Iterative Monomorphisation

Jasmin Blanchette and Tanguy Bozec

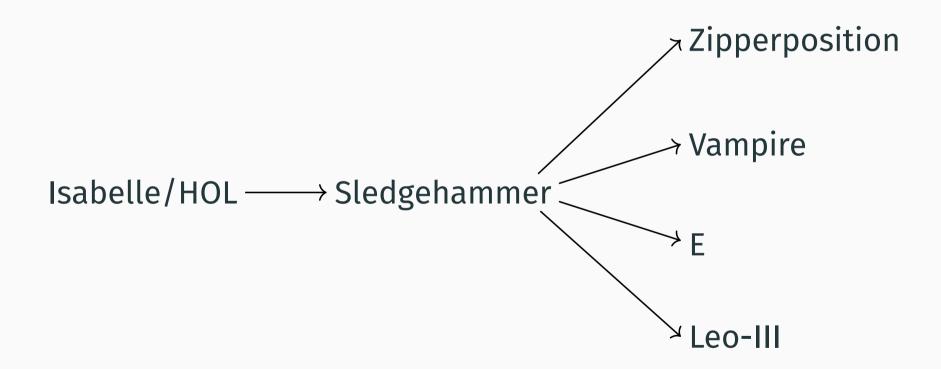
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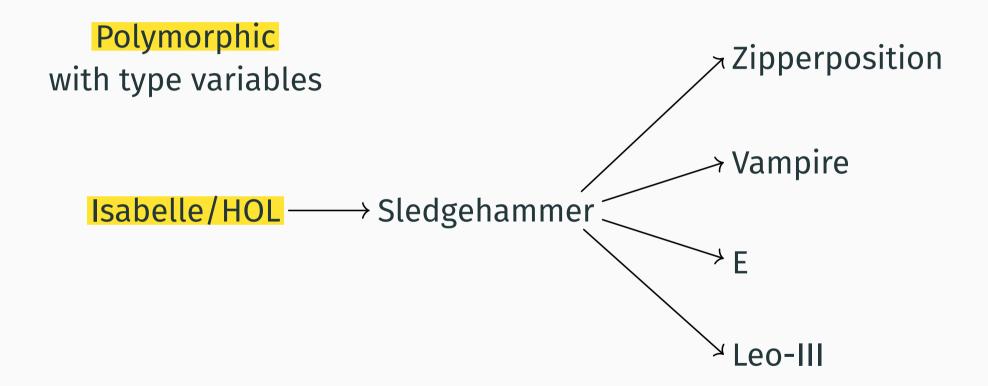
```
\forall x: \mathtt{list\_int}, f \langle \mathtt{list\_int} \rangle (x)
```

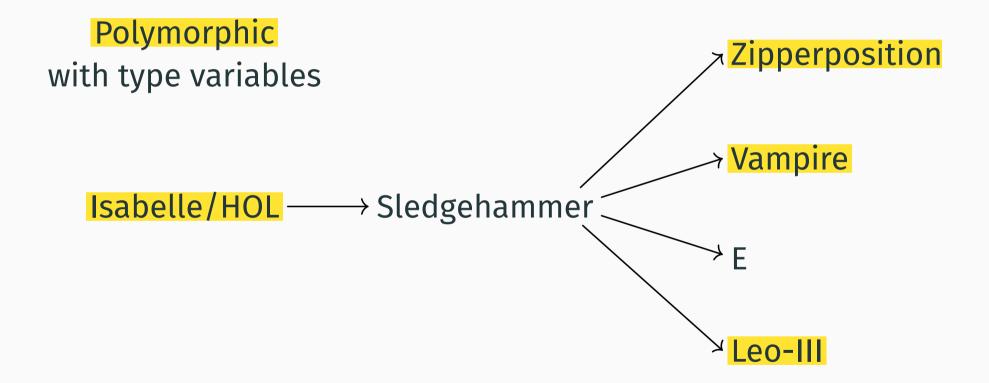
```
\begin{split} \forall x: & \texttt{list\_int}, f \langle \texttt{list\_int} \rangle(x) \\ \forall x: & \texttt{list\_nat}, f \langle \texttt{list\_nat} \rangle(x) \\ \forall x: & \texttt{list\_bool}, f \langle \texttt{list\_bool} \rangle(x) \\ \forall x: & \texttt{list\_string}, f \langle \texttt{list\_string} \rangle(x) \end{split}
```

