

# Formalization of matching numbers with mathcomp-finmap and -classical

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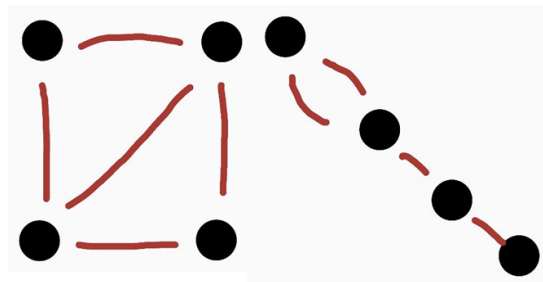
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# Motivation

# Graphs

Graphs we talk about consist of vertices and edges, and are undirected:

- $V$  : type of vertices
- $E$  : type of edges
- $d$  : mapping from edges to sets of vertices
- axiom :  $|d(x)| = 2$



# Motivation: relation to commutative algebra

From a graph  $G = (V, E, d)$ , algebraic objects can be constructed:

- a commutative polynomial ring  $S$ , by regarding vertices as variables
- an edge ideal  $I$ , by reading each edge  $\{x, y\}$  as a monomial  $xy$

It is known that some invariants of the quotient ring  $S/I$  are bounded by the graph invariants we formalized.

Towards this goal, we have managed to finish the graph theory side, leaving formalization of ideals almost untouched.

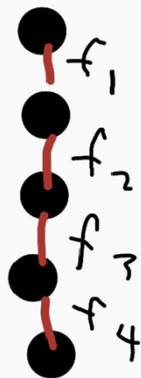
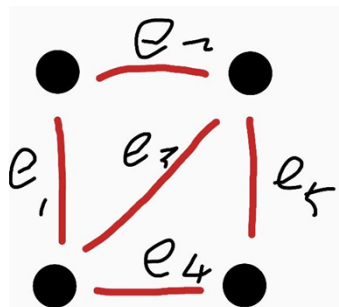
# Graph invariants – Matching numbers

For a graph  $(V, E, d)$ , a subset of edges  $S \subset E$  is called a  
    matching set                      if no two edges share a vertex, and an  
    induced matching set      if no two edges are connected by an edge

From these sets, the following graph invariants are defined:

matching number	Maximum size of a matching set
induced matching number	Maximum size of an induced matching set
minimal matching number	<u>Minimum</u> size of a maximal matching set

## Graph invariants – Matching numbers (contd.)



$\{e_1, e_5\}$ ,  $\{e_2, e_4\}$  and singletons are matching sets for the first graph, but only the singletons are induced matching sets.

Similarly,  $\{f_1, f_3\}$ ,  $\{f_2, f_4\}$ ,  $\{f_1, f_4\}$ , and singletons are matching sets for the second graph, but in this case  $\{f_1, f_4\}$  is also an induced matching.

## Graph invariants – independence number

For a graph  $(V, E, d)$ , a subset of vertices  $S \subset V$  is called an independent set, if no two points in it do not have an edge between them.

The independence number  $\text{nindep}$  is the maximum size of an independent set.



## In our formalization

We formalized inequalities between these invariants, which all appear not only in graph theory, but in the context of commutative algebra:

$$\text{nindmatch} \leq \text{nminmatch} \leq \text{nmatch} \leq 2\text{nminmatch}$$

$$\text{nindmatch} \leq \text{nindep}$$

$$2(\text{nmatch} - \text{nminmatch}) \leq \text{nindep}$$

## Rocq definitions of graphs

# Graph as a module

In the first attempt, we formalized graphs as a module:

```
Module LooplessUndirectedGraph.  
Section def.  
Record t := mk {  
  V : finType;  
  E : finType;  
  boundary : E -> {fset V};  
  _ : forall e : E, #|` boundary e | = 2;  
}.  
End def.  
Module Exports.  
Notation llugraph := t.  Notation "`d" := boundary.  
Notation "`E"         := E.  Notation "`V" := V.  
End Exports.  
End LooplessUndirectedGraph.  
Import LooplessUndirectedGraph.Exports.
```

# Graph as an HB structure

We rewrote the definition using HB for future extensions:

```
HB.mixin Record isLooplessUndirectedGraph T := {  
  vertex : finType;  
  edge : finType;  
  boundary : edge -> {fset vertex};  
  size_boundary : forall e : edge, size (boundary e) = 2;  
}.
```

```
#[short(type=llugraph)]  
HB.structure Definition LooplessUndirectedGraph :=  
  {T of isLooplessUndirectedGraph T}.
```

Notation "`V" := vertex.

Notation "`E" := edge.

Notation "`d" := boundary.

## Transition to HB

To move from **Module** to HB, changes were needed  
only in concrete examples .

