



Data-Driven Runtime Complexity Analysis

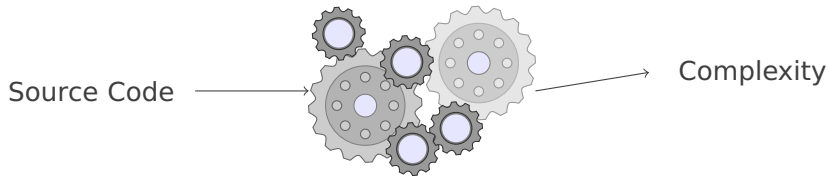
15th International Symposium on Frontiers of Combining Systems (FroCoS 2025)

Samuel Frontull Manuel Meitinger Georg Moser

<https://tcs-informatik.uibk.ac.at>

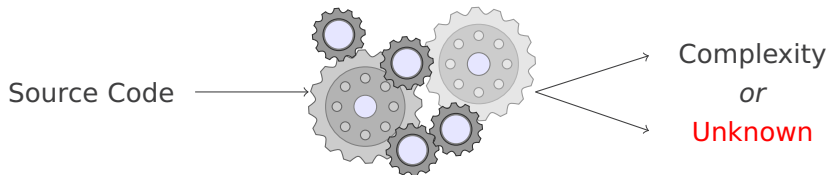
Resource Analysis

- Resource Analysis is a fundamental problem
- it is used to understand the efficiency of algorithms
- it is used to identify bugs



Resource Analysis

- Resource Analysis is a fundamental, **undecidable** problem
- it is used to understand the efficiency of algorithms
- it is used to identify bugs
- (Fully automated) Static analysis is in general not complete:



What To Do When Automation Fails?

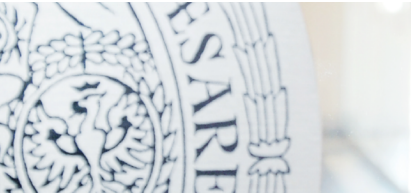
Statistical Approach

run program on various inputs, measure the cost, infer complexity empirically

Our Work¹

We have implemented this idea for term rewrite systems and compared our approach against known results.

¹Samuel Frontull, Manuel Meitinger, and Georg Moser. “Data-Driven Runtime Complexity Analysis”. In: *15th International Symposium on Frontiers of Combining Systems (FroCoS 2025)*. Springer Nature Switzerland, 2025, pp. 228–246.



Runtime Complexity of a Term Rewrite System (TRS)

Multiplication and Addition as TRS

$$\mathcal{F} := \{0/0, s/1, +/2, \cdot/2\}$$

$$\mathcal{R} :=$$

$$1: \quad x \cdot s(y) \rightarrow (x \cdot y) + x$$

$$2: \quad x \cdot 0 \rightarrow 0$$

$$3: \quad s(x) + y \rightarrow s(x + y)$$

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Example

$$t = s(s(0)) \cdot s(s(s(0)))$$

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normal form

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Example

basic term

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normal form

Multiplication and Addition in TDC

defined symbols

constructors

$$\mathcal{F} := \{0/0, s/1, +/2, \cdot/2\}$$

$$\mathcal{F}_D := \{\cdot, +\}$$

$$\mathcal{F}_C := \{0, s\}$$

$$\mathcal{R} :=$$

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basic term

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normal form

Runtime Complexity of a TRS

$s^2(0) \cdot s^3(0) \rightarrow \dots \rightarrow s^6(0)$ in 10 steps

Runtime Complexity of a TRS

$s^2(0).s^3(0) \rightarrow \dots \rightarrow s^6(0)$ in **10** steps

Derivation Height

Let $s, t \in \mathcal{T}(\mathcal{F}, \mathcal{V})$ such that t is in normal form. The *derivation height* of a term s wrt. a well-founded, finitely-branching relation \rightarrow is defined as $\text{dh}(s, \rightarrow) := \max\{n \mid \exists t. s \rightarrow^n t\}$

$$\text{dh}(s^2(0).s^3(0), \rightarrow) = \max\{\mathbf{10}, \dots\}$$

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Runtime Complexity

$$\text{rc}_{\mathcal{R}}(n) := \max\{\text{dh}(s, \rightarrow_{\mathcal{R}}) \mid s \text{ is basic and } |s| \leq n\}$$