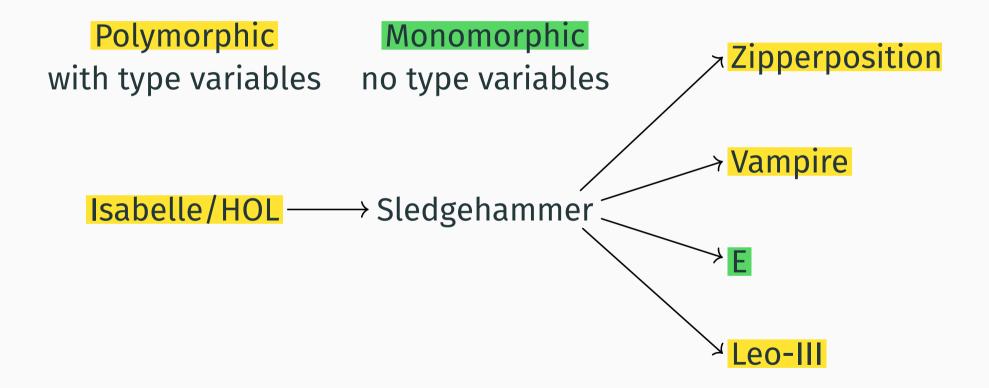
```
\forall x: \texttt{list\_int}, f \langle \texttt{list\_int} \rangle (x) \\ \forall x: \texttt{list\_nat}, f \langle \texttt{list\_nat} \rangle (x) \\ \forall x: \texttt{list\_bool}, f \langle \texttt{list\_bool} \rangle (x) \\ \forall x: \texttt{list\_string}, f \langle \texttt{list\_string} \rangle (x) \\ \forall \alpha, \forall x: \texttt{list}(\alpha), f \langle \texttt{list}(\alpha) \rangle (x) \\ \end{aligned}
```

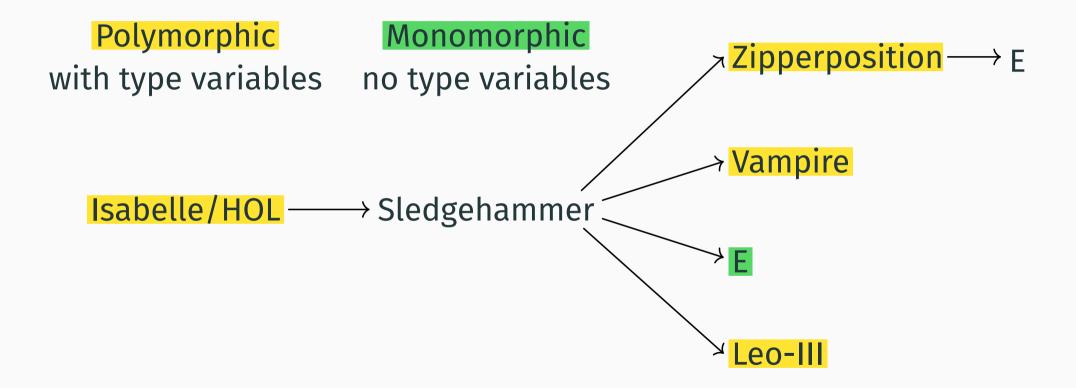
Type variables are quantified universally at the top level of a formula.

