General Topics in Machine Learning "Modern" Wave of Machine Learning

DATA SCIENCE II: Machine Learning MTH 9899 Baruch College

Lecture 1: Introduction to Machine Learning

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Outline

- General Topics in Machine Learning
 - Supervised vs Unsupervised Learning
 - Classification vs Regression
 - Cross Validation
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 - Bias vs Variance Example Ridge Regression
- "Modern" Wave of Machine Learning
 - Logistic Regression
 - Stochastic Gradient Descent and Batch Learning
 - Keras
 - Further Preview of Keras: Multi-Layer Perceptron
 - Further Preview of Keras: Regularizations

Supervised Learning

Supervised machine learning consists of learning a function from a set of labeled training examples.

- Generally, You are given input examples AND output values.
- Success can be easily measured through a variety of metrics on in and out-of-sample observations.
- Sometimes, we don't have exact output values, but instead, a notion of 'maximizing' a function (ie Reinforcement Learning).

Unsupervised Learning

In Unsupervised Learning, you're trying to learn a structure that you don't know at the beginning. There are 2 main categories of Unsupervised Learning:

- Clustering Identify similar/related items based on their features.
 - Identify 'similar' stocks based on returns or other characteristics.
 - Group mortgages together based on geographic data to understand default correlations.
- Latent Variable Models Identify underlying variables that drive the features you can observe.
 - Latent Variable A variable who's value is never known, but instead is implied by it's state.

Classification

Identifying which category a variable belongs to. The categories can be:

- Ordinal Variables which have an intrinsic order, ie. credit ratings
- Categorical Variables No implicit ordering, such as what industry a stock belongs to.

Classification Metrics

Reciver Operating Characteristic (ROC) - A graph of the true positive vs false positive rate parameterized by the cutoff used to discriminate between outcomes in a true/false classification. Confusion Matrix - A table of correct vs incorrect values across all categories.

Regression

Regression refers to prediction a continuous numerical variable - which is what we will focus on in this course. There are a wide variety of different metrics to measure the quality of fit of a regression, each with their own strengths and weaknesses.

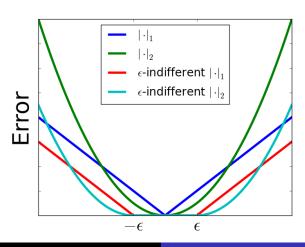
- Mean Squared Error (L2 Norm) MSE is the most common metric for regression because it's intuitive and very easy to calculate. The problem is, it's not robust to outliers.
- Absolute Error (L1 Norm) The L1 Norm is a very robust metric that can deal with outliers. Unfortunately, it's very costly to optimize since it's not a convex problem.

Regression

• ϵ Indifferent - This is a metric where we don't penalize for things within some constant, ϵ , of the training value, then apply another metric (ie L1 or L2 norm) to points outside of this area.

Ultimately, the best metric is a tradeoff of computational speed, robustness, and the underlying goal.

Regression



Regression

You might need to do some cleaning or filtering if you're using an L2 Norm metric.

 Median Absolute Deviation (MAD) Filtering - Calculate the MAD - defined as the median of the deviation of every point in a series from the series' median. Then pull in all points to be within n (typically 3 to 5) MADs of the median:

$$MAD_X = \text{med } |x_i - \text{med } X| \tag{1}$$

$$x_{i}^{'} = \operatorname{clip}(x_{i}, \operatorname{med}_{X} + / - n \operatorname{MAD}_{X})$$
 (2)

• Winsorization - Clip points to a given percentile or number of σ of μ

Summary

- Cross Validation (CV) refers to fitting your model on a portion of your data, and testing it on the out-of-sample portion repeatedly, omitting a different section each time.
- First, divide your data up into *F* chunks, or 'folds'.
- For example, for the 3-Fold CV shown below, we would fit a model to portions 1,2 and 2,3 and use those models to calculate the error on samples 3 and 4 respectively.
- At an extreme, we can perform 'Leave One Out' CV, which is equivalent to N-Fold CV.
- Model Selection Does adding a new variable really improve our model?

