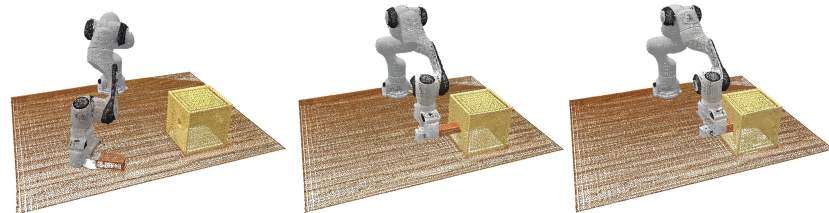
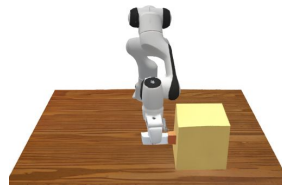
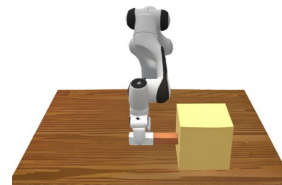
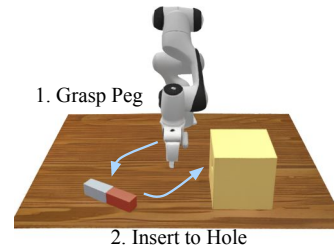


3D latents from
multi-view observations



Predictive rollout of future 3D latent states



Robotic action execution

