

Adequacy and Expressiveness, of Timed Modal Logic

REVISITED

Workshop in Honour of
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Aalborg University, DENMARK



AALBORG UNIVERSITET

First meeting – 1985

DATALOGI PÅ AALBORG UNIVERSITETSCENTER PIONERTIDEN 1974-84



104 Lars
Fischer



106 Jens Chr.
Godskesen



181 Hanne Riis
Nielson



138 Bent Bruun
Kristensen



132 Anna
Ingolfsdottir



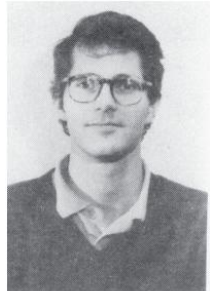
107 Hans
Hüttel



192 Jan
Stage



195 Liu
Xinxin



141 Kim Guldstrand
Larsen



166 Frank
Jensen



190 Arne
Skou



csj
Christian S. Jensen

First meeting – 1985

Algebraic Specification: List

Sorts

bash

`sort` Elem, List

Constructors

mathematica

`nil` : \rightarrow List

`cons` : Elem \times List \rightarrow List

Selectors / Observers

mathematica

`head` : List \rightarrow Elem

`tail` : List \rightarrow List

`isEmpty` : List \rightarrow Bool



Axioms

For all `x : Elem`, `xs : List`:

csharp

`isEmpty(nil)` = true

`isEmpty(cons(x, xs))` = false

`head(cons(x, xs))` = x

`tail(cons(x, xs))` = xs



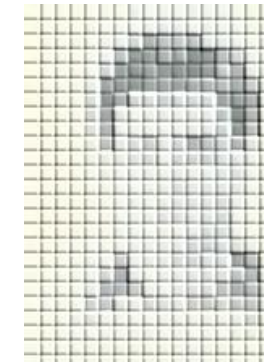
104 Lars Fischer



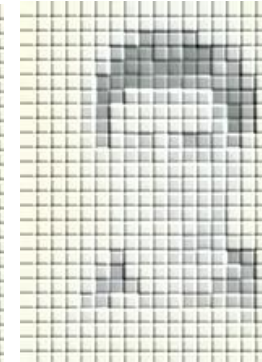
106 Jens Chr. Godskesen



132 Anna Ingolfssdottir



Michael Zeeberg



Jens Peter Christensen

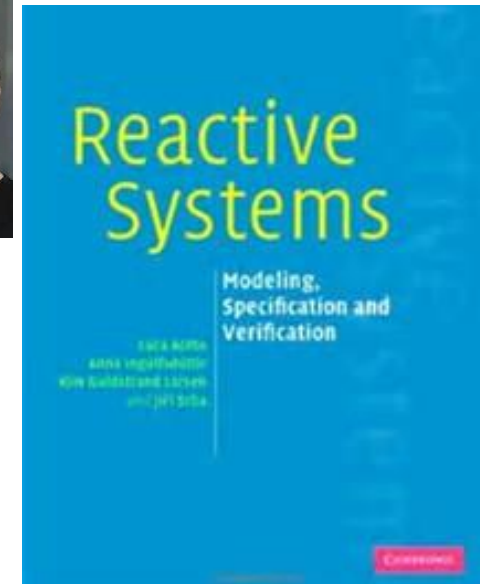


192 Jan Stage

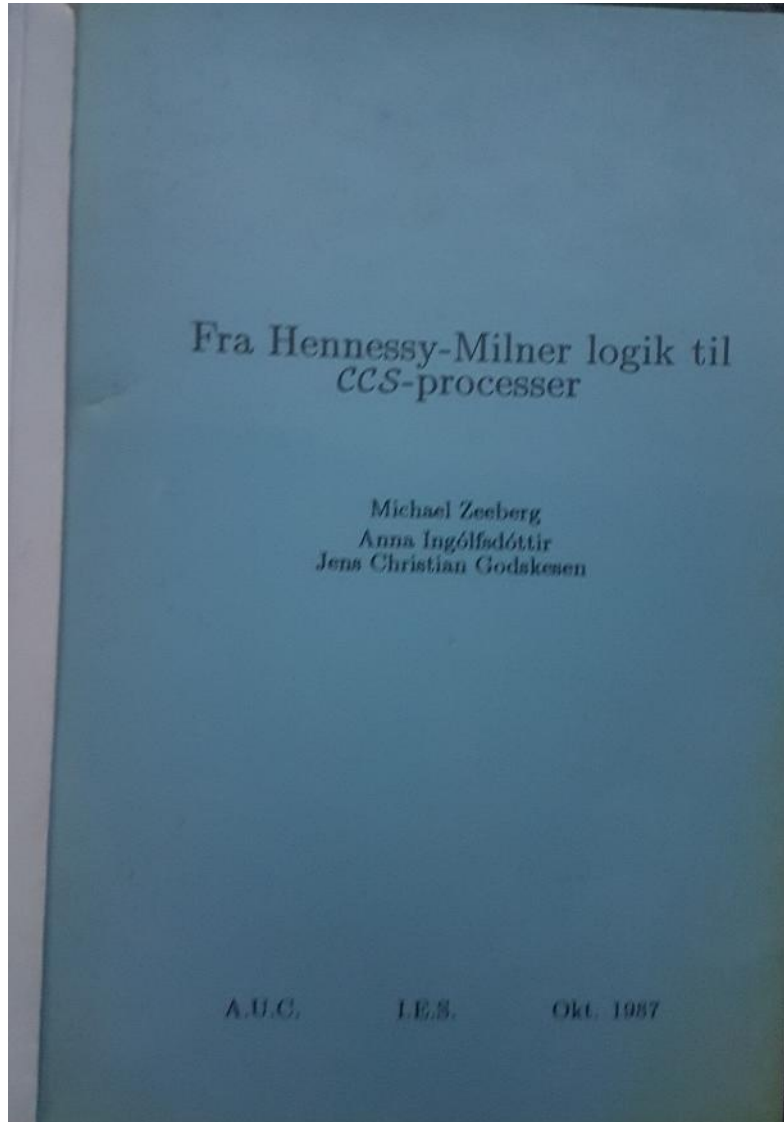
GAS (Generator for Algebraic Specifications)

Observing & Monitoring Anna

- **Reactive Systems (2007)**
- Allegro version 2 (2005)
- **Characteristic Formulas (1994)**
- **Timed Rebecca (2014)**
- Value-Passing (1993, 2001)
- **Runtime Monitoring (2017, 2017, 2017, 2019, ..)**
- Leikur og læsi í leikskólum (2011)
- Axiomatizing Finite Prefixes (1995)
- **MM for Learning Stochastic Models (2021)**
- Finite Equational Bases in Process Algebra (2005)
- **Characteristic Formulas for Time (2000)**



