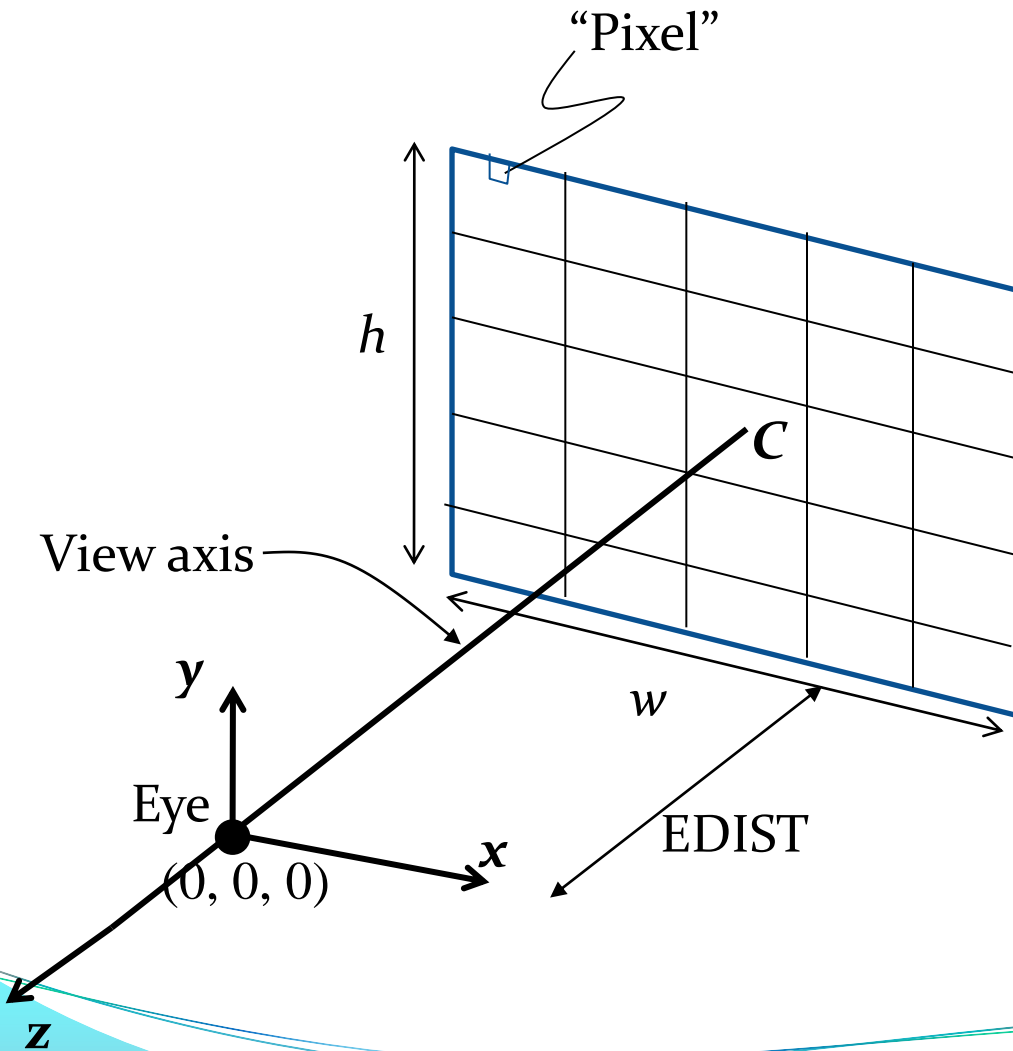
Reflections

- If the surface is reflective, then a secondary ray along the direction of reflection is traced.
- If this secondary ray meets a surface at a point with intensity I_B , then $\rho_r I_B$ is added to the pixel color
 - ρ_r is a scale factor (<1), called the coeff. of reflection
 - ρ_r represents how much of colour I_B is reflected on the surface A.
- The colour of the pixel is now

$$I = I_A + \rho_r I_B$$



Ray Tracing Setup



w = Width of screen in world units (eg. 5 units).

h = Height of screen in world units (eg. 5 units).

$EDIST$ = Eye dist in world units (eg. 10 units)

PPU = Pixels per unit (eg. 100)

$XMIN = -w/2$; $XMAX = w/2$;

$YMIN = -h/2$; $YMAX = h/2$;

Primary Ray

$i : 0 \dots w * PPU - 1$

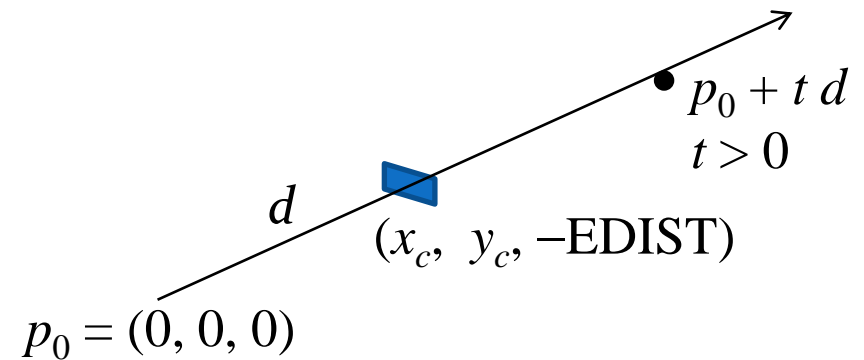
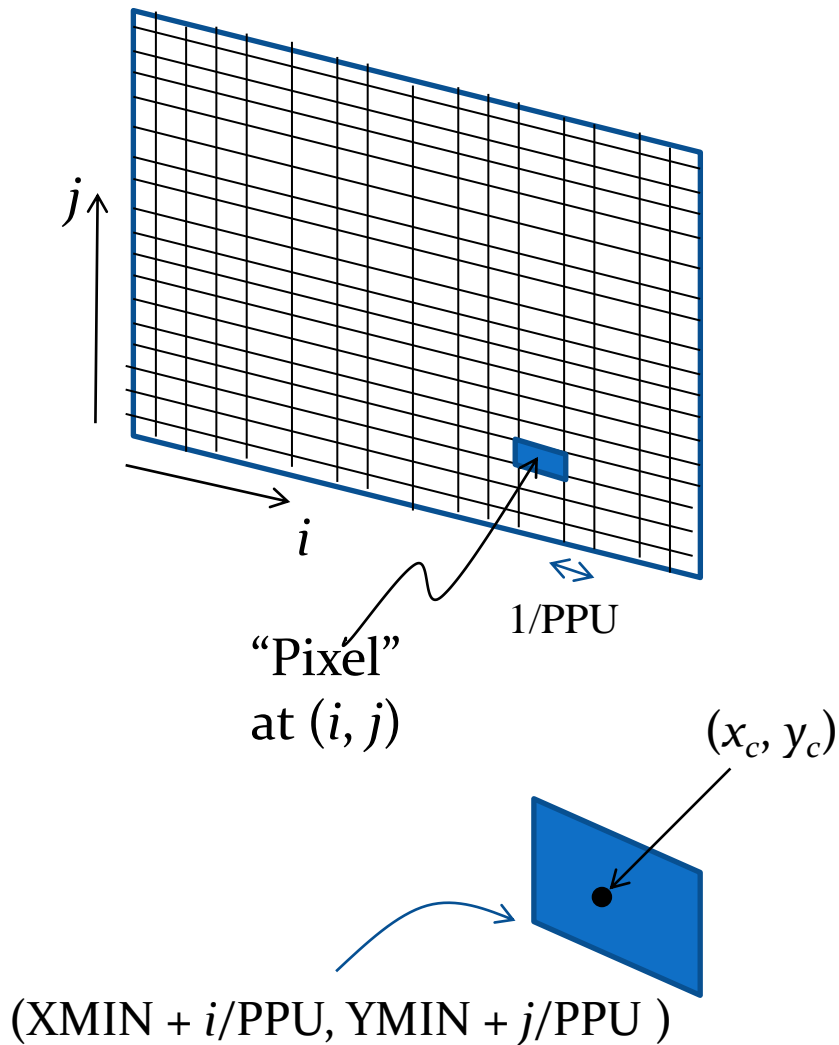
$j : 0 \dots h * PPU - 1.$

