

Nanopass Back-Translation of Call-Return Trees for Mechanized Secure Compilation Proofs

Jérémy Thibault, Joseph Lenormand, Catalin Hritcu

MAX PLANCK INSTITUTE
FOR SECURITY AND PRIVACY



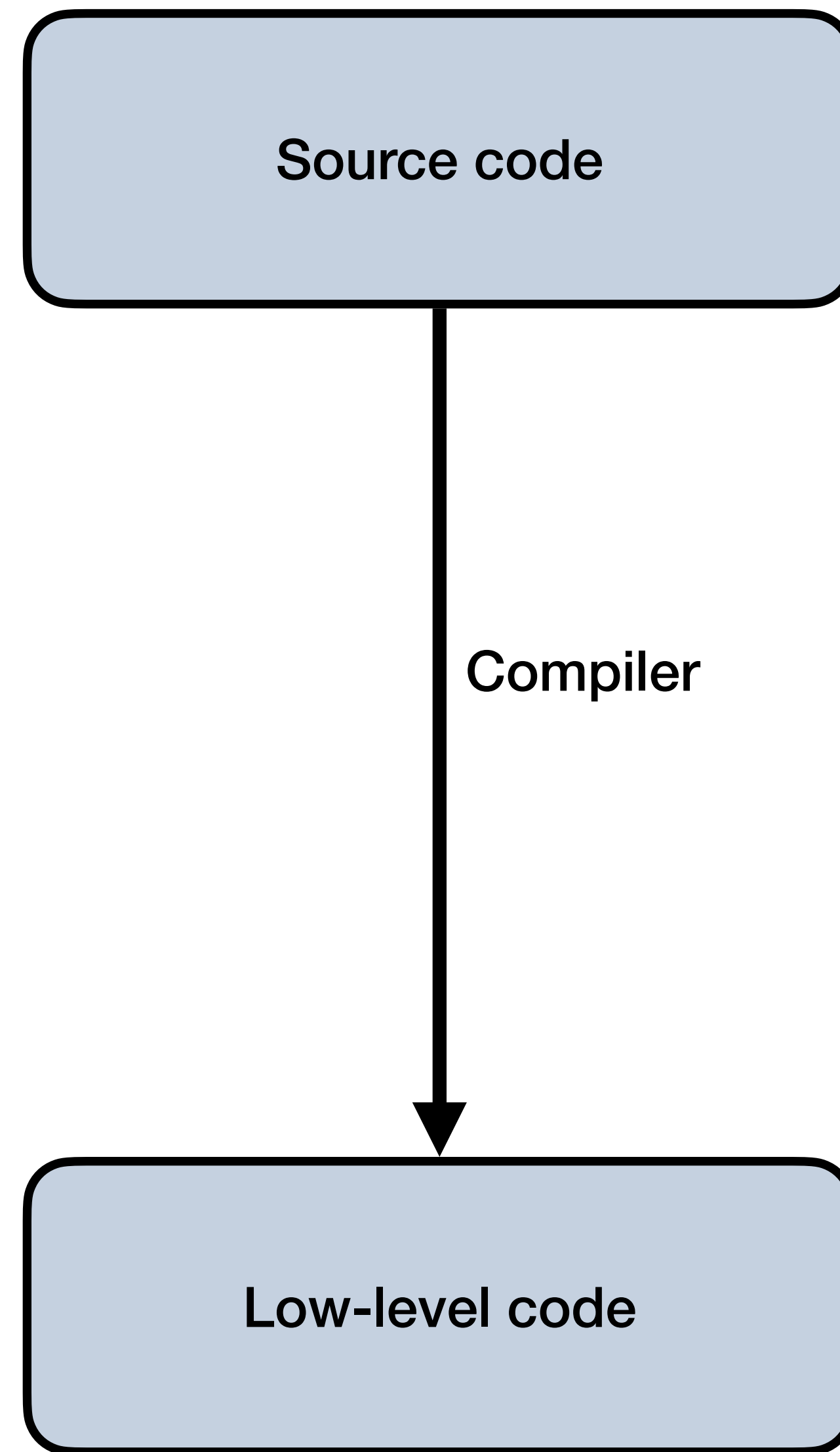
Source code



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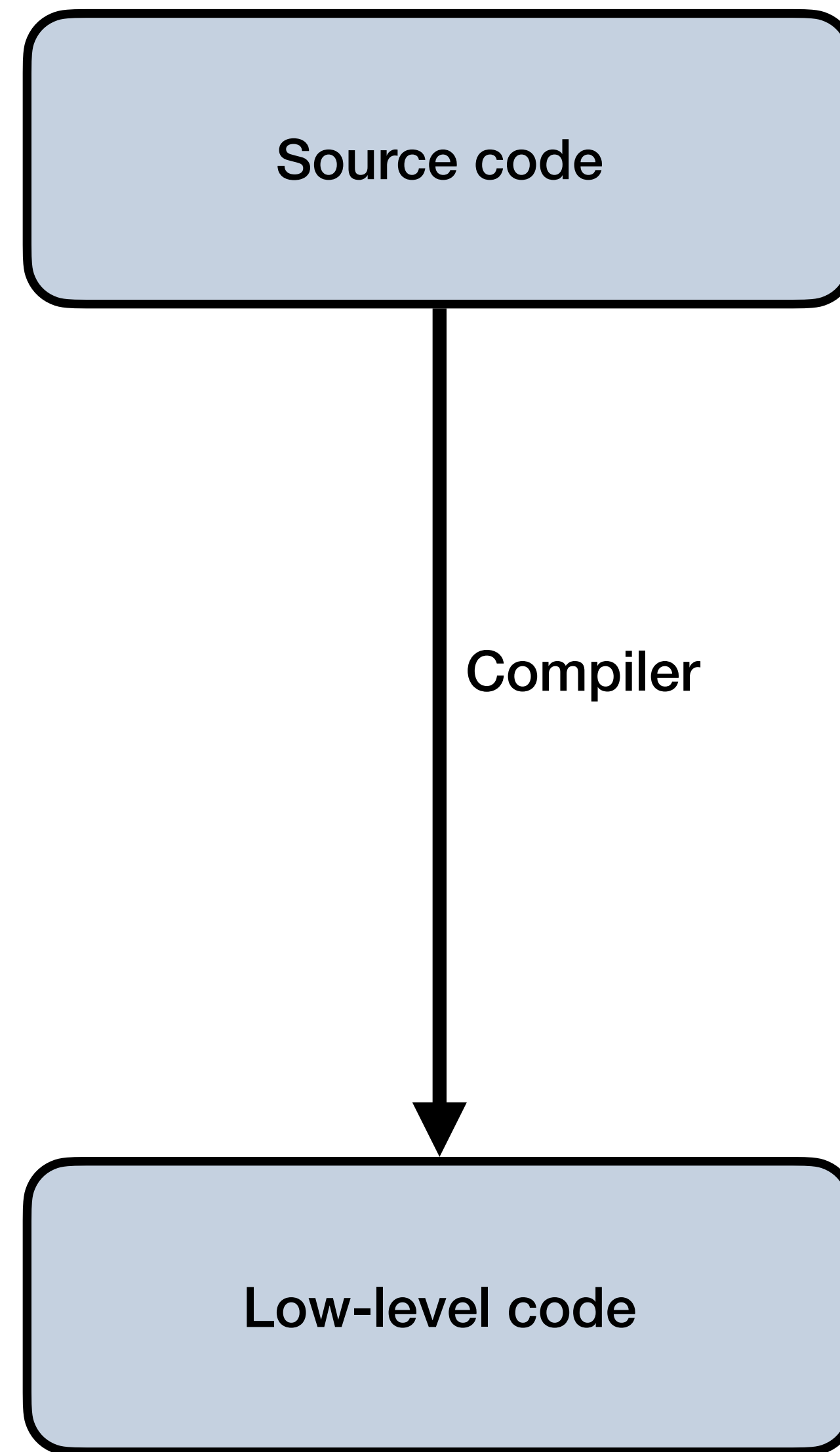
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- Types
- Structured control-flow
- Verification, static analysis, etc.



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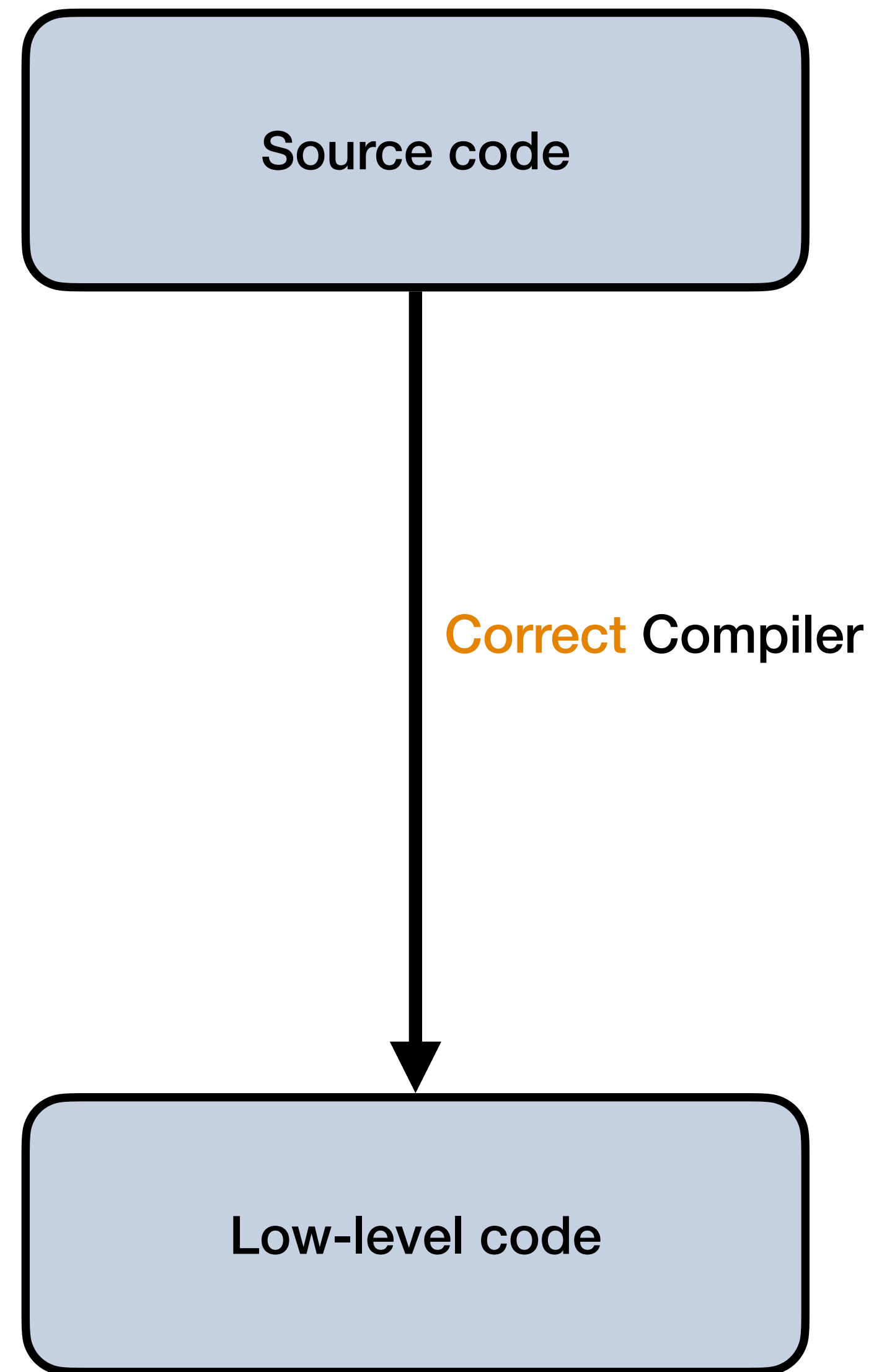
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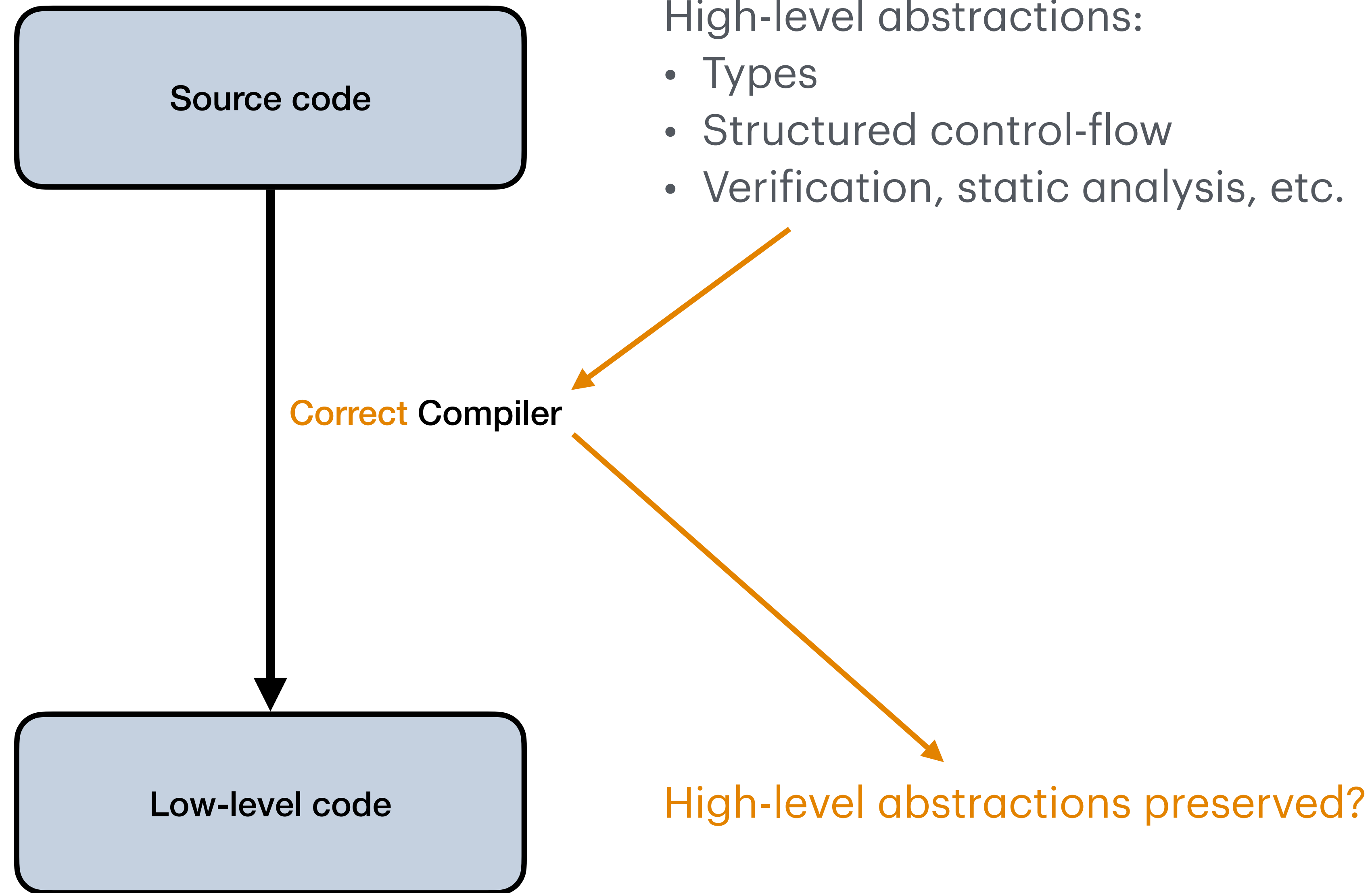
No high-level abstraction anymore

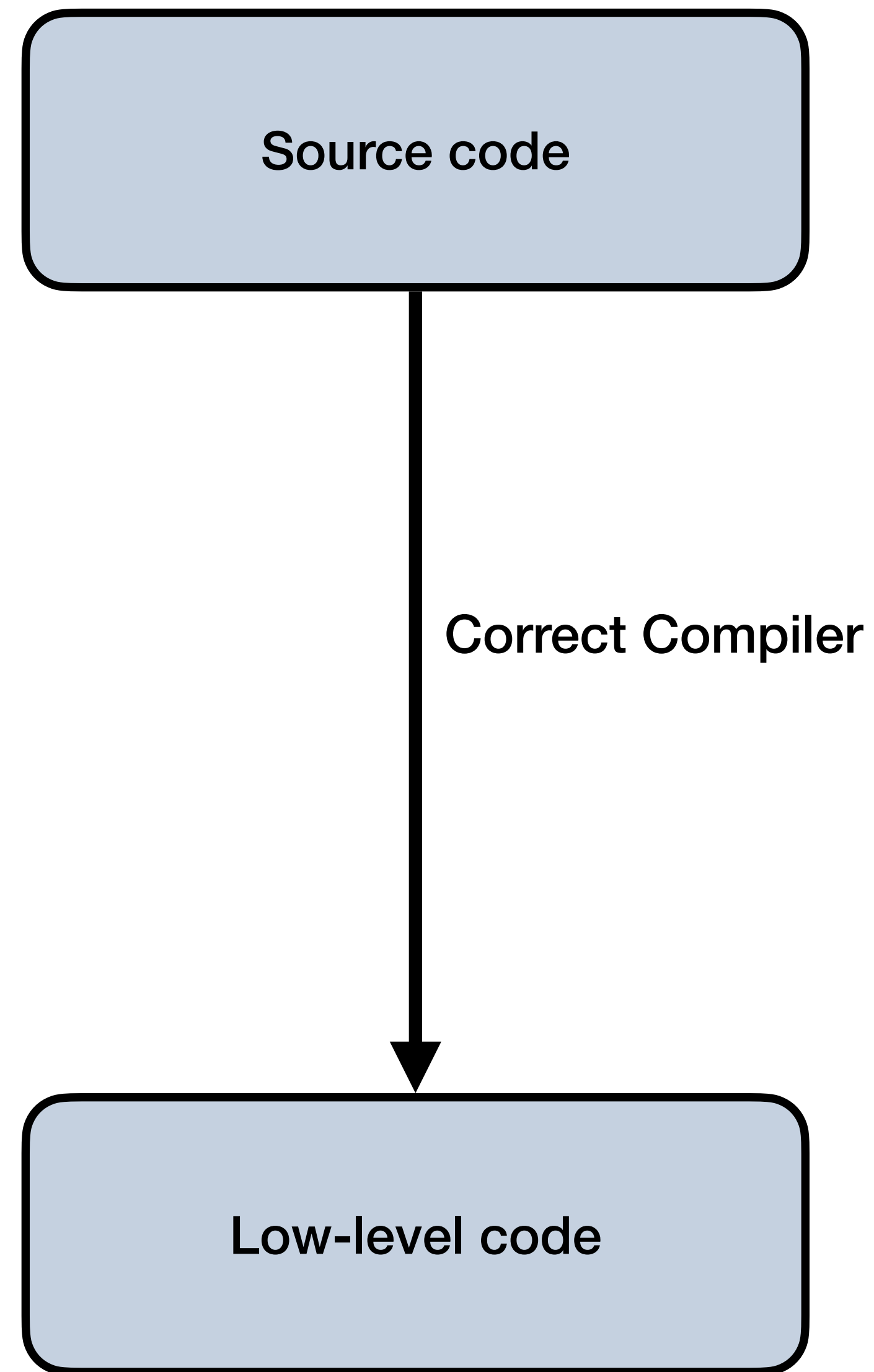


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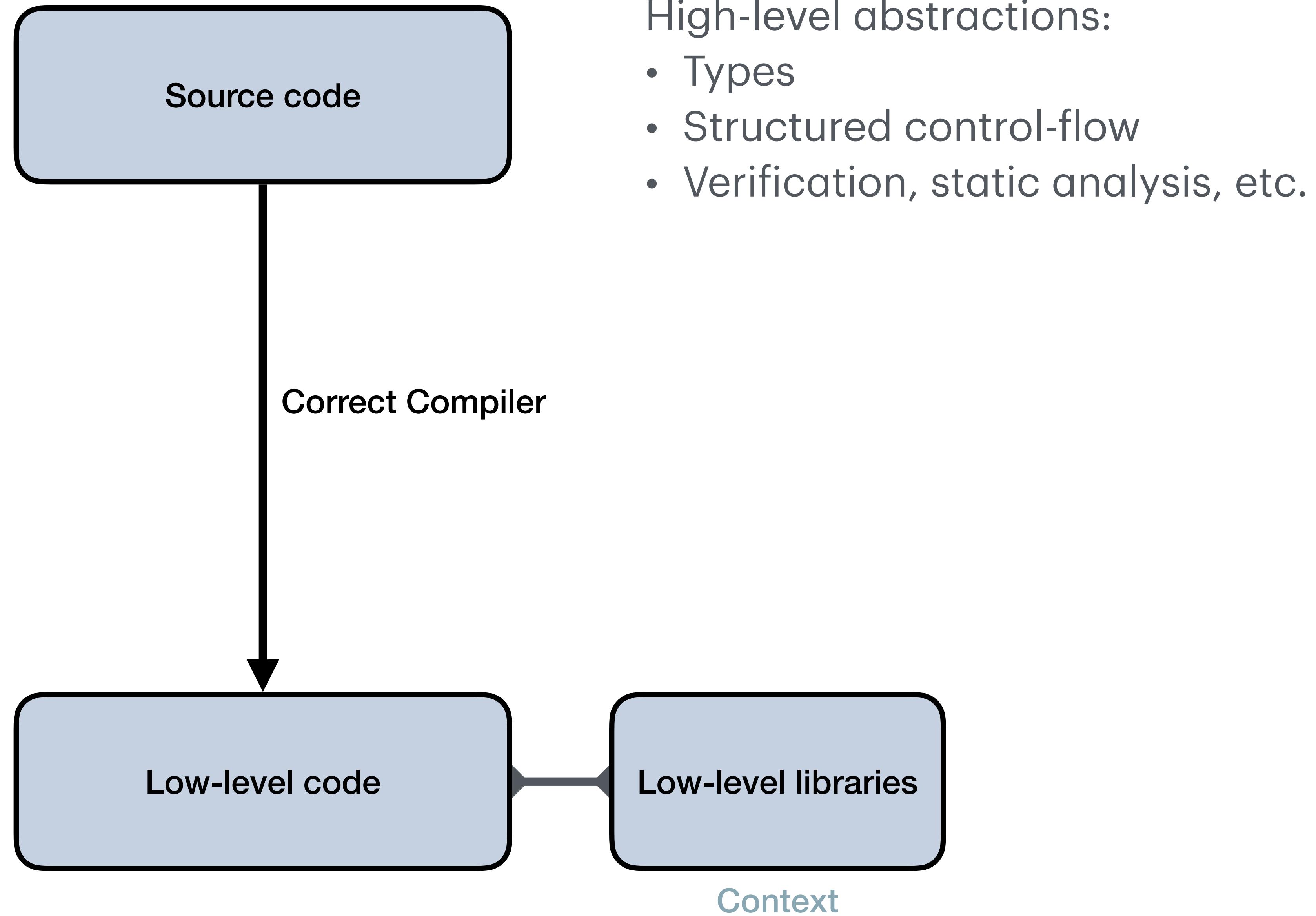
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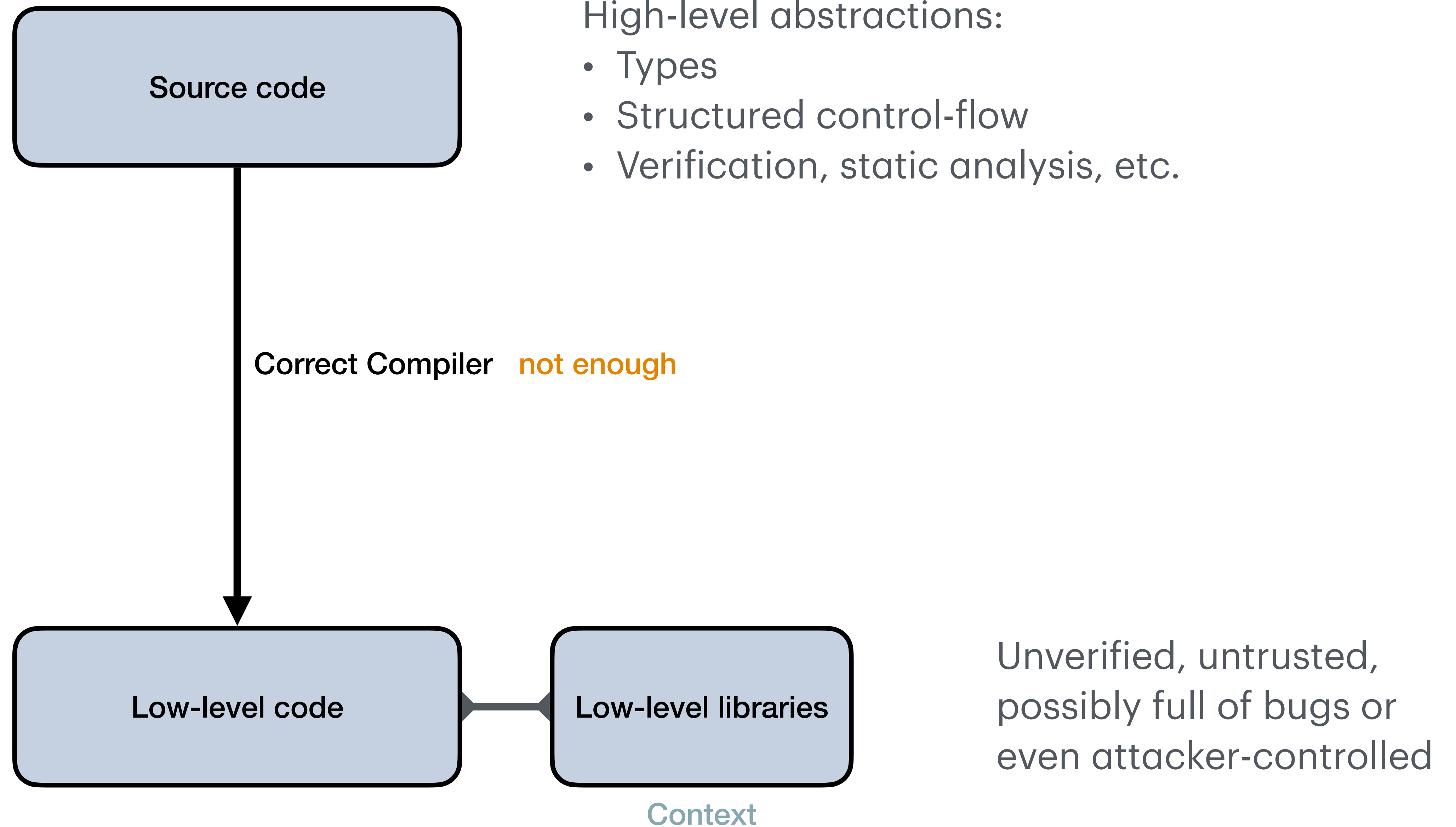