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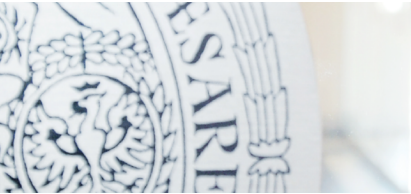
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$$|s^2(0).s^3(0)| = 8, \text{rc}_{\mathcal{R}}(8) = ?$$



Worst-Case Input Computation

Simple and Complex Rules

Definition

A rewrite rule $\ell \rightarrow r$ is *simple* if r does not contain any defined symbol or $\text{arity}(\ell) = 0$. Otherwise, it is *complex*.

$$1: \quad x \cdot s(y) \rightarrow (x \cdot y) + x$$

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Complex Rules:

$$1: \quad x \cdot s(y) \rightarrow^1 (x \cdot y) + x$$

$$3: \quad s(x) + y \rightarrow^1 s(x + y)$$

$$5: \quad x + s(y) \rightarrow^1 s(x + y)$$

Simple Rules:

$$2: \quad x \cdot 0 \rightarrow^1 0$$

$$4: \quad 0 + x \rightarrow^1 x$$

$$6: \quad x + 0 \rightarrow^1 x$$

We write $s \rightarrow^n t$ if exactly n steps are performed to rewrite s to t .

Narrowing

Narrowing

$s \rightsquigarrow_{\mathcal{R}, \mu | V(s)} t$ if $\text{mgu}(s|_p, \ell) = \mu$ and $t = s[r\mu]_p$ and $\ell \rightarrow r \in \mathcal{R}$ and $p \in \text{FPos}(s)$.

Combination of Simple and Complex Rules

Let $s : \ell_s \rightarrow^a r_s$ be a simple rule and $c : \ell_c \rightarrow^b r_c$ a complex rule². If $r_c \rightsquigarrow_{\mathcal{R}, \mu | V(s)} \ell_s$, then $\ell_c \mu \rightarrow^{a+b} r_s \mu$. We denote this combination by $c \circ s$.

$$c_1: \quad x \cdot s(y) \rightarrow^1 (x \cdot y) + x$$

$$s_6: \quad x + 0 \rightarrow^1 x$$

²we rename variables such that $\text{Var}(s) \cap \text{Var}(c) = \emptyset$

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$$r_{c_1} \rightsquigarrow_{\mathcal{R}, \mu | V(s)} \ell_{s_6} \text{ for } \mu = \{x_6 \mapsto x_1 \cdot y_1, x_1 \mapsto 0\}$$

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²we rename variables such that $\text{Var}(s) \cap \text{Var}(c) = \emptyset$

Backward Narrowing

$$x \cdot s(y) \rightarrow^1 (x \cdot y) + x$$

$$x \cdot 0 \rightarrow^1 0$$

$$s(x) + y \rightarrow^1 s(x + y)$$

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$$0 \cdot s(y_1) \rightarrow^2 0 \cdot y_1$$

$$x_5 + s(0) \rightarrow^2 s(x_5)$$

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$$x_5 + s(0) \rightarrow^2 s(x_5)$$

$$0 \cdot s(0) \rightarrow^3 0$$

$$s(@var_7) + 0 \rightarrow^2 s(@var_7)$$

$$0 + s(@var_6) \rightarrow^2 s(@var_6)$$

$$s(0) + @var_8 \rightarrow^2 s(@var_8)$$

$$s(0) \cdot s(@var_2) \rightarrow^3 s(s(0) \cdot @var_2)$$

...

$$s^4(0) \cdot s^4(0) \rightarrow^{19} s^{12}(0) + s^4(0)$$

$$s^4(0) \cdot s^4(0) \rightarrow^{24} s^{16}(0)$$

$$s^{16}(0) + s^{10}(@var_{74}) \rightarrow^{27} s^{26}(@var_{74})$$

...

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$$s(0) + @var_8 \rightarrow^2 s(@var_8)$$

$$s(0) \cdot s(@var_2) \rightarrow^3 s(s(0) \cdot @var_2)$$

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...

Method designed for term rewrite systems that correspond to functional programs.