“Master Thesis” by Anna

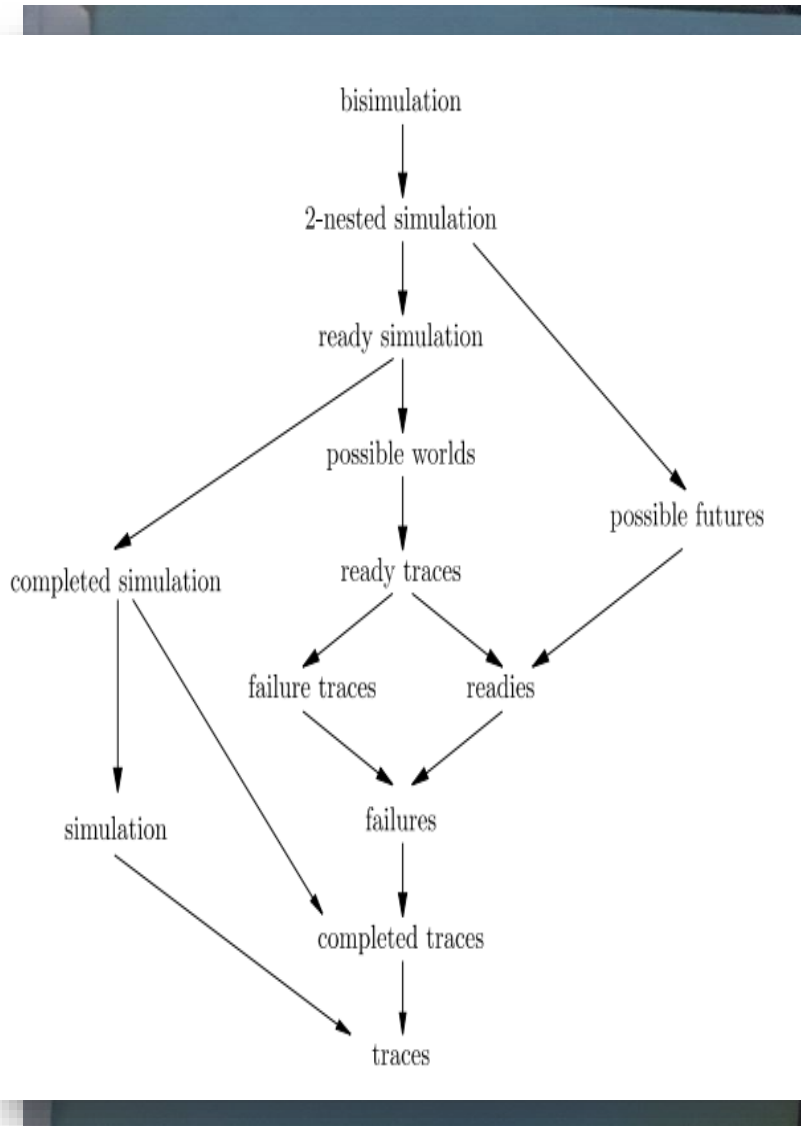


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Characteristic Formulas by Anna



- Michael Zeeberg, Anna Ingólfssdóttir, Jens Chr Godskesen: Fra Hennessy–Milner Logic til CCS Processor, 1987
- Bernhard Steffen, Anna Ingólfssdóttir: Characteristic Formulae for Processes with Divergence. Inf. Comput., 1994
- Luca Aceto, Anna Ingólfssdóttir, Mikkel Lykke Pedersen, Jan Poulsen: Characteristic formulae for timed automata. ITA 2000.
- Luca Aceto, Anna Ingólfssdóttir: Characteristic Formulae: From Automata to Logic. Bulletin of the EATCS 91, 2007.
- Luca Aceto, Anna Ingólfssdóttir, Joshua Sack: Characteristic Formulae for Fixed–Point Semantics: A General Framework. EXPRESS 2009
- Luca Aceto, Dario Della Monica, Ignacio Fábregas, Anna Ingólfssdóttir: When Are Prime Formulae Characteristic? MFCS, 2015
- Luca Aceto, Dario Della Monica, Ignacio Fábregas, Anna Ingólfssdóttir: When are prime formulae characteristic? Theor. Comput. Sci. 777: 3–31 (2019)
- Luca Aceto, Antonis Achilleos, Adrian Francalanza, Anna Ingólfssdóttir: The complexity of identifying characteristic formulae. J. Log. Algebraic Methods Program, 2020
- Luca Aceto, Antonis Achilleos, Aggeliki Chalki, Anna Ingólfssdóttir: The Complexity of Deciding Characteristic Formulae in Van Glabbeek's Branching–Time Spectrum. CSL 2025

Process Calculi Ingredients:

Models=Processes A, B, \dots

Operators $+, |, ||, \dots$

Equivalences, Preorders $\sim, \approx, \leq, \dots$

Specifications=Logical Properties ϕ, ψ, \dots

Equivalence Checking

Given A and B : $A \sim B$?

Model Checking:

Given ϕ and A : $A \models \phi$?

Satisfiability:

Given ϕ : $\exists A. A \models \phi$?

Adequacy:

$A \sim B$ iff $\forall \phi. A \models \phi \Leftrightarrow B \models \phi$.

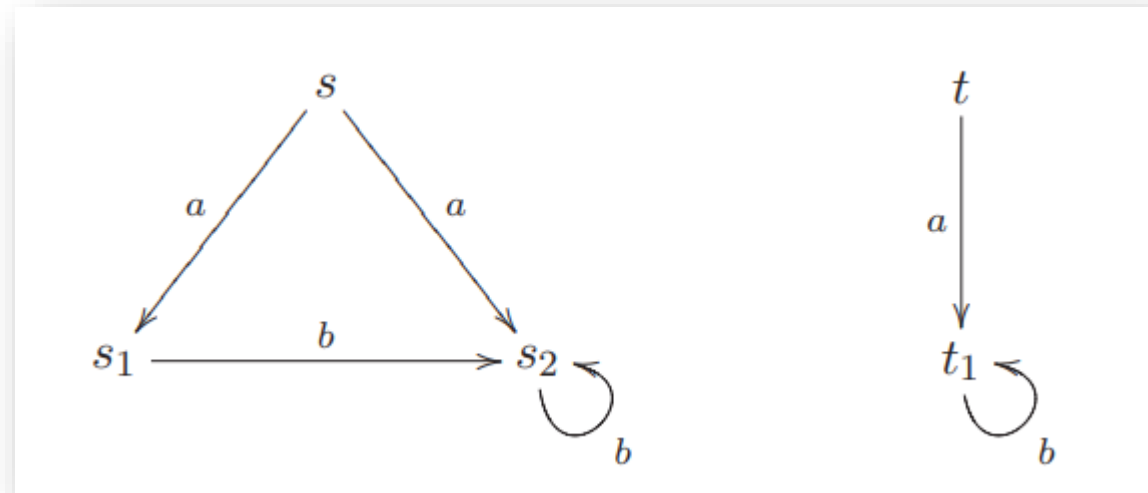
Characteristic Properties (ϕ_A):

Given A : $B \models \phi_A$ iff $A \sim B$?

Quotienting (ϕ/B):

Given B, ϕ : $(A|B) \models \phi$ iff $A \models \phi/B$?