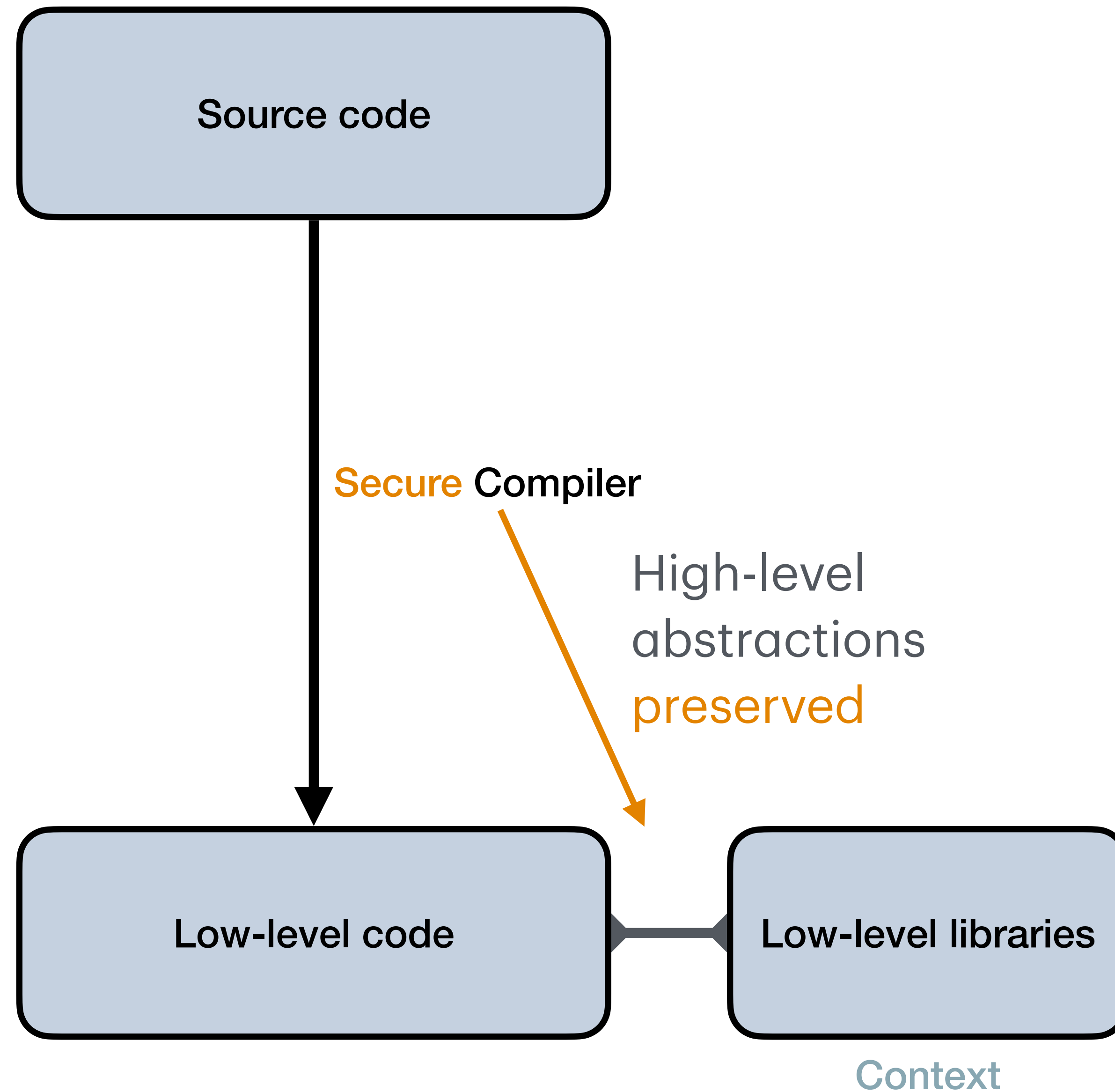


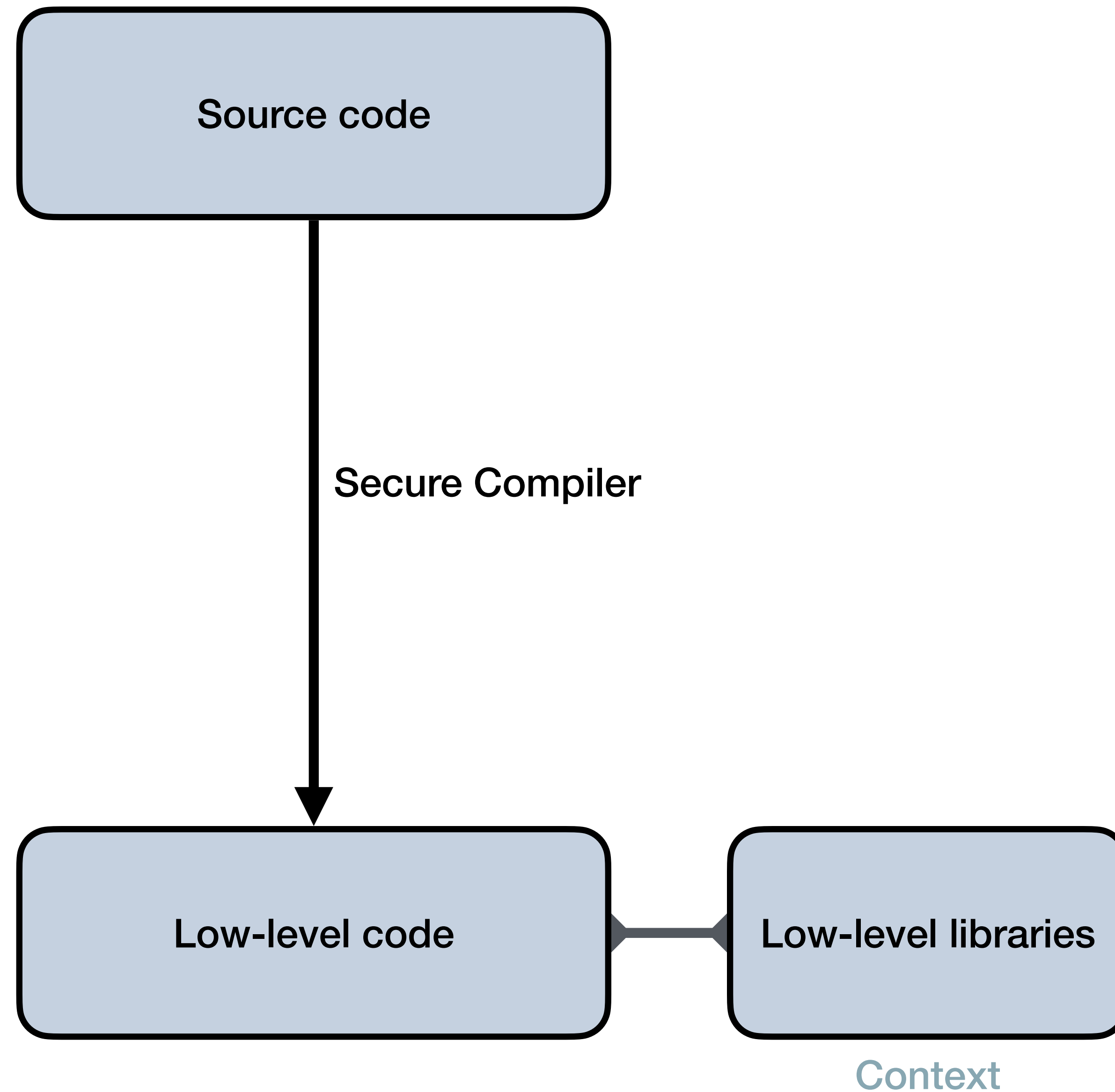
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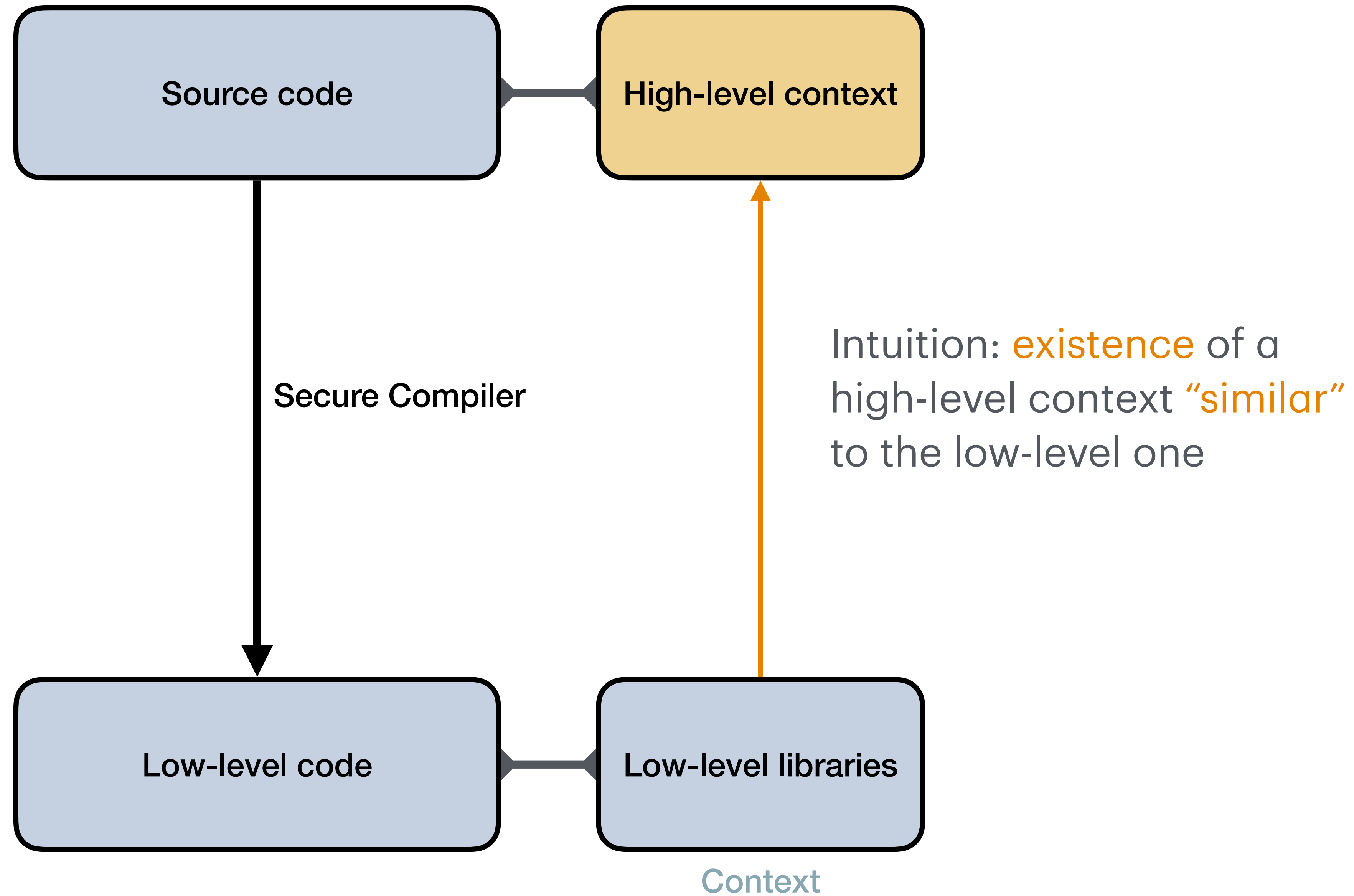
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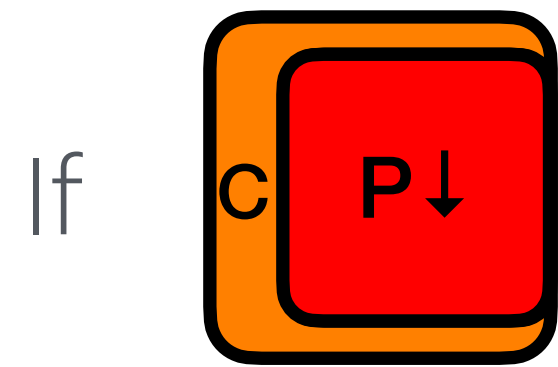






Example: Robust Safety Preservation (RSP)

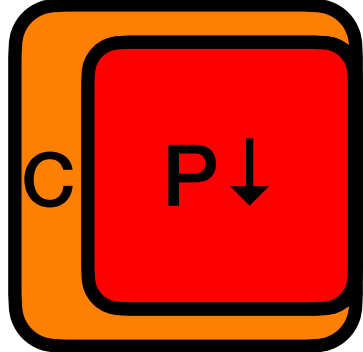
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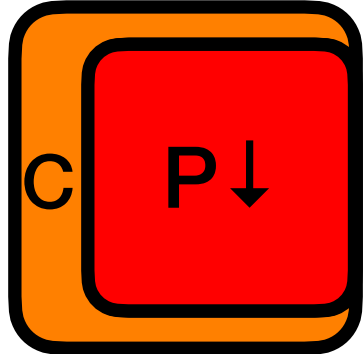
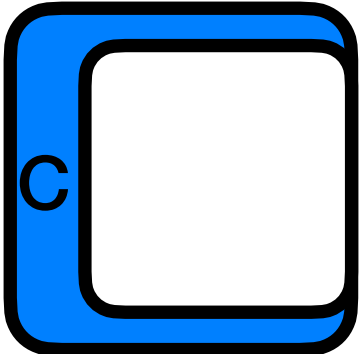
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⇒ preservation of **safety properties**

Trace-based **back-translation**:

given **m**, build a context 

A Proof Technique for RSP

A Proof Technique for RSP

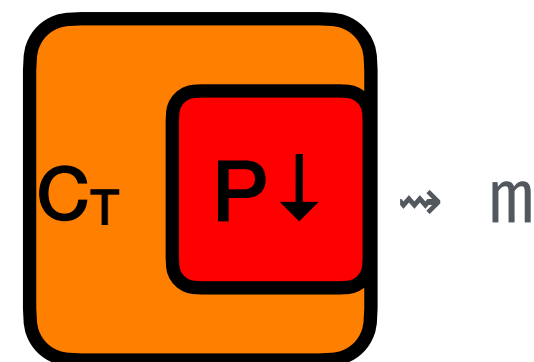
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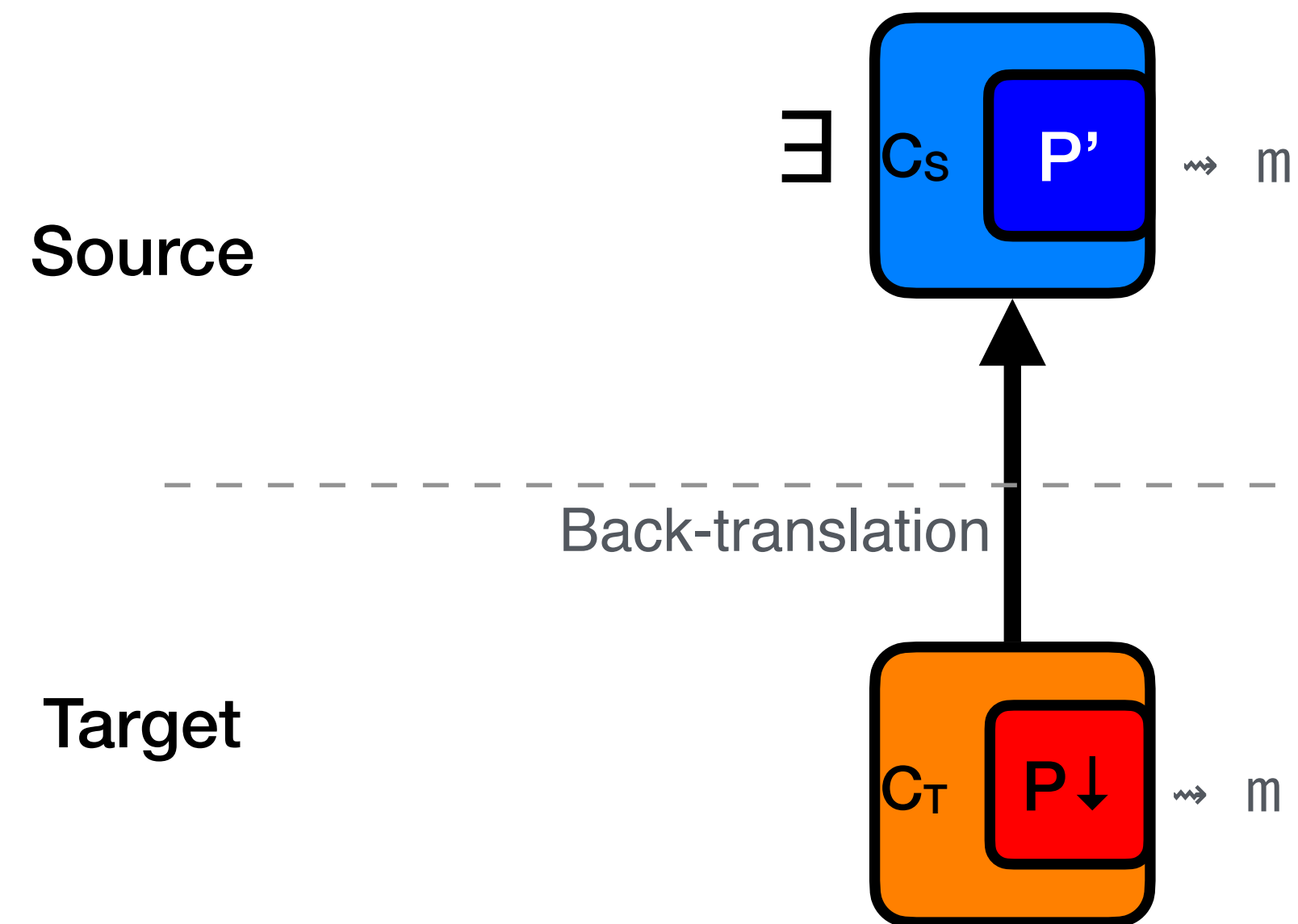
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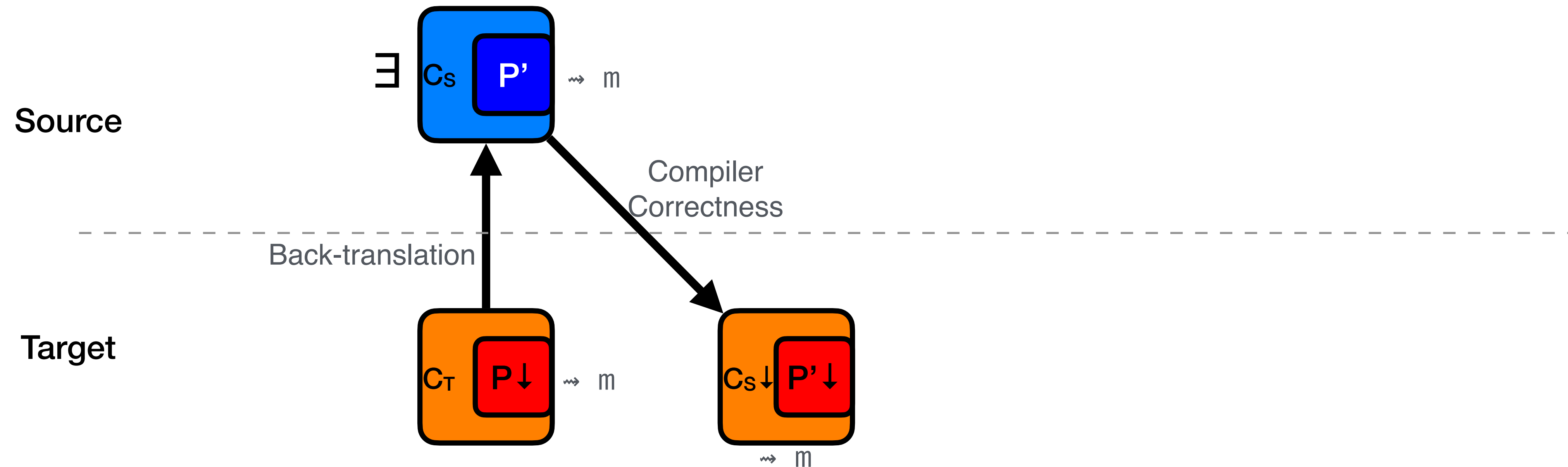
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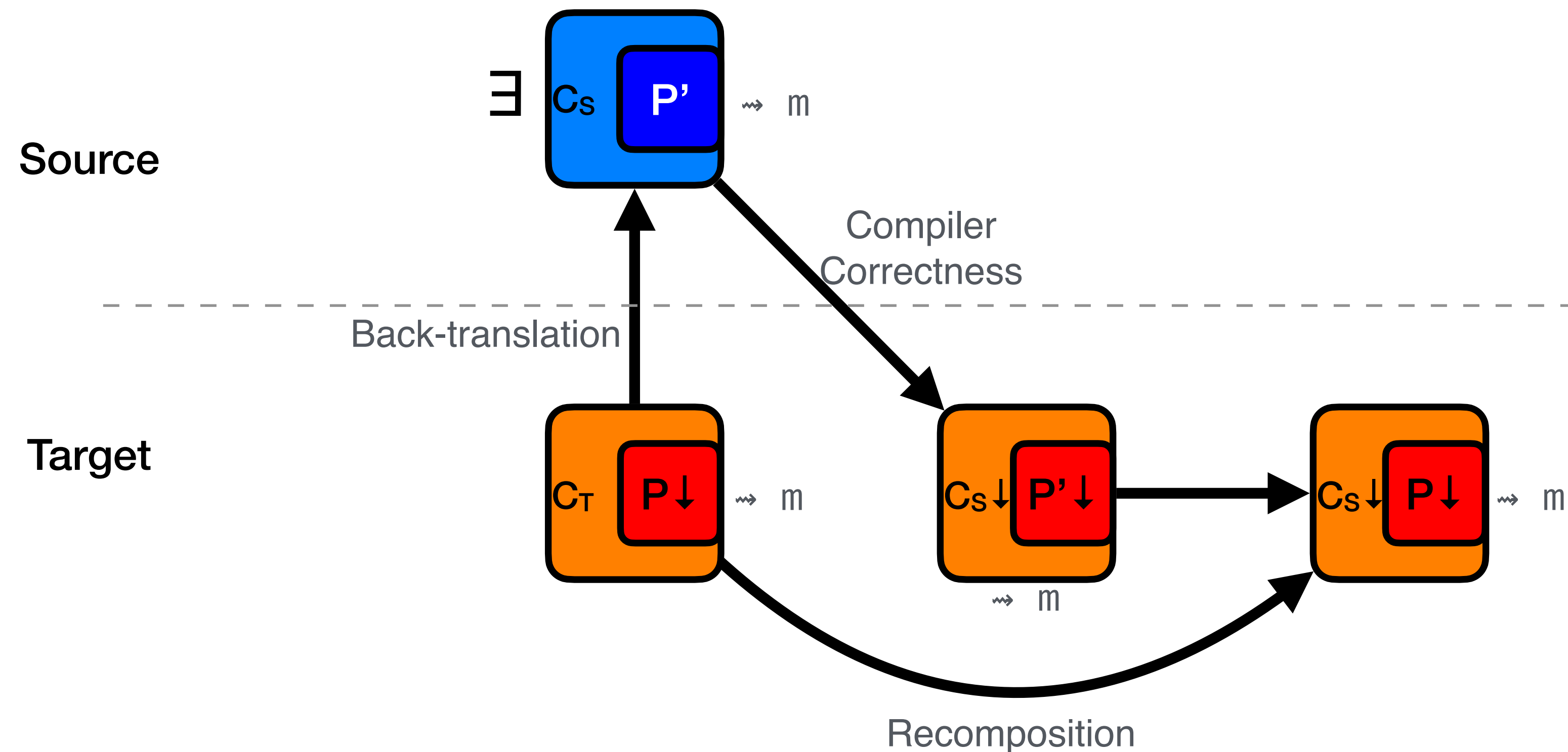
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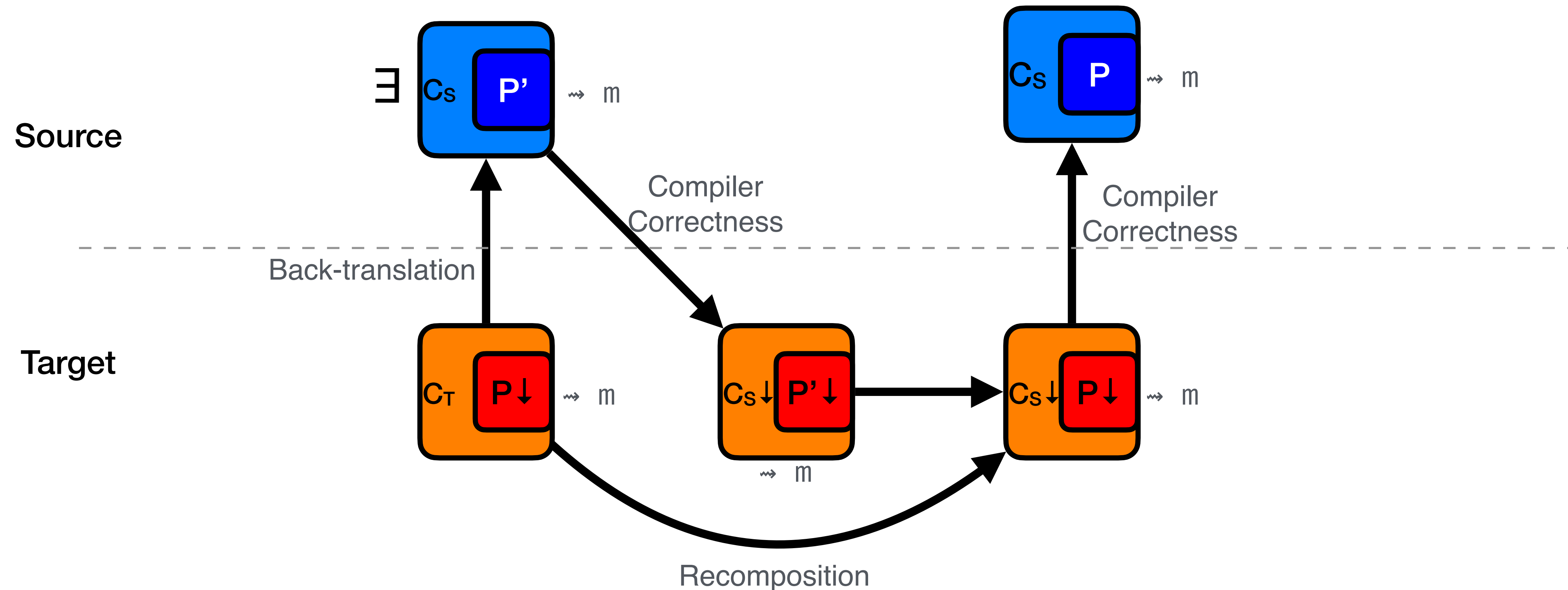
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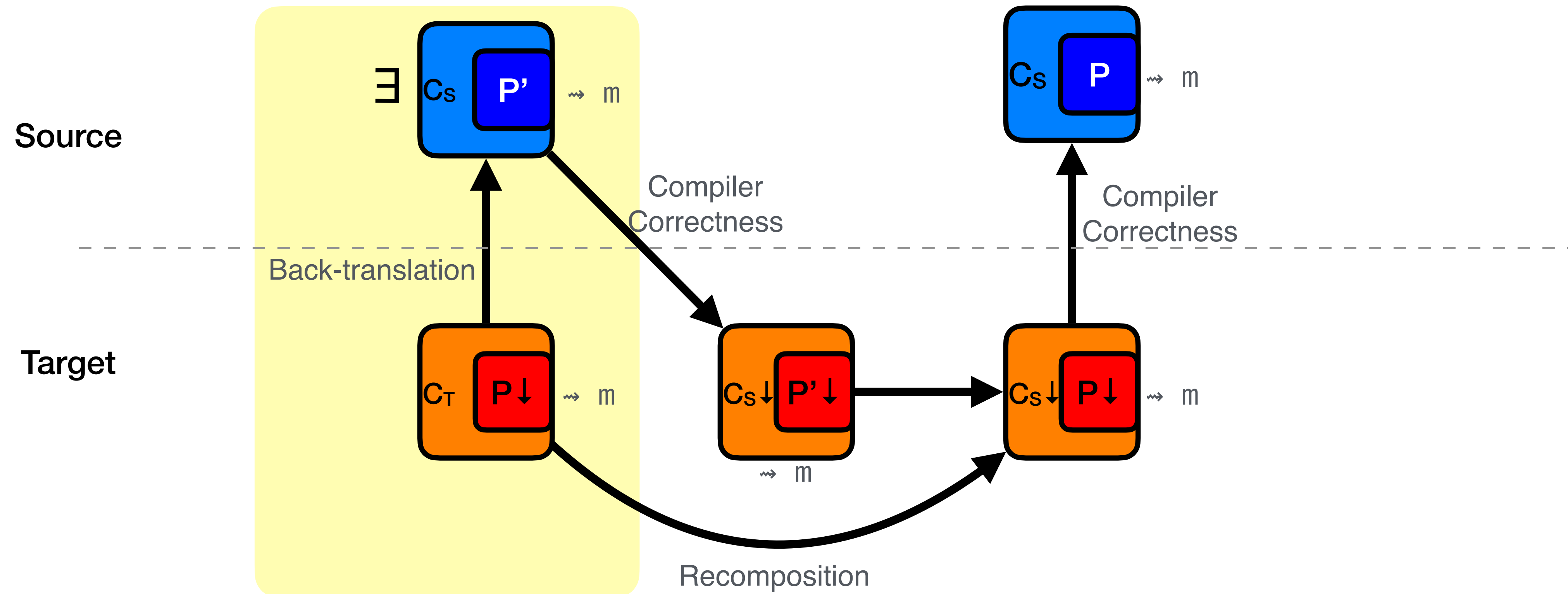
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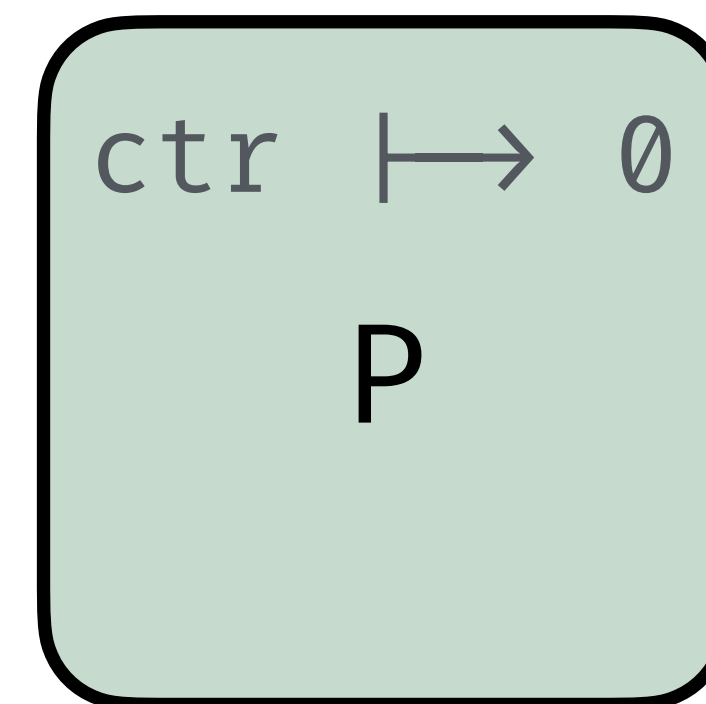
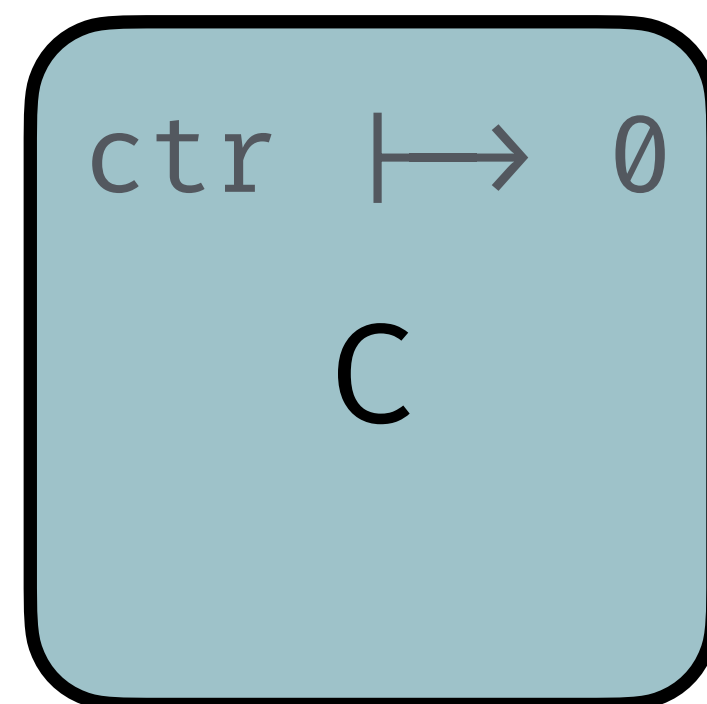
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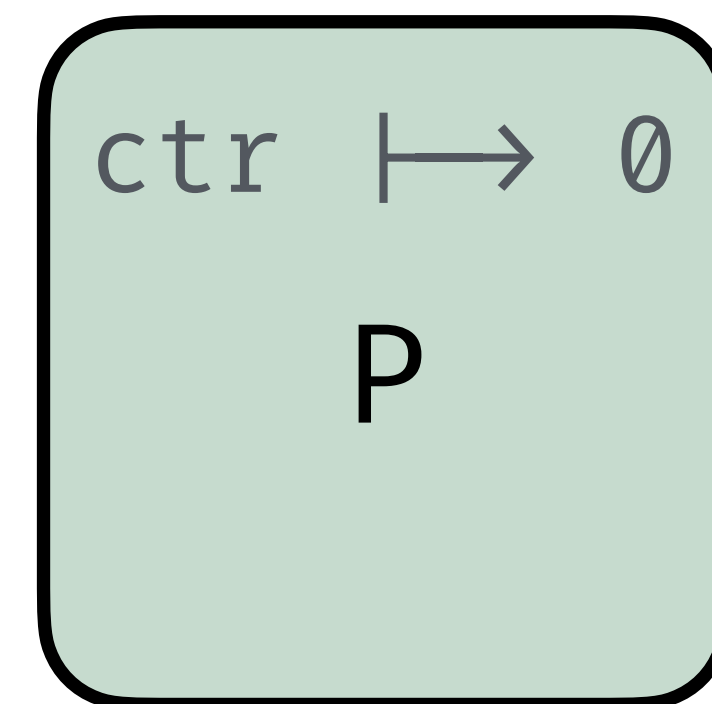
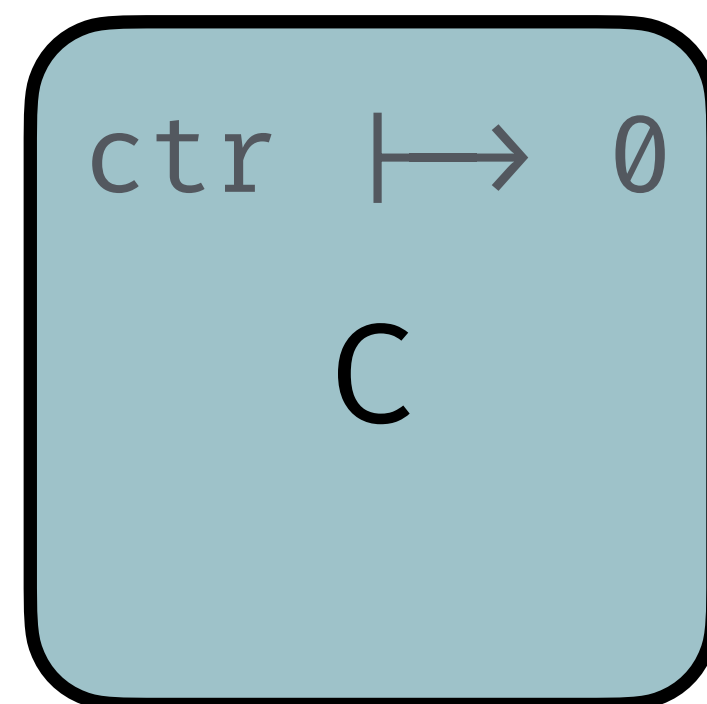
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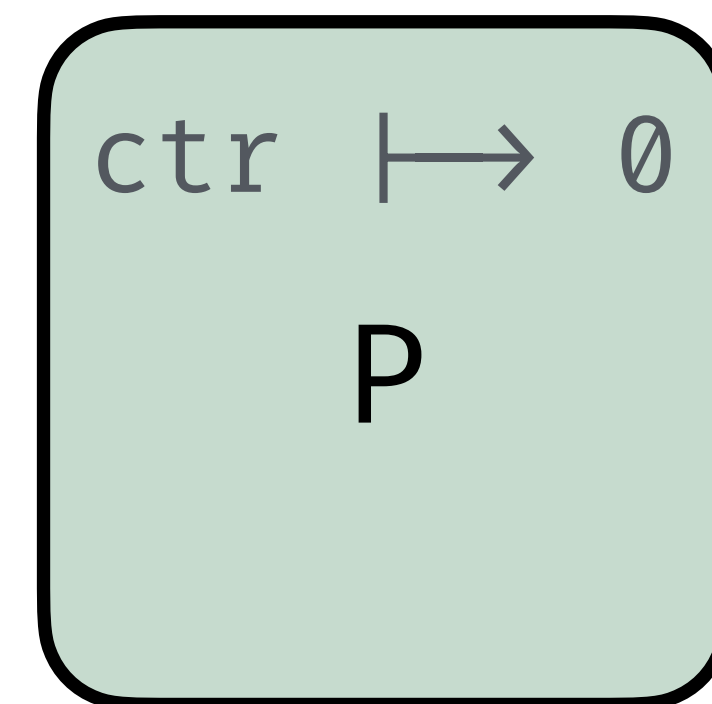
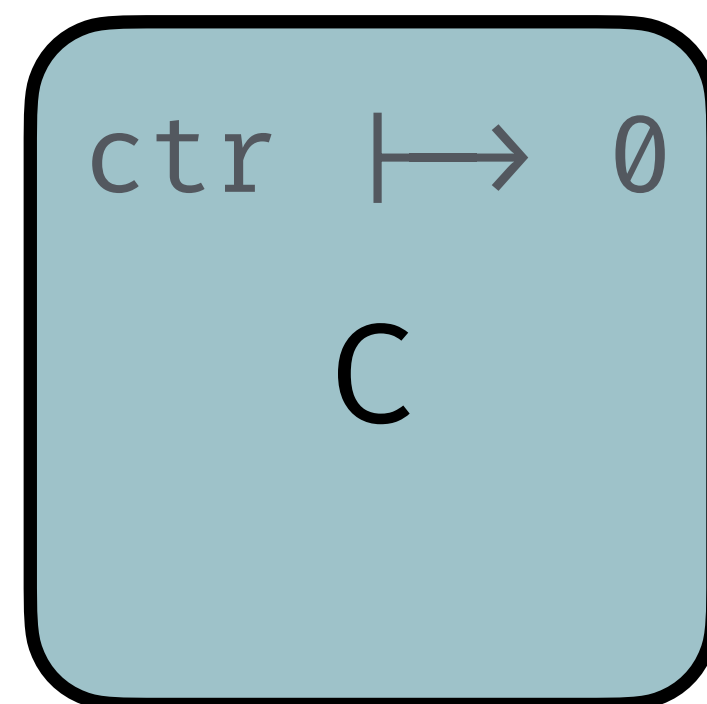
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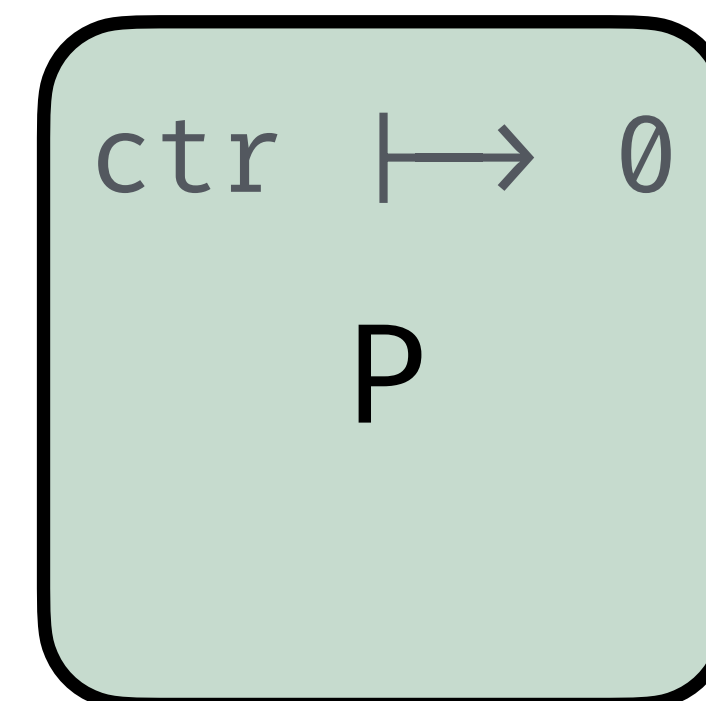
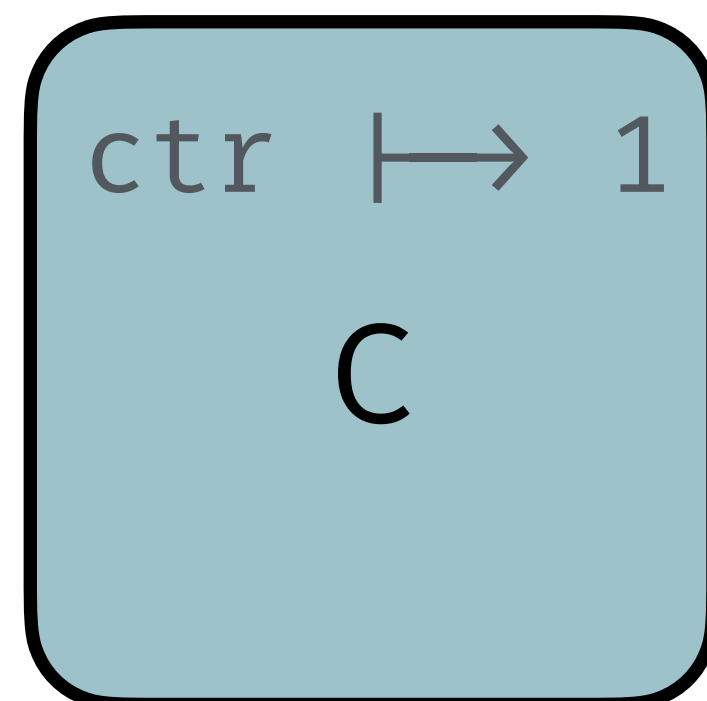
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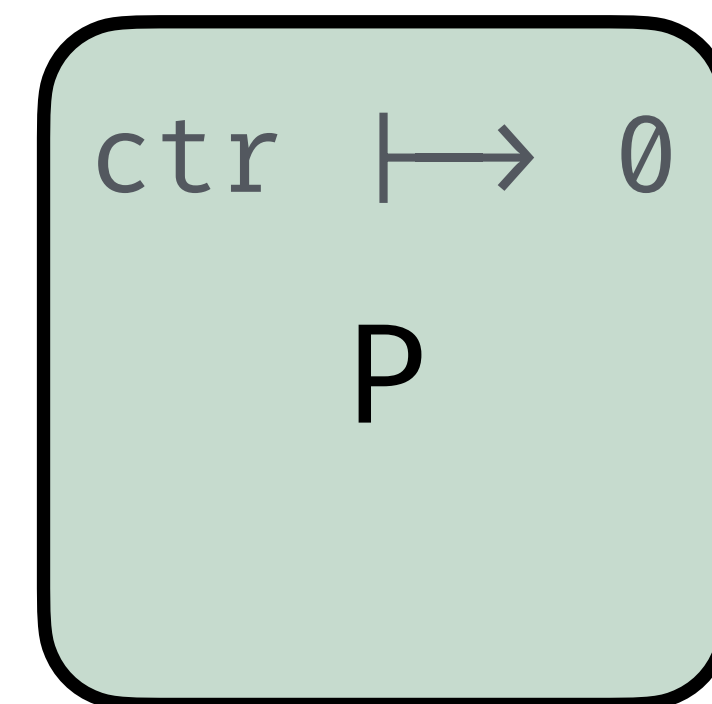
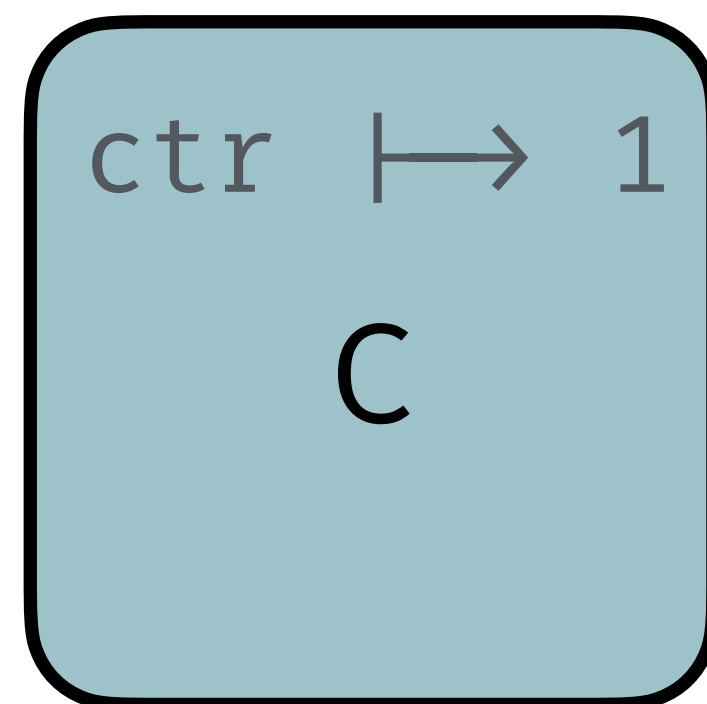
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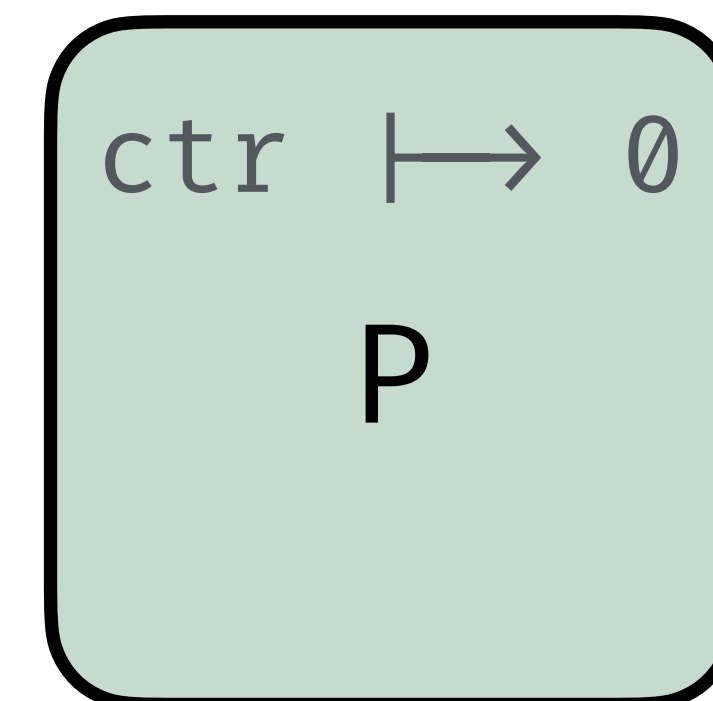
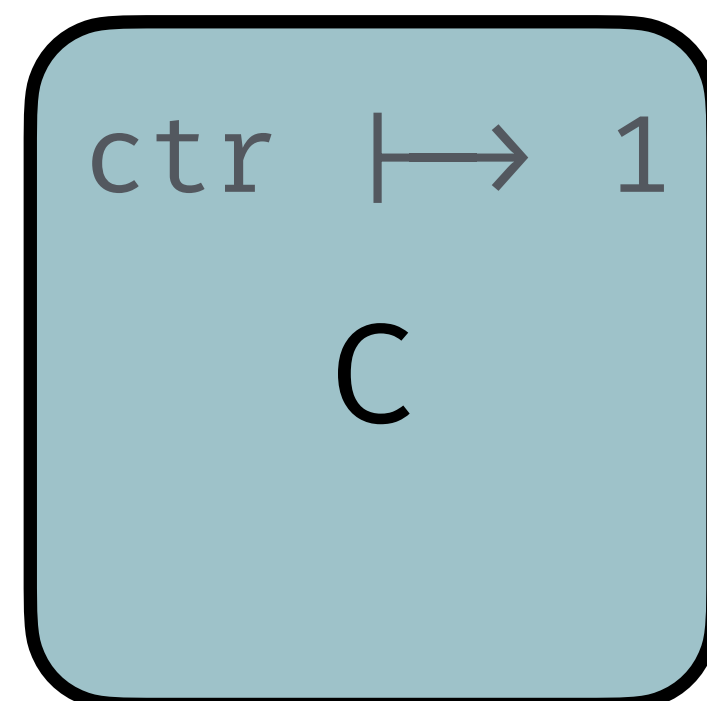