Primary ray:

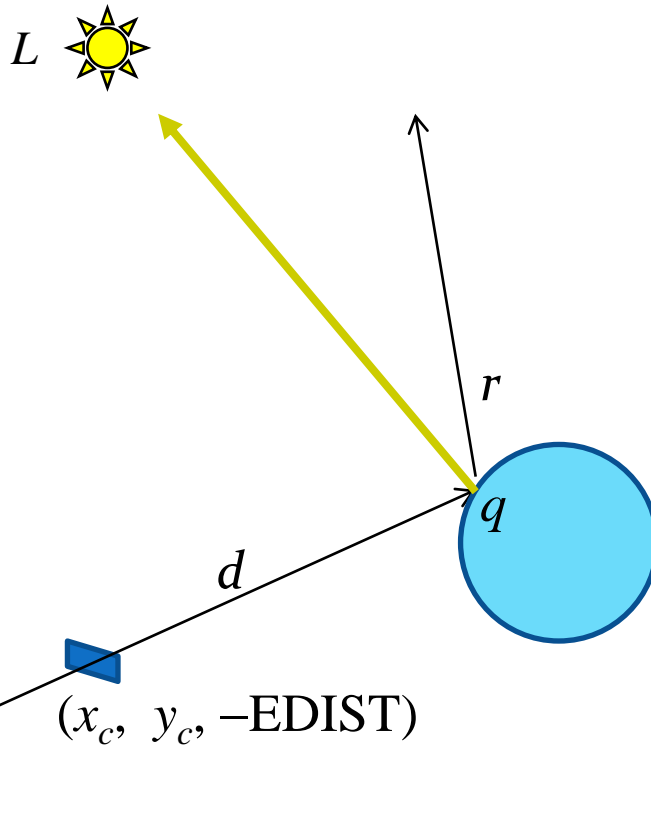
Position $p_0 = (0, 0, 0)$

Direction $d = (x_c, y_c, -EDIST)$

(Always normalize direction!)



Secondary Rays



Shadow ray:

Position = q

Direction = $L - q$ normalized.

Reflection ray:

Position = q

Direction:

$$r = -2(d \cdot n)n + d \text{ normalized.}$$

- Every ray is specified using its point of origin, and a unit vector denoting its direction.
- Any point on the ray can be represented by a single parameter $t > 0$. The distance of the point from the source of the ray is t .

Ray-plane intersection

- Given a point a on a plane, and the normal vector n of the plane, the plane's equation can be written as

$$(p - a) \bullet n = 0$$

- A ray is given by the equation

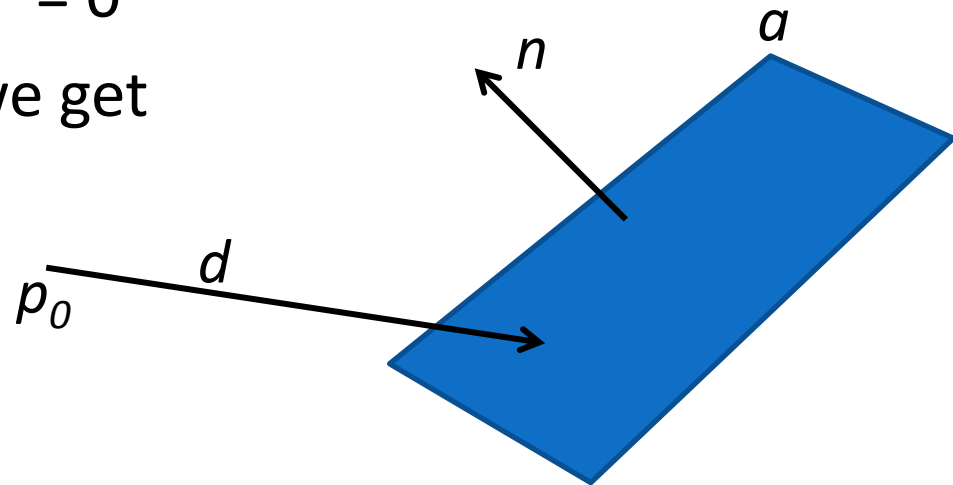
$$p = p_0 + t d.$$

- At the point of intersection, both equations are true.

Therefore, $(p_0 + t d - a) \bullet n = 0$

- From the above equation, we get

$$t = \frac{(a - p_0) \bullet n}{d \bullet n}$$



Ray-sphere intersection

- Equation of a sphere centred at C with radius r is

$$(p - C) \bullet (p - C) = r^2$$

- Consider a ray given by the equation

$$p = p_0 + t d.$$

- At the point of intersection, both equations are true.

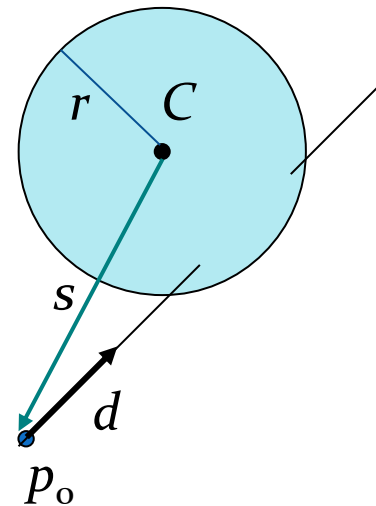
$$\text{Therefore, } (p_0 + t d - C) \bullet (p_0 + t d - C) = r^2$$