First, applications of the record constructor mk

```
Record t := mk { V:finType; E:finType; boundary:E->{fset V};  
  _ : forall e : E, #|` boundary e | = 2; }.
```

had to be replaced by HB.instance:

```
Definition V := 'I_2.
```

```
Definition E := 'I_2.
```

```
Definition d (_ : E) : {fset V} := fsetT.
```

```
Lemma axiom (e : E) : #|` d e | = 2.
```

```
Proof. by rewrite cardfst card_ord. Qed.
```

```
- Definition G := LooplessUndirectedGraph.mk axiom.
```

```
+ HB.instance Definition _ :=
```

```
+ isLooplessUndirectedGraph.Build unit axiom.
```

```
+ Notation G := unit.
```

## Transition to HB (contd.)

Second, we had to insert a trivial rewrite when doing a case analysis:

**Definition** V := 'I\_3. (\* v0, v1, v2 \*)

**Definition** E := 'I\_2. (\* e0, e1 \*)

**Definition** d (e : E) : {fset V} :=  
 if e == e0 then [fset v0; v1] else [fset v1; v2].

**Example** inj\_boundary\_is\_not\_necessarily\_matching :  
 exists S : {fset `E G}, inj\_boundary S /\ ~ @is\_matching G S.

**Proof.**

exists [fset: `E G]; split.

move => e f \_ \_ / =.

- rewrite /d.

+ rewrite (\_ : `d = d) // /d. (\* NB: `d is a mixin field \*)  
 by case: ifPn; (\* ... \*)

# A glitch?

```
Context {V E : finType} {d : E -> {fset V}}.  
  (proof : forall e : E, #|` d e | = 2).  
HB.instance Definition _ :=  
  isLooplessUndirectedGraph.Build unit axiom.  
Notation G := unit
```

The key type unit can however be anything:

```
Context (* ... *) (any_type : Type).  
HB.instance Definition _ :=  
  isLooplessUndirectedGraph.Build any_type axiom.  
Notation G := any_type
```

I might have abused HB  
(by not relating the mixin to its parameter)

## Rocq definitions of matching sets



# Finite sets and classical sets

MathComp, -Finmap and -Classical each provide a library for sets:

`set` in `MathComp` finite sets in a finite type;

list representation by enumerating `T`

`fset` in `Finmap` finite sets in a type with a choice function;

list representation by linear-ordering `T` by the choice

`set` in `Classical` arbitrary sets in an arbitrary type;

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- We need the cardinality of each matching set, so it has to be finite.
- Finmap fsets are better than MathComp sets for compatibility with the others.
- There can be a few design options for the set of all matching sets.

## matching as Finmap and Classical sets

Here are two definitions of `matching`, the set of all matching sets.  
With `Finmap`, we need to prepare a `bool`-valued (bracketed) predicate:

**Definition** `is_matching` (`S` : {fset `E G}) :=  
  $[\forall e \text{ in } S, [\forall f \text{ in } S, (e \neq f) \implies [\text{`d } e \perp \text{`d } f]]]$ .  
 *(\* [ X  $\perp$  Y ] = X and Y are disjoint \*)*

**Definition** `matching` : {fset {fset `E G}} :=  
 [fset S : {fset `E G} | `is_matching` S].

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With `Finmap`, we need to prepare a `bool`-valued (bracketed) predicate:

```
Definition is_matching (S : {fset `E G}) :=  
  [∀ e in S, [∀ f in S, (e != f) ==> [!d e ⊥ !d f]]].  
  (* [ X ⊥ Y ] = X and Y are disjoint *)
```

```
Definition matching : {fset {fset `E G}} :=  
  [fset S : {fset `E G} | is_matching S].
```

Doing classically, the predicate can be `Prop`-valued:

```
Definition is_matching (S : {fset `E G}) :=  
  ∀ e f, e ∈ S -> f ∈ S -> e != f -> [!d(e) ⊥ !d(f)].  
Definition matching : set {fset `E G} :=  
  [set S : {fset `E G} | is_matching S].
```

# Matching numbers

The following definition of the matching number works with both Finmap or classical matching:

**Definition**  $\text{nmatch} := \max_{(S \in \text{matching})} \# | \sim S | .$

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- The operator `\max` demands `matching` to be coercible to a finite type.
- Finmap `fset` is a finite type by the coercion `fset_sub_type`  
`fset_sub_type (K : choiceType) : {fset K} -> finType`

**Record** `fset_sub_type K A : predArgType` :=  
    { `fsval` : `Choice.sort K`; `fsvalP` : `is_true (fsval \in A)` }.

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- Classical set is coerced to a type by `set_type`  
`set_type (T : Type) : set T -> Type`  
**Definition** `set_type T A` := {`x` : `T` | `x \in A`}

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- Classical set is coerced to a type by `set_type`  
`set_type (T : Type) : set T -> Type`  
**Definition** `set_type T A` := {`x` : `T` | `x \in A`}
- If `T` is finite, then `set_type T A` also becomes finite by subtyping.