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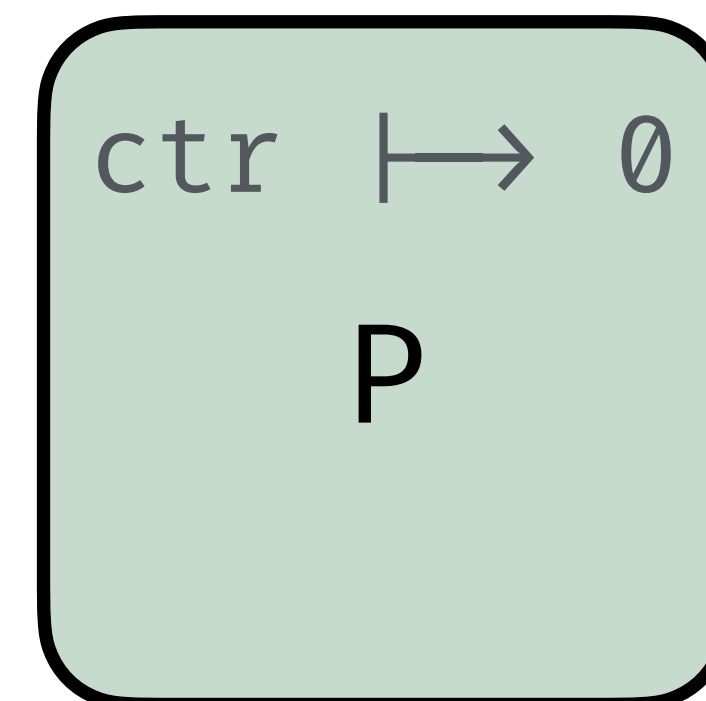
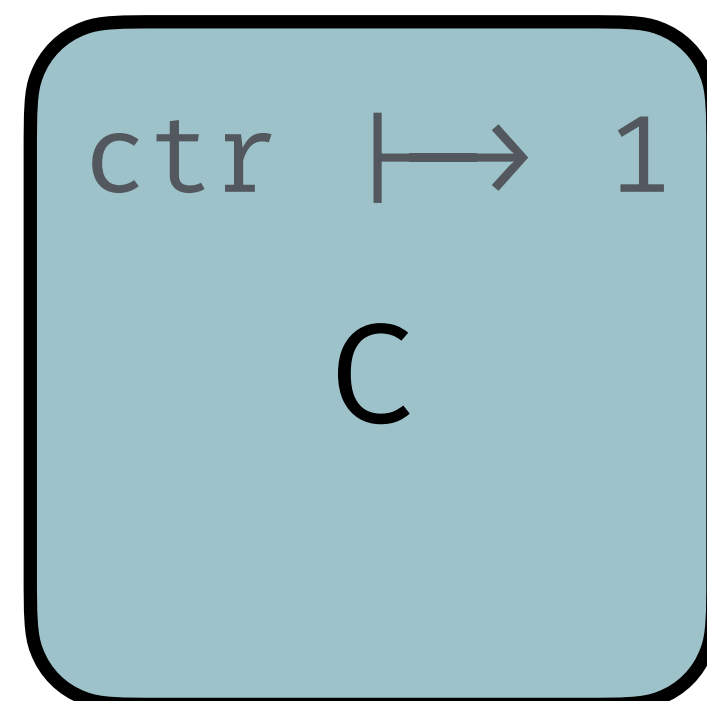


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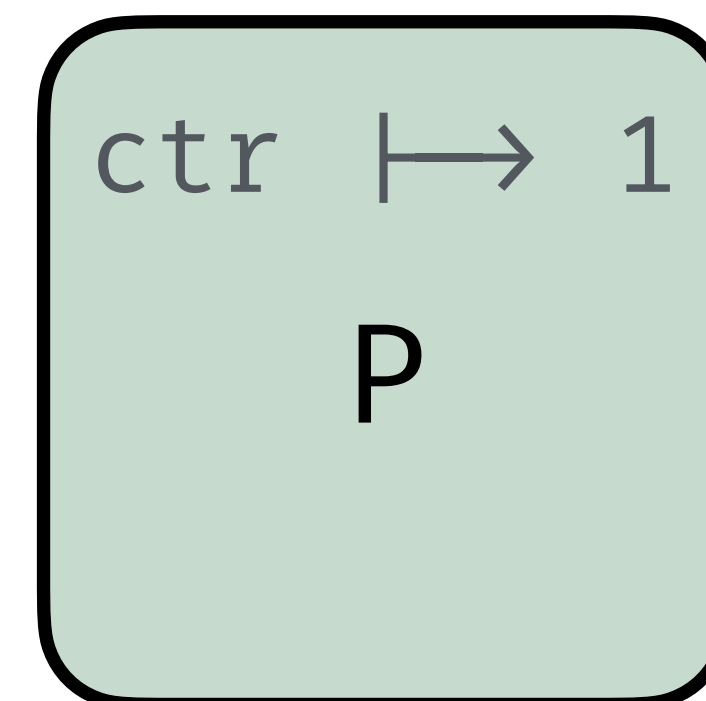
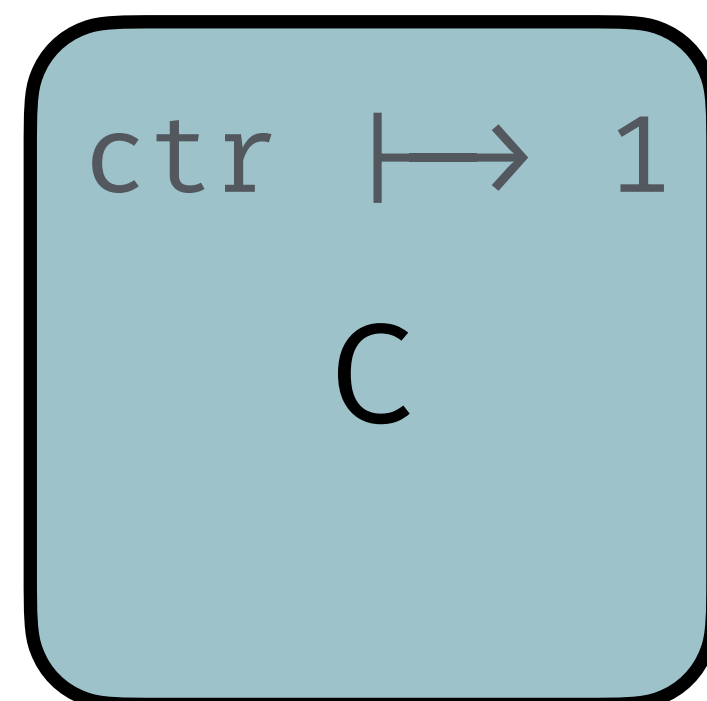


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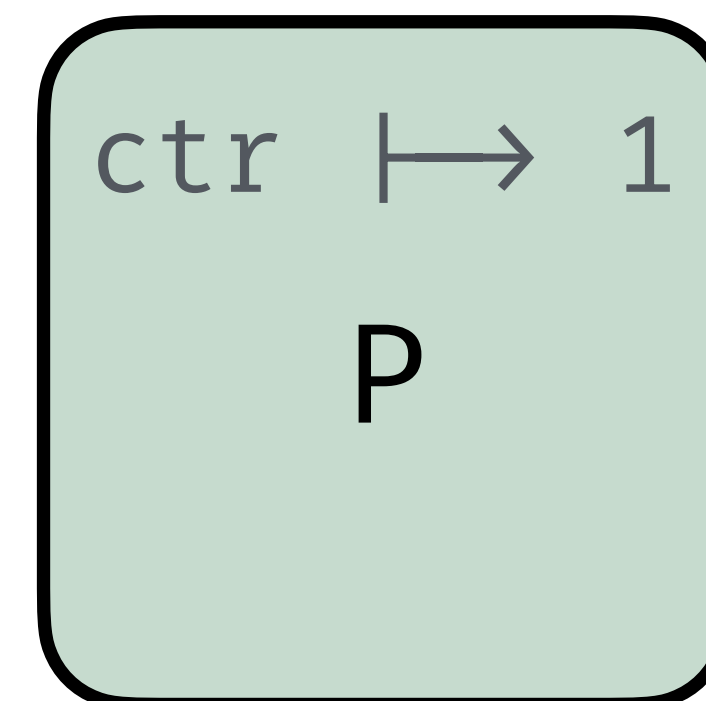
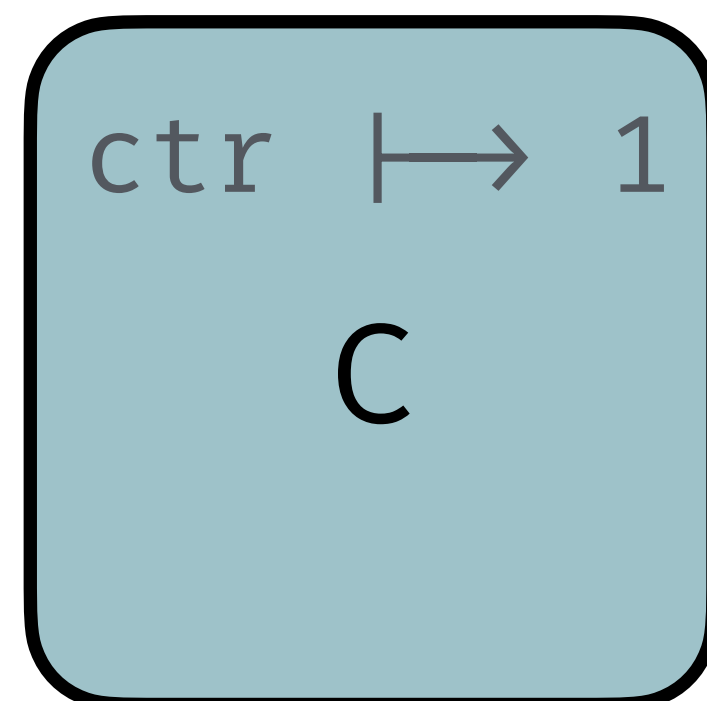


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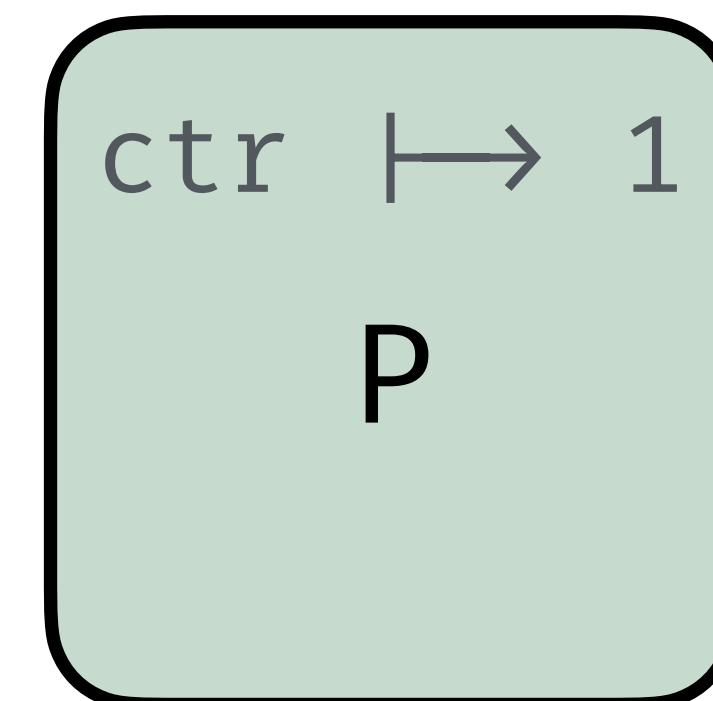
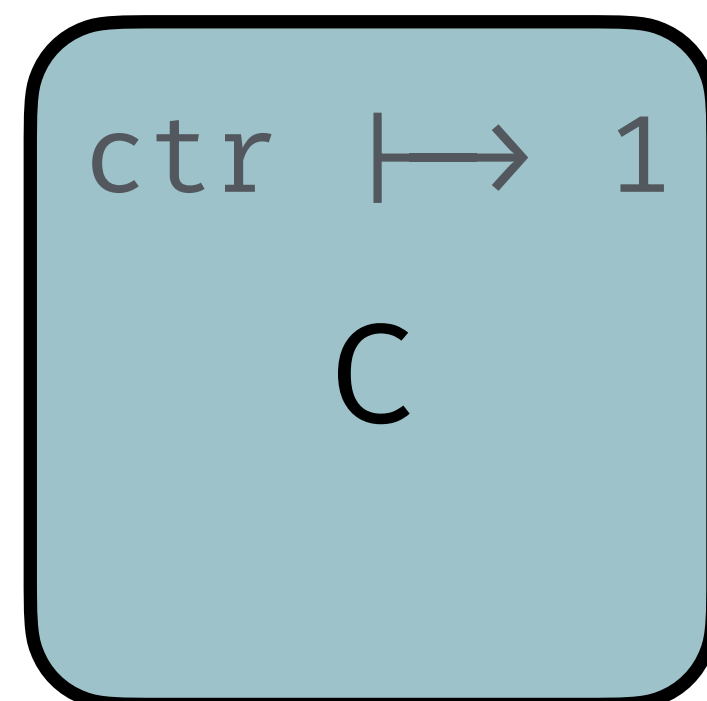


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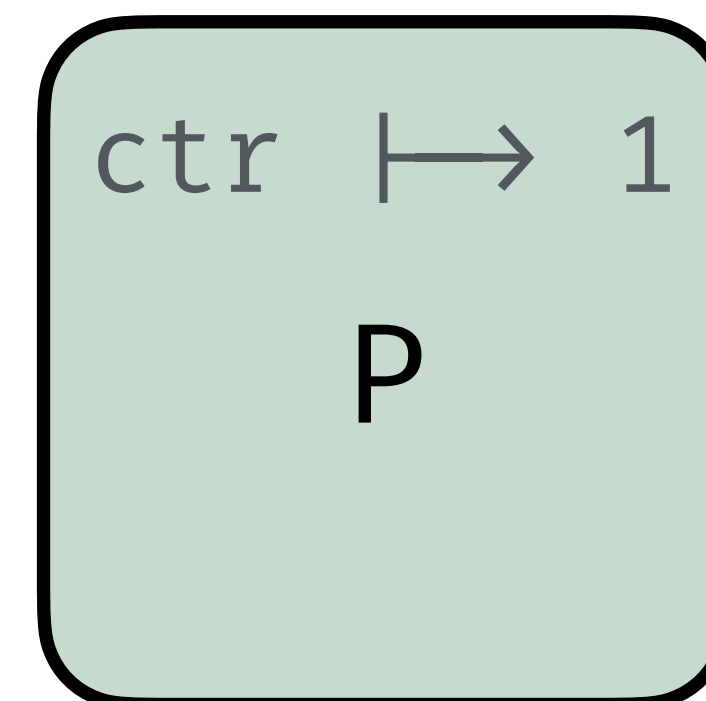
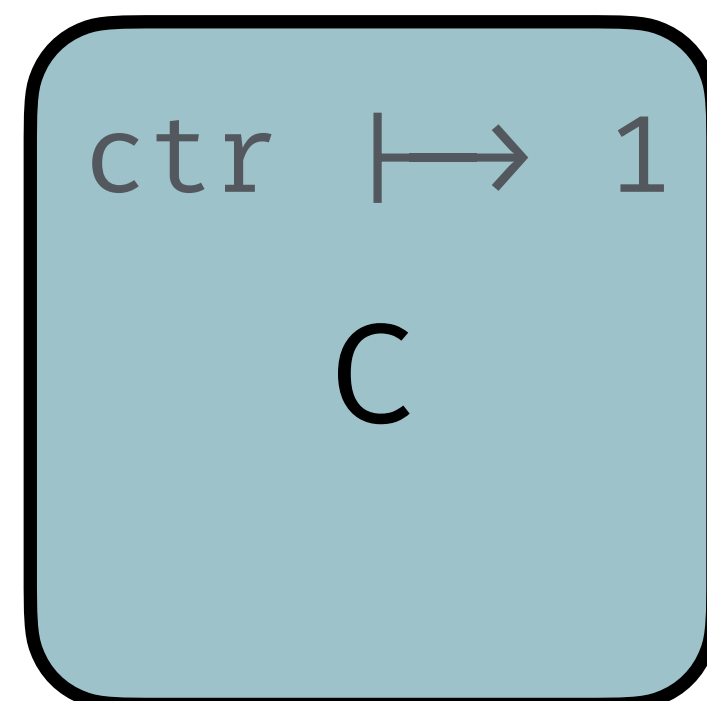


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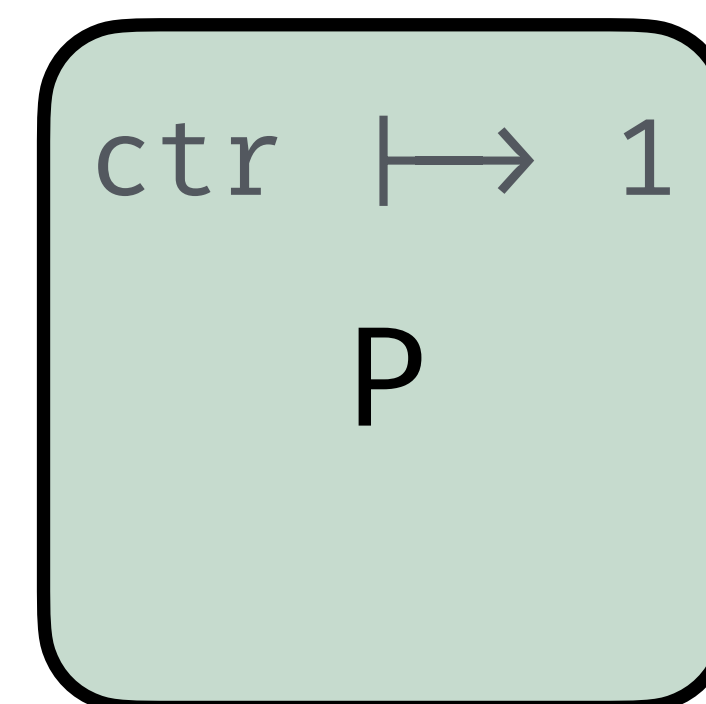
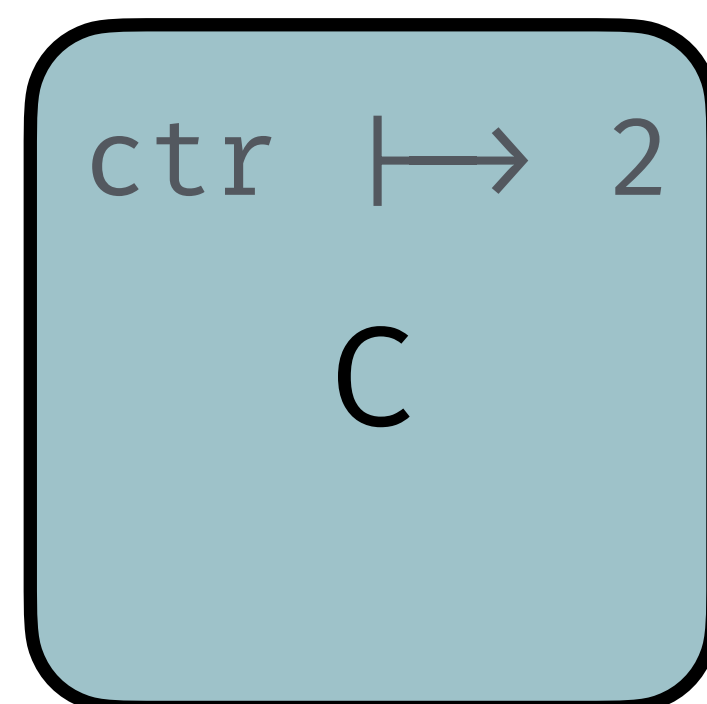


