

LocalizationKF::updateGPSReference



```
graph LR; A[LocalizationKF::updateGPSReference] --> B[LocalizationKF::GPStoECEF]
```

A diagram showing a horizontal flow from left to right. On the left is a gray rectangular box with a black border containing the text 'LocalizationKF::updateGPSReference'. A blue arrow points from the right side of this box to the left side of a white rectangular box with a black border on the right. This second box contains the text 'LocalizationKF::GPStoECEF'.

LocalizationKF::GPStoECEF