Finite State Systems



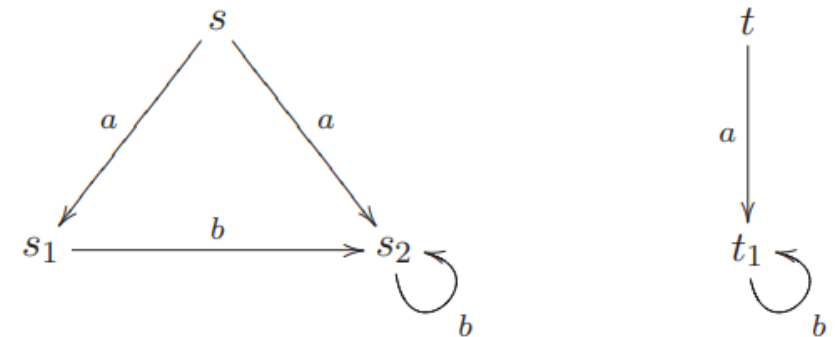
Bisimulation

Definition A transition system is as structure $T = (S, \rightarrow, Act)$ where:

- S is a finite set of states
- Act is a finite set of actions
- $\rightarrow \subseteq S \times Act \times S$ is the transition relation.



Robin Milner
David Park



Bisimulation

Definition A transition system is a structure $T = (S, \rightarrow, Act)$ where:

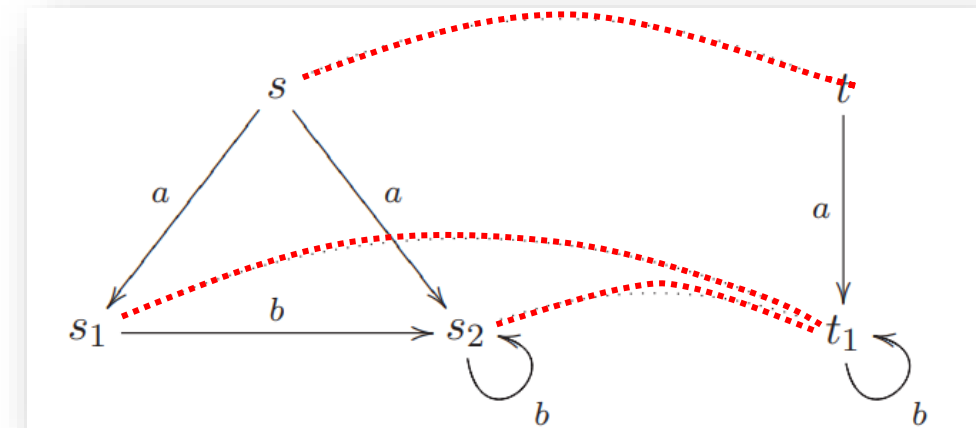
- S is a finite set of states
- Act is a finite set of actions
- $\rightarrow \subseteq S \times Act \times S$ is the transition relation.

Definition $\mathcal{B} \subseteq S \times S$ is a bisimulation iff whenever $(P, Q) \in \mathcal{B}$ then

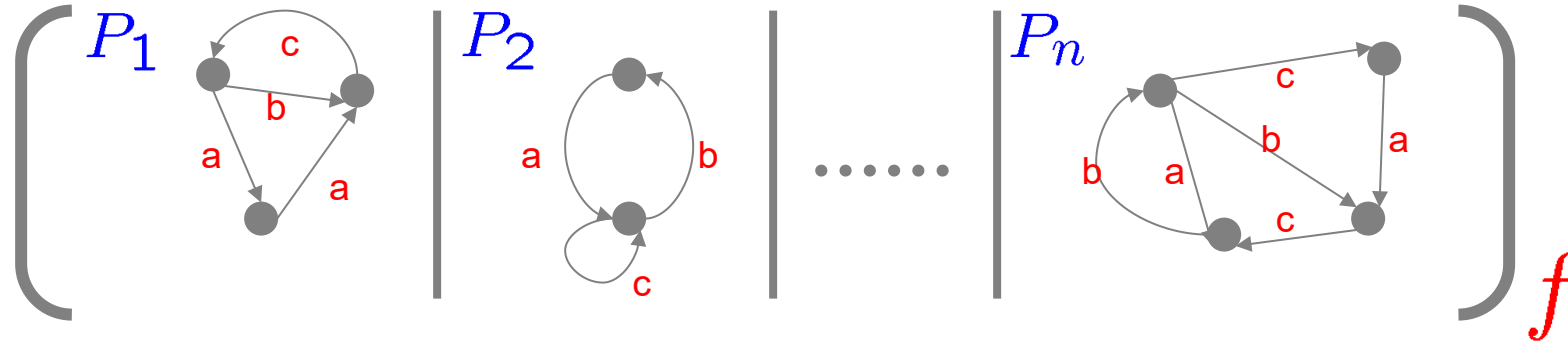
- Whenever $P \rightarrow_a P'$ then $Q \rightarrow_a Q'$ with $(P', Q') \in \mathcal{B}$
 - Whenever $Q \rightarrow_a Q'$ then $P \rightarrow_a P'$ with $(P', Q') \in \mathcal{B}$
- $P \sim Q$ if and only if $(P, Q) \in \mathcal{B}$ for some bisimulation \mathcal{B} .



Robin Milner
David Park



Networks of Finite Automata



Semantics

Synchronization function:

$$f : (Act \cup \{0\})^n \rightarrow Act$$

$$\frac{[P_i \xrightarrow{a_i} P'_i] \quad i=1..n}{(P_1, \dots, P_n)[f] \xrightarrow{a} (P'_1, \dots, P'_n)[f]} \quad f(a_1, \dots, a_n) = a$$

where $P_i \xrightarrow{0} P_i$

Examples:

$$f_{inter}(0, \dots, a, 0 \dots) = a$$

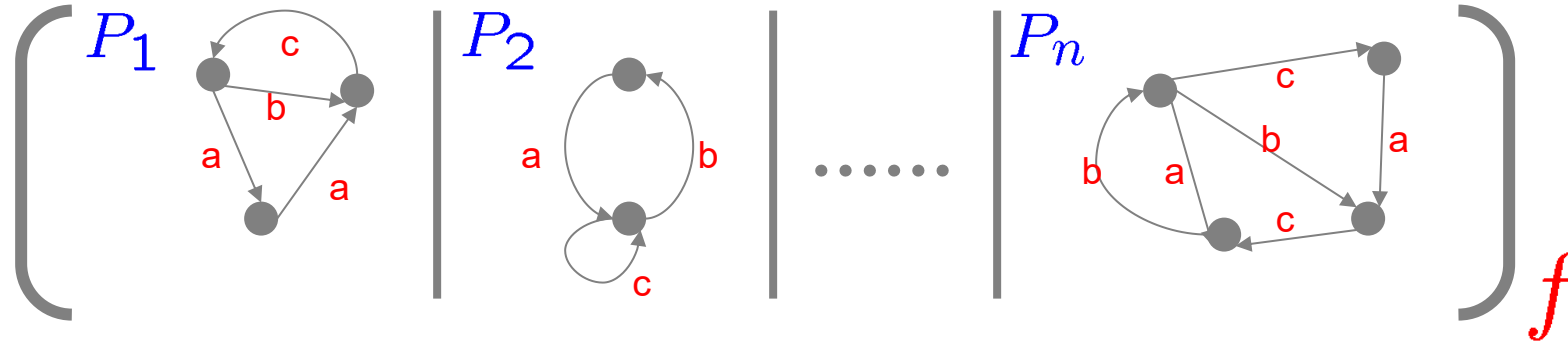
$$f_{sync}(a, a, \dots, a) = a$$

Notation:

$(P_1 \mid \dots \mid P_n)$: Interleaving

$(P_1 \parallel \dots \parallel P_n)$: Synchronous

Networks of Finite Automata



Semantics

Synchronization function:

$$f : (Act \cup \{0\})^n \rightarrow Act$$

$$\frac{[P_i \xrightarrow{a_i} P'_i] \quad i=1..n}{(P_1, \dots, P_n)[f] \xrightarrow{a} (P'_1, \dots, P'_n)[f]} \quad f(a_1, \dots, a_n) = a$$

where $P_i \xrightarrow{0} P_i$

Theorem

Whenever

$$P_1 \sim Q_1 \quad \dots \quad P_n \sim Q_n$$

Then

$$(P_1, \dots, P_n)[f] \sim (Q_1, \dots, Q_n)[f]$$

Syntax:

Hennessy-Milner Logic

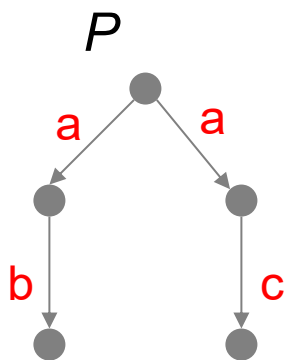
$$\phi ::= \text{tt} \mid \text{ff} \mid \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \langle a \rangle \phi \mid [a] \phi$$

Semantics:

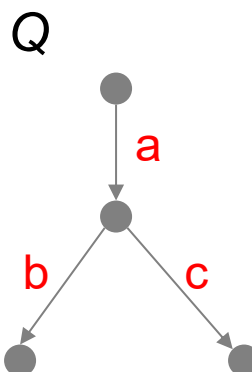
$$P \models \langle a \rangle \phi \text{ iff } \exists P'. P \xrightarrow{a} P' \wedge P' \models \phi$$

$$P \models [a] \phi \text{ iff } \forall P'. P \xrightarrow{a} P' \Rightarrow P' \models \phi$$

Example:



$[a] \langle b \rangle \text{tt}$



Adequacy Theorem

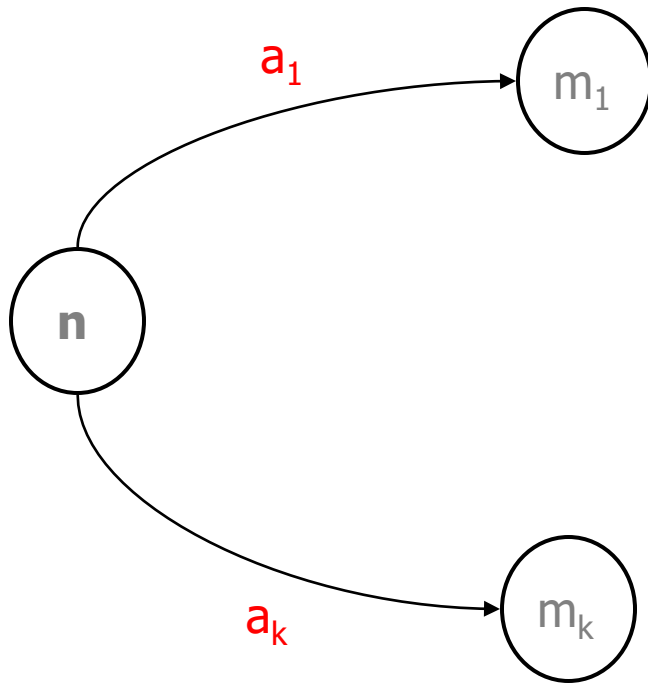
$$P \sim Q$$

if and only if

$$\forall \phi. P \models \phi \Leftrightarrow Q \models \phi$$

Characteristic Property

for finite state automata

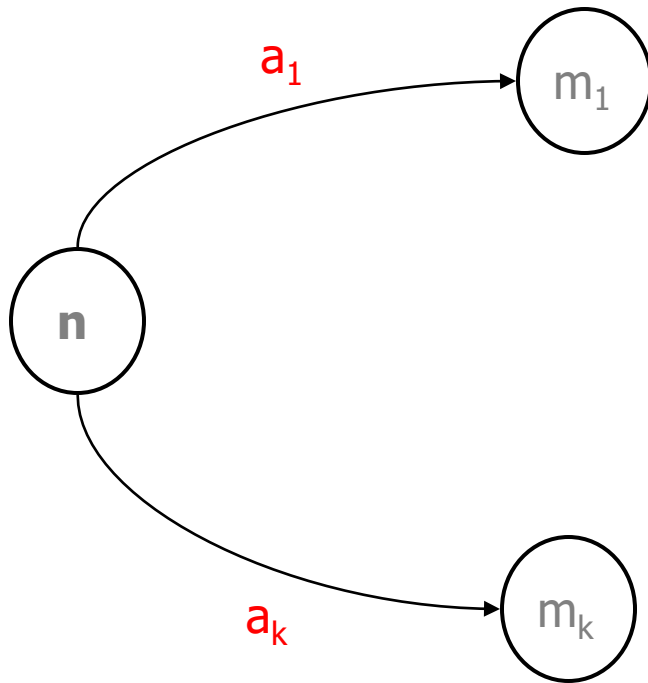


Graf&Sifakis'87
Zeeberg&Ingolfisdottir&Godskesen'87
Ingolfisdottir&Steffen'94

Characteristic Property

for finite state automata

Given A : $\exists \phi_A. B \models \phi_A$ iff $A \sim B$?



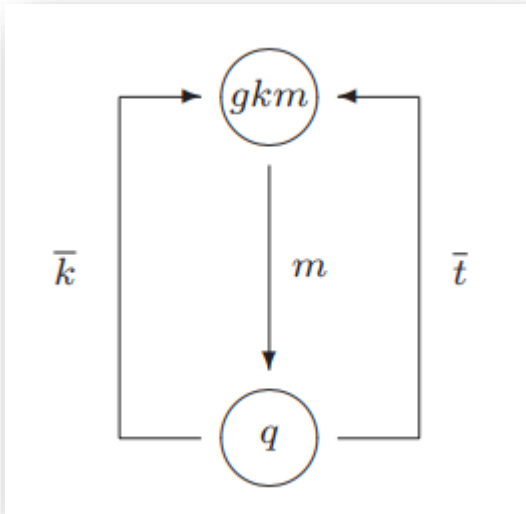
$$\begin{aligned} \phi_n &= \\ &\bigwedge_i \langle a_i \rangle \phi_{m_i} \wedge \\ &\bigwedge_a [a] (\bigvee_{i. a_i = a} \phi_{m_i}) \end{aligned}$$

Graf&Sifakis'87
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Characteristic Property

for finite state automata

Given A : $\exists \phi_A. B \models \phi_A$ iff $A \sim B$?