Estimating the Asymptotic Complexity

Measurements

Rule-induced Measurement

We define the rule-induced measurement as a function

$$\text{meas}(\ell \rightarrow^n r) = (\text{root}(\ell), |\ell|, n).$$

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rule **meas**

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rule	meas
$x \cdot s(y) \rightarrow^1 (x \cdot y) + x$	$(\cdot, 4, 1)$

Measurements

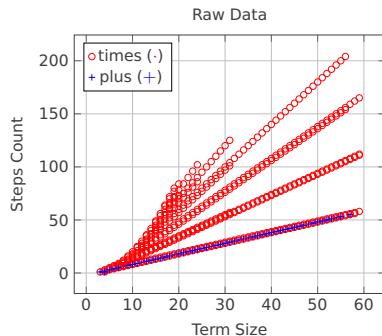
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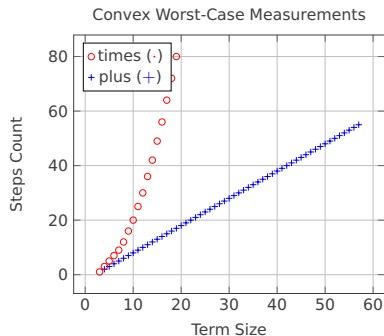
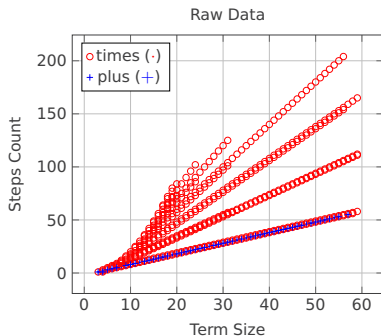
$$\text{meas}(\ell \rightarrow^n r) = (\text{root}(\ell), |\ell|, n).$$

rule	meas	rule	meas
$x \cdot s(y) \rightarrow^1 (x \cdot y) + x$	$(\cdot, 4, 1)$	$s(@\text{var}_7) + 0 \rightarrow^2 s(@\text{var}_7)$	$(+, 4, 2)$
$x \cdot 0 \rightarrow^1 0$	$(\cdot, 3, 1)$	$x_5 + s(0) \rightarrow^2 s(x_5)$	$(+, 4, 2)$
$0 \cdot s(y_1) \rightarrow^2 0 \cdot y_1$	$(\cdot, 4, 2)$	$s^4(0) \cdot s^4(0) \rightarrow^{19} s^{12}(0) + s^4(0)$	$(\cdot, 11, 19)$
$0 \cdot s(0) \rightarrow^3 0$	$(\cdot, 4, 3)$	$s^4(0) \cdot s^4(0) \rightarrow^{24} s^{16}(0)$	$(\cdot, 11, 24)$
$s(0) + @\text{var}_8 \rightarrow^2 s(@\text{var}_8)$	$(+, 4, 2)$	$s^{16}(0) + s^{10}(@\text{var}_{74}) \rightarrow^{27} s^{26}(@\text{var}_{74})$	$(+, 29, 27)$

Convex Worst-Case Measurements



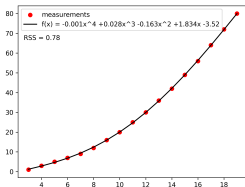
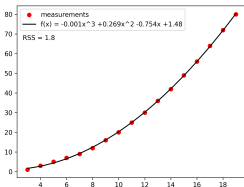
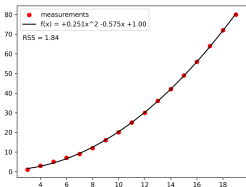
Convex Worst-Case Measurements



From Measurements to Complexity

Problem: Any set of points can be fitted arbitrarily well

Residual sum of squares is not a reliable indicator of asymptotic complexity.

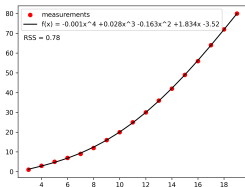
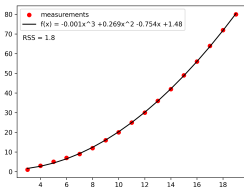
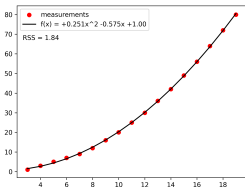


³C. C. McGeoch and P. R. Cohen. "How to Find Big-Oh in Your Data Set (and How Not To)". In: *Proceedings of the Sixth International Workshop on Artificial Intelligence and Statistics*. Ed. by David Madigan and Padhraic Smyth. Vol. R1. Proceedings of Machine Learning Research. PMLR, 1997, pp. 347–354. URL: <https://proceedings.mlr.press/r1/mcgeoch97a.html>.

From Measurements to Complexity

Problem: Any set of points can be fitted arbitrarily well

Residual sum of squares is not a reliable indicator of asymptotic complexity.



Solution: Use the *difference rule heuristic*³.