$$(s + t d) \bullet (s + t d) = r^2, \quad \text{where } s = p_0 - C$$

$$(d \bullet d) t^2 + 2 (s \bullet d) t + (s \bullet s) - r^2 = 0.$$

Since d is a unit vector, we get

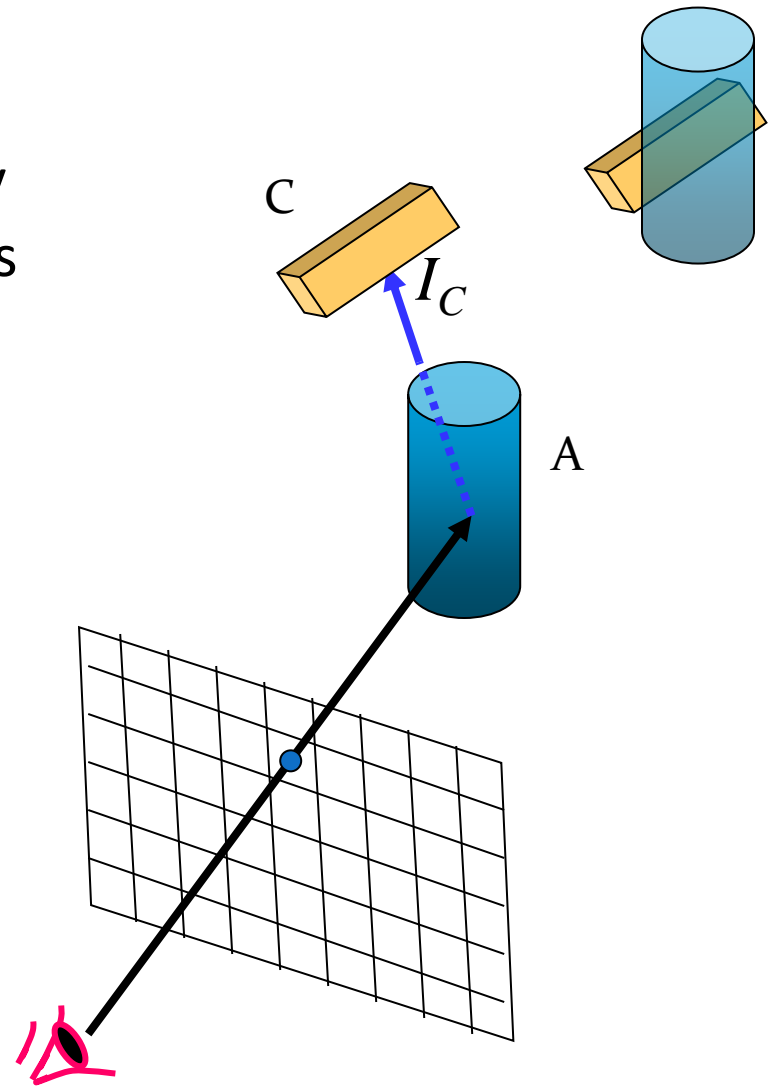
$$t = -(s \bullet d) \pm \sqrt{(s \bullet d)^2 - (s \bullet s) + r^2}$$



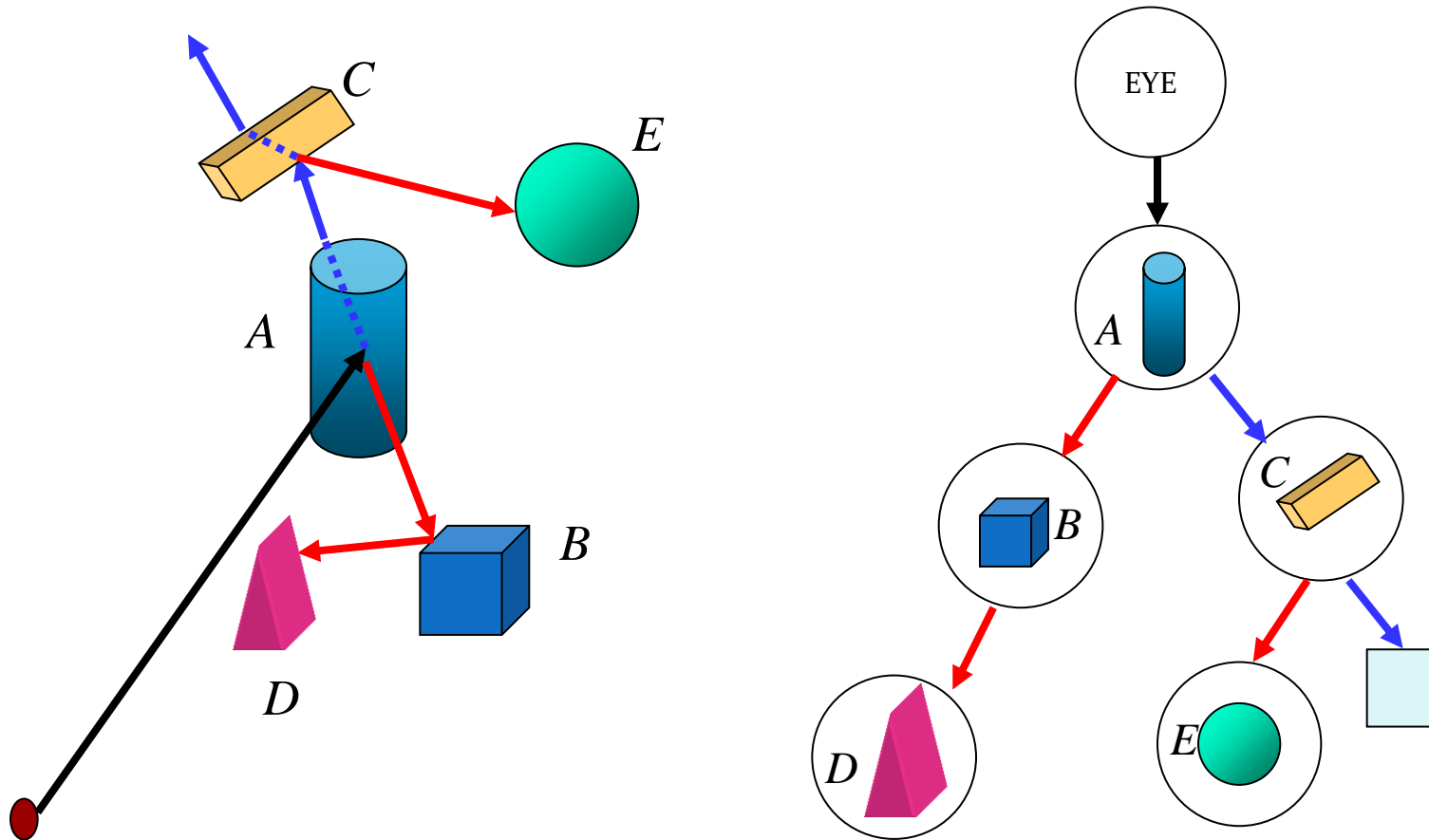
Refractions

- If the surface is transparent/translucent, a secondary ray along the direction of refraction is traced.
- If this secondary ray meets a surface at a point with intensity I_C , then $\rho_t I_C$ is added to the pixel color.
 - ρ_t is a scale factor (<1), called the coeff. of transmission
- The colour of the pixel is now