$\phi_n =$

$\bigwedge_i \langle a_i \rangle \phi_{m_i} \wedge$

$\bigwedge_a [a] (\bigvee_{i. a_i = a} \phi_{m_i})$

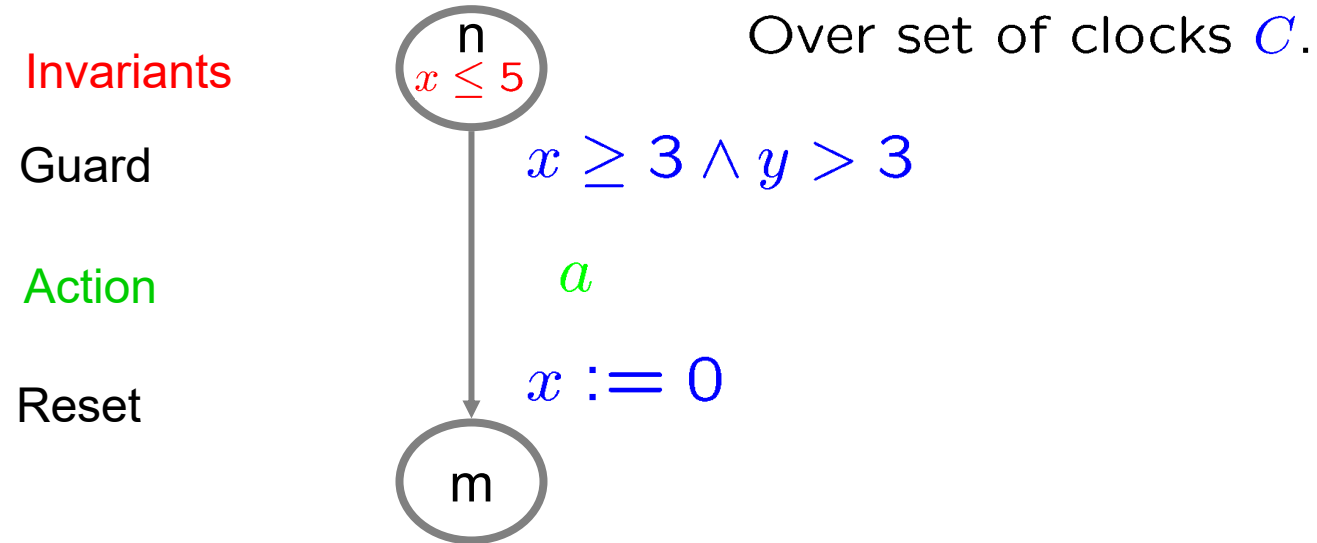
$$X_{gkm} \equiv \langle m \rangle X_q \wedge [m] X_q \wedge [\{\bar{t}, \bar{k}\}] ff,$$

$$X_q \equiv \langle \bar{t} \rangle X_{gkm} \wedge \langle \bar{k} \rangle X_{gkm} \wedge [\{\bar{t}, \bar{k}\}] X_{gkm} \wedge [m] ff.$$

Graf&Sifakis'87
Zeeberg&Ingolfssdottir&Godskesen'87
Ingolfssdottir&Steffen'94

Timed Systems





Semantics

States: (n, ν) where $\nu : C \longrightarrow \mathbb{R}$.

Transitions:

Delay: $(n, x = 0, y = \pi) \xrightarrow{\epsilon(\pi)} (n, x = \pi, y = 2\pi)$

Action: $(n, x = \pi, y = 2\pi) \xrightarrow{a} (m, x = 0, y = 2\pi)$

Syntax

Over formula clocks K .

$$\begin{aligned} \phi &::= \text{tt} \mid \text{ff} \mid Z \mid \\ &\quad \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \\ &\quad \langle a \rangle \phi \mid [a] \phi \mid \\ &\quad \exists \phi \mid \forall \phi \mid \\ &\quad x \text{ in } \phi \mid x \sim n \mid x - y \sim n \end{aligned}$$

Action Quant.

Delay Quant.

Intr. Formula Clock

Test Formula Clock

where $\sim \in \{, =, <, >, \leq, \geq\}$, Z is an identifier.

Declarations

$$\begin{aligned} \mathcal{E} : \quad & Z_1 =_\nu \phi_1 \\ & Z_2 =_\nu \phi_2 \\ & \dots \\ & Z_m =_\nu \phi_m \end{aligned}$$

ϕ holds between l and u : $x \text{ in } \exists(l \leq x \leq u \wedge \phi)$

Invariantly ϕ : $X =_{\nu} \phi \wedge \bigwedge_{a \in A} [a]X \wedge \forall X$

ϕ Until ψ : $X =_{\nu} \psi \vee (\phi \wedge \bigwedge_{a \in A} [a]X \wedge \forall X)$

ϕ Until $_{\leq t}$ ψ : $x \text{ in } ((\phi \wedge x \leq t) \text{ Until } \psi)$

Interpretation

$$\langle (n, v), u \rangle \models \phi$$

Diagram illustrating the components of the interpretation:

- $\langle (n, v), u \rangle$ is labeled "State of TA over C" (with a line pointing to (n, v)).
- u is labeled "Time assignment over K" (with a line pointing to u).
- ϕ is labeled "Formula over K" (with a line pointing to ϕ).

Semantics

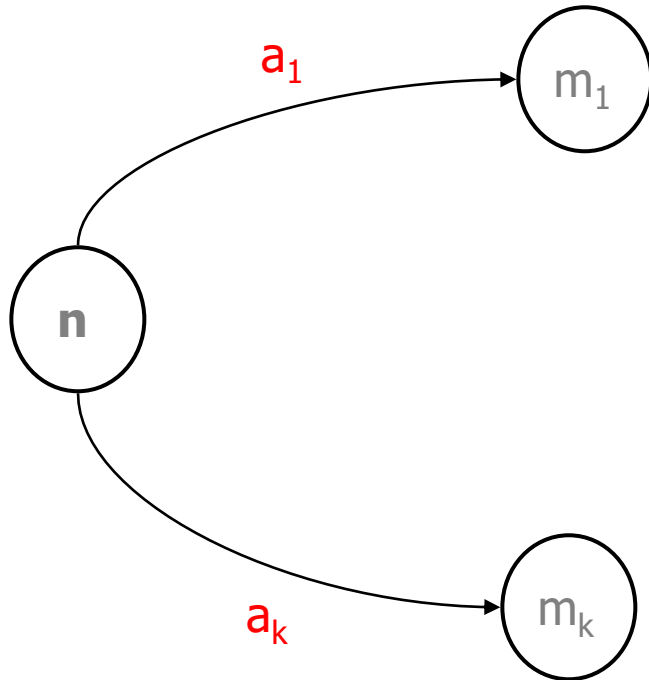
$$\langle (n, v), u \rangle \models \langle a \rangle \phi \text{ iff} \\ \exists (n, v) \xrightarrow{a} (n', v') \text{ st. } \langle (n', v'), u \rangle \models \phi$$

$$\langle (n, v), u \rangle \models \exists \phi \text{ iff} \\ \exists d \in \mathbb{R} \text{ st. } \langle (n, v + d), u + d \rangle \models \phi$$

