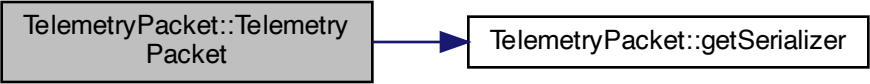


TelemetryPacket::Telemetry
Packet



```
graph LR; A[TelemetryPacket::TelemetryPacket] --> B[TelemetryPacket::getSerializer]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'TelemetryPacket::TelemetryPacket' on two lines. The right box is white with a black border and contains the text 'TelemetryPacket::getSerializer' on one line. A dark blue arrow points from the right side of the gray box to the left side of the white box.

TelemetryPacket::getSerializer