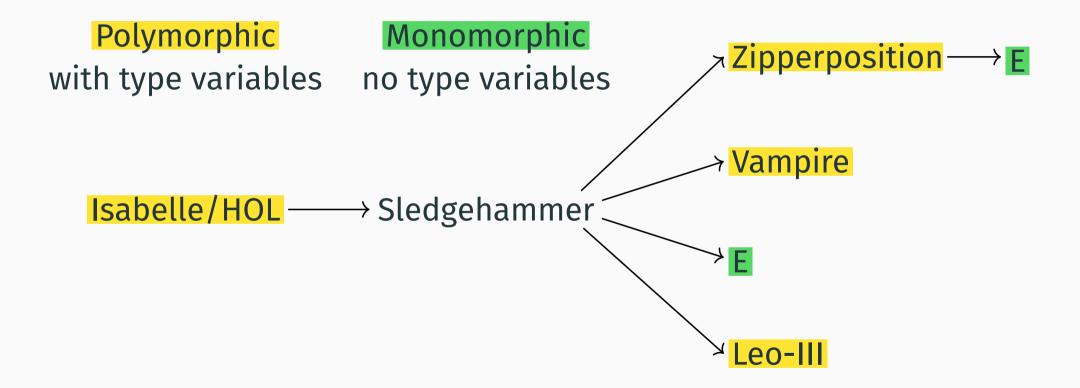


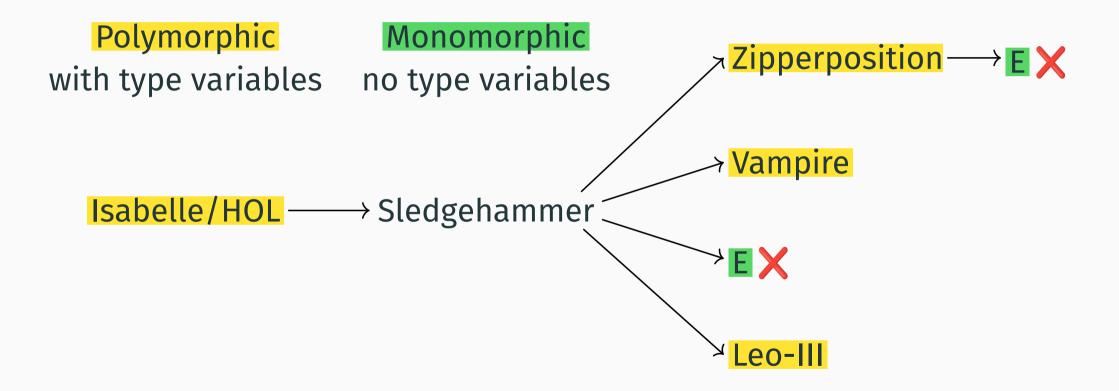












Solution

Polymorphic problem → Monomorphic problem

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Polymorphic problem ⇒ Monomorphic problem

Two possibilities:

- 1. Encode type variables in a monomorphic logic.
- 2. Instantiate type variables.

- 1 *P* is the set of input formulae
- 2 **while** new formulae are added to P **do**

```
for all \varphi \in P do
3
        for all occurrences f(\pi)(...) in \varphi with \pi polymorphic do
4
5
```

- for all occurrences $f\langle \tau \rangle(...)$ in P with τ monomorphic do
- if π matches against τ then 6
- add σ , the unifier of π and τ to S
 - for all $\sigma \in S$ do
- add $\varphi \sigma$ to P
- 10 **return** $\{\varphi \in P \mid \varphi \text{ is monomorphic}\}$

Soundness: instantiation of universally quantified type variables.

Completeness: this algorithm is incomplete.

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• Finding a finite equisatisfiable set of monomorphic instances of a first-order polymorphic formula is undecidable.

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Completeness: this algorithm is incomplete.

- Finding a finite equisatisfiable set of monomorphic instances of a first-order polymorphic formula is undecidable.
- Bounds limit the instantiations we perform.

Initial problem:

- 1. $\forall x : \mathsf{int}, f(\mathsf{int})(x)$
- 2. $\forall x : \alpha, y : \mathsf{list}(\alpha), f(\alpha)(x) \land f(\mathsf{list}(\alpha))(y)$

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Successful match of against int.

Failure to match $list(\alpha)$ against int.

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Successful match of against int.

We apply the substitution $\alpha \mapsto int$ to clause 2.

3. $\forall x : \text{int}, y : \text{list}(\text{int}), f(\text{int})(x) \land f(\text{list}(\text{int}))(y)$

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Successful match of α against list(int).

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4. $\forall x: \text{list(int)}, y: \text{list(list(int))},$ $f\langle \text{list(int)} \rangle(x) \wedge f\langle \text{list(list(int))} \rangle(y)$

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4.
$$\forall x: list(int), y: list(list(int)),$$

$$f\langle list(int)\rangle(x) \wedge f\langle list(list(int))\rangle(y)$$

This can generate an infinite number of new formulae.

Bounds

Since we cannot **exhaustively enumerate** all type variables instantiations, we use **heuristics** to determine which instantiations we perform:

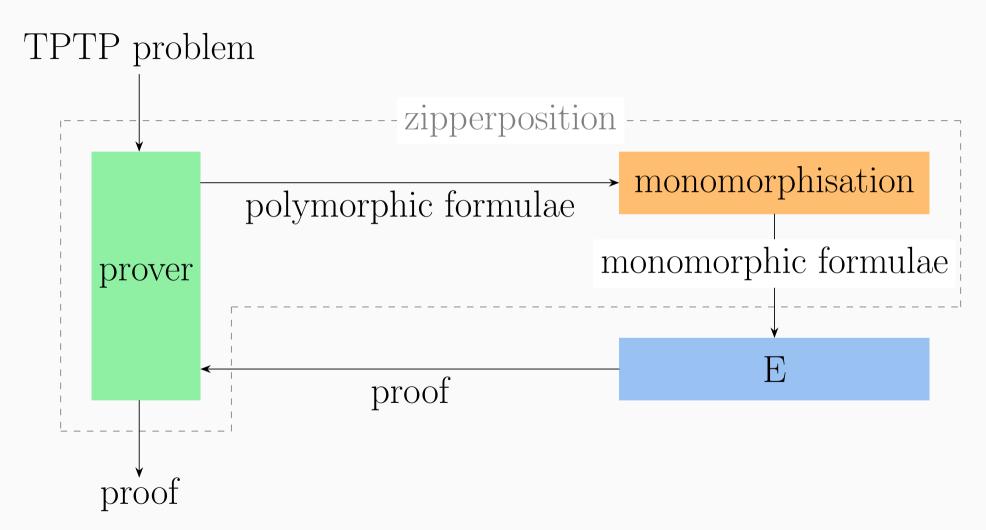
- We limit the number of iterations.
- We filter type arguments by function symbol.

Bounds

Since we cannot **exhaustively enumerate** all type variables instantiations, we use **heuristics** to determine which instantiations we perform:

- We limit the number of iterations.
- We filter type arguments by function symbol.
- We limit the number of substitutions we generate.
- We limit the number of applications of the substitutions.

Zipperposition and E



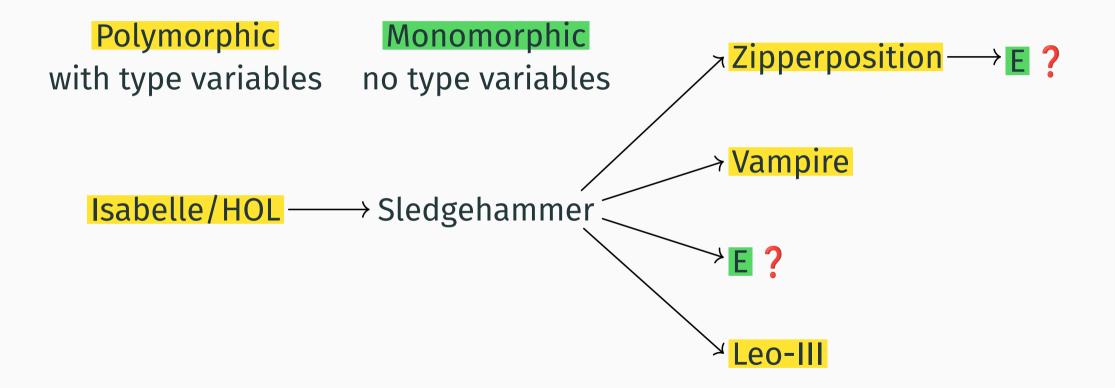
Benchmarks

We wanted to test the usefulness of our implementation of iterative monomorphisation.

We had two questions:

- 1. Does Zipperposition benefit from the ability to call E on monomorphised problems?
- 2. Does E perform well on monomorphised problems?

Benchmarks



Methodology

We used the TPTP (Thousand Problems for Theorem Provers) problem set for our evaluations.

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We split the problem set into two:

- 500 problems for adjusting bounds and parameters
- 1034 problems for the benchmarks

Zipperposition benefits from monomorphisation

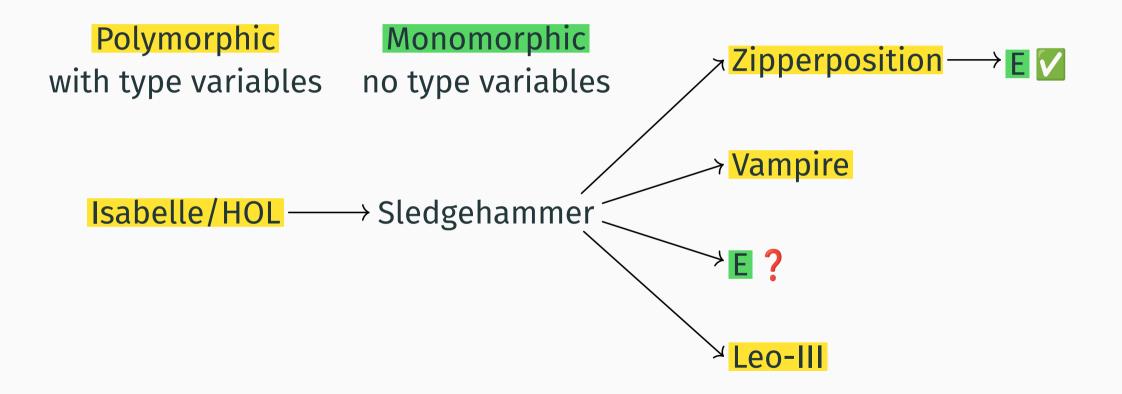
	Zipperposition without E	Zipperposition with E	Union
500 problems	168	198	207
1034 problems	337	410	434

Zipperposition benefits from monomorphisation

	Zipperposition without E	Zipperposition with E	Union
500 problems	168	198	207
1034 problems	337	410	434

This is **expected** Zipperposition benefits greatly from E in a monomorphic setting.

