CODE BOOK FOR DATASET (FROM OUTPUT_DS.TXT)

experiment_id	integer
Identifies the experiment that was conducted	
subject_id	integer
Identifies the subject of the experiment	
activity_name	factor

Identifies the activity that the subject was performing in the experiment

- WALKING
- WALKING_UPSTAIRS
- WALKING DOWNSTAIRS
- SITTING
- STANDING
- LAYING

Other variables	numeric
(List of variables are given in the following)	

Describes the signal that was measured by the accelerometer and gyroscope and the estimated statistic that was derived:

- a) <t/f>BodyAcc_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals from the accelerometer in the X/Y/Z direction
- b) <t/f>GravityAcc_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals for gravity acceleration in the X/Y/Z direction
- c) <t/f>BodyAccJerk_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals for the jerk signals of body acceleration in the X/Y/Z direction
- d) <t/f>BodyGyro_<mean/std>_<X/Y/Z> Mean/standard deviation of the time/frequency domain signals from the gyroscope in the X/Y/Z direction

- e) <t/f>BodyGyroJerk_<mean/std>_<X/Y/Z> Mean/standard deviation of the time/frequency domain signals for the jerk signals from the gyroscope in the X/Y/Z direction
- f) <t/f>BodyAccMag_<mean/std>_<X/Y/Z> Mean/standard deviation of the time/frequency domain signals from the accelerometer in the X/Y/Z direction using the Euclidean norm
- g) <t/f>tGravityAccMag_<mean/std>_<X/Y/Z> Mean/standard deviation of the time/frequency domain signals for gravity acceleration in the X/Y/Z direction using the Euclidean norm
- h) <t/f>BodyAccJerkMag_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals for the jerk signals of body acceleration in the X/Y/Z direction using the Euclidean norm
- i) <t/f>BodyGyroMag_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals from the gyroscope in the X/Y/Z direction using the Euclidean norm
- j) <t/f>BodyGyroJerkMag_<mean/std>_<X/Y/Z>
 Mean/standard deviation of the time/frequency domain signals for the jerk signals from the gyroscope in the X/Y/Z direction using the Euclidean norm