# $Yang_Jinxin_1168646_homework-4-Q1$

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## 1 Description

Write a code to use reinforcement learning to generate a solution for the given wumpus world. The solution must present the best action to perform at each section of the board and calculate the expected reward of the optimal solution.

The output of program contains three parts:

- Utility (initial and final)
- Policy (show as arrows)
- Path

For the directory of this homework-4-Q1:

- src: Wumpus is a Java project file folder, you can just import this directory as "Existing Projects into Workspace" by Eclipse (both Windows and Linux works well) and run src→wumpus→Wumpus.java as "Java Application"
- outputs: the direct outputs from eclipse (the output is too long to paste in the report)
- *graphs*: all the screenshots

I will go though the logic of my program to explain the work I did.

## 2 Data Structure

After analyzing the problem, I extracted three basic data structures:

- Agent: current position, last block
- Block: basic blocks in the Wumpus world, coordinates, utility, name, policy (Pit, Wumpus, etc.)
- Wumpus (main function): initialize the Block and Agent, keep track of path, iteration process

## 3 Data Generation

Except Pit, Gold, Wumpus and Start, all the blocks should have a initial Utility, I generate them  $(0\sim5000)$  using random function. Here is my initial utility:

#### Initial World

Pit	Gold		Pit
		•	
	Wumpus		
	•		Pit
Start			

Figure 1. Initial World

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#### Initial Utilities -500 2648 5000 3737 -500 1782 1467 4791 4353 4441 2564 890 -1000 3160 2151 -500 2200 1902 2522 4721 2479 4549 1596 1927 Θ

Figure 2. Initial Utility

## 4 Iteration

First, it will take several iterations to let the utilities converge:

- start from every block in the Wumpus world
- every block will find its best choice of next block it will move into
- update current block's utility with U = U' + R

After 7 iterations, it will converge:

```
after 7 iterations Utilities
-500
      4990
             5000
                   4990
                          -500
4970
            4990
                   4980
      4980
                         4970
4960
      4970 -1000
                   4970
                         4960
-500
      4960
             4950
                   4960
                         4950
4940
      4950
            4940
                   4950
                             0
```

 ${\bf Figure \ 3.} \ \ {\rm Utility \ converge}$ 

Then starting from world[4,4], agent will do following steps until reach the Gold block:

- check which block it will go next, which means determine the right direction
- agent moves forward (simply change the position of agent class)

once setting a new direction of agent, printPolicy() function will print the matrix with policy, you can see the arrow is changing the direction just like these:

Pit	. Gold	. Pit	Pit	. (	Gold	•	Pit
			-	C	$rac{1}{2}$	Policy	
	. Wumpus			. Wui		. \	<b>A</b> .
Pit	Curren	t position	Pit	·•			^
		. *					*

Figure 4. Start

Figure 5. 1 iteration

Final Results 3

Pit	. Gold		Pit	Pit	. 0	iold		Pit
			•					<b>A</b> <
•	. Wumpus		^		. Wum	pus	•	*
Pit		•	*	Pit				1.
•		. Sta	art				•	Start
	Figure 6. 2 iteration Figure 7. 3 iteration				ation			
Pit	. Gold	. 1	Pit	Pit	. G	iold	<	Pit
•		7	*			. /	*	
•	. Wumpus		•		. Wum	pus		
Pit			•	Pit	•	·		
•		. Sta	art		•	·		Start
	Figure 8. 4 iteration Figure 9. 5 iteration				tion			
Pit	. Gold ←	*	Pit	Pit				Pit
		•	•					
	. Wumpus	•			. Wum	pus		
Pit		•	•	Pit				
		. Sta	art			10		Start

Figure 10. 6 iteration

Figure 11. Catch the gold!

# 5 Final Results

After grabing the gold successfully, the final reward will be:

#### Final Utilities -500 4990 5000 4990 -500 4970 4980 4990 4980 4970 4960 4970 -1000 4970 4960 -500 4950 4960 4950 4960 4950 4940 4950 4940 Θ Total Reward: 4840

Figure 12. Final Utility and Reward

Here is the optimal path output:

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Path:

Figure 13. Path

If your want to see the full output of one example, there is one in /outputs/output.