Characteristic Property

for finite state automata

Given A : $\exists \phi_A. B \models \phi_A$ iff $A \sim B$?



$$\begin{aligned}\phi_n &= \\ &\bigwedge_i \langle a_i \rangle \phi_{m_i} \wedge \\ &\bigwedge_a [a] (\bigvee_i .a_i = a \phi_{m_i})\end{aligned}$$

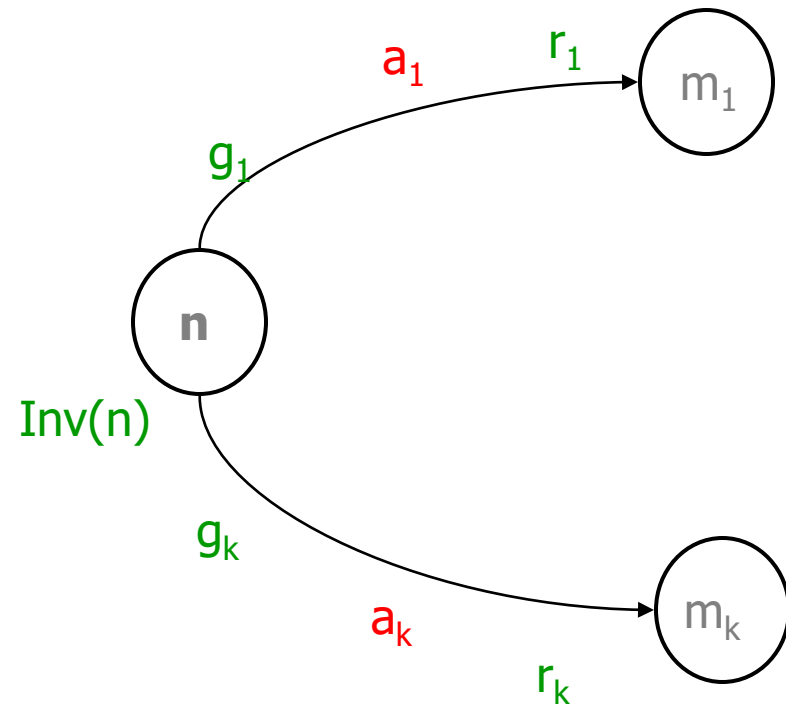
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Characteristic Property

for timed automata

Larsen, Laroussinie, Weise, 1995

Aceto, Ingólfssdóttir, Pedersen, Poulsen, 2000



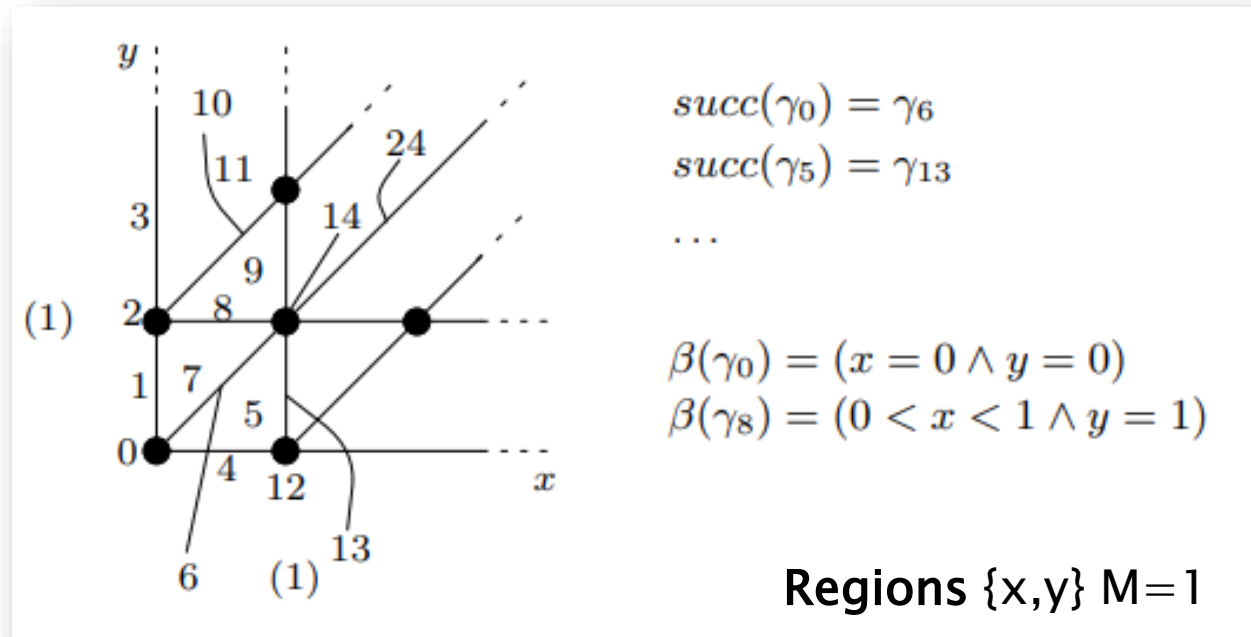
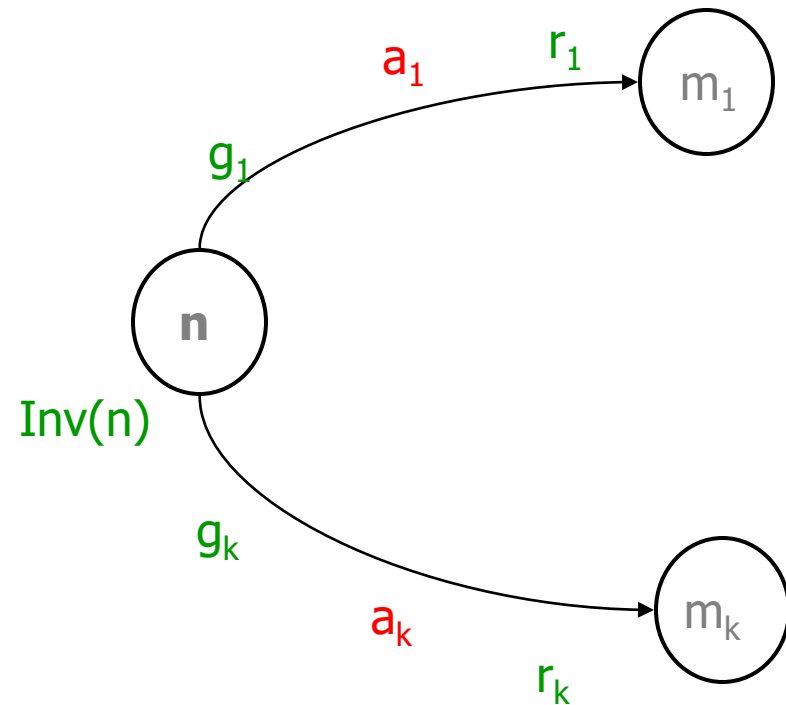
IDEA: Automata clocks become formula clocks

Characteristic Property

for timed automata

Larsen, Laroussinie, Weise, 1995

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regions grow exponentially in #clock & M