³C. C. McGeoch and P. R. Cohen. "How to Find Big-Oh in Your Data Set (and How Not To)". In: *Proceedings of the Sixth International Workshop on Artificial Intelligence and Statistics*. Ed. by David Madigan and Padhraic Smyth. Vol. R1. Proceedings of Machine Learning Research. PMLR, 1997, pp. 347–354. URL: <https://proceedings.mlr.press/r1/mcgeoch97a.html>.

From Measurements to Complexity

Lagrange Interpolation Theorem⁴

Given $n + 1$ points $(x_0, y_0), \dots, (x_n, y_n)$ with pairwise distinct x_i , there exists a *unique* polynomial P_n of degree at most n such that $P_n(x_i) = y_i$ for all $i \in \{0, 1, \dots, n\}$.

The Newton form of a polynomial of degree n is expressed as:

$$P_n(x) = \sum_{k=0}^n a_k \cdot \prod_{j=0}^{k-1} (x - x_j)$$

where $\prod_{j=0}^{-1} (x - x_j) = 1$.

The (unique) coefficients a_k can be computed using the divided-difference scheme.

⁴Josef Stoer et al. *Introduction to numerical analysis*. Vol. 1993. Springer, 1980.

Divided-Differences

	$k = 0$	$k = 1$	$k = 2$	\dots	$k = n$
x_0	y_0	y_0^1	y_0^2	\dots	y_0^n
x_1	y_1	y_1^1	y_1^2		
x_2	y_2	y_2^1			
\vdots	\vdots				
x_n	y_n				

where $y_j^{k+1} = \frac{y_{j+1}^k - y_j^k}{x_{j+1} - x_j}$ ($y_i^0 = y_i$) with $k > 0$ and $j \leq n - k$.

Interpolating Polynomial


$$P_n(x) = y_0 + y_0^1(x - x_0) + \dots + y_0^n(x - x_0)(x - x_1) \dots (x - x_{n-1})$$

Divided-Differences

Theorem

If $P(x)$ is a polynomial of degree n with $P(x_i) = y_i$, then $y_0^k = 0$ for $k > n$.

Proof.

Because of the unique solvability $P_k(x) = P(x)$ for $k \geq n$. The coefficients y_0^k in P_n must therefore vanish for $k > n$. 

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x_i	$k = 0$	1	2	3	4
0	0	1	1	0	0
1	1	3	1	0	
2	4	5	1		
3	9	7			
4	16				

⇒ We can exploit this method to estimate the asymptotic complexity.

Divided-Differences

Theorem

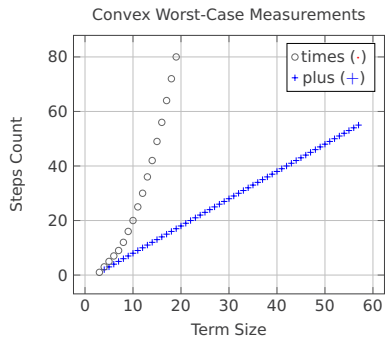
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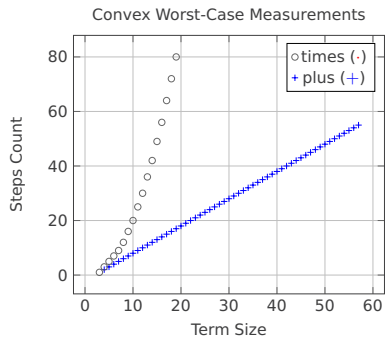
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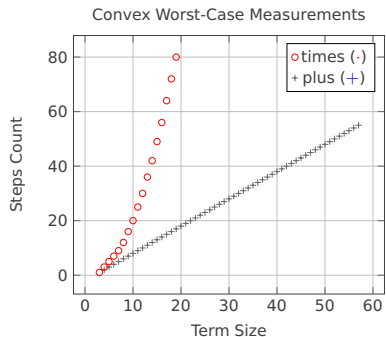
$\mathcal{R}_2 +$


·	$k = 0$	1	2	3	4
3	1	1	0	0	0
4	2	1	0	0	0
5	3	1	0	0	0
6	4	1	0	0	0
7	5	1	0	0	0
8	6	1	0	0	0
9	7	1	0	0	0
10	8	1	0	0	0
11	9	1	0	0	0
12	10	1	0	0	0
13	11	1	0	0	0
...

$\mathcal{R}_2 +$


⇒ **linear (n)**

·	$k = 0$	1	2	3	4
3	1	1	0	0	0
4	2	1	0	0	0
5	3	1	0	0	0
6	4	1	0	0	0
7	5	1	0	0	0
8	6	1	0	0	0
9	7	1	0	0	0
10	8	1	0	0	0
11	9	1	0	0	0
12	10	1	0	0	0
13	11	1	0	0	0
...


