/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/include/config.h

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Comms/interfaces/radio.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Comms/interfaces/usb.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Logging/logController.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/baro.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/battery.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/gps.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/imu.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/kalman.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/Sensors/sensors.cpp

/Users/kiran/Documents/Projects/ICLR/Avionics/Ricardo_OS/Ricardo_OS/src/States/setup.cpp