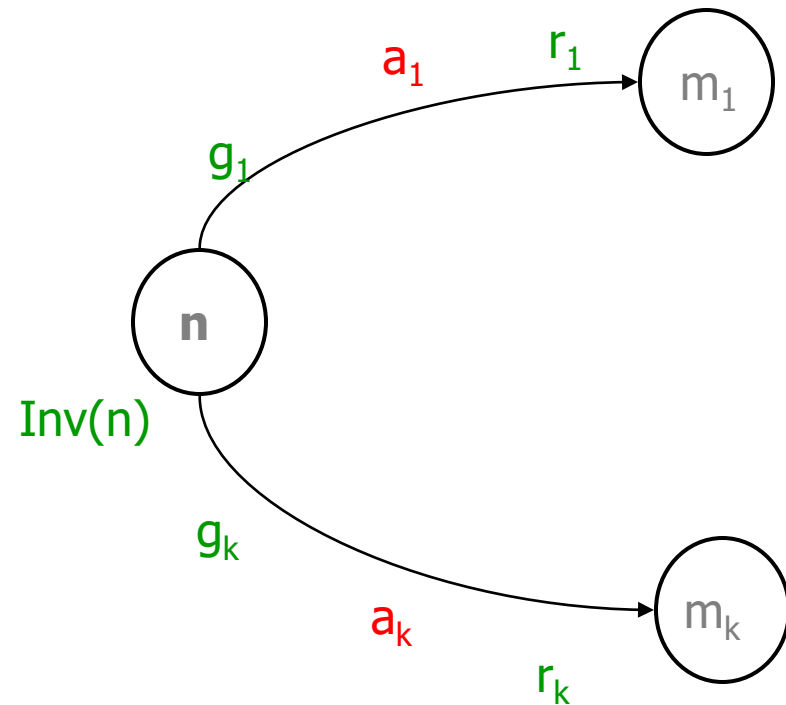
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$$\Phi(\eta, \gamma) \stackrel{\text{def}}{=} \left(\bigwedge_{e \in E(\eta, \gamma)} \langle a_e \rangle (r_e \text{ in } \Phi(\eta'_e, r_e(\gamma))) \wedge \bigwedge_a \left(\bigvee_{e \in E(\eta, \gamma, a)} (r_e \text{ in } \Phi(\eta'_e, r_e(\gamma))) \right) \right) \wedge \forall \left(\bigwedge_{l=0..l_\gamma} \beta(\gamma^l) \Rightarrow \Phi(\eta, \gamma^l) \right)$$

regions grow exponentially in #clock & M

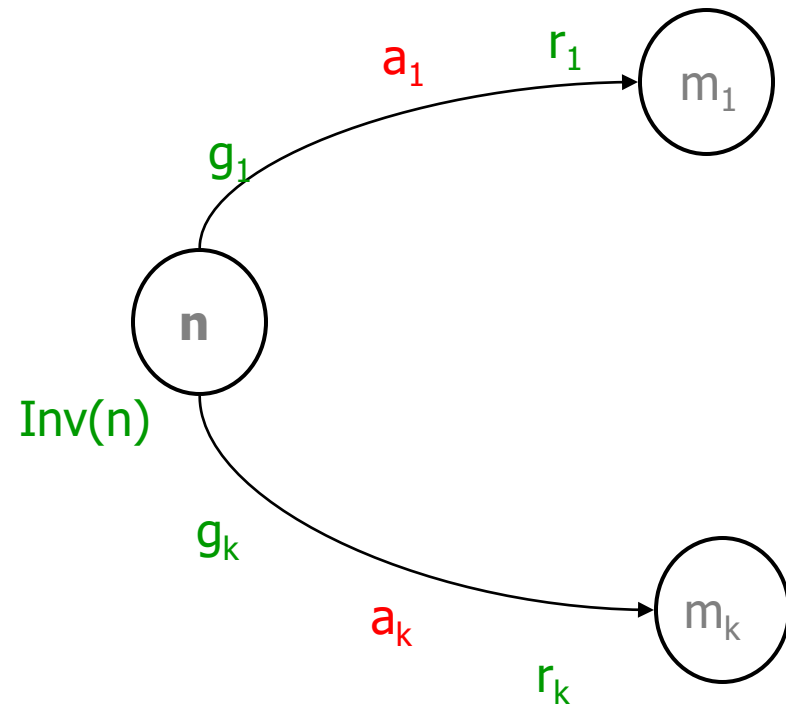
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Aceto, Ingólfssdóttir, Pedersen, Poulsen, 2000



$$\begin{aligned}
 \phi_n = & \\
 & \forall [\text{Inv}(n) \wedge \\
 & \quad \wedge_i g_i \Rightarrow (\langle a_i \rangle r_i \text{ in } \phi_{m_i}) \wedge \\
 & \quad \wedge_a [a] (\vee_{i.a_i=a} (r_i \text{ in } \phi_{m_i}) \wedge g_i)) \\
 &] \\
 & \exists \text{Inv}(n) \text{ boarder}
 \end{aligned}$$

$$(l, u) \sim (n, v) \text{ iff } \langle (l, u), v \rangle \models \phi_n$$

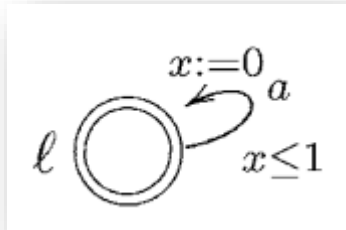
IDEA: Automata clocks become formula clocks

Characteristic Property

for timed automata

Larsen, Laroussinie, Weise, 1995

Aceto, Ingólfssdóttir, Pedersen, Poulsen, 2000



$$X_\ell \stackrel{\text{max}}{=} (y \leq 1 \Rightarrow (\langle a \rangle y \text{ in } X_\ell)) \\ \wedge [a](y \leq 1 \wedge (y \text{ in } X_\ell)) \\ \wedge \forall X_\ell.$$

$$\begin{aligned} \phi_n = & \\ & \forall [\text{Inv}(n) \wedge \\ & \wedge_i g_i \Rightarrow (\langle a_i \rangle r_i \text{ in } \phi_{m_i}) \wedge \\ & \wedge_a [a] (\vee_{i.a_i=a} (r_i \text{ in } \phi_{m_i}) \wedge g_i)) \\ &] \\ & \exists \text{Inv}(n) \text{ boarder} \end{aligned}$$

$$(l, u) \sim (n, v) \text{ iff } \langle (l, u), v \rangle \models \phi_n$$

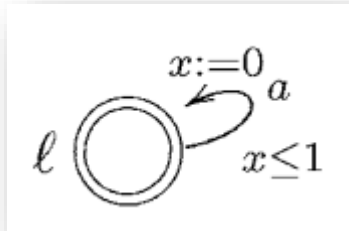
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$$X_\ell \stackrel{\text{max}}{=} (y \leq 1 \Rightarrow (\langle a \rangle y \text{ in } X_\ell)) \\ \wedge [a](y \leq 1 \wedge (y \text{ in } X_\ell)) \\ \wedge \forall X_\ell.$$