$$I = I_A + \rho_t I_C$$

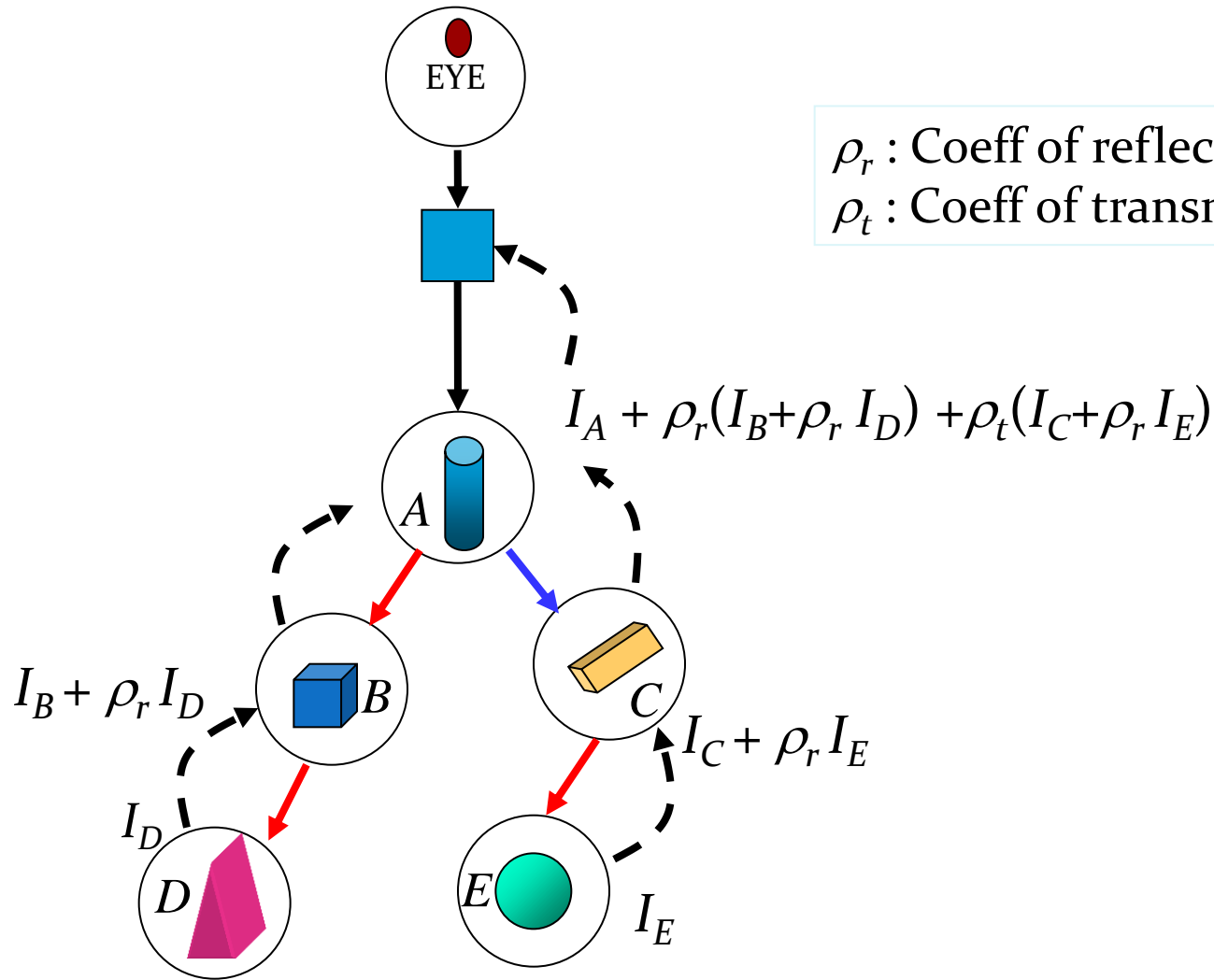


Binary Ray-tracing Tree

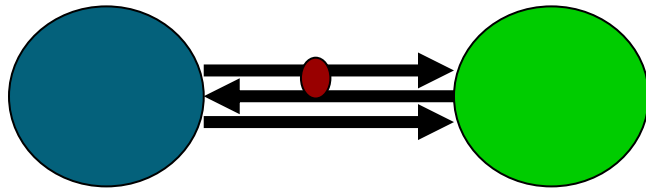


- • Left branches represent reflections
- • Right branches represent transmission paths

