Certified programming with dependent types made simple with proxy-based small inversions

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Motivation

Proxy-based small inversions allow for dependent programming with simplified and readable code.





Examples

- Definition of transposition of size-indexed matrices (vectors of vectors) and proof that this transposition is involutive.
- Manipulation of finite sets Fin.t, following a challenging use-case proposed by Clément Pit-Claudel





Example: RGB

Inductive rgb := $R \mid G \mid B$.

Definition my_rgb_rect

 $(P: rgb \rightarrow Type)$

(p1: PR) (p2: PG) (p3: PB)

(r : rgb) : P r :=

match ras r' return P r' with

 $R \Rightarrow p1$

 $\mathtt{G}\Rightarrow\mathtt{p2}$

 $B \Rightarrow p3$

end.



 $\texttt{Inductive Fin.t}: \mathtt{nat} \to \mathtt{Set} :=$

 \mid F1: \forall n: nat, t (S n)

 $\mid \ \mathtt{FS}: \ \forall \ \mathtt{n}: \ \mathtt{nat}, \ \mathtt{t} \ \mathtt{n} \to \mathtt{t} \ (\mathtt{S} \ \mathtt{n}).$



```
{\tt Inductive\ Fin.t:nat} \to {\tt Set} :=
```

| F1 : ∀ n : nat, t (S n)

| FS: \forall n: nat, t n \rightarrow t (S n).

Definition Fin_3_rect

 $(P: Fin.t 3 \rightarrow Type)$

(p1: PF1) (p2: P (FS F1)) (p3: P (FS (FS F1)))

(x : Fin.t 3) : P x :=

match x as _x return P _x with

| F1 ⇒ p1

| FS F1 \Rightarrow p2

 \mid FS (FS F1) \Rightarrow p3

end.





Inductive Fin.t : nat \rightarrow Set :=

F1: \forall n: nat, t (S n)

FS: \forall n: nat, t n \rightarrow t (S n).

Definition Fin_3_rect

(P: Fin.t 3 \rightarrow Type) (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))

(x : Fin.t 3) : P x :=

match x as _x return P _x with

 $\mathtt{F1}\Rightarrow\mathtt{p1}$

FS F1 \Rightarrow p2

FS (FS F1) \Rightarrow p3

end.

Error: The term "_x" has type "t n" while it is expected to have type "t 3".



```
Definition Fin_3_rect
  (P: Fin.t 3 \rightarrow Type)
  (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))
  (x : Fin.t 3) : P x :=
match x as _x return P _x with
  F1 \Rightarrow p1
  FS x' \Rightarrow
    match x' return P (FS x') with
     F1 \Rightarrow p2
     FS x'' \Rightarrow
         match x'' return P (FS (FS x'')) with
          \mathtt{F1}\Rightarrow\mathtt{p3}
           FS x''' \Rightarrow (*???*)
         end end end.
```





Example: small inversion

```
Definition Fin_3_rect_smallinv
  (P: Fin.t 3 \rightarrow Type)
  (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))
  (x : Fin.t 3) : P x :=
match Fin_proxy 3 x with
is_F1 \rightarrow p1
is FS x' \Rightarrow
    match Fin_proxy 2 x' with
     is_F1 \rightarrow p2
     is FS x'' \Rightarrow
        match Fin_proxy 1 x" with
         is_F1 = p3
         is FS x''' \Rightarrow
            match Fin_proxy 0 x''' with end
    end end end.
```





Example: small inversion intermediary objects

Inductive Fin_0 : Fin.t $0 \rightarrow Set :=$.

Inductive Fin_S $(n : nat) : Fin.t (S n) \rightarrow Set :=$

is_F1: Fin_S n F1 is_FS (r:Fin.t n): Fin_S n (FS r).

Definition Fin_proxy_type (n:nat) : Fin.t $n \rightarrow Set :=$

match n with $0 \Rightarrow Fin_0$

 $S m \Rightarrow Fin_S m end.$

Definition Fin_proxy(n:nat) (r : Fin.t n) : Fin_proxy_type n r := match r as r' in Fin.t n' return Fin_proxy_type n' r' with

 $F1 n \Rightarrow is_F1 n$ $FS n t' \Rightarrow is_FS n t' end.$





Example: inversion tactic

```
Definition Fin_3_rect_inv
```

```
(P: Fin.t 3 \rightarrow Type)
```

Proof.

inversion x as [n' eq | n' i' eq].

Goal: Px





Example: inversion tactic

```
Definition Fin_3_rect_inv
  (P: Fin.t 3 \rightarrow Type)
  (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))
  (x : Fin.t 3) : P x.
Proof.
  inversion x as [n' eq | n' i' eq].
Goal: Px
 exact p1.
Error: The term "p1" has type "P F1"
while it is expected to have type "P x".
```





Example: dependent inversion tactic

```
Definition Fin_3_rect_inv
```

(P: Fin.t 3 \rightarrow Type)

(p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))

(x : Fin.t 3) : P x.

Proof.

dependent inversion x.



Example: dependent inversion tactic

```
Definition Fin_3_rect_inv
  (P: Fin.t 3 \rightarrow \text{Type})
  (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))
  (x : Fin.t 3) : P x.
Proof.
  dependent inversion x.
```

Error: The term "P" of type "t 3 \rightarrow Type" cannot be applied to the term "x0": "t n" This term has type "t n" which should be a subtype of "t 3".