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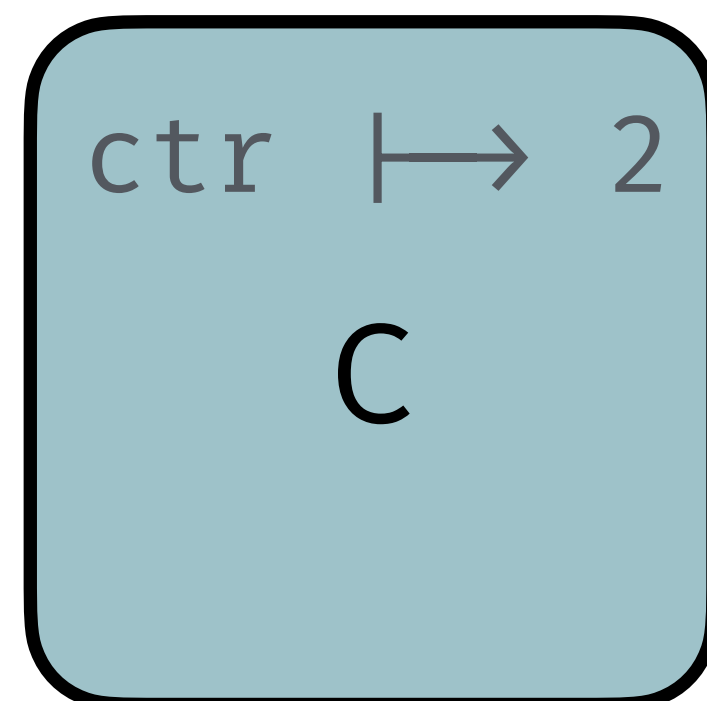
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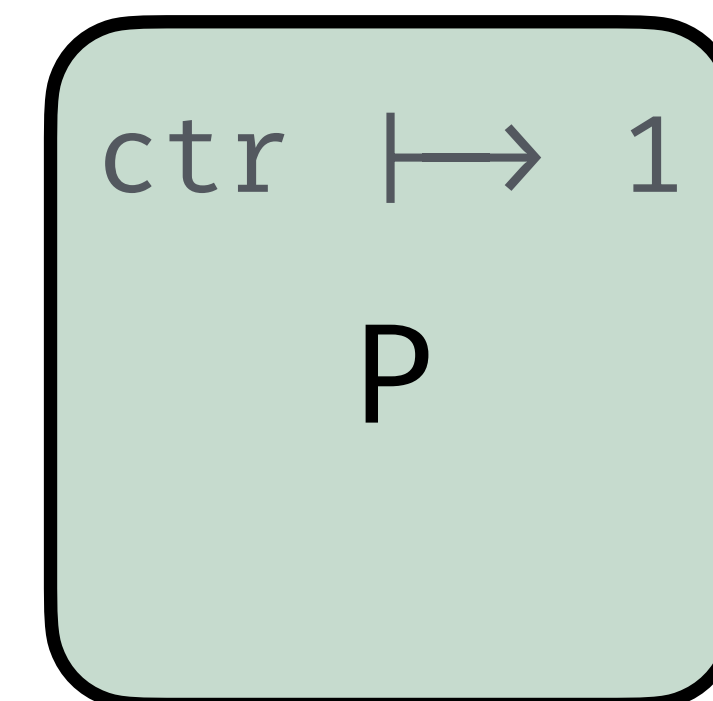
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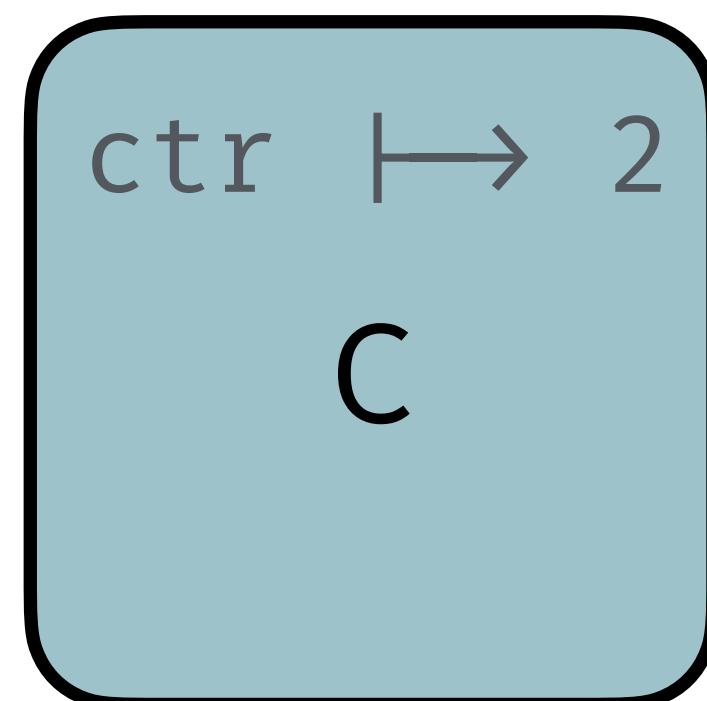
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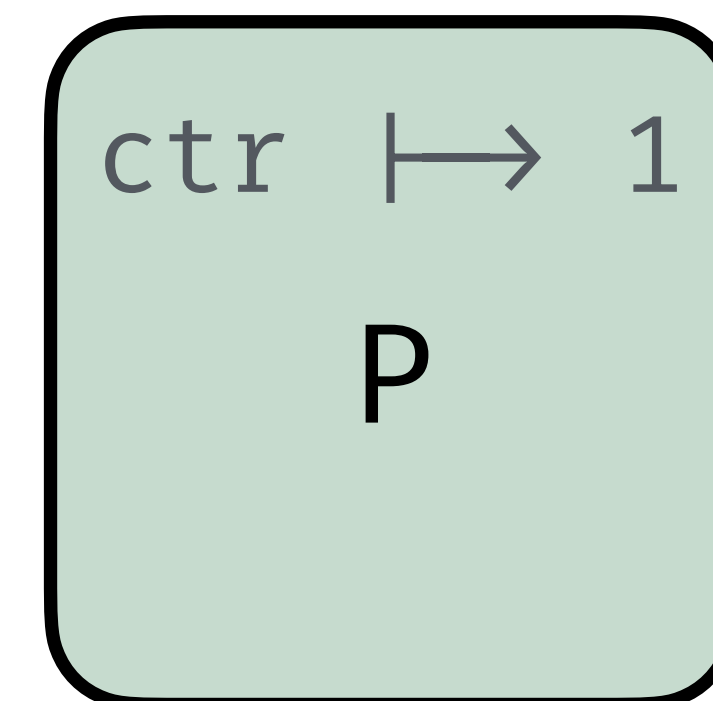
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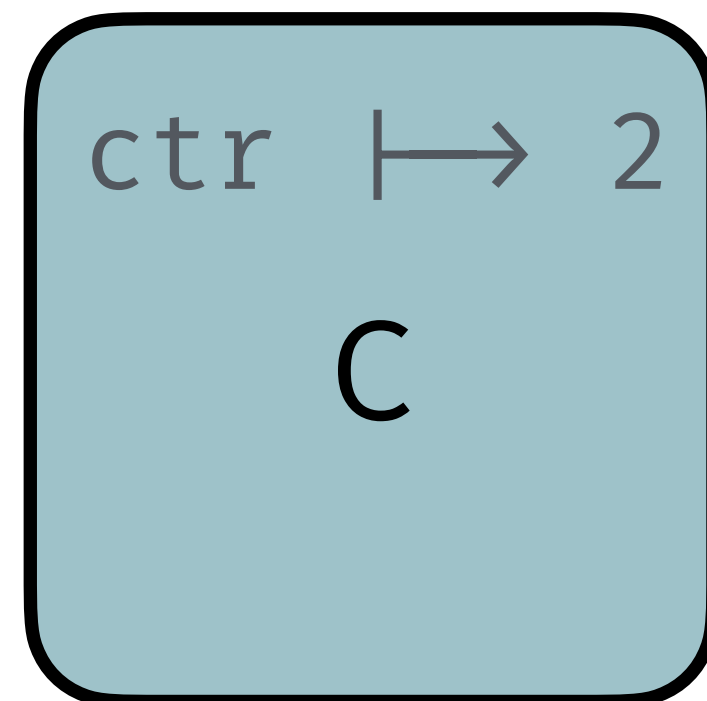
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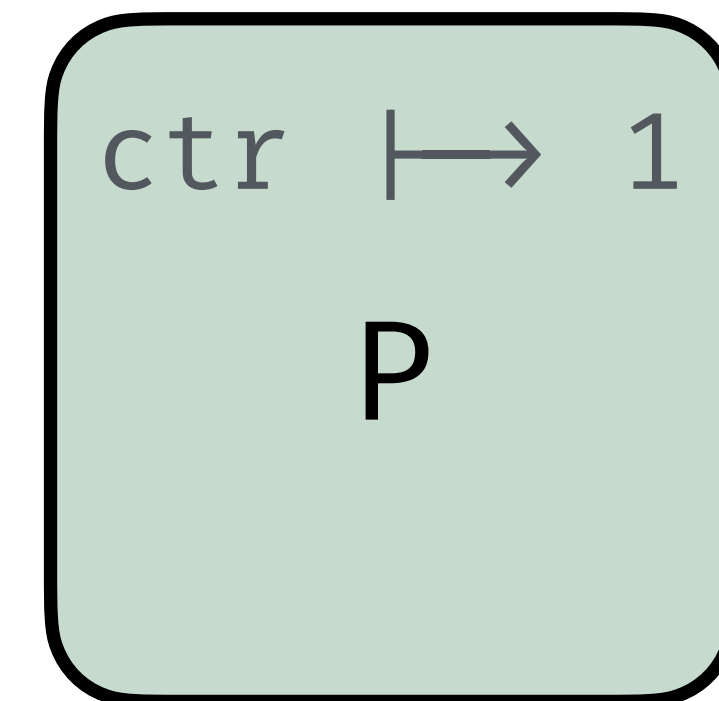
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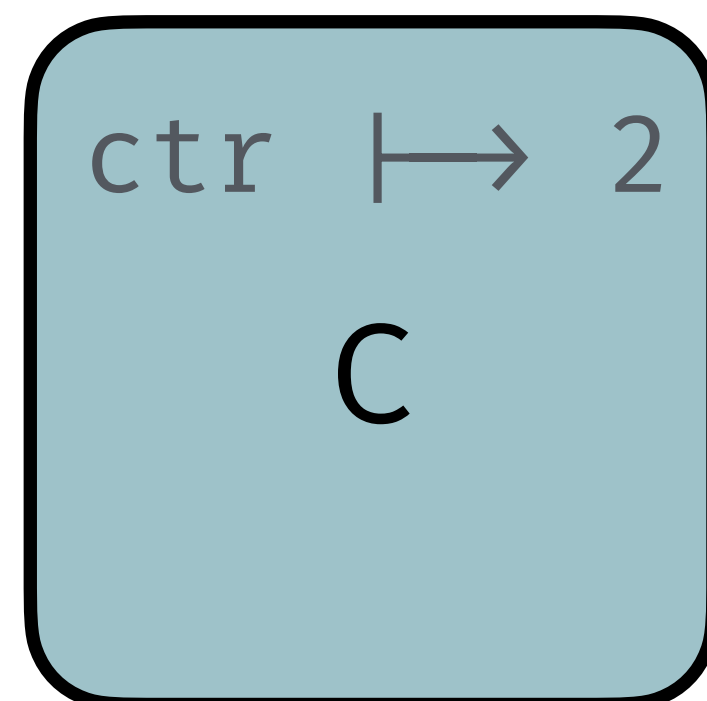
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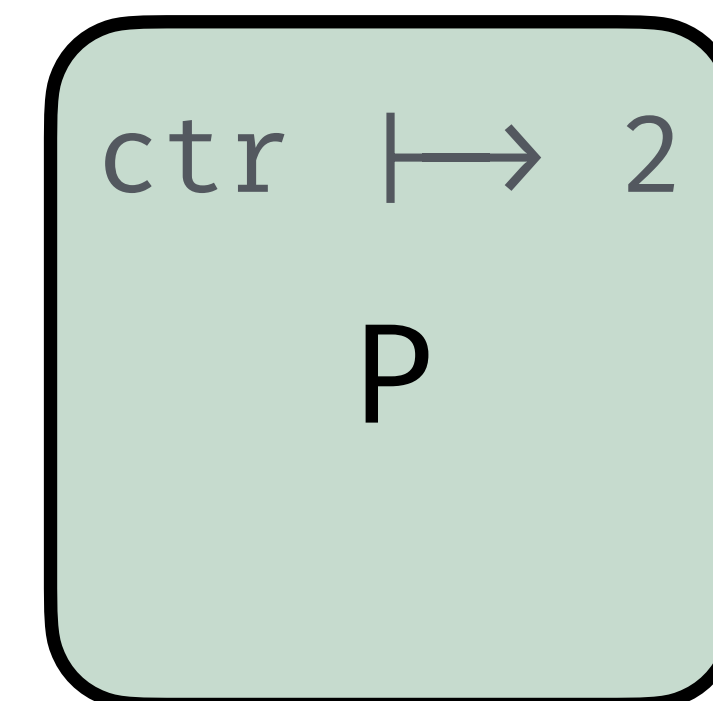
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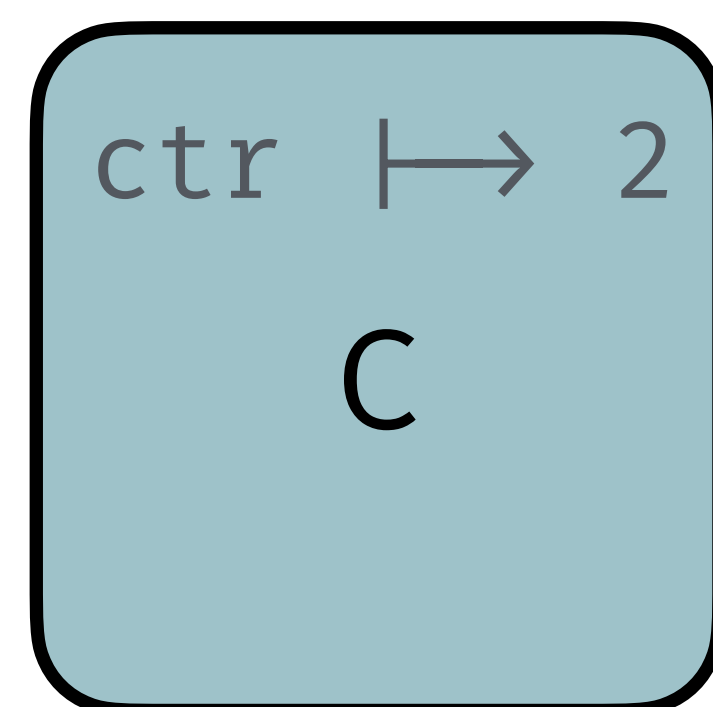
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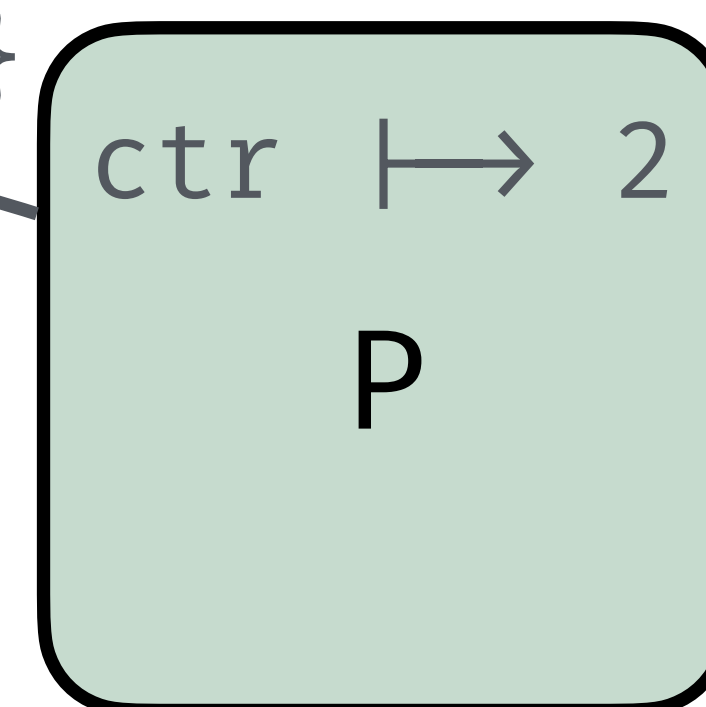
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Ret P C 4

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Decently easy:

- Manipulates **one finite object** (a trace)
- **Simple logic**: just emit the events one by one
- Proof by **induction** on the trace
- Less than 600 LoC (including comments)

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- So far: **safety properties** only
- Some security properties are more than safety: **hypersafety** (noninterference), **relational hypersafety** (observational equivalence)
- Can we adapt the proof technique to obtain a **stronger criterion** than RSP?

Can we get a stronger result?

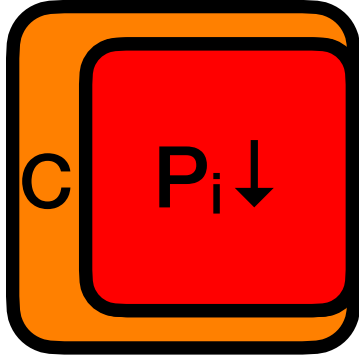
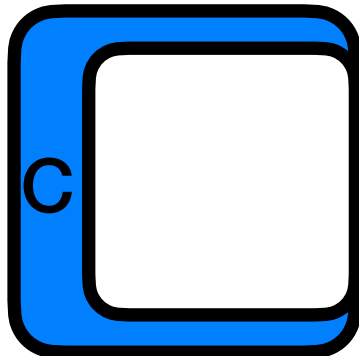
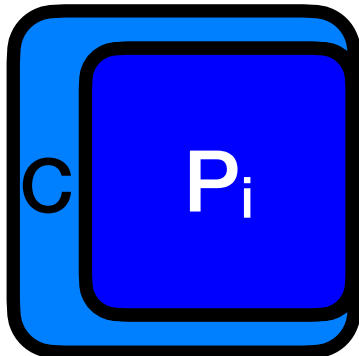
- So far: **safety properties** only
- Some security properties are more than safety: **hypersafety** (noninterference), **relational hypersafety** (observational equivalence)
- Can we adapt the proof technique to obtain a **stronger criterion** than RSP?

Yes!

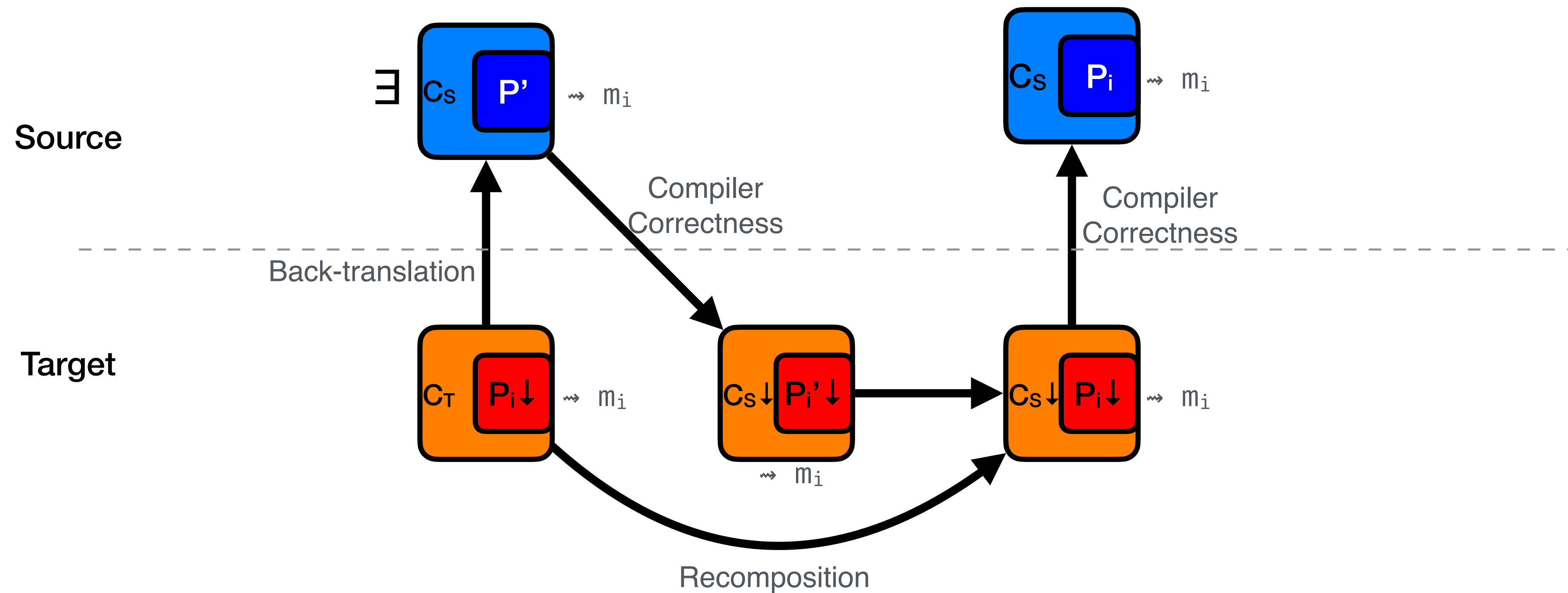
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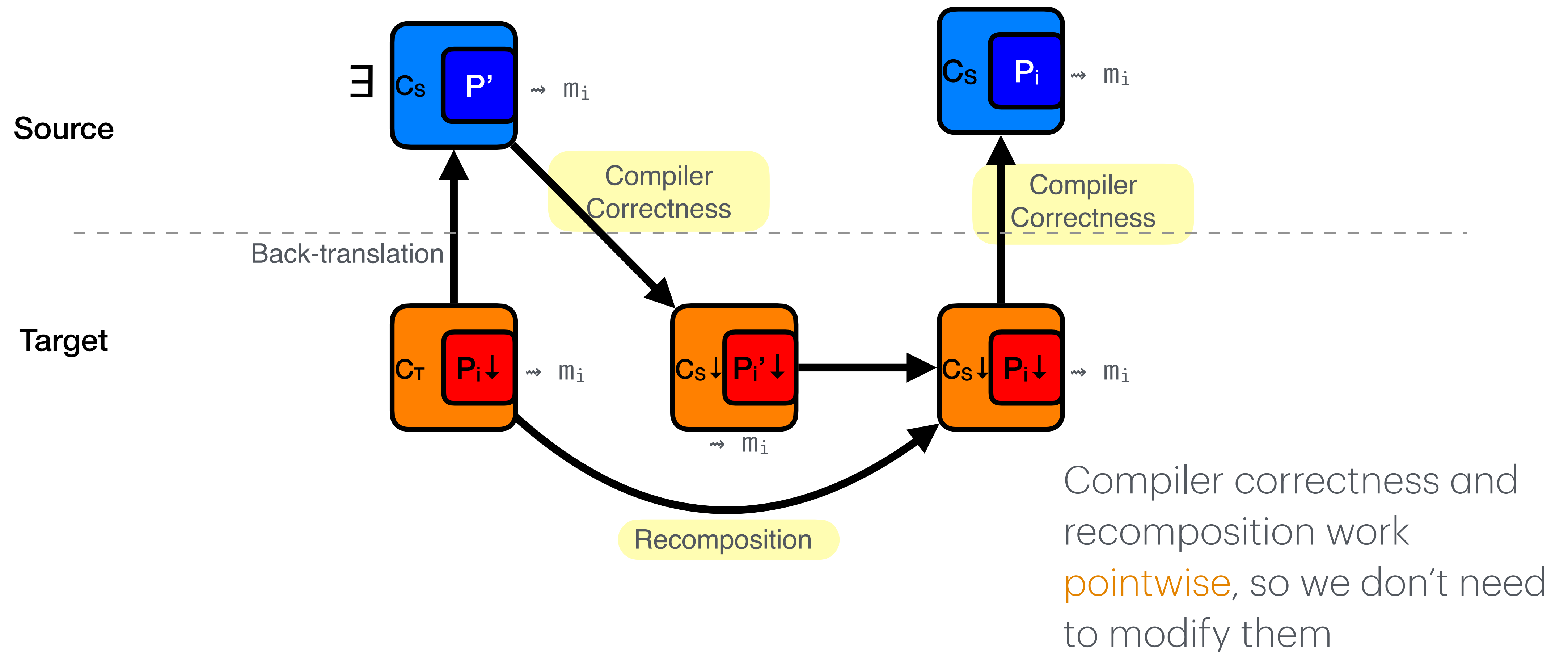
Yes!

If  produces finite trace **m_i** (for $0 \leq i < n$)
then there exists  such that  produces **m_i**

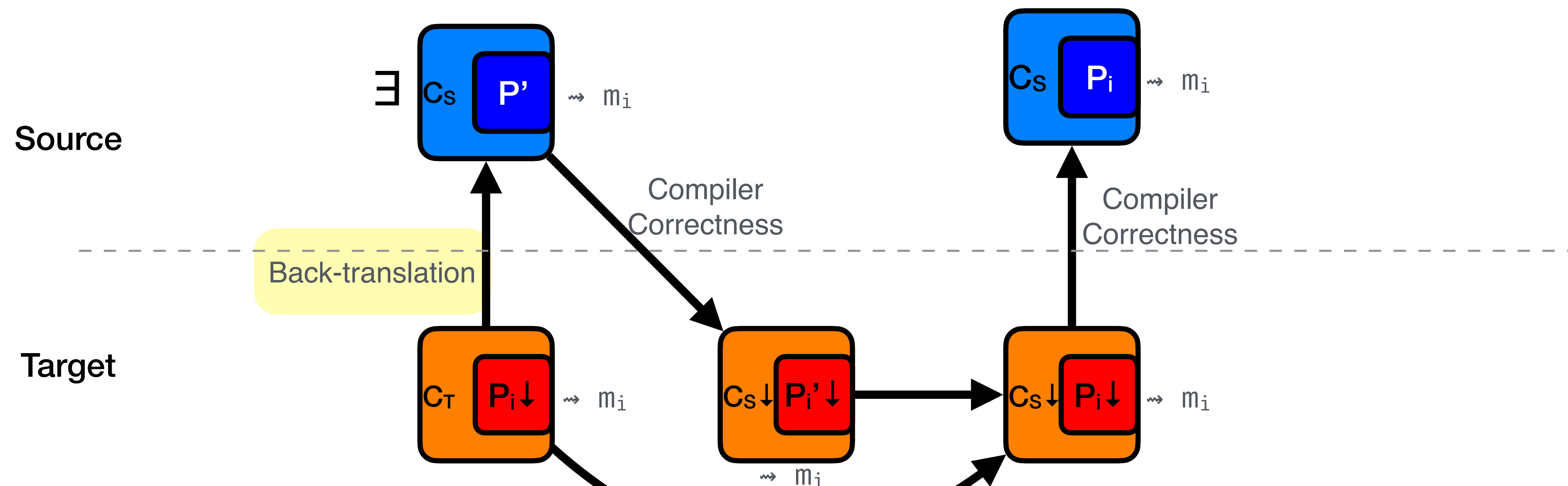
Adapting the proof for multiple programs



Adapting the proof for multiple programs



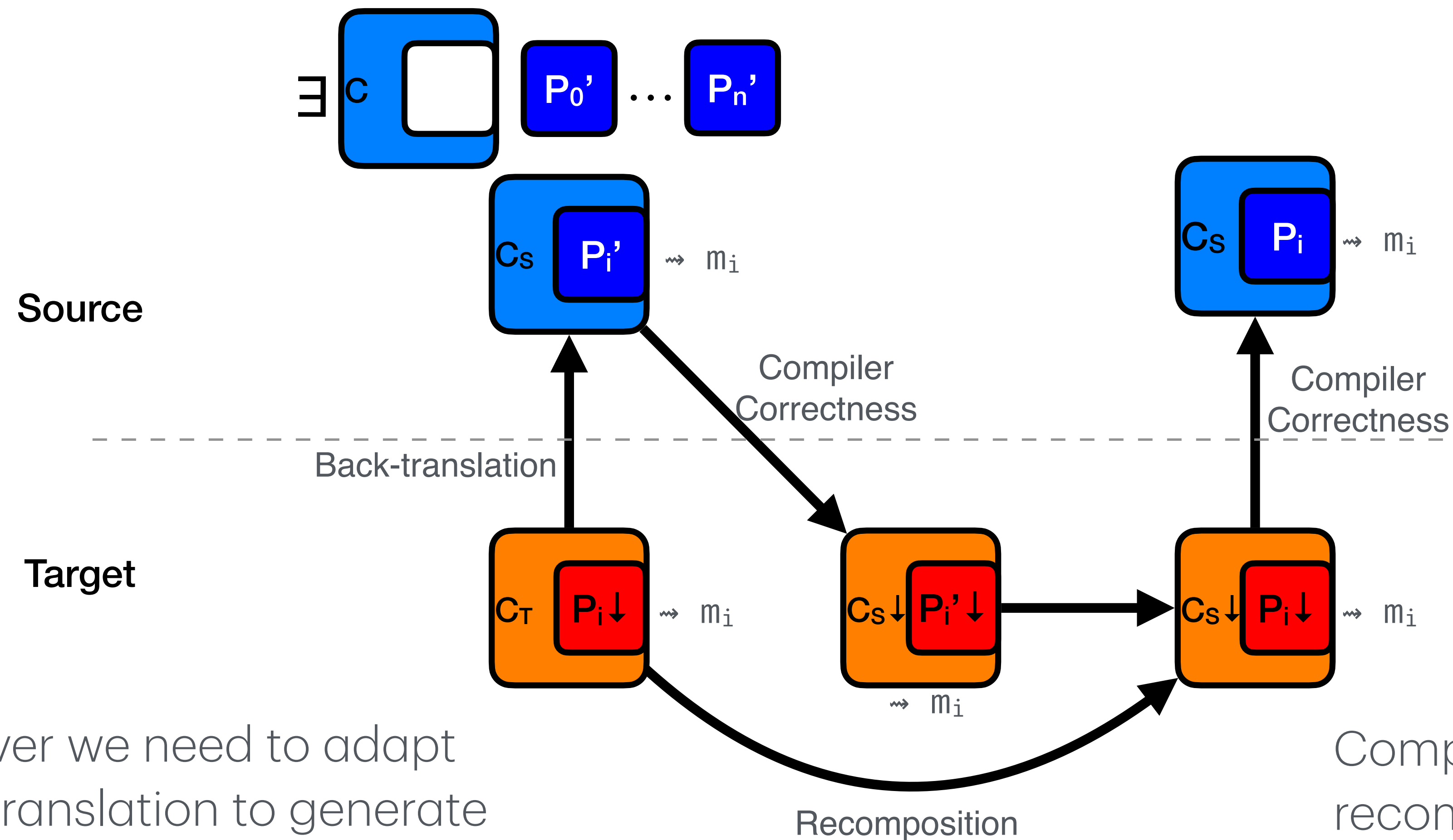
Adapting the proof for multiple programs