 $\Rightarrow n^3$

·	$k = 0$	1	2	3	4	5	6	7
3	1	2	0	0	0	0.01	0	0
4	3	2	0	0	0.04	-0.02	0	0
5	5	2	0	0.17	-0.04	0	0	0
6	7	2	0.50	0	-0.04	0.03	0.01	0
7	9	3	0.50	-0.17	0.08	-0.03	0.01	0
8	12	4	0	0.17	-0.08	0.03	0.01	0
9	16	4	0.50	-0.17	0.08	-0.03	0.01	0
10	20	5	0	0.17	-0.08	0.03	0.01	0
11	25	5	0.50	-0.17	0.08	-0.03	0.01	0
12	30	6	0	0.17	-0.08	0.03	0.01	0
13	36	6	0.50	-0.17	0.08	-0.03	0	0



Results

Termination Problem Database (TPDB)

The Termination Problems Data Base

collects termination problems that are being used in termination competitions

<https://termination-portal.org/wiki/TPDB>

Termination and Complexity Competition (termCOMP)⁵

several categories for termination and complexity from the areas of term rewriting

<https://termcomp.github.io/Y2024/>

⁵https://termination-portal.org/wiki/Termination_Competition

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Our Method vs. VBS

compare the results to validate our approach (timeout 3 seconds)

⁵https://termination-portal.org/wiki/Termination_Competition

Experimental Validation

fp + term.	#	unsound (%)	compl. (%)	no val.	unk.	new (%)	acc. (%)
<i>innermost</i>	169	7 (4.1)	138 (81.7)	24	0	27 (16.0)	74 (74.7)
<i>full</i>	111	7 (6.3)	80 (72.1)	24	0	30 (27.0)	39 (75.0)

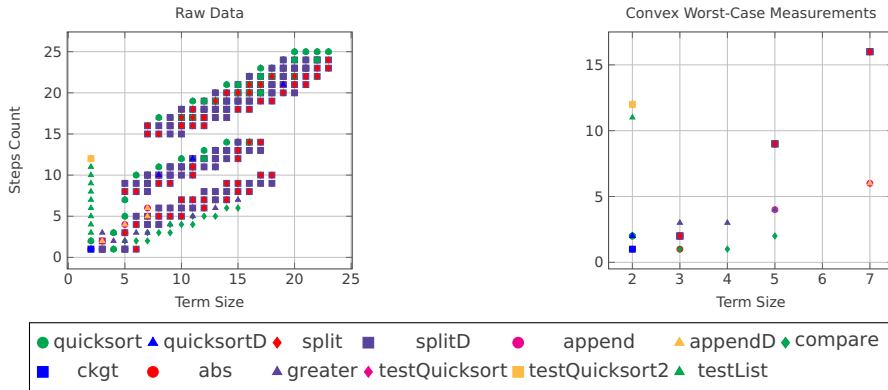
- Accuracy is defined wrt. to known results on the (innermost) runtime complexity of TRSs.
- *fp + term.* are TRSs that encode (uniformly) terminating functional programs (left-linear, strongly non-overlapping constructor TRSs).

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TPDB							
<i>innermost</i>	663	81 (12.2)	486 (73.3)	75	21	224 (33.8)	138 (51.3)
<i>full</i>	959	203 (21.2)	568 (59.2)	113	75	306 (31.9)	204 (46.8)

- Accuracy is defined wrt. to known results on the (innermost) runtime complexity of TRSs.
- *fp + term.* are TRSs that encode (uniformly) terminating functional programs (left-linear, strongly non-overlapping constructor TRSs).

Limitation



We may not be able to find (enough) worst-case inputs

timeout or memory constraints



Summary

Conclusion and Next Steps

Contributions

- we have developed a (fast) method to synthesise worst-case inputs for term rewrite systems that model functional programs
- we have shown how to estimate the asymptotic complexity on the inferred measurements
- we have validated our approach on the TPDB

Future Work

- integration of machine learning techniques for rule selection
- infer polynomial bounds
- guarantees on the input size



Thank You for Your Attention!