## Other invariants

The first definition of the set of all matching sets, `matching`, is as follows:

**Definition** `is_induced_matching` :=

$$\forall e f, e \in S \rightarrow f \in S \rightarrow e \neq f \rightarrow$$
$$[\text{`d}(e) \perp \text{`d}(g)] \vee [\text{`d}(f) \perp \text{`d}(g)].$$

**Definition** `is_maximal_matching` :=

$$(S \in \text{matching}) \wedge \forall T : \{\text{fset } \text{`E}\}, (S \subset T) \rightarrow (T \notin \text{matching}).$$

**Definition** `induced_matching` : `set` `{fset `E G}` :=

$$[\text{fset } S : \{\text{fset } \text{`E } G\} \mid \text{is\_induced\_matching } S].$$

**Definition** `maximal_matching` : `set` `{fset `E G}` :=

$$[\text{fset } S : \{\text{fset } \text{`E } G\} \mid \text{is\_maximal\_matching } S].$$

# Comparing the two `matchings`

## pros of `Finmap`

- coherence of the proof script by sticking to one library
- boolean rewriting is well-supported by `MathComp`

## cons of `Finmap`

Need many reflections between `bool` and `Prop`:

```
Lemma matchingP G (S : {fset `E G}) :  
  reflect  
    {in S & S, forall e f, e != f -> [disjoint (`d e) & (`d f)]}  
    (S \bin matching G).
```

## pros of `Classical`

No need to prepare or use the reflection; mostly just `rewrite inE`.

## cons of `Classical`

- Insertions of `mem_set` and `set_mem` are often necessary:

```
mem_set (T : Type) (A : set T) (u : T) : A u -> u \bin A  
set_mem (T : Type) (A : set T) (u : T) : u \bin A -> A u
```

- `S \notin matching` cannot be simplified by `rewrite inE`

## Comparing the two `matchings` (contd.)

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Moreover, both have issues when formalizing subsets of matching:

**Lemma** `induced_sub_matching G : induced_matching G ≤ matching G.`

**Lemma** `maximal_sub_matching G : maximal_matching G ≤ matching G.`

We need to manually apply these subset lemmas, yet they look automatable.



# Use HB?

Using HB to define a type of matching sets will solve the subset issues, and may provide better reasoning than using sets

```
HB.mixin Record isMatching (G : llugraph) (S : {fset `E G}) :=  
  { ismatching : is_matching S }.
```

```
#[short(type=matching)]  
HB.structure Definition Matching (G : llugraph) :=  
{ S of isMatching G S }.
```

```
Definition nmatch := \max_(S in matching) #|` \val S |.
```

However, the last line fails because `matching` is not immediately a finite type.

## Other invariants (contd.)

For a graph  $(V, E, d)$  and  $S \subset V$ ,  $S$  is said to be an independent set if it does not contain both of the boundary vertices of any edge.

**Definition** `is_independent_set` :=  
[forall  $e : \text{`E}$ ,  $\sim\sim (\text{`d}(e) \subset S)$ ].

**Definition** `independent_set` :=  
[fset  $S : \{\text{fset } \text{`V}\} \mid \text{is\_independent\_set } S$ ].

*(\* independence number;  
often denoted by  $\alpha$  in the literature \*)*

**Definition** `nindep` :=  $\max_{(S \in \text{independent\_set})} \# \mid \text{` } S \mid$ .

# Formalizing lemmas from [Hirano-Matsuda <https://arxiv.org/abs/2001.10704>]

**Lemma** `nindmatch_leq_nindep` (`G : llugraph`) :  
    `nindmatch G <= nindep G`.

**Lemma** `nmatch_minmatch_leq_nindep` `G` :  
    `(nmatch G - nminmatch G) * 2 <= nindep G`.

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**Lemma** `nindmatch_leq_nindep` (`G : llugraph`) :  
    `nindmatch G <= nindep G`.

**Lemma** `nmatch_minmatch_leq_nindep` `G` :  
    `(nmatch G - nminmatch G) * 2 <= nindep G`.

- Pen-paper proof: 4+4 lines
- Coq proof: 6+7 lines

## Concluding remarks

# Why not Coq-Graph?

The Coq-Graph library by Doczkal et al. was present when we started this formalization, and we assessed if we could start using it:

- Our aim was to reason about sets of edges, and the definition of edges in terms of relations as in Coq-Graph seemed like a detour for us.
- We were about to deal only with undirected graphs, and Coq-Graph's formalization did not look direct in this respect.

A bit more of our expertize on MathComp at that time might have changed the decision to go with a new definition.

- MathComp, -Finmap, and -Classical together work as a practical basis for working with graph theory
- Subsets and invariants of a graph can be formalized without an extreme frustration.
- They could be however more smooth.
- TODO:
  - Connection to ring theory
  - Use Hierarchy-Builder more effectively
  - Bridge to Coq-Graph