```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Logging/logController.h
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Logging/logController.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/stateMachine.h
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Comms/commandHandler.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Comms/networkManager.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Logging/storageController.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Logging/systemstatus.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/main.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Pyros/pyroHandler.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Sensors/esitmator.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/Sensors/sensors.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/stateMachine.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/States/groundstation.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/States/preflight.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/States/Setup.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/States/state.cpp
```

```
/Users/kiran/Documents
/Projects/ICLR/Avionics
/Ricardo_OS/Ricardo_OS/src
/States/usbmode.cpp
```