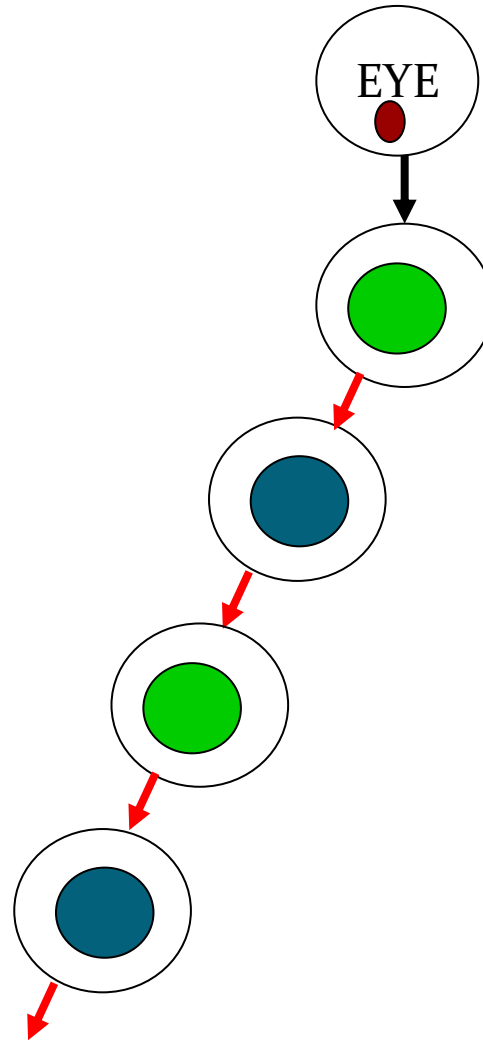
Accumulation of Intensities



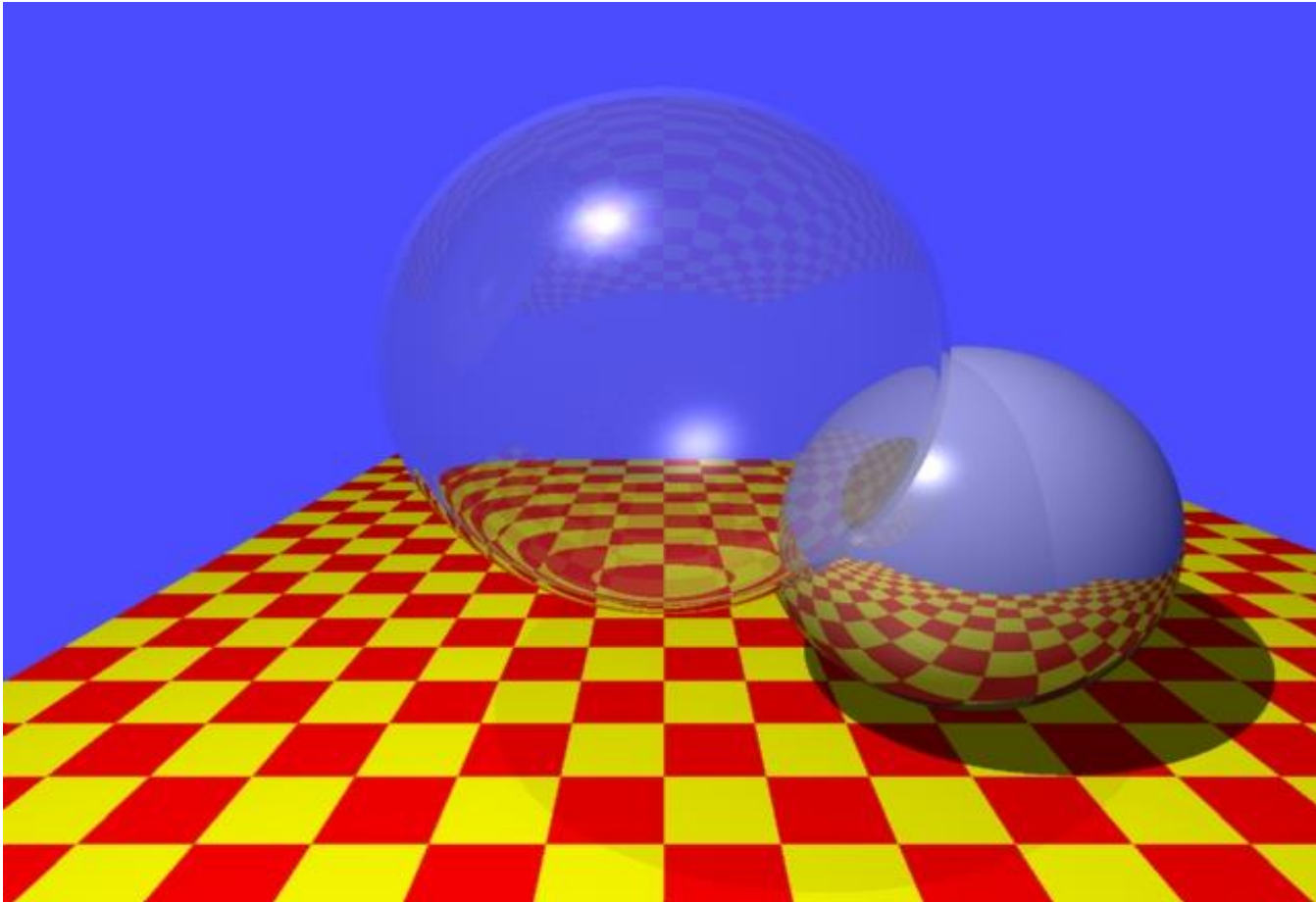
Multiple Reflections



Must limit recursion depth

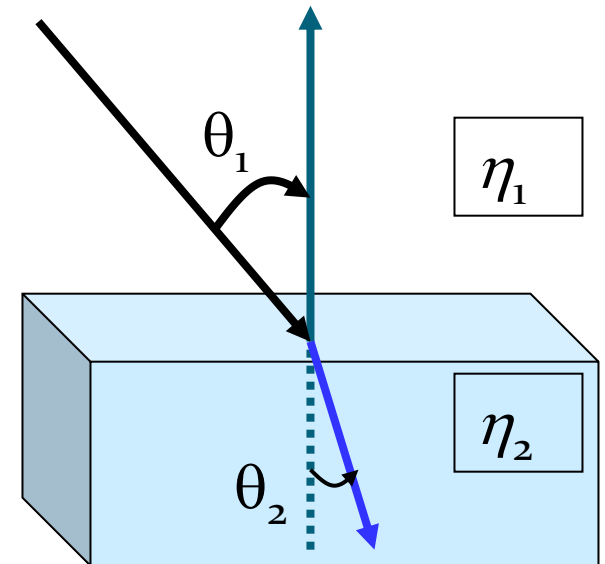


Ray Tracing: Example

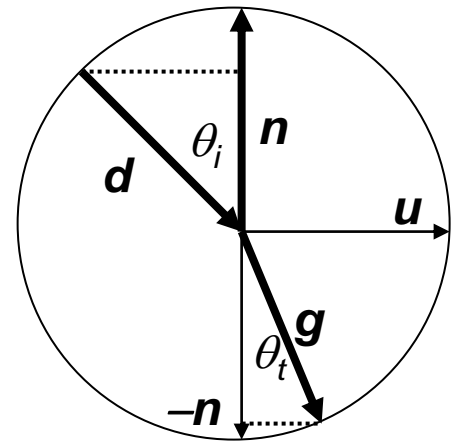
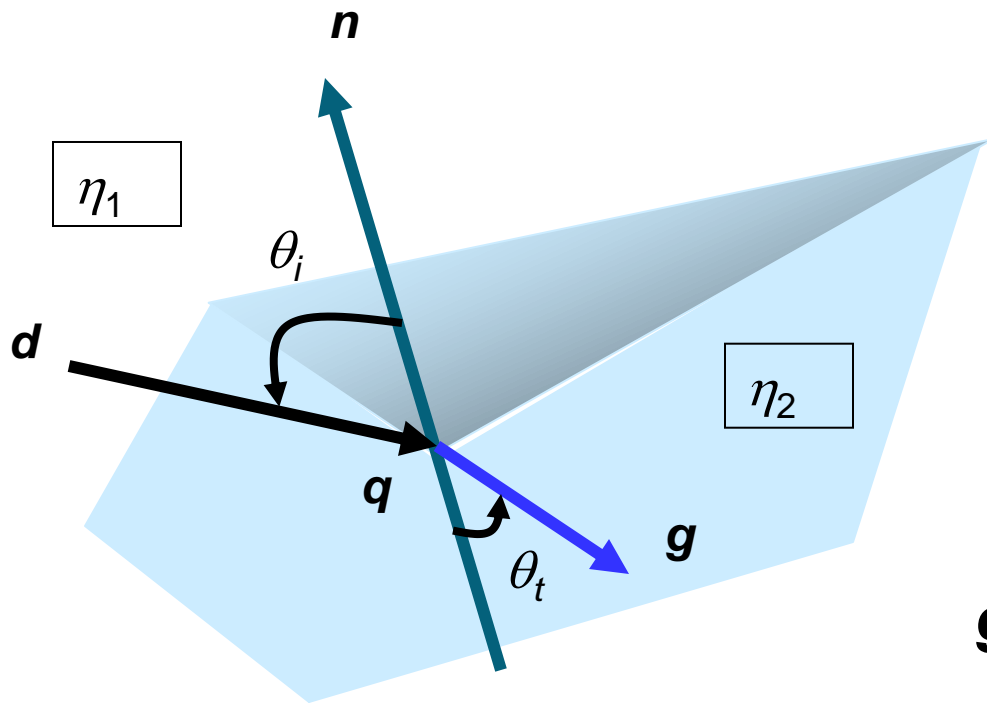