Example: dependent elimination

```
From Equations Require Import Equations.
Definition Fin_3_rect_depelim
  (P: Fin.t 3 \rightarrow Type)
  (p1: PF1) (p2: P(FSF1)) (p3: P(FS(FSF1)))
  (x : Fin.t 3) : P x.
```

Proof.

dependent elimination x as [F1|FS F1|FS (FS F1)].

- exact p1.
- exact p2.
- exact p3.

Defined.





Example: result of dependent elimination

```
match x as t0 in (t n) return
    \{ \{ | pr1 := n; pr2 := t0 | \} = \{ | pr1 := 3; pr2 := x | \} \rightarrow P x \}
with
 F1 n \Rightarrow
  DepElim.eq_simplification_sigma1_dep (S n) 3 F1 x
    (apply_noConfusion (S n) 3
         (fun H: n = 2 \Rightarrow
         DepElim.solution_left_dep 2
           (fun HO: eq_rect 3
             (fun n0 : nat \Rightarrow t n0)
             F1 3
             (noConfusion eq_refl) = x
```

DepElim.solution_right (eq_rect 3 (fun n0 : nat \Rightarrow t n0) F1 3







(noConfusion eq_refl)) p1 x H0) n H))

Small inversion

- The conclusion of the elimination scheme for Fin.t is \forall n, \forall (x:Fin.t n), P n x
- Objective: constrain n to be $3 : \forall (x:Fin.t 3), P x$
- Historical methods change the conclusion:

 \forall n, \forall (x:Fin.t n), n = 3 => P n x.

- Proxy-based small inversions change the matched objet.
 - ► Create a proxy inductive type that mimics Fin.t 3, and can be eliminated without loss of information.
 - ► We go from (x:Fin.t 3) $(x:Fin.t 3) \longrightarrow proxy(Fin.t (S 2)) \longrightarrow P x$





Partial inductive types

- First, partial inductive types mimic the comportment of the inductive type when specialised to a given pattern of the index.
- We work with inductive indices, the possible primitive patterns for the index are built from the constructors of its type.

```
Inductive Fin.t : nat \rightarrow Set :=
```

F1: \forall n: nat, Fin.t (S n)

FS: \forall n: nat, Fin.t n \rightarrow Fin.t (S n).

```
Inductive Fin_0 : Set :=.
```

Inductive Fin_S (n : nat) : Set :=

is F1: Fin Sn

is_FS (r:Fin.t n): Fin_S n.







Partial inductive types for dependent inversion

For dependent inversion, we also keep trace of the structure of the object we invert.

```
Inductive Fin_0 : Fin.t 0 -> Set :=.
Inductive Fin_S (n : nat) : Fin.t (S n) -> Set :=
| is_F1 : Fin_S n F1
| is_FS (r:Fin.t n) : Fin_S n (FS r).
```





Selecting the inductive type

- Then, two translation functions translate the original object into an object of the corresponding partial inductive type.
- The first maps index values to the partial inductive types.

```
\label{eq:definition} \begin{split} & \text{Definition Fin\_proxy\_type (n:nat)}: \text{Fin.t n} \to \text{Set} := \\ & \text{match n with} \\ & \mid 0 \quad \Rightarrow \text{Fin\_0} \\ & \mid \text{S m} \Rightarrow \text{Fin\_S m} \\ & \text{end.} \end{split}
```







The second maps constructors to their proxy counterpart.

```
Definition Fin_proxy{n} (r : Fin.t n) : Fin_proxy_type n r := match r as r' in Fin.t n' return Fin_proxy_type n' r' with \mid F1 n \Rightarrow is_F1 n \mid FS n t' \Rightarrow is_FS n t' end.
```







Using the proxy

- These objects only need to be created once.
- To use them, we then perform an elimination of the translated proxy object:

```
match Fin_proxy x with
  is_F1 \rightarrow p1
  is_FS _ x' \Rightarrow
    match Fin_proxy x' with
       is_F1 \rightarrow p2
       is_FS _ x'' \Rightarrow ...
```





It is possible to wrap the proxy in a typeclass so that remembering the proxy name is not necessary.

```
Class Proxy (T:Type) :=
  proxy_type: Type;
   proxy: T \rightarrow proxy\_type  }.
Class dProxy (T:Type) :=
{ dproxy_type: T \rightarrow Type;
  dproxy: \forall t:T, dproxy_type t \}.
```

match dProxy/proxy (x : Fin.t 3) with ...





Systematic creation

Partial inductive types and proxies are systematically derived by successive refinements of the inductive type through different transformations:

- Derecursivation: removing recursive references to the inductive type.
- Deparameterisation: transforming parameters into indices.
- Transformation into dependent inversion if needed.
- Specialisation: creating partial inductives for a given inductively typed index; can be iterated for deep or multiple patterns.
- Parameterisation: transforming as many indices as possible into parameters.





Current and future work

Ongoing work:

- MetaRocq plugin that automates the definition of proxies.
- Exploration of edge cases in the transformations.
- Case studies (CompCert...)

Future objectives:

- Support for inversion with dependently typed indices.
- Support for inversion with non-linear patterns.
- Eventually: integration of proxy-based small inversions into the Equations plugin?



