

Shortest-Path Algorithms II

Shortest Path with Negative Costs

Given a weighted directed graph (weights can be negative), a start node **s**, and end node **e**, find the cost of the shortest path from **s** to **e** (or report that it does not exist)

Using Dijkstra's Algorithm

Does Dijkstra's Algorithm work for this problem?

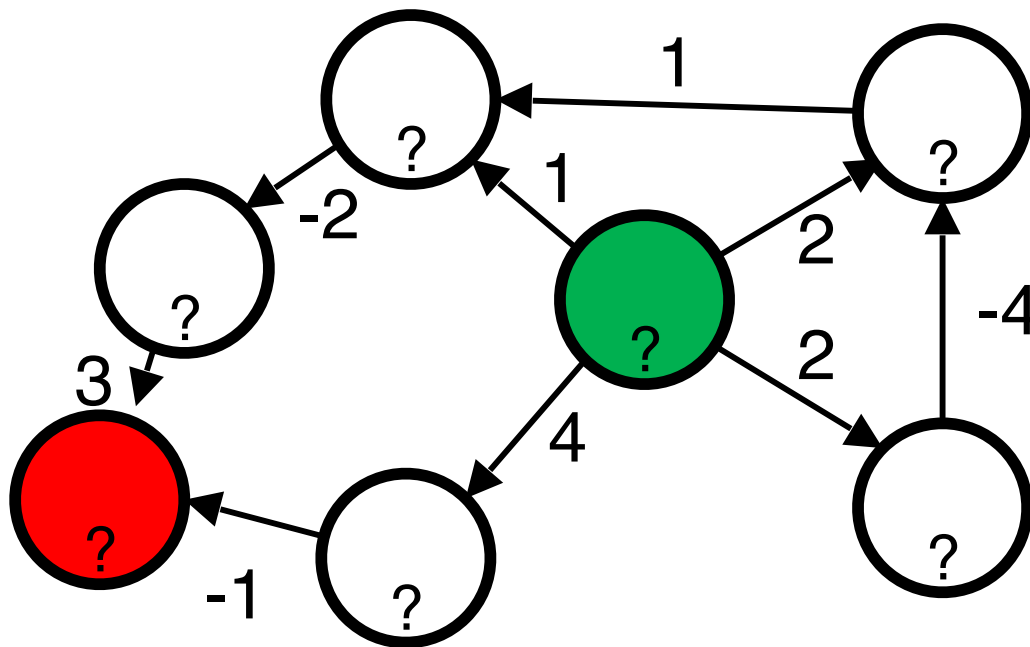
Using Dijkstra's Algorithm

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Breaks invariants

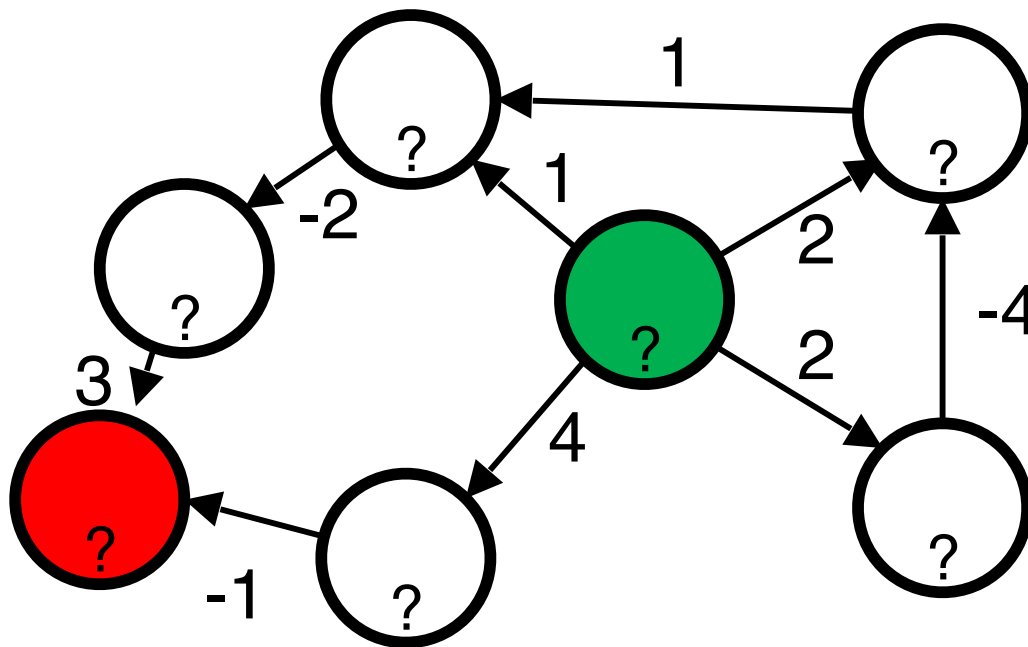
- start state
- goal states

Negative Costs



- start state
- goal states

Negative Costs



Is there anything we **know**?