Motivation

- In ML, we face a risk of overfitting our model to the data.
 CV will help us avoid this, by measuring the performance on data that is not used to build the underlying model.
- Without CV, we will overestimate the accuracy of our models. This is what leads us to adjusted R².
- Regularization is a valuable technique we will use, and CV is well-suited to calibrating parameters.

Caveats

- With time series data, you have to be careful. If you divide your data up such that a single time is distributed across multiple folds, you might be using forward looking data! For example, imagine you're fitting a complex Neural Network
- Without CV, we will overestimate the accuracy of our models. This is what leads us to adjusted R².
- Regularization is a valuable technique we will use, and CV is well-suited to calibrating parameters.
- Model Selection Does adding a new variable really improve our model?

Bias & Variance

Normally, we try to calculate unbiased estimators:

$$E\left[\hat{x}\right] = x \tag{3}$$

Sometimes, we'd rather introduce a bias, if it can reduce the variance of our predictions. We have an inherent *variance* in our predictor, based on the input dataset, which can be considered a random sample.

Bias vs Variance in Linear Regression

In a traditional linear model (LM), of the form $Y=X\beta+\epsilon$, we assume $\epsilon\sim N(0,\sigma^2)$ and $\hat{\beta}=(X^TX)^{-1}X^TY$. Let's consider our expected squared prediction error:

$$\begin{array}{lll} \mathbb{E}_{\hat{\beta}}[\|y-\hat{\beta}x\|_2] & = & \mathbb{E}_{\hat{\beta}}[\|(\beta x+\epsilon)-\hat{\beta}x\|_2] \\ & = & \mathbb{E}_{\hat{\beta}}[\|(\beta x+\epsilon)\|_2 - 2(\beta x+\epsilon)\hat{\beta}x + \|(\beta x+\epsilon)\|_2] \\ & = & \mathbb{E}_{\hat{\beta}}(\hat{\beta}x)^2 + \epsilon^2 - 2\beta x \, \mathbb{E}_{\hat{\beta}}\,\hat{\beta}x + (\beta x)^2 \\ & = & [\mathbb{E}_{\hat{\beta}}[(\hat{\beta}x)^2] - \, \mathbb{E}_{\hat{\beta}}[\hat{\beta}x]^2] + \epsilon^2 + (\mathbb{E}_{\hat{\beta}}[\hat{\beta}x] - \beta x)^2 \\ & & \text{Variance of the Prediction} & \text{Bias of the Predictor} \end{array}$$

Bias vs Variance in Linear Regression

For normal linear regression, $\mathbb{E}\,\hat{\beta}=\beta$, so the bias term can be eliminated:

$$\begin{split} \mathbb{E}_{\hat{\beta}}[\|y - \hat{\beta}x\|_2] &= [\mathbb{E}_{\hat{\beta}}[(\hat{\beta}x)^2] - \mathbb{E}_{\hat{\beta}}[\hat{\beta}x]^2] + \epsilon^2 + (\mathbb{E}_{\hat{\beta}}[\hat{\beta}x] - \beta x)^2 \\ &= [\mathbb{E}_{\hat{\beta}}[(\hat{\beta}x)^2] - \mathbb{E}_{\hat{\beta}}[\hat{\beta}x]^2] + \epsilon^2 \end{split}$$

Later, when we cover Ridge Regression, we'll see if allowing a biased estimator can improve the overall prediction quality.

Ridge Regression

Ridge Regression, also known as Tikhonov Regularization, is an extension of a normal least squares regression.

- We will add a penalty term to our normal linear regression $\lambda \|\beta\|_2$
- This forces a tradeoff between the magnitude of the β s and the error terms.
- This is an example of **Regularization**, the notion of adding a penalty to shrink fitted parameters and reduce variance.