However we need to adapt back-translation to generate **one context** and **several programs**

Compiler correctness and recomposition work **pointwise**, so we don't need to modify them

Adapting the proof for multiple programs



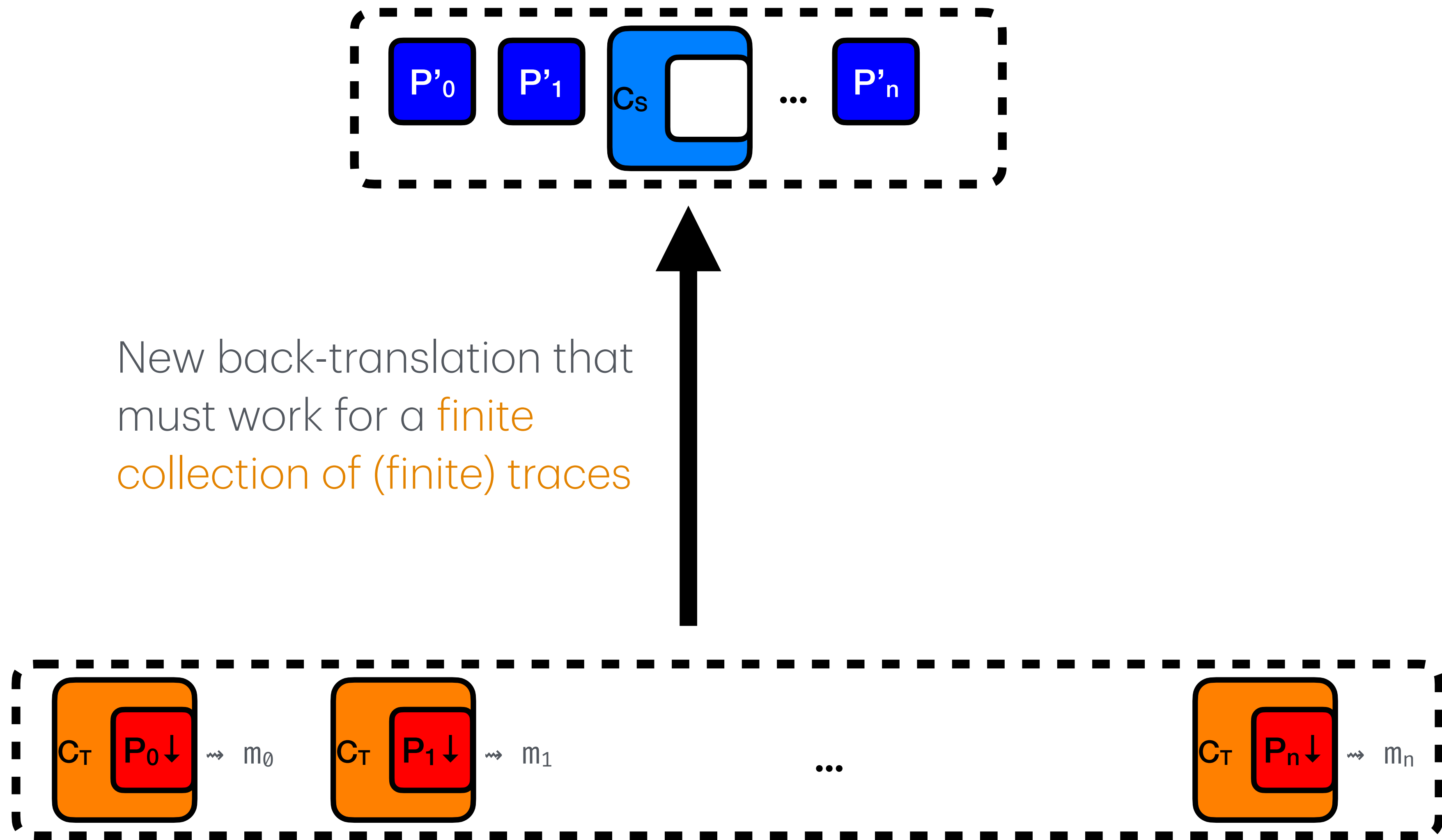
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Back-translation for several traces



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Back-translation for several traces

$$\boxed{P'_0 \quad P'_1 \quad C_s \quad \dots \quad P'_n} = (m_0, m_1, \dots, m_n) \uparrow$$

New back-translation that
must work for a **finite**
collection of (finite) traces



Structure of the traces



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Traces are produced by
the **same context** but
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Determinacy property:
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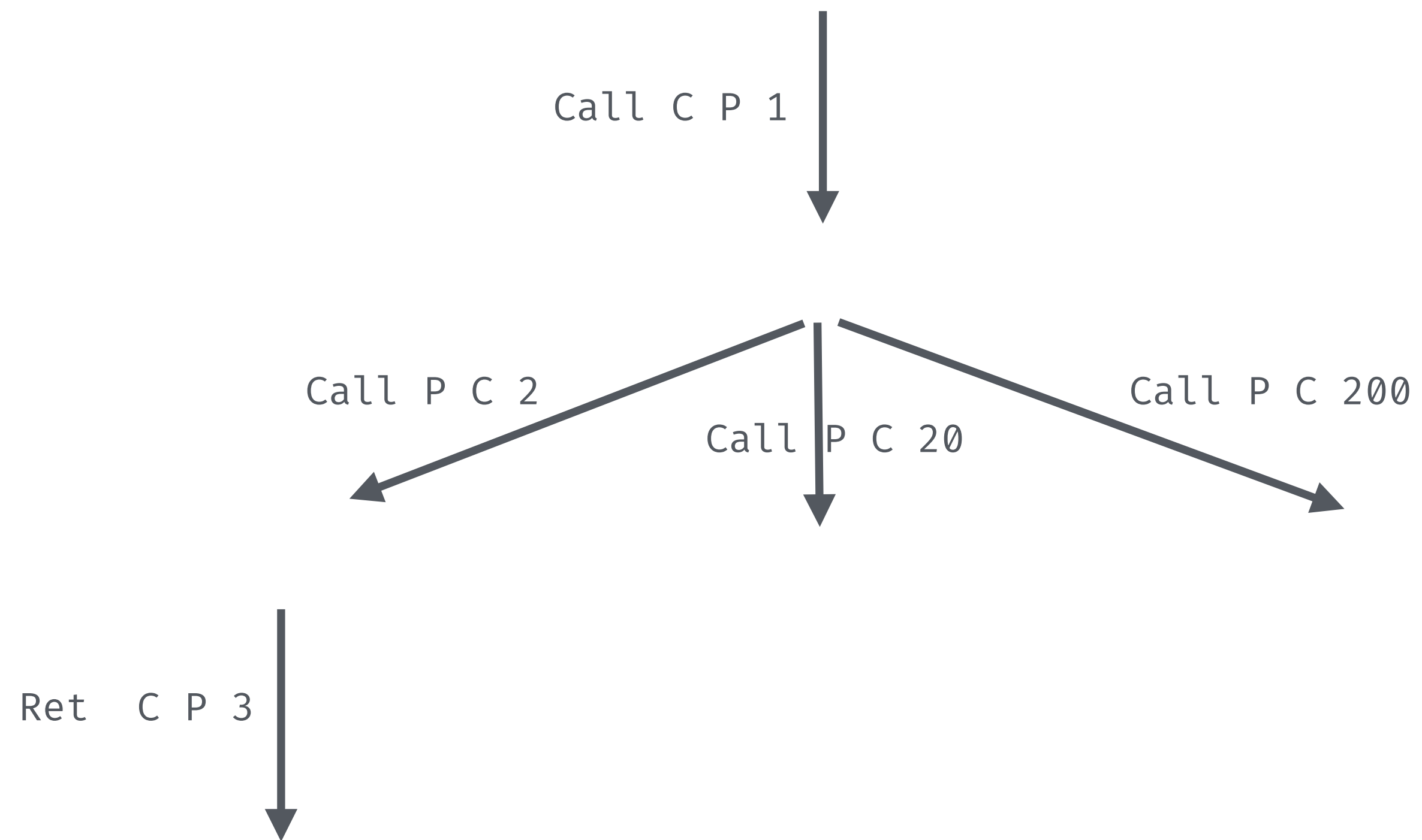
Traces are produced by the **same context** but **different programs**

Traces m_0, m_1, \dots, m_n can be represented by a tree T that **branches on events from P**

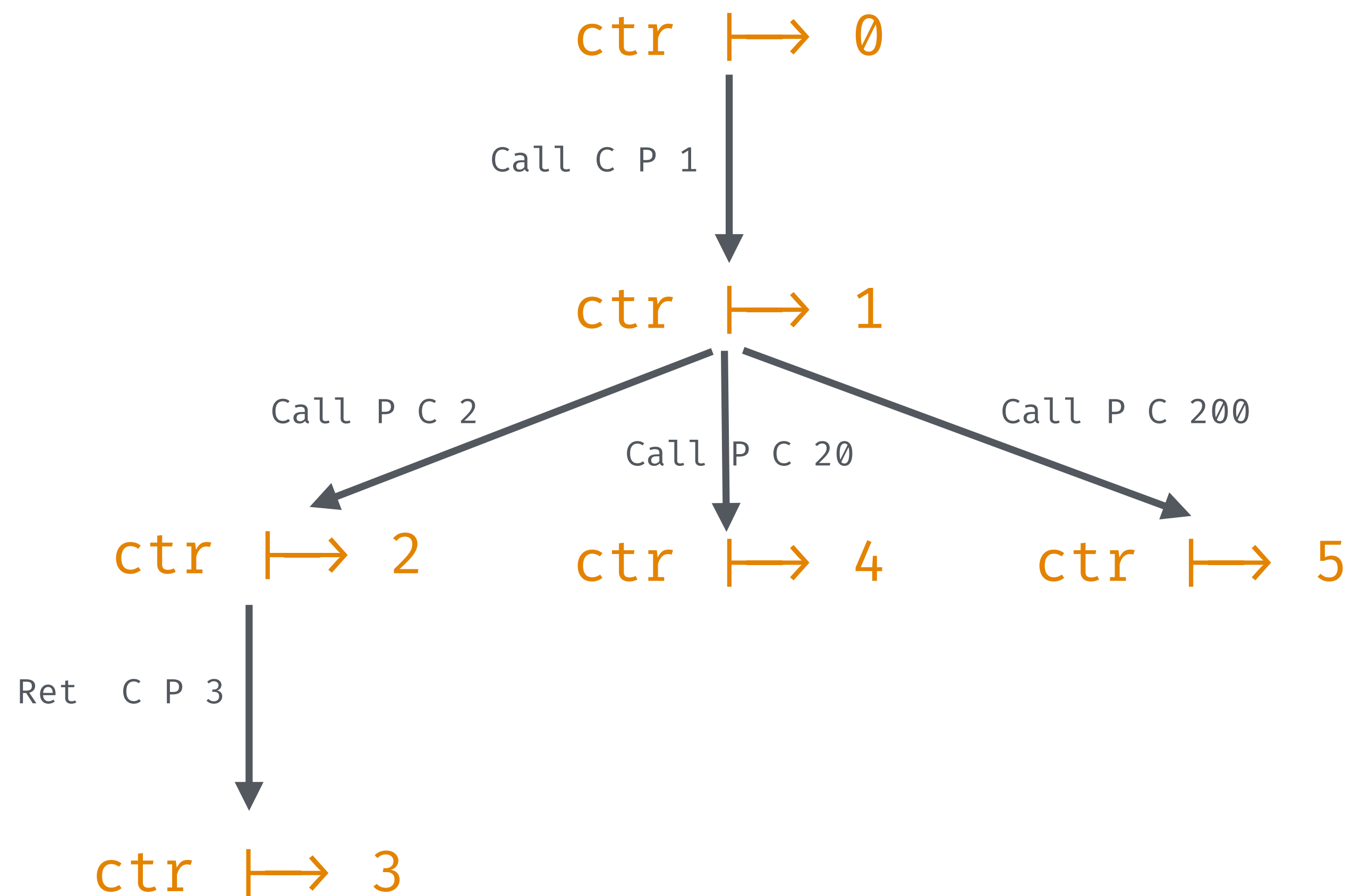
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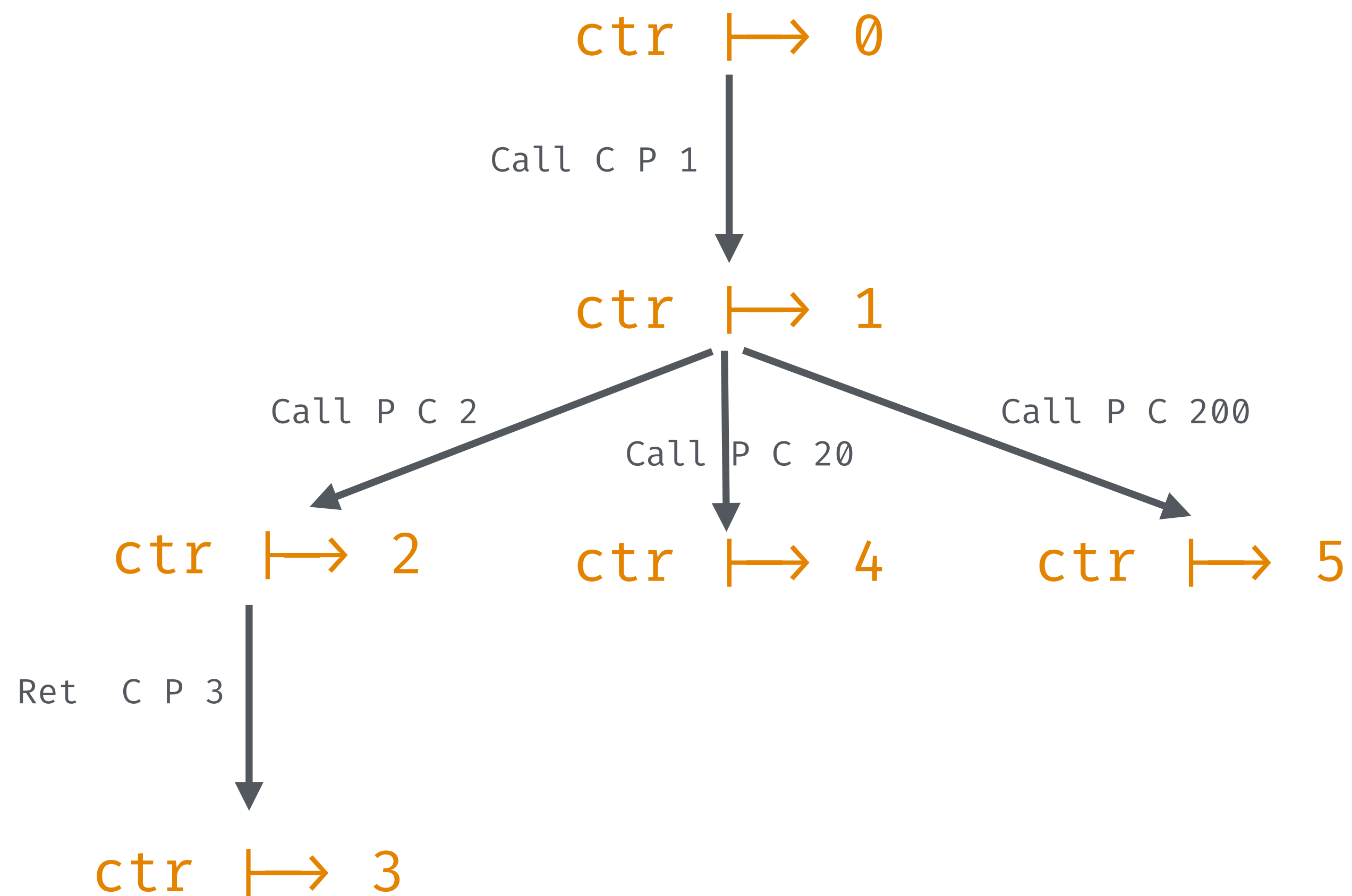
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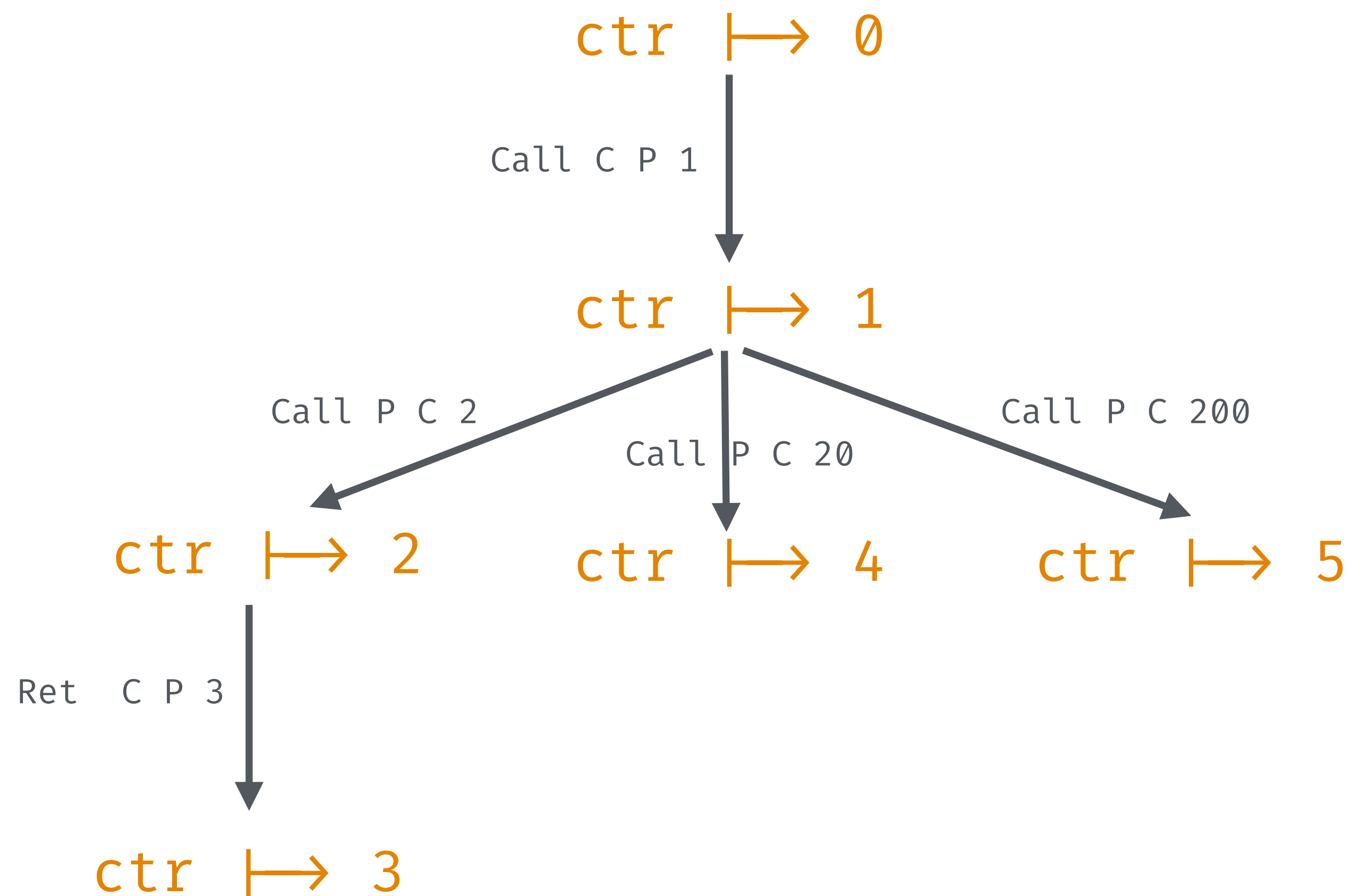
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To back-translate:

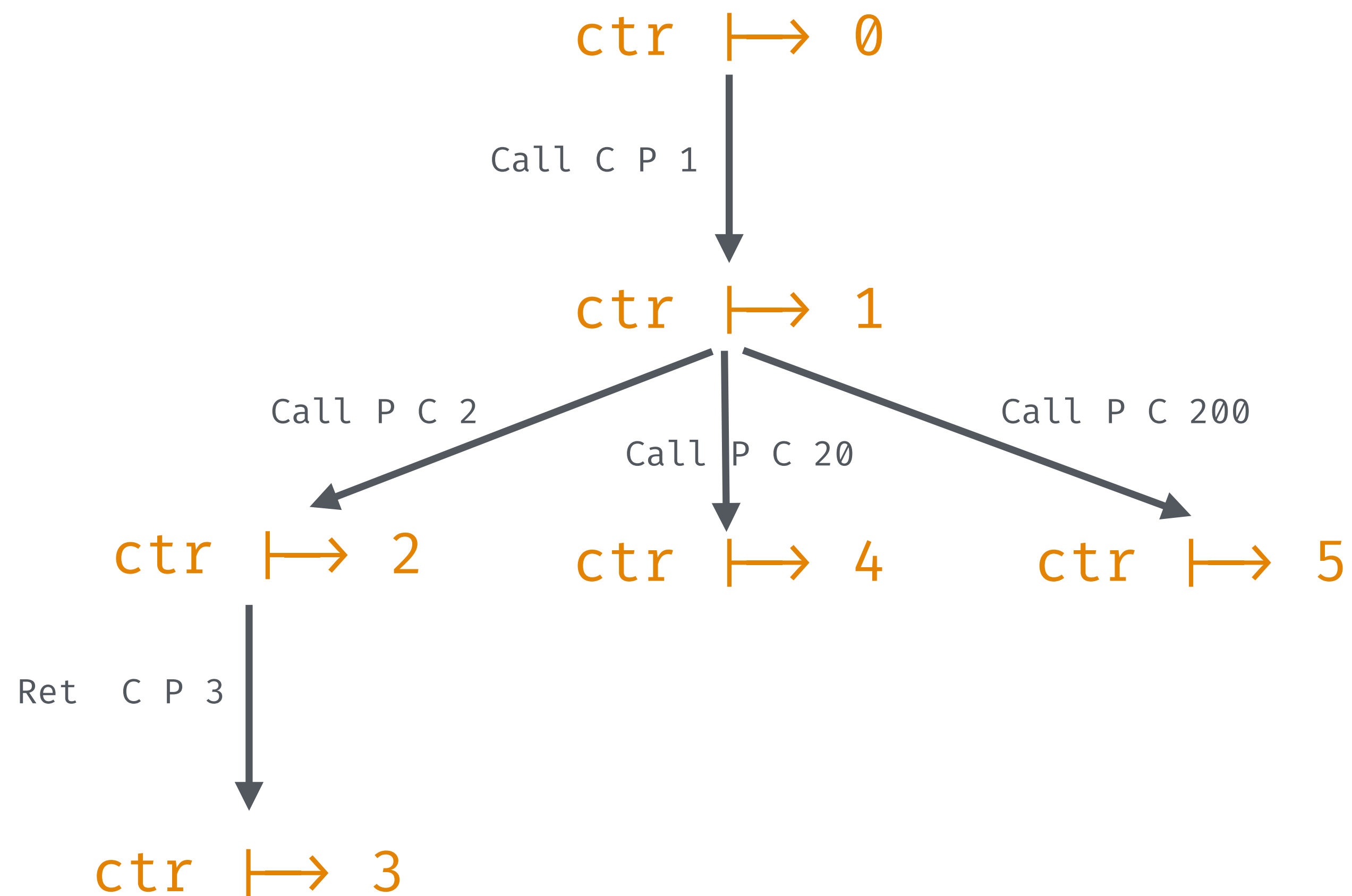
- Generalize the counter to **record position in the tree**
- Context needs to **look at argument and return value** before updating its local counter
- Also need to look at **current local counter**

Back-translating trees is harder



```
if (ctr = K && call_arg = V) {  
    ctr := NEXT_CTR(K, V);  
    DO_EVENT(K, V);  
    C();  
}  
...
```