Index of Refraction

- Light travels at speed c/η in a medium with index of refraction η .
- Common values of index of refraction:
 - Air 1.
 - Water 1.33
 - Glass 1.5
 - Diamond 2.4
- Snell's Law of Refraction:
 - $\eta_1 \sin\theta_1 = \eta_2 \sin\theta_2$



Refracted Ray

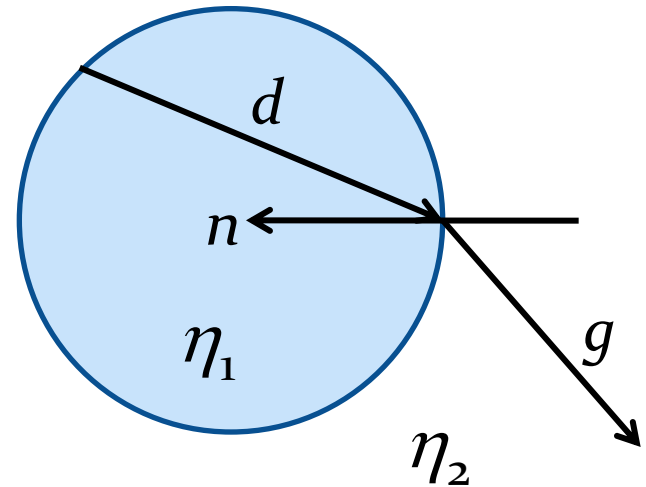
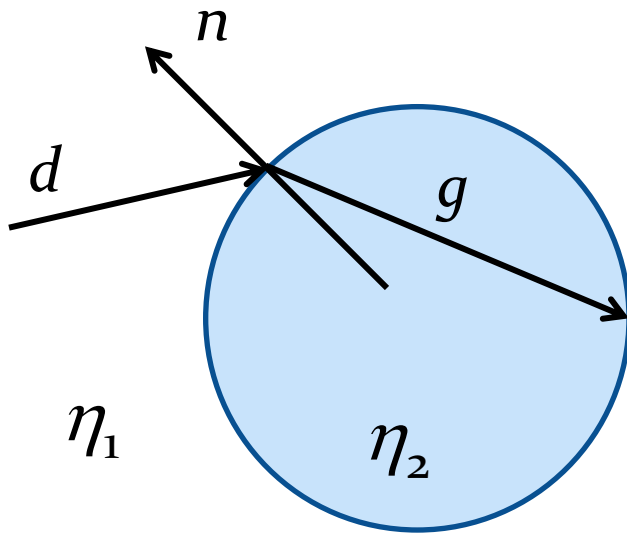


$$\begin{aligned} \mathbf{u} \sin \theta_i - \mathbf{n} \cos \theta_i &= \mathbf{d} \\ \mathbf{u} \sin \theta_t - \mathbf{n} \cos \theta_t &= \mathbf{g} \end{aligned}$$

$$\mathbf{g} = \left(\frac{\eta_1}{\eta_2} \right) \mathbf{d} - \left(\frac{\eta_1}{\eta_2} (\mathbf{d} \cdot \mathbf{n}) + \cos \theta_t \right) \mathbf{n}$$

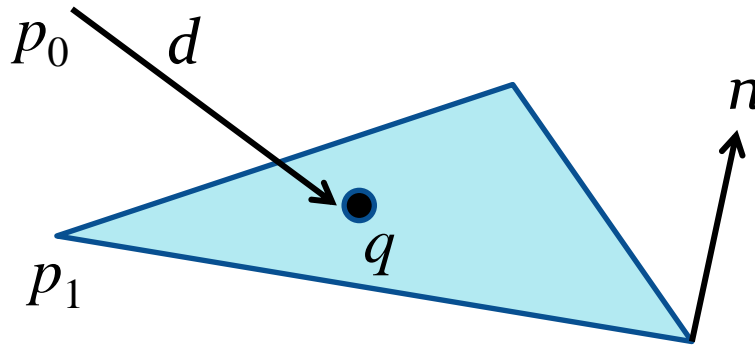
$$\cos \theta_t = \sqrt{\left(1 - \left(\frac{\eta_1}{\eta_2} \right)^2 (1 - (\mathbf{d} \cdot \mathbf{n})^2) \right)}$$

Sphere Refraction



Ray intersection with polygonal objects

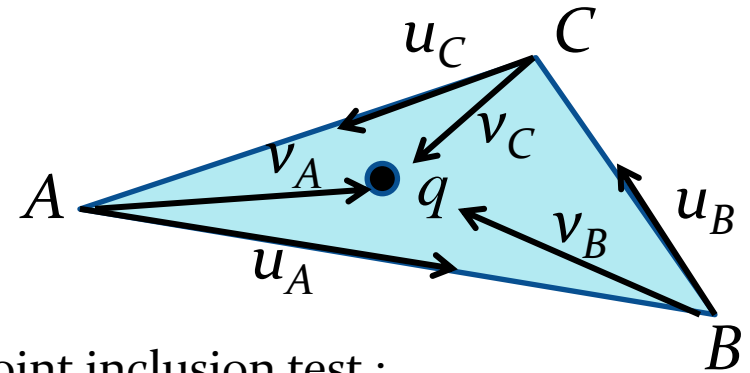
- Use the plane equation of each triangle to get the point of intersection with the ray.
- Check if the point of intersection lies within the triangle.



Intersection :