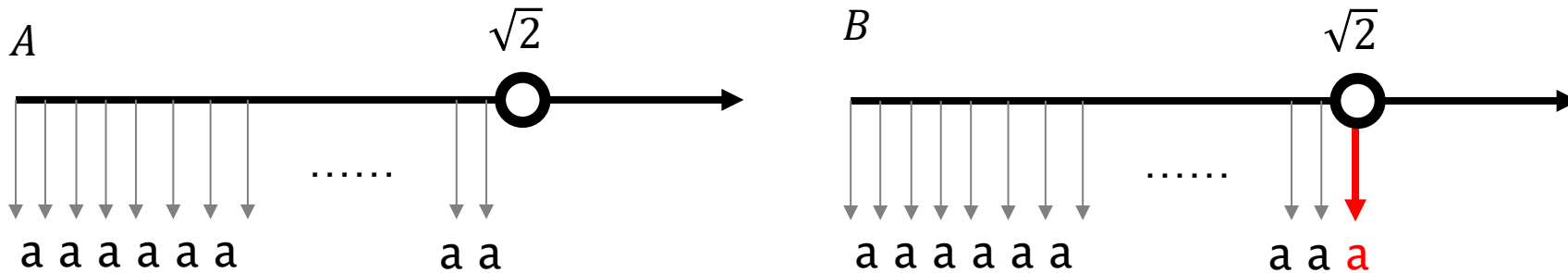
$$\begin{aligned} \phi_n = & \forall [\text{Inv}(n) \wedge \\ & \wedge_i g_i \Rightarrow (\langle a_i \rangle r_i \text{ in } \phi_{m_i}) \wedge \\ & \wedge_a [a](\bigvee_{i.a_i=a} (r_i \text{ in } \phi_{m_i}) \wedge g_i)) \\ &] \\ & \exists \text{Inv}(n) \text{ boarder} \end{aligned}$$

Timed (bi)similarity
Timed ready simulation
Faster-than bisimilarity
Timed Trace Inclusion

$$(l, u) \sim (n, v) \text{ iff } \langle (l, u), v \rangle \models \phi_n$$

IDEA: Automata clocks become formula clocks

Adequacy ☹️

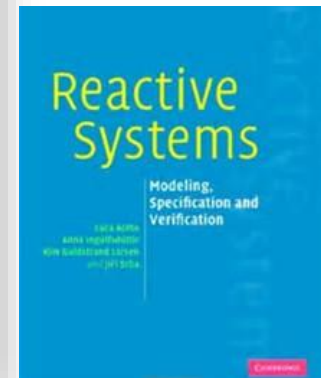


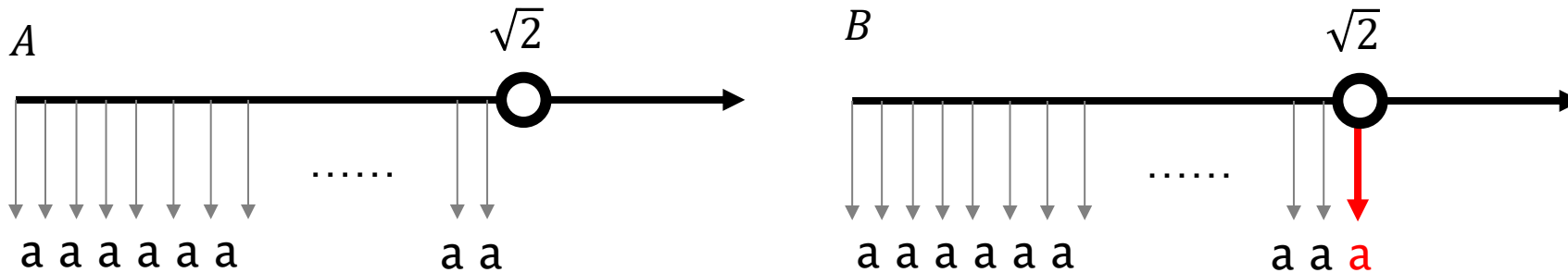
$$\neg(A \sim B) \quad \text{but} \\ \forall \phi. A \models \phi \Leftrightarrow B \models \phi$$

Exercise 12.12 (For the keenest) Show the claim made in the above proof. To this end, you might find it useful to begin by proving the claim by induction on the structure of formulae, assuming the following auxiliary statements:

1. $(A, \sqrt{2})$ and (B, d) are timed bisimilar for each $d > \sqrt{2}$;
2. for each $d, e > \sqrt{2}$ the states (A, d) and (B, e) are timed bisimilar; and
3. for each $d < \sqrt{2}$, for clock valuations u, u' and for each formula F ,
 $((A, \sqrt{2}), u) \models F$ and $((A, d), u') \models F$ imply $((B, \sqrt{2}), u) \models F$.

Next you should proceed to establish each of the above auxiliary statements. For the last statement, use structural induction on F . ♦





$$\phi = \forall x (x = 2 \rightarrow [a]\perp)$$

$$i = [x = (2 - \sqrt{2})]$$

$$(A, i) \models \phi \quad (B, i) \not\models \phi$$

TML

$$\mathcal{L}: \quad \phi ::= \perp \mid x \trianglelefteq r \mid \phi \rightarrow \phi \mid [a]\phi \mid \forall x. \phi \mid \exists x. \phi$$

where: $r \in \mathbb{Q}_{\geq 0}, \trianglelefteq \in \{\leq, \geq\}, x \in \mathcal{K}$

Samy Jaziri, L,
Radu Mardare,
Bingting Xue, 2014

Semantics

$$M, m, i \models \forall x. \phi \text{ iff}$$

$$\text{for any } t \in \mathbb{R}_{\geq 0}, M, m, i[x \mapsto t] \models \phi$$

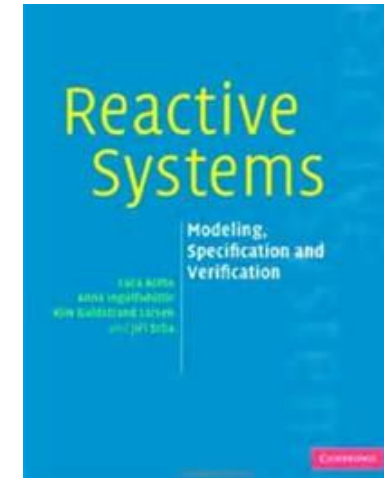
Theorem (Adequacy)

$$m \sim m' \text{ iff for any } \phi \text{ and } i,$$

$$M, m, i \models \phi \Leftrightarrow M, m', i \models \phi$$

Summary & Next

	Finite State Systems	Timed Systems	Probabilistic Systems	Quantum Systems
Model Checking <u>XML+rec</u> => XCTL	P Y	PSPACE Y	P N	Y
Adequacy	Y	N (Y when modifying logic)	Y	Y
Characteristic Property	Y	Y	Y	?
Quotient	Y	Y	N (Y when extending logic)	?
Finite Model Property	Y	N	Y (N for PCTL)	?
Satisfiability (decidability)	Y	N (Y restricting #cl & max const)	Y (? PCTL)	?
Validity (axiom.)	Y (Kozen)	Y	Y	?



2nd Edition



Giorgio



Giovanni



Max



Jens Chr



Elli

Congratulation & Best Wishes Kim & Merete