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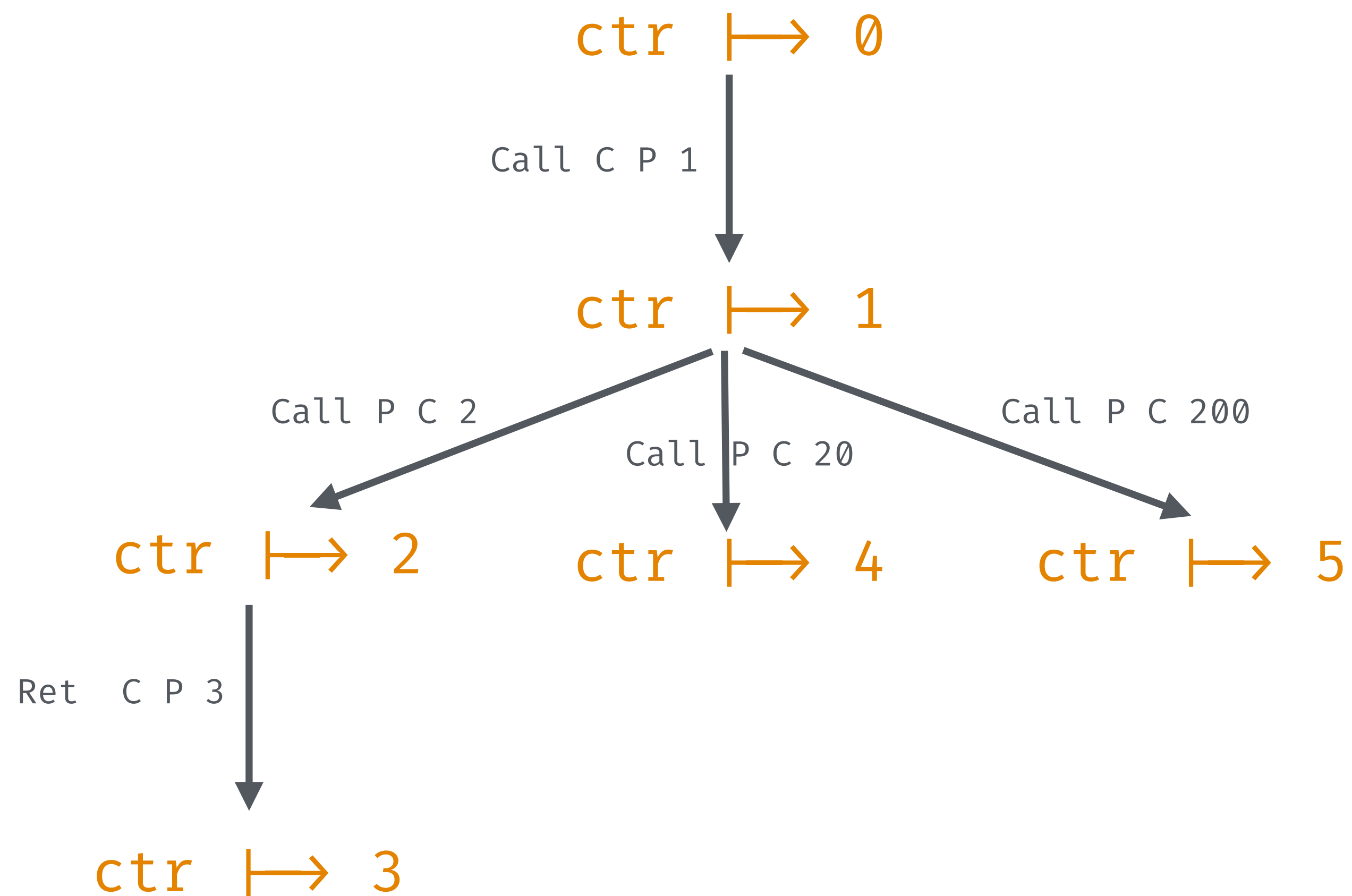


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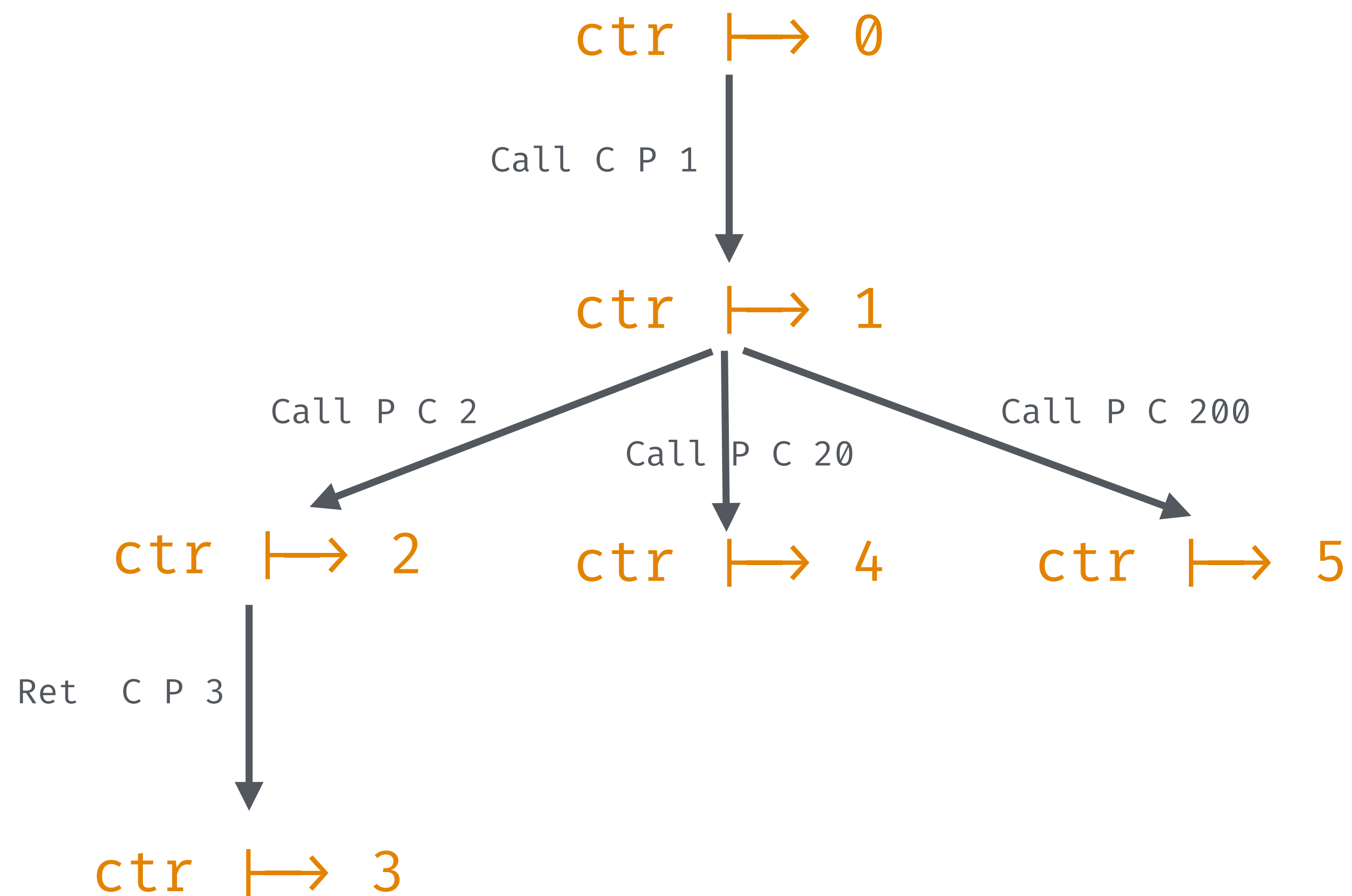
Back-translation function is not trivial!

Proving the back-translation is also harder

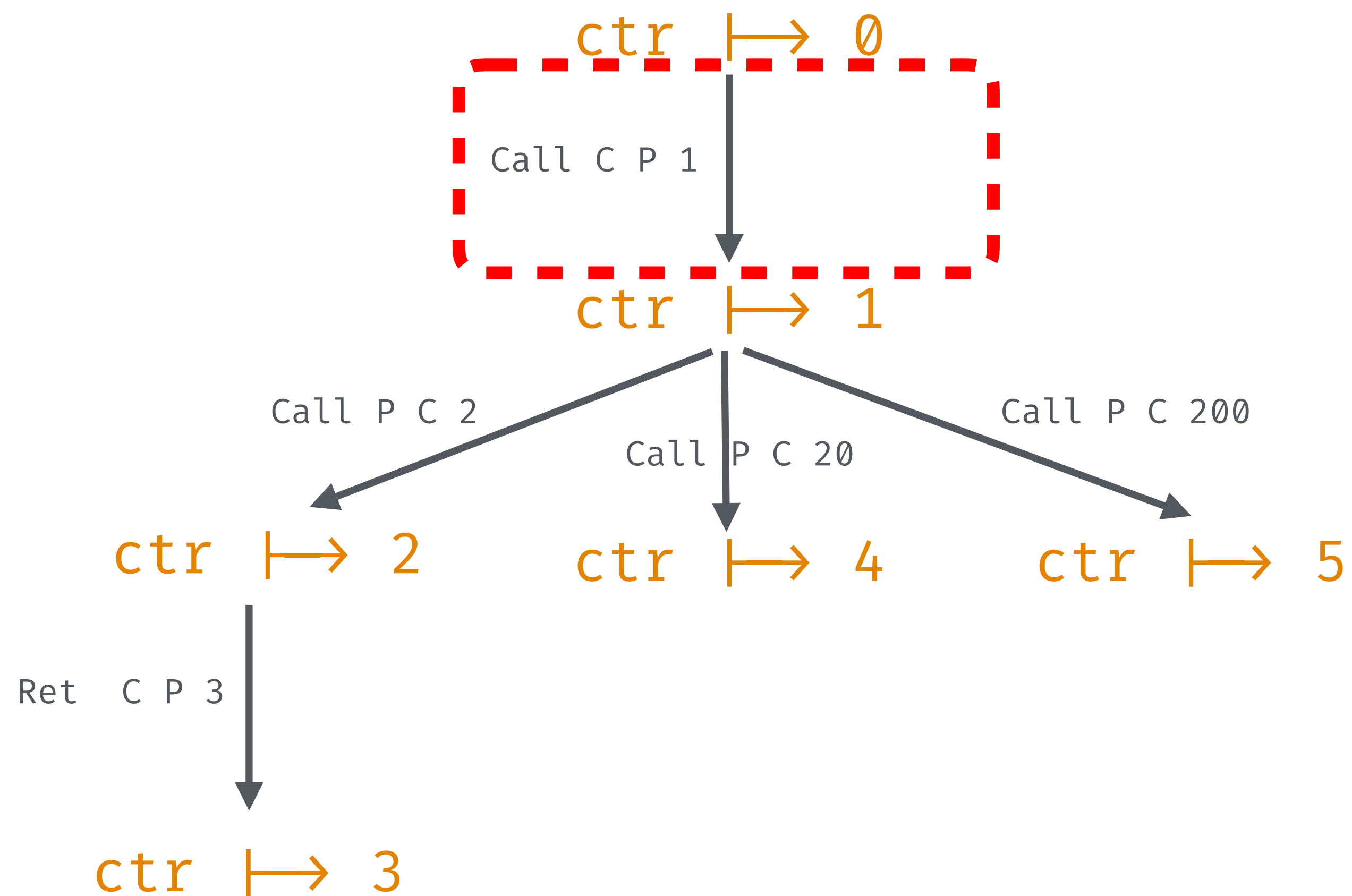


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Non-trivial invariants!



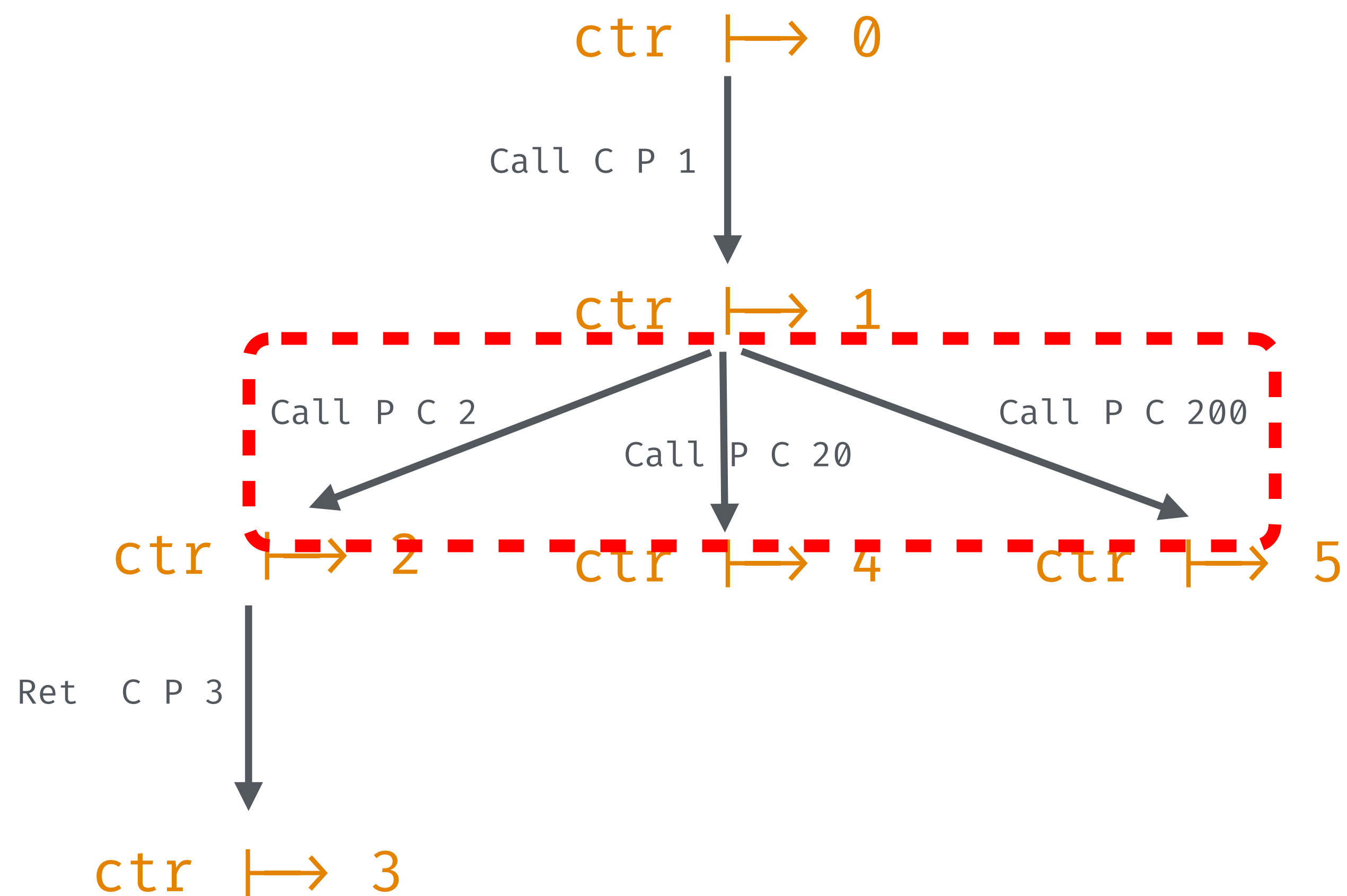
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Non-trivial invariants!

- Context can only do one event

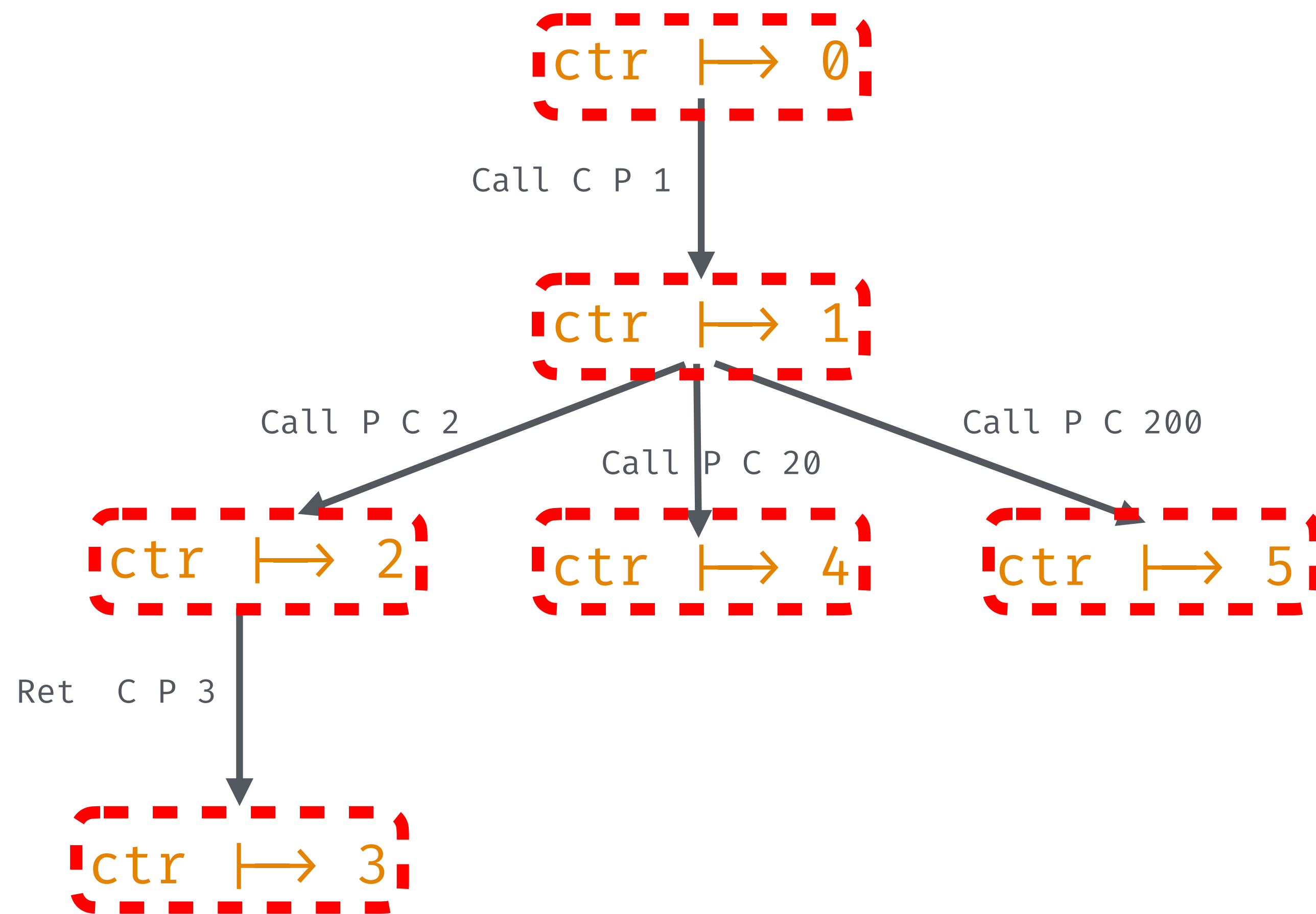
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Non-trivial invariants!

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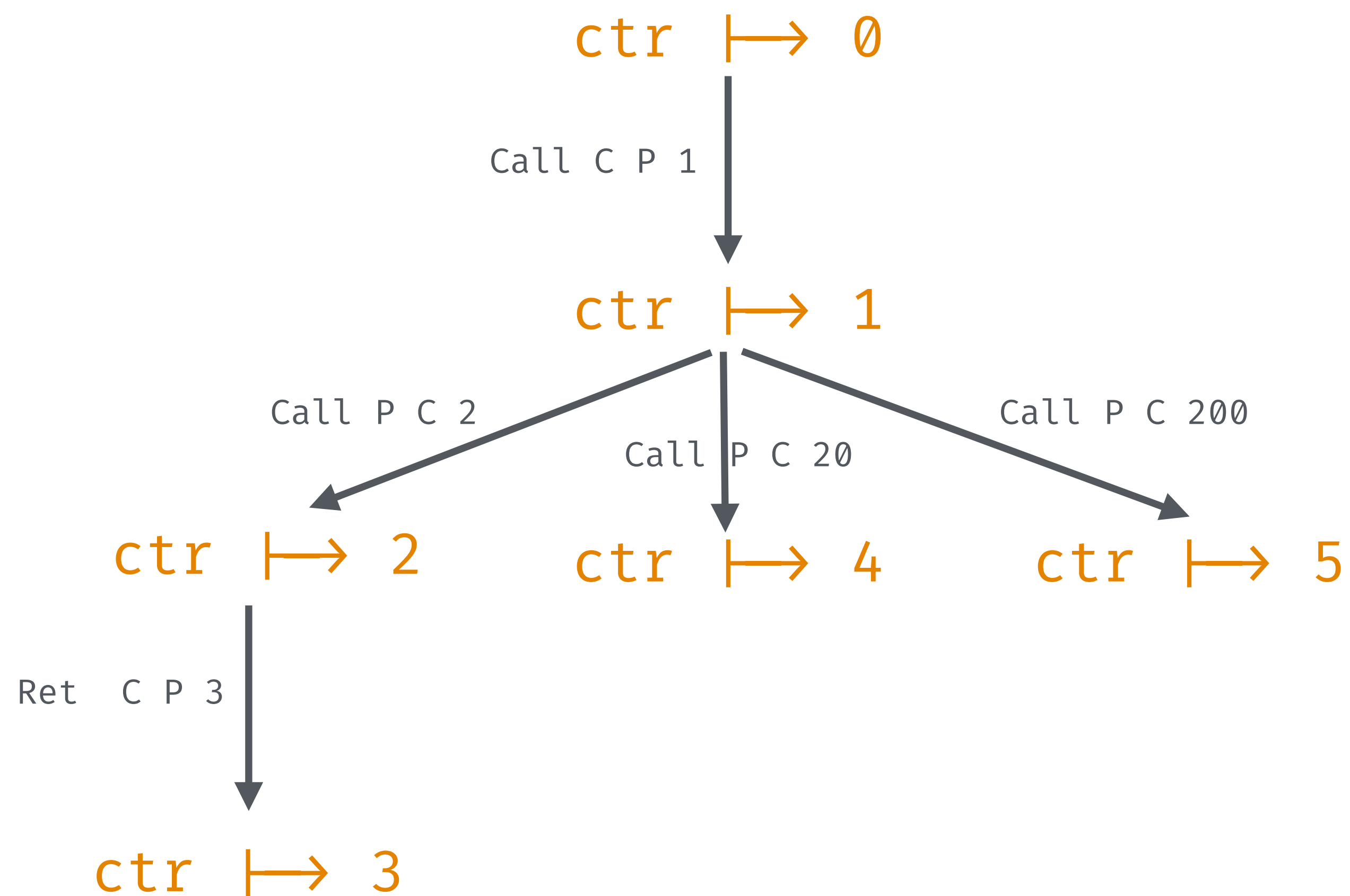
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Non-trivial invariants!