Web-Tool

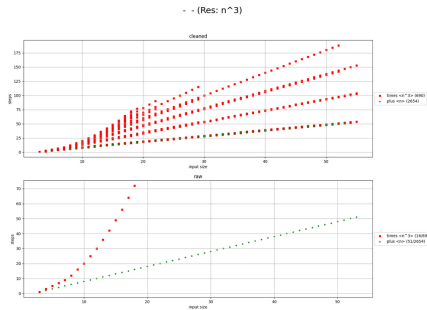
AG01/#3.16.xml.trs (n^2 , n^3)

```
(VAR x y)
(STRATEGY INNERMOST)
(RULES
  times(x,0) -> 0
  times(x,s(y)) -> plus(times(x,y),x)
  plus(x,0) -> x
  plus(0,x) -> x
  plus(x,s(y)) -> s(plus(x,y))
  plus(s(x),y) -> s(plus(x,y))
)
```

Analyse

Version worstcase4.ts

Timeout [in ms] 10000



WCA LOG

RESULT: n^3

Ground Truth: (n^2 , n^3)

<https://www.uibk.ac.at/en/theoretical-computer-science/research/ddrca/>

Worst-Case Input Computation

Algorithm 1 Pseudo-code of work list algorithm.

Require: *initialRules*
foundRules $\leftarrow \emptyset$
pendingRules \leftarrow *initialRules*
delayedRecursiveRules $\leftarrow \emptyset$
while *pendingRules* $\neq \emptyset$ **or** *delayedRecursiveRules* $\neq \emptyset$ **do**
 if *pendingRules* $= \emptyset$ **then**
 steps $\leftarrow 0$
 for *rule* **in** *delayedRecursiveRules* **do**
 steps $\leftarrow \max(\text{steps}, \text{getStepsToLastRecursion}(\text{rule}))$
 end for
 for *rule* **in** *delayedRecursiveRules* **do**
 if $\text{getStepsToLastRecursion}(\text{rule}) = \text{steps}$ **then**
 pendingRules \leftarrow *pendingRules* \cup *rule*
 delayedRecursiveRules \leftarrow *delayedRecursiveRules* \setminus *rule*
 end if
 end for
 end if
 for *rule* **in** *pendingRules* **do**
 foundRules \leftarrow *foundRules* \cup *rule*
 pendingRules \leftarrow *pendingRules* \setminus *rule*
 for *derivedRule* **in** $\text{getDerivableRules}(\text{rule}, \text{foundRules})$ **do**
 if $\text{isRecursive}(\text{derivedRule})$ **then**
 delayedRecursiveRules \leftarrow *delayedRecursiveRules* \cup *derivedRule*
 else
 pendingRules \leftarrow *pendingRules* \cup *derivedRule*
 end if
 end for
 end for
end while

Divided-Differences – Example

	$k = 0$	$k = 1$	$k = 2$
0	1	2	$-5/6$
1	3	$-1/2$	
3	2		

Interpolating Polynomial

$$P_n(x) = y_0 + y_0^1(x - x_0) + \cdots + y_0^n(x - x_0)(x - x_1) \cdots (x - x_{n-1})$$

$$P_2(x) = 1 + 2(x - 0) - 5/6(x - 0)(x - 1)$$

$$P_2(x) = 1 + \frac{17}{6}x - \frac{5}{6}x^2$$

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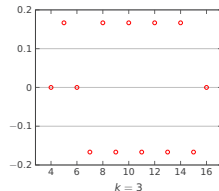
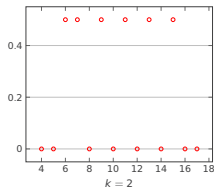
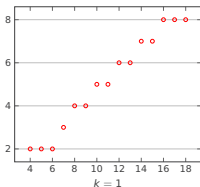
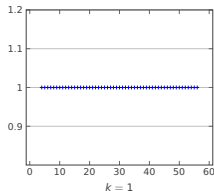
$$P_2(x) = 1 + 2(x - 0) - 5/6(x - 0)(x - 1)$$

$$P_2(x) = 1 + \frac{17}{6}x - \frac{5}{6}x^2$$

The Difference Rule⁶

The Difference Rule

extends Newton's divided difference method for polynomial interpolation to be defined when Y contains random noise. The method iterates numerical differentiation until the data **appears non-increasing**.



⁶C. C. McGeoch and P. R. Cohen. "How to Find Big-Oh in Your Data Set (and How Not To)". In: *Proceedings of the Sixth International Workshop on Artificial Intelligence and Statistics*. Ed. by David Madigan and Padhraic Smyth. Vol. R1. Proceedings of Machine Learning Research. PMLR, 1997, pp. 347–354. URL: <https://proceedings.mlr.press/r1/mcgeoch97a.html>.