Zipperposition benefits from monomorphisation



Polymorphic	Monomorphised
-------------	---------------

E	-	340	
Zipperposition	339		

Calling E on monomorphised problems is a viable option.

Polymorphic	Monomorphised

E	_	340	
Zipperposition	339	351	

Calling E on monomorphised problems is a viable option.

Polymor	ohic	Monomorphised
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E	-	340	
Zipperposition	339	351	
Leo-III	157	231	

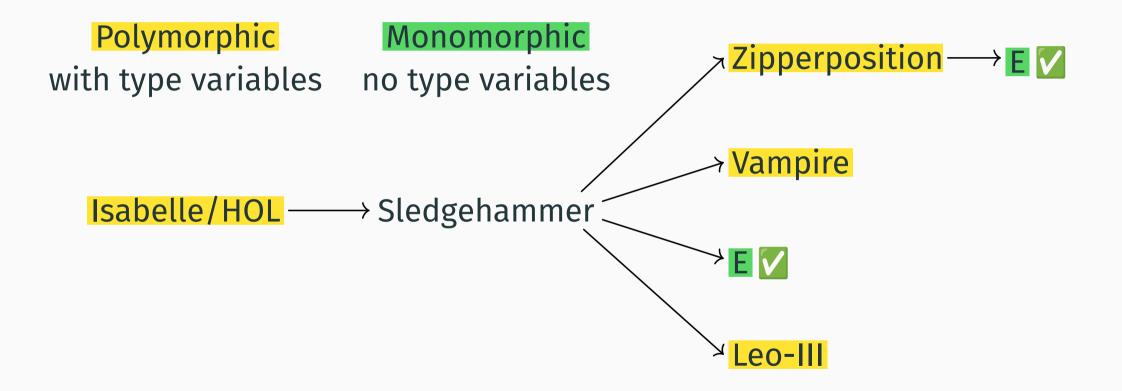
Calling E on monomorphised problems is a viable option.

Polymorphic provers perform better on monomorphised problems.

	Polymorphic	Monomorphised	Union
E	-	340	340
Zipperposition	339	351	404
Leo-III	157	231	274

Calling E on monomorphised problems is a viable option.

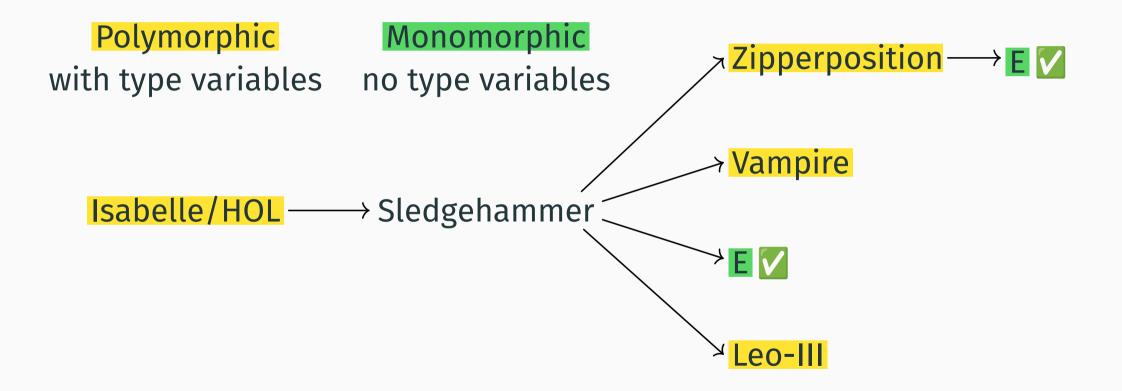
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- Solution: instantiating type variables with ground types.

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- Goal: Polymorphic problem \Longrightarrow Monomorphic problem.
- · Solution: instantiating type variables with ground types.
- Bounds are necessary in practice.
- It is a viable means for extending monomorphic provers.
- Iterative monomorphisation can outperform native implementations of polymorphism.



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