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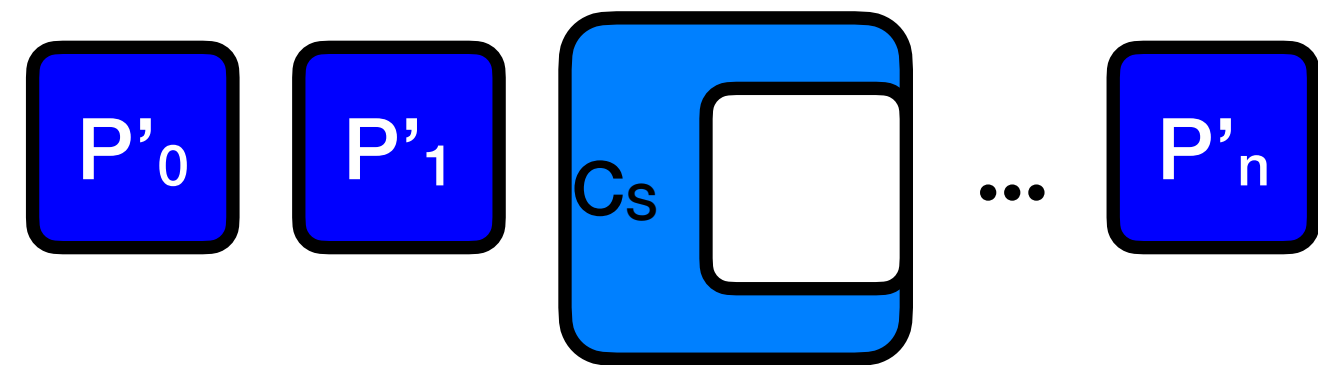


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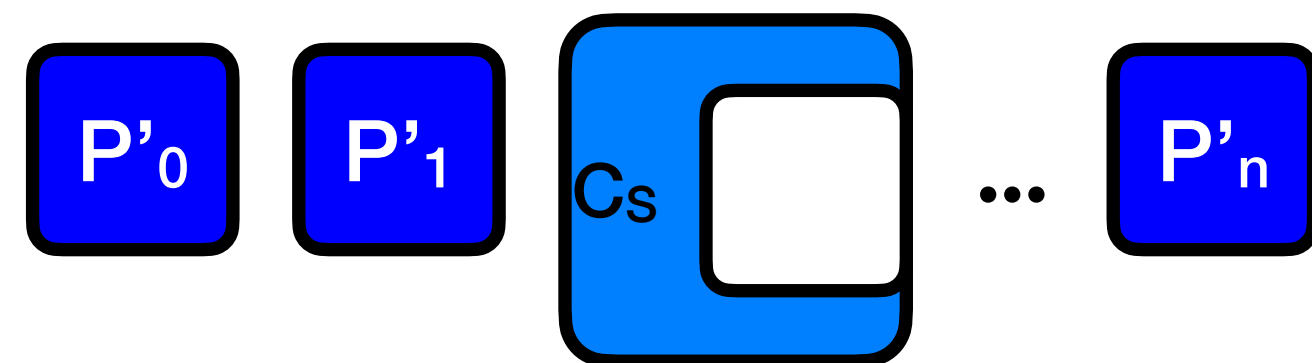
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- To handle returns: well-bracketedness

Back-translation in several steps

Back-translation in several steps

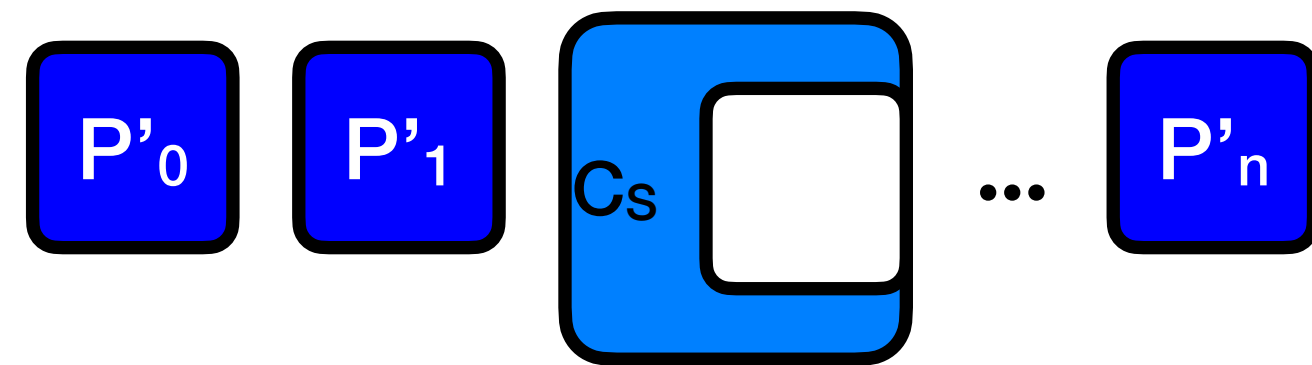


Back-translation in several steps



Tree T

Back-translation in several steps

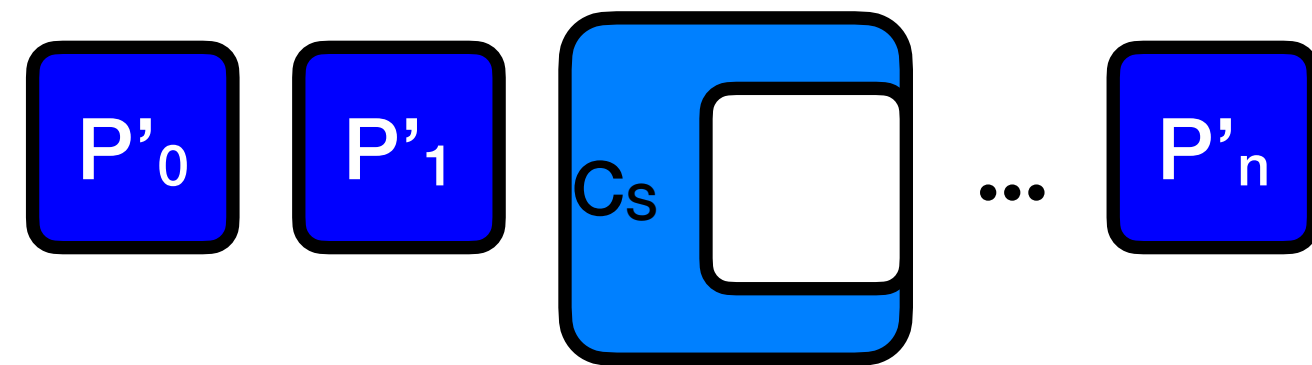


Tree T' with **ctr**



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Back-translation in several steps



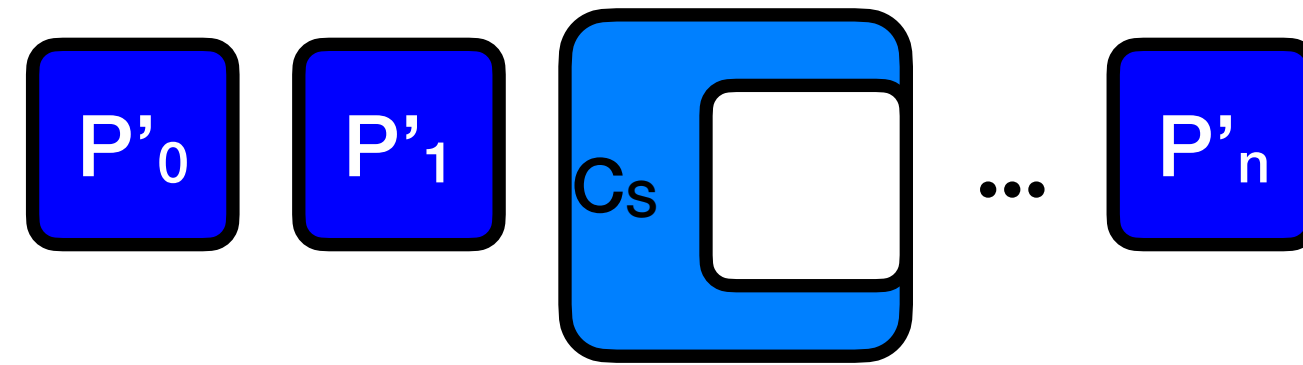
Tree T' with **stack record**

Tree T' with **ctr**

Tree T



Back-translation in several steps



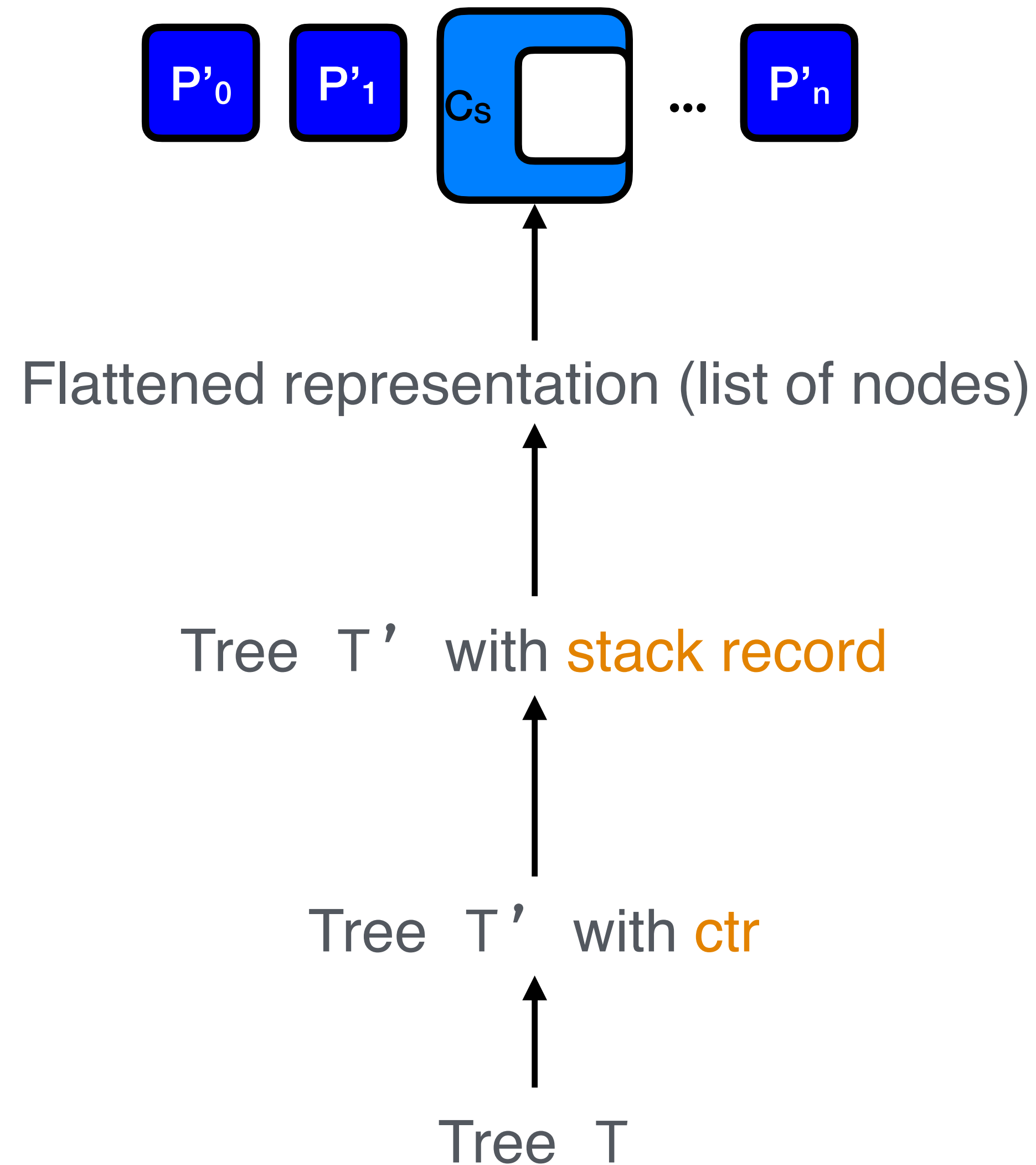
Flattened representation (list of nodes)

Tree T' with **stack record**

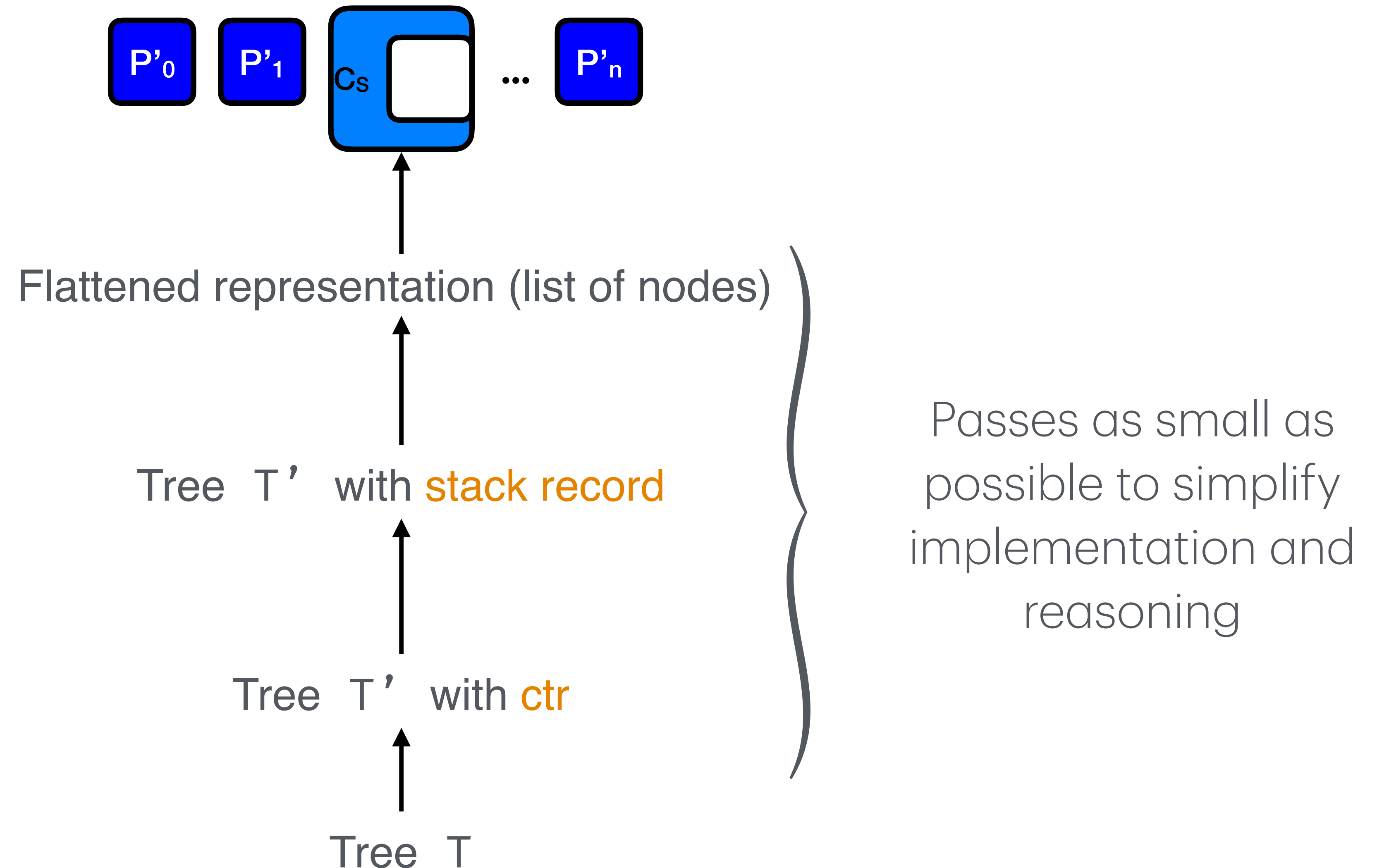
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Back-translation in several steps



Proving back-translation (2)

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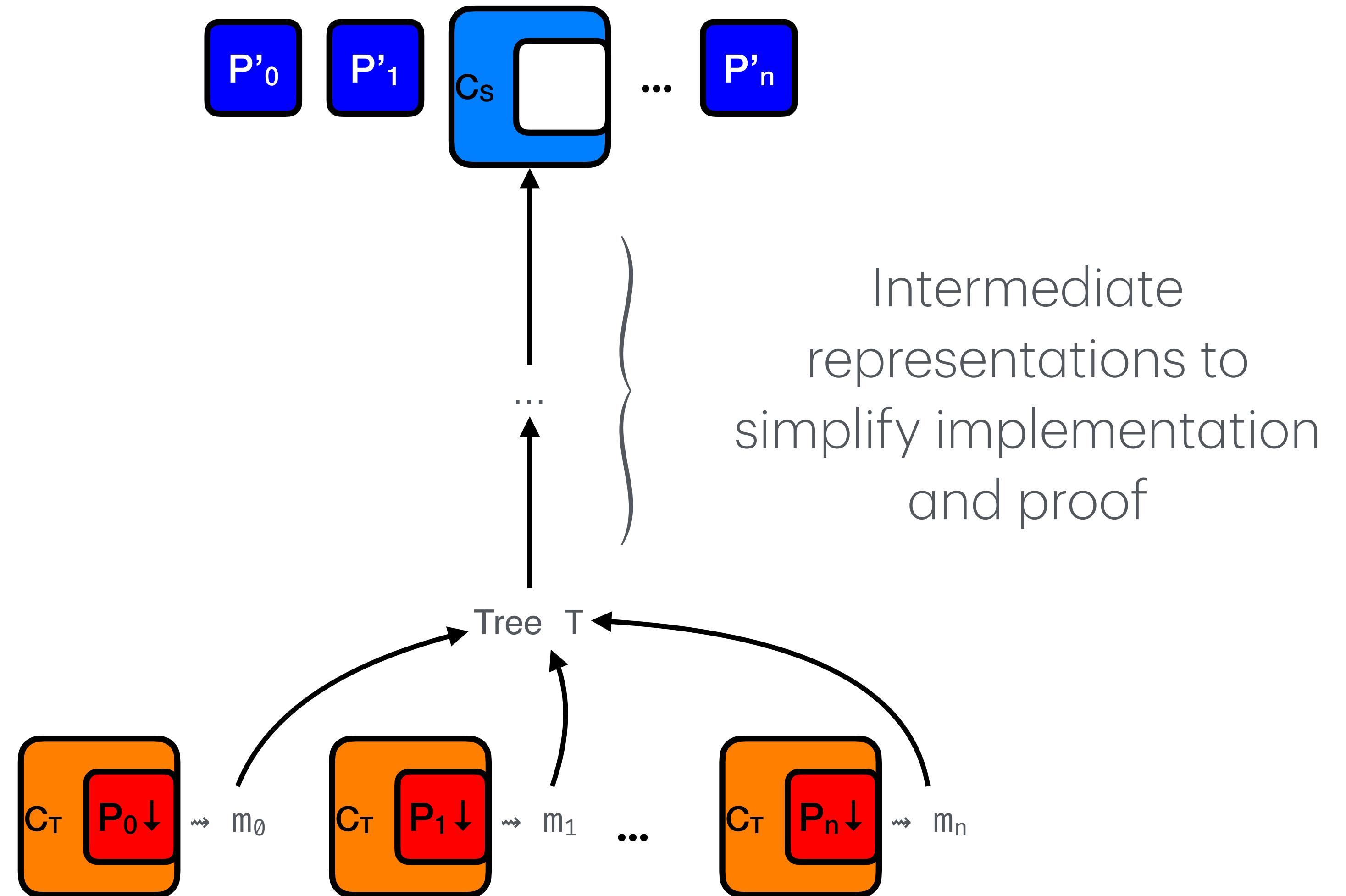
- For instance, **returns** can only occur when the **stack isn't empty** and the top stack-frame records the caller/callee

$$\begin{array}{c} \text{stack} = (C, P) :: \text{stack}' \\ e = \text{Ret } P \ C \ z \\ \dots \\ \hline s, \text{stack} \rightarrow_e s', \text{stack}' \end{array}$$

Proving back-translation (3)

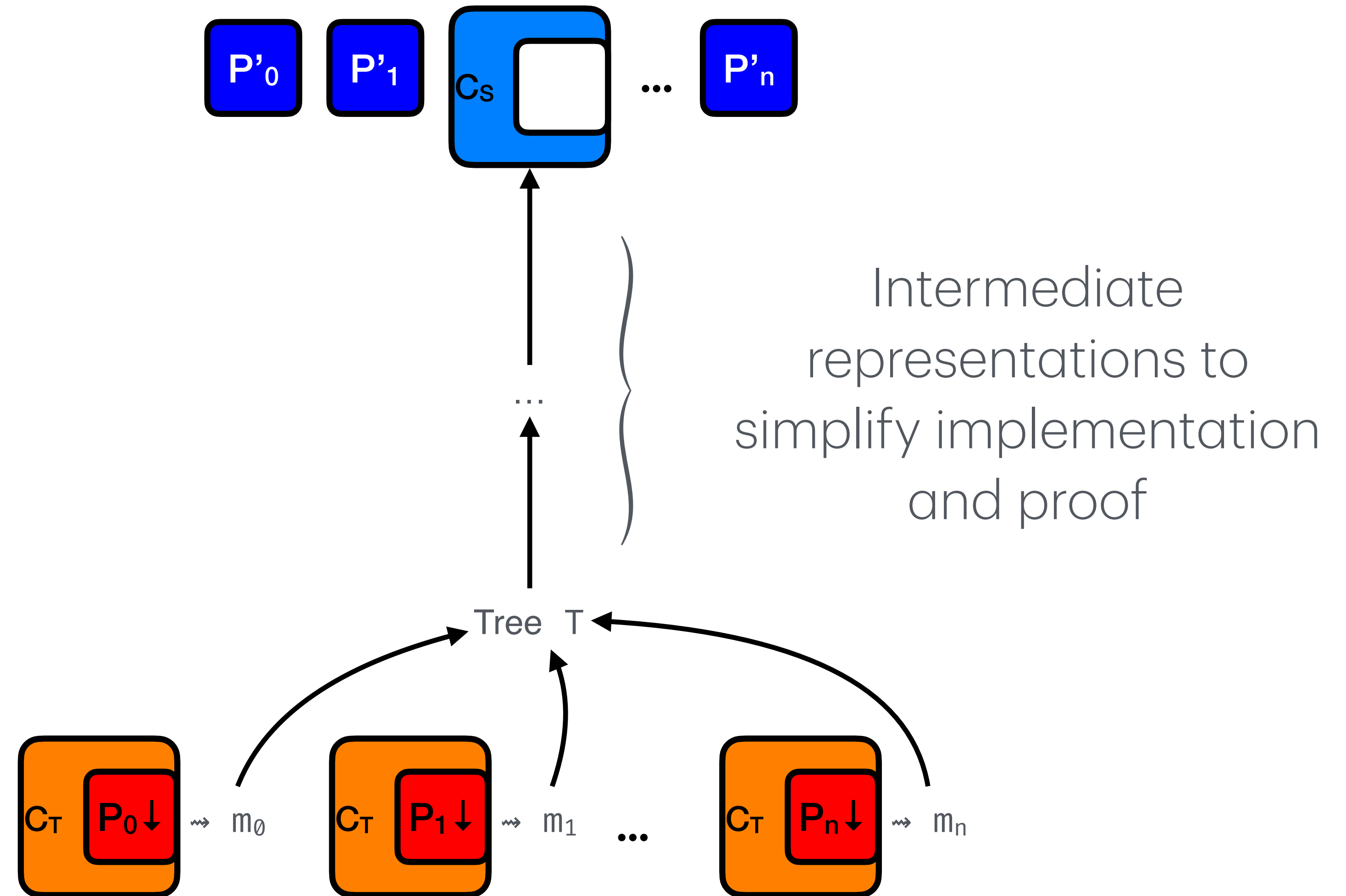
- Each pass: CompCert-style forward simulation
 - Small passes means individual proofs are not so complicated
- What is difficult: “flattening”
 - Pass that goes from trees to list of nodes (closer to final code)
 - Unicity and determinacy conditions
- In the actual implementation: multiples compartments, not just two

Conclusion



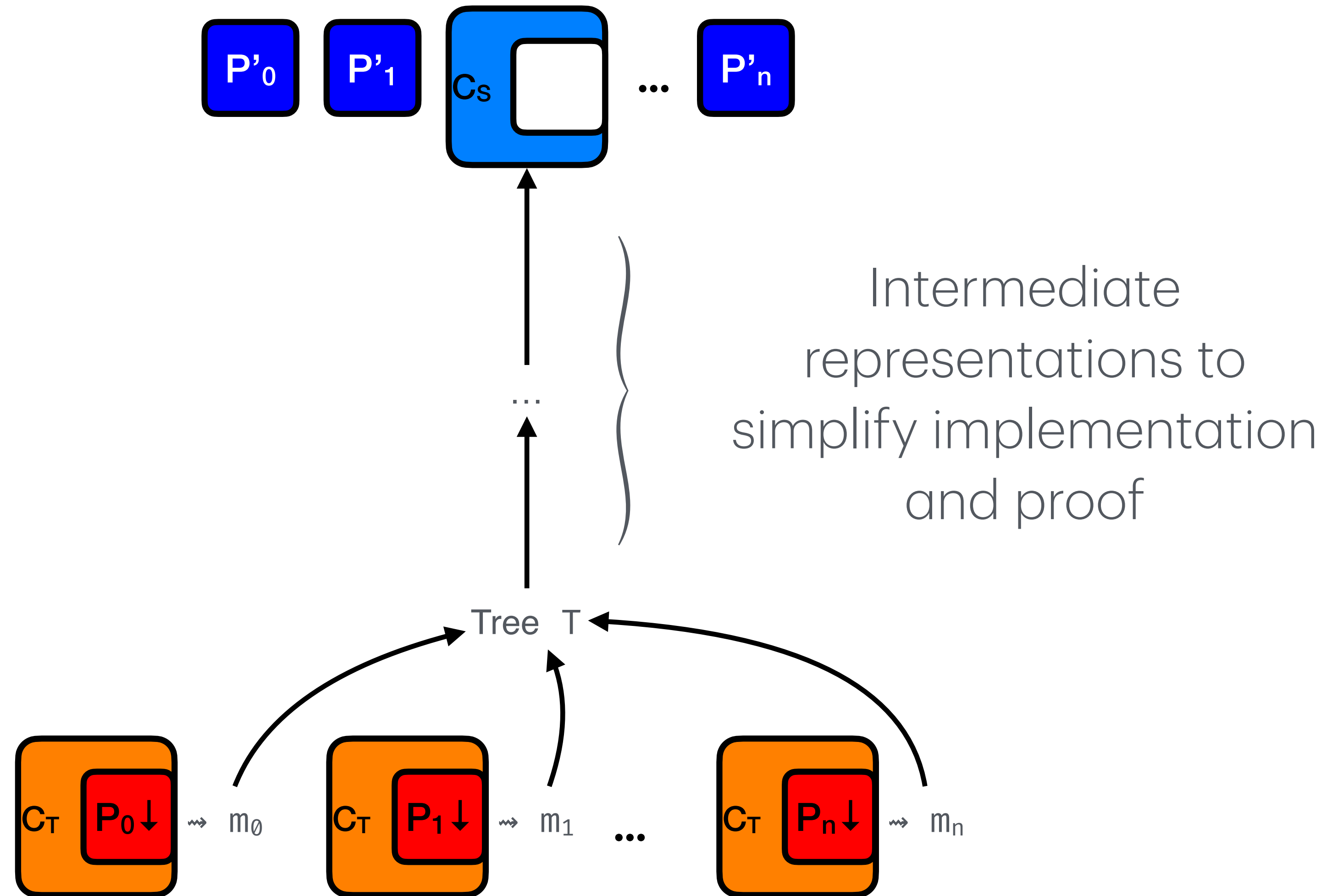
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- Also helps with parallelizing the proof process