Ridge Regression

$$\begin{split} \min_{\beta^R} \|Y - X \hat{\beta}^R\| + \lambda \|\beta^R\|_2 \\ \mathcal{L} &= \|Y - X \hat{\beta}^R\| + \lambda \|\hat{\beta}^R\|_2 \\ \frac{\partial \mathcal{L}}{\partial \hat{\beta}^R} &= -2Y^T X + 2X^T X \hat{\beta}^R + 2\lambda \hat{\beta}^R \\ \hat{\beta}^R &= (X^T X + \lambda I)^{-1} X^T Y \\ \hline \text{Regularization} \\ \text{penalty} \end{split}$$

Ridge Regression

As we saw, in Ridge Regression, the estimate of β is no longer unbiased, in fact, we can show that:

$$Bias(\hat{\beta}^R) = -\lambda (X^T X + \lambda I)^{-1} \beta$$
$$Var(\hat{\beta}^R) = \sigma^2 (X^T X + \lambda I)^{-1} X^T X (X^T X + \lambda I)^{-1}$$

Compare this to OLS:

$$Bias(\hat{\beta}^{LS}) = 0$$

$$Var(\hat{\beta}^{LS}) = \sigma^{2}(X^{T}X)^{-1}$$

Ridge Regression

Does it work? Does allowing a biased estimator with a lower variance improve our regression results? Let's see in an IPython Notebook.

Ridge Regression - Choosing λ

So how do we pick a good λ ?? Cross-Validation!!

- We test various values of λ and use the value that minimizes the out-of-sample MSE.
- For Ridge, we can do something called 'Generalized Cross Validation', which is an estimate of leave-one-out validation

Ridge Regression

A few caveats:

- Ridge Regression is dependent on scale. Since we penalize all β values equally, we need to make sure that all variables are normalized, ie $\mu=0,\sigma=1$.
- The λ value scales linearly with the number of points, ie if your sample size doubles, your λ should too.

$$\hat{\beta}^R = (X^T X + \lambda I)^{-1} X^T Y$$

Logistic Regression Stochastic Gradient Descent and Batch Learning Keras

Further Preview of Keras: Multi-Layer Perceptron Further Preview of Keras: Regularizations

- Logistic regression is the most basic model for conditional distribution of some variable y given some x.
- It models probability via linear model that is transformed via sigmoid

$$\frac{1}{1 + e^{\beta_0 + \beta_1 x_1}}$$

- If one has to predict either 0 or 1 rather than probability $\beta_0 + \beta_1 x_1$ is linear classifier.
- Simplicity is perhaps the main reasons why Logisitic Regression is so widely used in discrete data analysis (see Boltzmann distribution with two states for more details).

Logistic Regression
Stochastic Gradient Descent and Batch Learning
Keras

- Stochastic gradient descent is going down the gradient example by example since typically the function we are trying to minimize has form $\sum_i f(e_i)$ where sum is over examples.
- Hence the change is done via subtracting $\eta \nabla f(e_i)$, where η is the learning rate.
- Batch learning has the same idea except examples are grouped in *batches, for example of size 100, and then for butch* K *we subtract* $\eta \sum_{i=K+1}^{100*K+100} \nabla f(e_i)$.
- This does not make sense for all models specifically for models with closed solutions, but for non-linear models this technique had a lot of success especially if f has some properties like convexity.

Logistic Regression
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```
model = Sequential()
model.add(Dense(20, init='zero', Activation='sigmoid')
sgd = SGD(lr=0.1, decay=1e-6,
    momentum=0.9, nesterov=True)
model.compile(loss='binary_crossentropy', optimizer=sgd)
```

Logistic Regression
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Further Preview of Keras: Multi-Layer Perceptron

```
model = Sequential()
model.add(Dense(64, input_dim=20, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(64, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
model.compile(
  loss='categorical_crossentropy', optimizer='adadelta')
```

Logistic Regression
Stochastic Gradient Descent and Batch Learning
Keras

Further Preview of Keras: Multi-Layer Perceptro Further Preview of Keras: Regularizations

We wrap this together by introducing simple 4-line code for logistic regression.

```
model = Sequential()
model.add(Dense(64, input dim=20,
  W regularizer=12(0.01)), activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(64,
  W regularizer=11(1=0.01), activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10,
  W_regularizer=1112(11=0.01, 12=0.01),
  activation='softmax'))
model.compile(
  loss='categorical_crossentropy', optimizer='adadelta')
```