$$t = \frac{(p_1 - p_0) \cdot n}{d \cdot n}$$

$$q = p_0 + t d$$

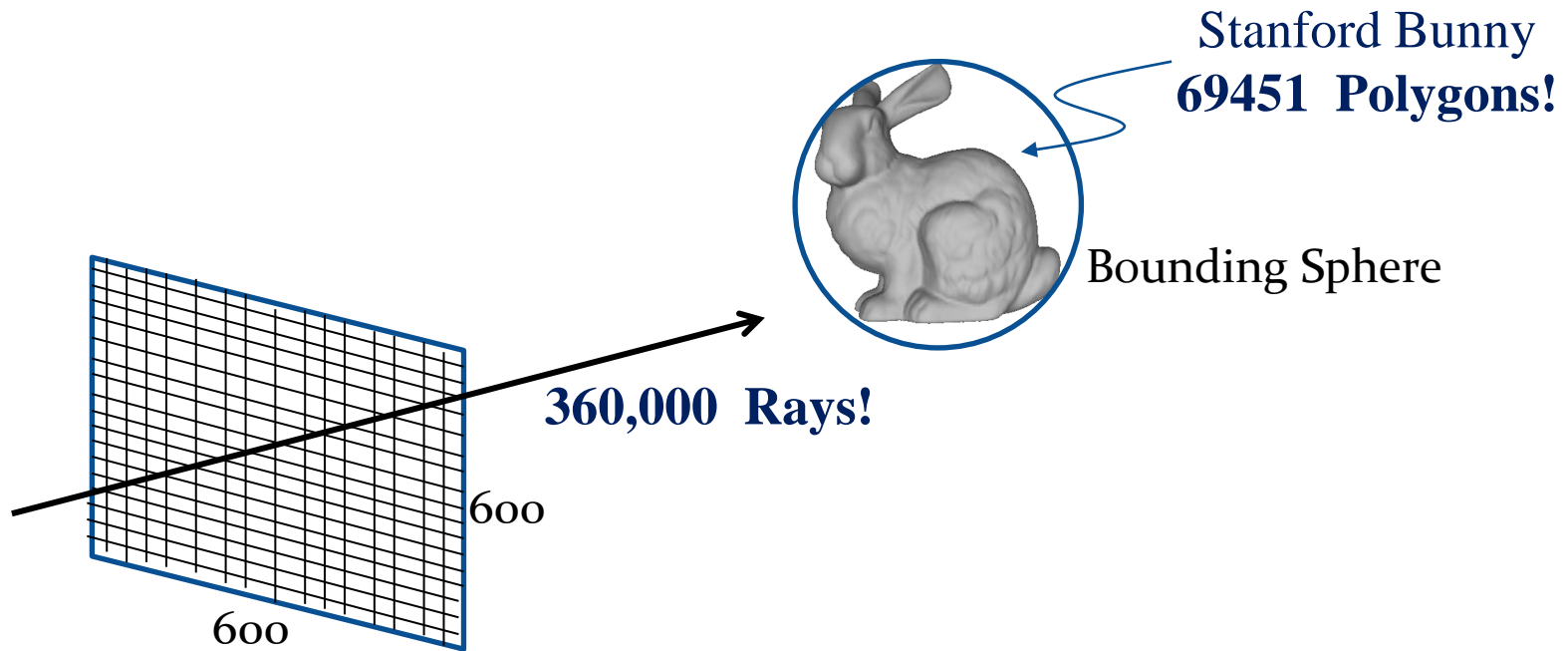


Point inclusion test :

If the cross products $(u_A \times v_A)$, $(u_B \times v_B)$, $(u_C \times v_C)$ have the same sign, then the point q is inside the triangle.

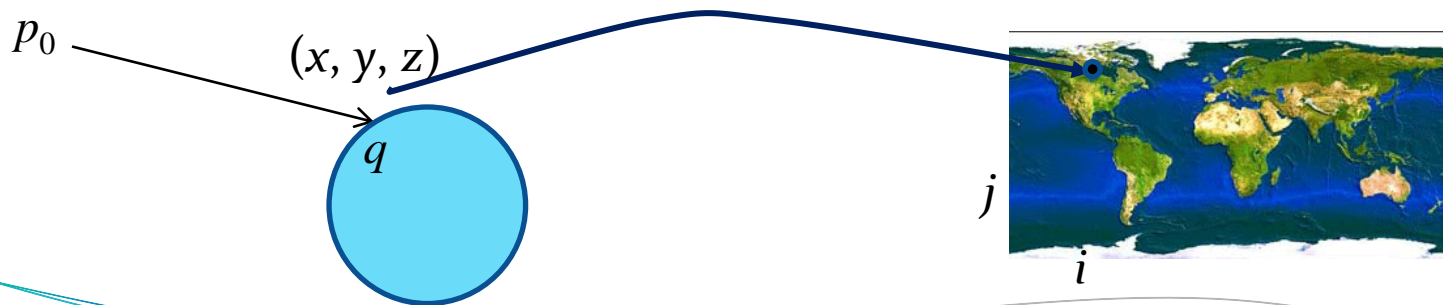
Ray intersection with polygonal objects

- Complex polygonal objects will require a large amount of ray-triangle intersection tests.
- Bounding volume hierarchies and spatial subdivision methods (*kd*-Trees, Octrees) are used to reduce the number of ray-primitive intersection tests.



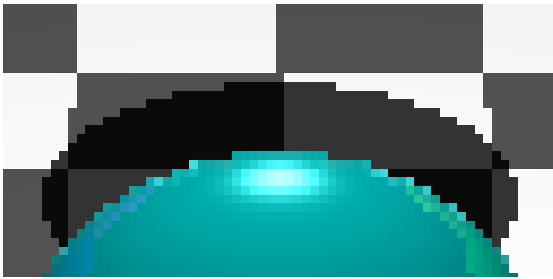
Texture Mapping

- 2D texturing:
 - Similar to OpenGL texturing (~~introduced later in this course~~), but does not use texture coordinates or texture memory.
 - Map the coordinates of the point of intersection (x, y, z) to image coordinates, and assign the colour of the pixel to that point.
- 3D texturing:
 - Define a function to map (x, y, z) coordinates to (r, g, b) colour values.

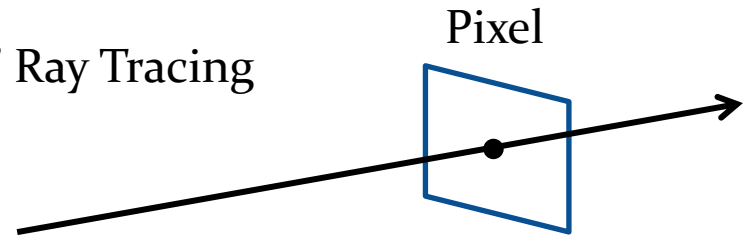


Anti-Aliasing

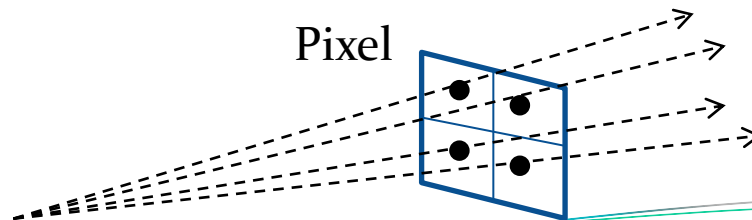
The ray tracing algorithm samples the light field using a finite set of rays generated through a discretized image space. This results in distortion artefacts such as jaggedness along edges of polygons and shadows.



