Defined recursively by

$$f(n) = \begin{cases} 0, & n = 0 \\ 1, & n = 1 \\ f(n-1) + f(n-2), & n \ge 2. \end{cases}$$

Problem: given k, compute f(k)

•  $(0 \le k \le 1,000,000)$ 

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There are **at least** six different solutions. Let's code up the most naïve one.

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#### Key Idea:

why recompute f(k) a bunch of times? store and reuse previous values.

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```
int f(int n, hashset h):
  if(n == 0) return 0;
  if(n == 1) return 1;
  if(h.contains(n)) return h[n];
  return h[n] = f(n-1,h) + f(n-2,h);
```

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What's the running time? What's the space usage?

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What's the running time?

What's the space usage? O(n)

O(n)

Called memoization: trade space for time

Iteratively **build a table** of partial sols:

$$\frac{f(0) \quad f(1) \quad f(2) \quad f(3) \quad f(4) \quad f(5)}{0 \quad 1}$$

Iteratively build a table of partial sols:

$$f(0)$$
  $f(1)$   $f(2)$   $f(3)$   $f(4)$   $f(5)$ 

we have accumulated just enough information to compute this

Iteratively build a table of partial sols:

Iteratively **build a table** of partial sols:

now "slide window right" and compute this

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```
int fib(int n):
  int table[n+1] = \{0, 0, ....\};
  table[0] = 0;
  table[1] = 1;
  for(int i=2; i<=n; i++)
    table[i] =
 table[i-1]+table[i-2];
  return table[n];
```

Iteratively build a table of partial sols

What's the running time?

What's the space usage?

Iteratively build a table of partial sols

What's the running time? O(n)

What's the space usage? O(n)

Called **dynamic programming**: trade space for time

Requires two things to be true:

1. Large problem can be recursively broken up into smaller sub-problems

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- 2. Results from sub-problems are reused many times in solving the large problem

Dynamic programming (bottom-up) and memoization (top-down) are **equivalent** 

 (but sometimes one approach is easier/ more natural)

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Hints to use dynamic programing:

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Hints to use dynamic programing:

- problem "smells exponential"
- there are ways to reuse/prune/cull partial results

"What title, what name, could I choose? In the first place I was interested in planning, in decision making, in thinking. But planning, is not a good word for various reasons. I decided therefore to use the word "programming". I wanted to get across the idea that this was dynamic, this was multistage, this was time-varying. I thought, let's kill two birds with one stone. Let's take a word that has an absolutely precise meaning, namely dynamic, in the classical physical sense. It also has a very interesting property as an adjective, and that it's impossible to use the word dynamic in a pejorative sense. Try thinking of some combination that will possibly give it a pejorative meaning. It's impossible. Thus, I thought dynamic programming was a good name. It was something not even a Congressman could object to. So I used it as an umbrella for my activities."

-Bellman

You are playing a game with 10 levels. Each level you can use 10 different strategies. You start with 100 health.

#### Strategy s on level I:

- Takes  $t_{l,s}$  seconds
- Costs  $h_{l,s}$  health

What's the quickest you can beat the game without dying?

	health cost	time		health cost	time		health cost	time
	0 hp	100 s		1 hp	90 s		0 hp	120 s
	2 hp	80 s		1 hp	80 s		1 hp	70 s
	4 hp	30 s		3 hp	70 s		2 hp	50 s
level 1		•	leve	el 2	•	leve	======================================	

	health cost	time		health cost	time	health cost	time	
	0 hp	100 s		1 hp	90 s	0 hp	120 s	
	2 hp	80 s		1 hp	80 s	1 hp	70 s	
	4 hp	30 s		3 hp	70 s	2 hp	50 s	
level 1		_	leve	el 2	 lev	el 3	-	

one possible run: 100+80+50 = 230 s. 2 hp left over

optimal?

Naïve solution: try all 10^10 sets of strategies (no chance)

What is the optimal substructure?

#### Thought process:

"I can beat level L with different amounts of health left. For each amount of health, I care about the **fastest** I can get to the end of level L with at least that amount of health. I don't care about slower strategies that also get me there with the same amount of health."