“Normal” Ray Tracing

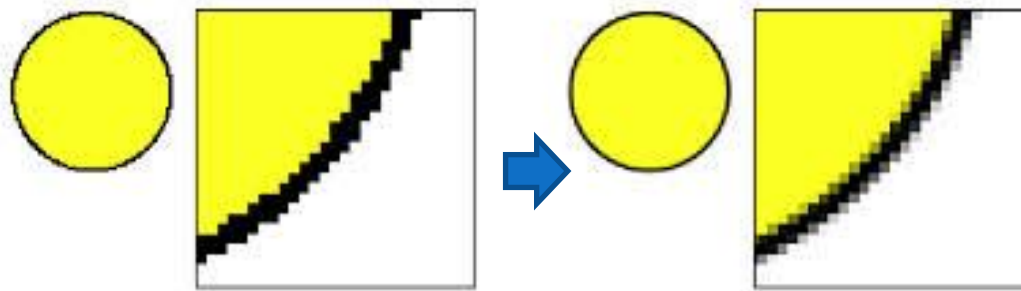


- Supersampling: Generate several rays through each square pixel (eg. divide the pixel into four equal segments) and compute the average of the colour values.



Anti-Aliasing

- Adaptive Sampling: As shown on the previous slide, each pixel is divided into four “sub-pixels”. Primary rays are generated through the centres of each sub-pixel. If the colour value along any ray varies significantly from the other three, that sub-pixel is split further into four sub-pixels, and more rays are generated through them.



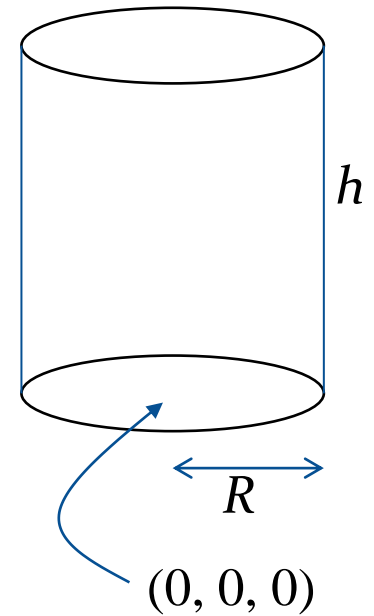
Cylinder

- A cylinder at the origin with axis along the y -axis, radius R and height h is given by

$$x^2 + z^2 = R^2$$

$$0 \leq y \leq h$$

- Normal vector at (x, y, z)
(un-normalized) $n = (x, 0, z)$
Normalized $n = (x/R, 0, z/R)$



Ray – Cylinder Intersection

- A cylinder at (x_c, y_c, z_c) , with axis parallel to the y -axis, radius R and height h is given by

$$(x - x_c)^2 + (z - z_c)^2 = R^2$$

$$0 \leq (y - y_c) \leq h$$

- Normal vector at (x, y, z)

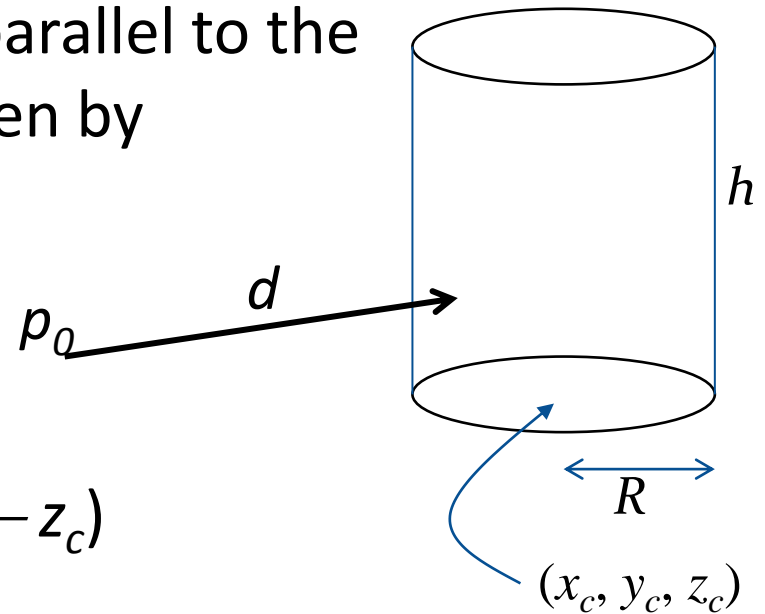
(un-normalized) $n = (x - x_c, 0, z - z_c)$

- Ray equation:

$$x = x_0 + d_x t; \quad y = y_0 + d_y t; \quad z = z_0 + d_z t;$$

- Intersection equation:

$$t^2(d_x^2 + d_z^2) + 2t\{d_x(x_0 - x_c) + d_z(z_0 - z_c)\} + \{(x_0 - x_c)^2 + (z_0 - z_c)^2 - R^2\} = 0.$$



Cone

- Consider a cone with base at the origin, axis parallel to the y -axis, radius R , and height h :

- Important equations:

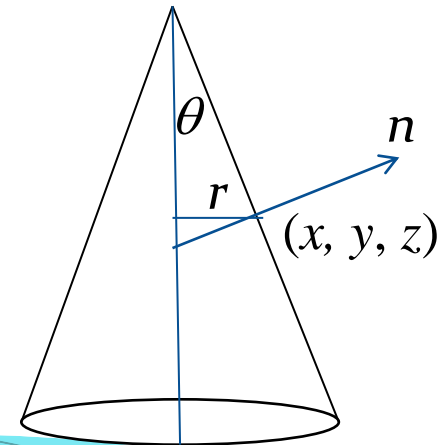
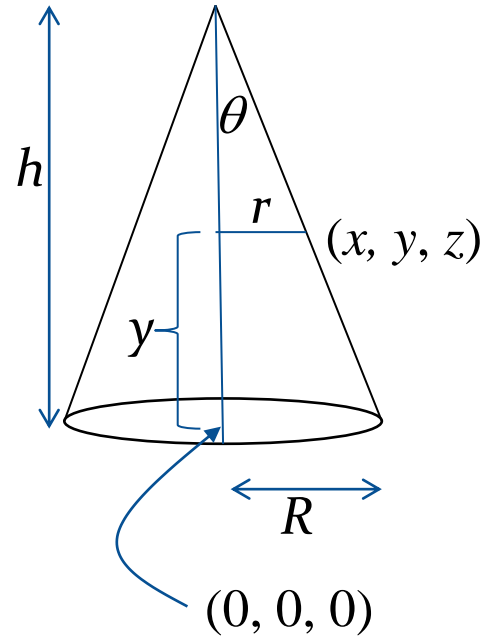
$$\tan(\theta) = R/h$$

$$x^2 + z^2 = r^2$$

$$x^2 + z^2 = \left(\frac{R}{h}\right)^2 (h - y)^2$$

- Surface normal vector (un-normalized):

$$n = (x, r \tan(\theta), z)$$



Ray-Cone Intersection

- Equation of a cone with base at (x_c, y_c, z_c) , axis parallel to the y -axis, radius R , and height h :

$$(x - x_c)^2 + (z - z_c)^2 = \left(\frac{R}{h}\right)^2 (h - y + y_c)^2$$

- Ray equation:

$$x = x_0 + d_x t; \quad y = y_0 + d_y t; \quad z = z_0 + d_z t;$$

- The points of intersection are obtained by substituting the ray equation in the cone's equation and solving for t .