Naïve solution: try all 10^10 sets of strategies (no chance)

#### What is the optimal substructure?

Compute f(L, h): the fastest you can beat level L with at least h health.

health cost	time
0 hp	100 s
2 hp	80 s
4 hp	30 s

health cost	time
1 hp	90 s
1 hp	80 s
3 hp	70 s

cost	time
0 hp	120 s
1 hp	70 s
2 hp	50 s

health

	0	30	
	1	30	
h	2	80	
	3	80	
	4	80	
	5	100	

health cost	time
0 hp	100 s
2 hp	80 s
4 hp	30 s

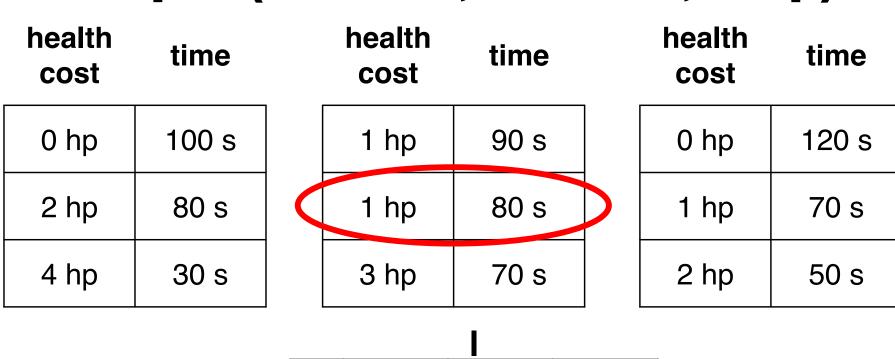
health cost	time		
1 hp	90 s		
1 hp	80 s		
3 hp	70 s		

cost	time
0 hp	120 s
1 hp	70 s
2 hp	50 s

health

	0	30	?	
	1	30		
h	2	80		
-	3	80		
	4	80		
	5	100		

strategy 1: 120 s



	0	30	?	
	1	30		
h	2	80		
	3	80		
	4	80		
	5	100		

strategy 1: 120 s

strategy 2: 110 s

haalth

health cost	time
0 hp	100 s
2 hp	80 s
4 hp	30 s

cost	time	
1 hp	90 s	
1 hp	80 s	
3 hp	70 s	

cost	tille	
0 hp	120 s	
1 hp	70 s	
2 hp	50 s	

time

health

h	0	30	110	
	1	30		
	2	80		
	3	80		
	4	80		
	5	100		

strategy 1: 120 s

strategy 2: 110 s

strategy 3: 150 s

Compute f(L, h): the fastest you can beat level L with at least h health.

Large problem: f(100, 1)

Recursive sub-problems:

$$f(L,h) = \min_{s=1,\dots,10} f(L-1,h+h_{L,s}) + t_{L,s}$$

Compute f(L, h): the fastest you can beat level L with at least h health.

Large problem: f(100, 1)

Recursive sub-problems:

$$f(L,h) = \min_{s=1,\dots,10} f(L-1,h+h_{L,s}) + t_{L,s}$$

"first get to level L-1 with at least  $h+h_{L,s}$  health. Then use level L strategy s."

Compute f(L, h): the fastest you can beat level L with at least h health.

#### Implementation notes:

- probably easiest to make the table for f size (# levels + 1) \* (maxhealth + 1)
  - allows for an easy "level 0" base case

Compute f(L, h): the fastest you can beat level L with at least h health.

#### Implementation notes:

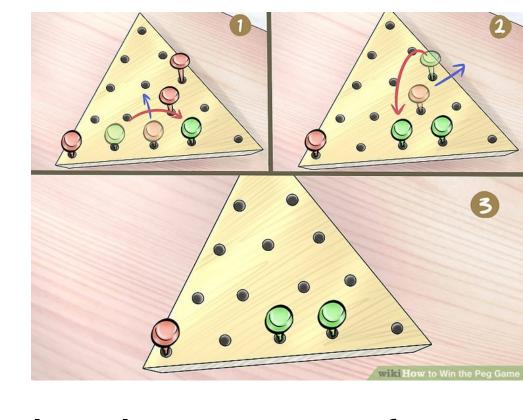
- probably easiest to make the table for f size (# levels + 1) \* (maxhealth + 1)
  - allows for an easy "level 0" base case
- need to deal with "impossible" entries in the table (including the final answer)

```
int Hades():
int f[11][101] = \{0,...\};
for(int L=1; L<=10; L++)
  for(int h=0; h<=100; h++)
    int best = infinity;
    for(int s=0; s<10; s++)
      int hneeded = h+hpcost[L][s];
      if(hneeded <= 100)</pre>
        stime = f[L-1][hneeded] + t[L][s];
        best = min(best, stime);
    f[L][h] = best;
return f[10][1];
```

### The Peg Game

Given starting board state, what is the fewest number of

pegs possible after a legal sequence of jump?



Has obvious recursive subproblems. Can dynamic programming be used? How?

Requires two things to be true:

- Large problem can be recursively broken up into smaller sub-problems (has optimal substructure)
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Ok, because many different move sequences can end at the same peg state

Aren't there still exponential many subproblems we need to examine?

(Board with n holes a p pegs has n choose p possible configurations)

Aren't there still exponential many subproblems we need to examine?

(Board with n holes a p pegs has n choose p possible configurations)

Only a few such configurations are reachable from the starting state

Memoization much easier than DP