Adjustment: Adding Constant

Proposed Idea: What if we add a fixed constant to each edge such that all negative edges become positive?

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Doesn't work because this penalizes paths with more edges

Edge Relaxation

for each edge **e**:

if(**e.dest.cost** > **e.src.cost** + **e.cost**)

e.dest.cost = **e.src.cost** + **e.cost**;

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Questions:

1. Will this process terminate?
2. How many iterations are needed?

Key Observations

If the shortest path to a node involves L edges, it will be found in L iterations.

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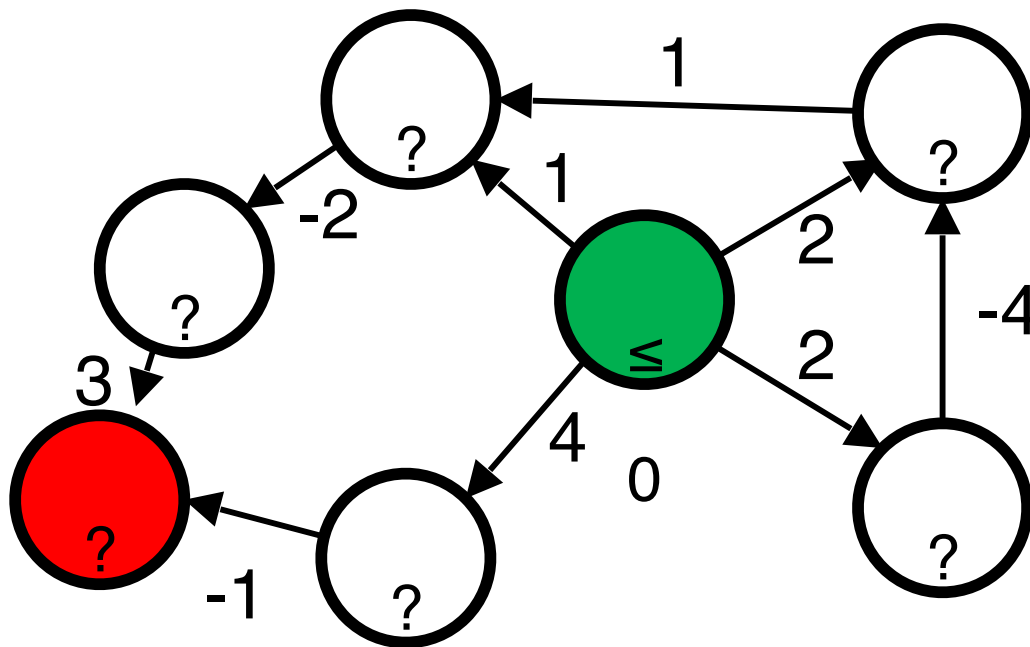
If the shortest path to a node involves L edges, it will be found in L iterations.

The shortest path to any node is either:

- 1) $\leq |V|$
- 2) infinite

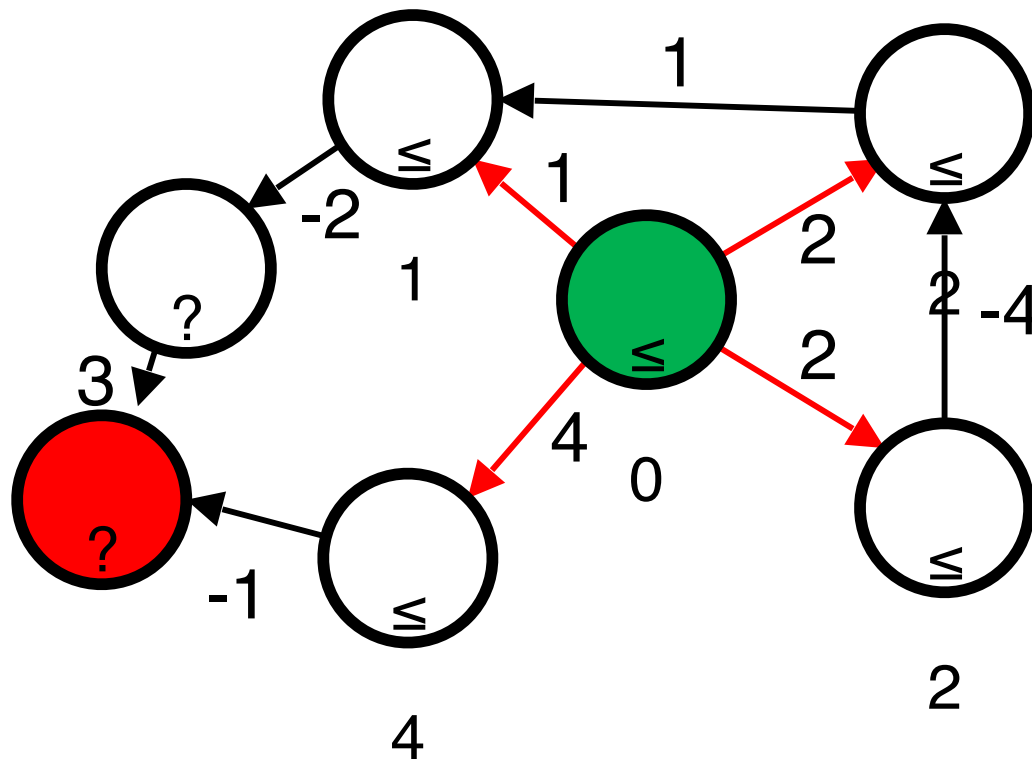
- start state
- goal states

Bellman-Ford



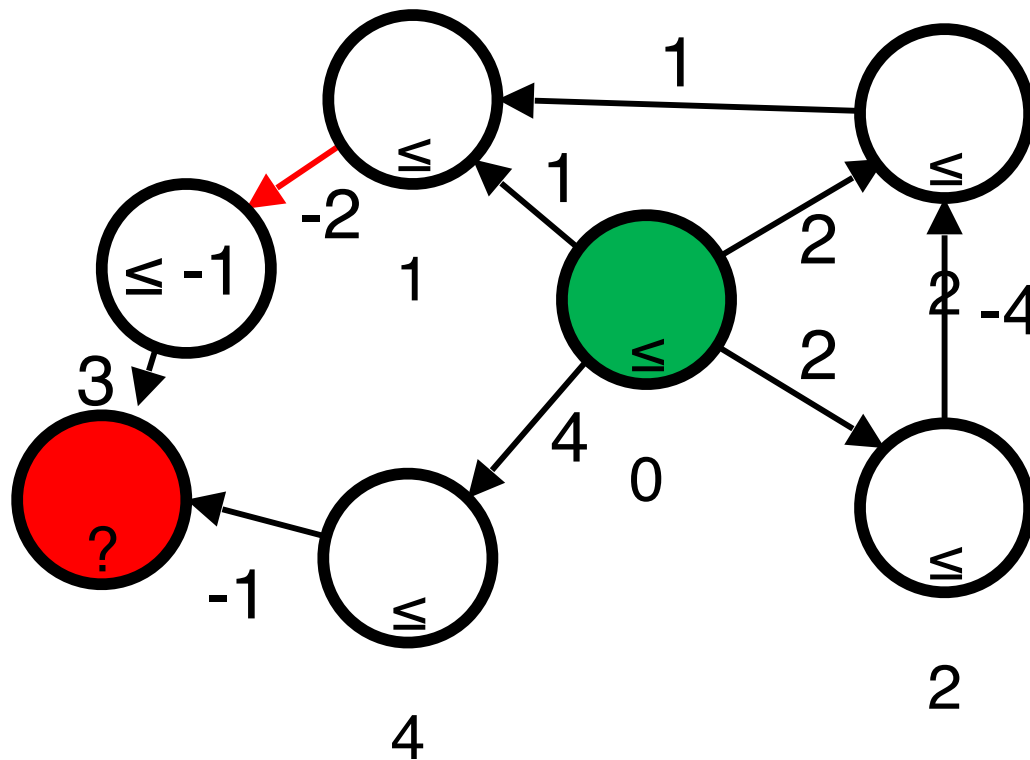
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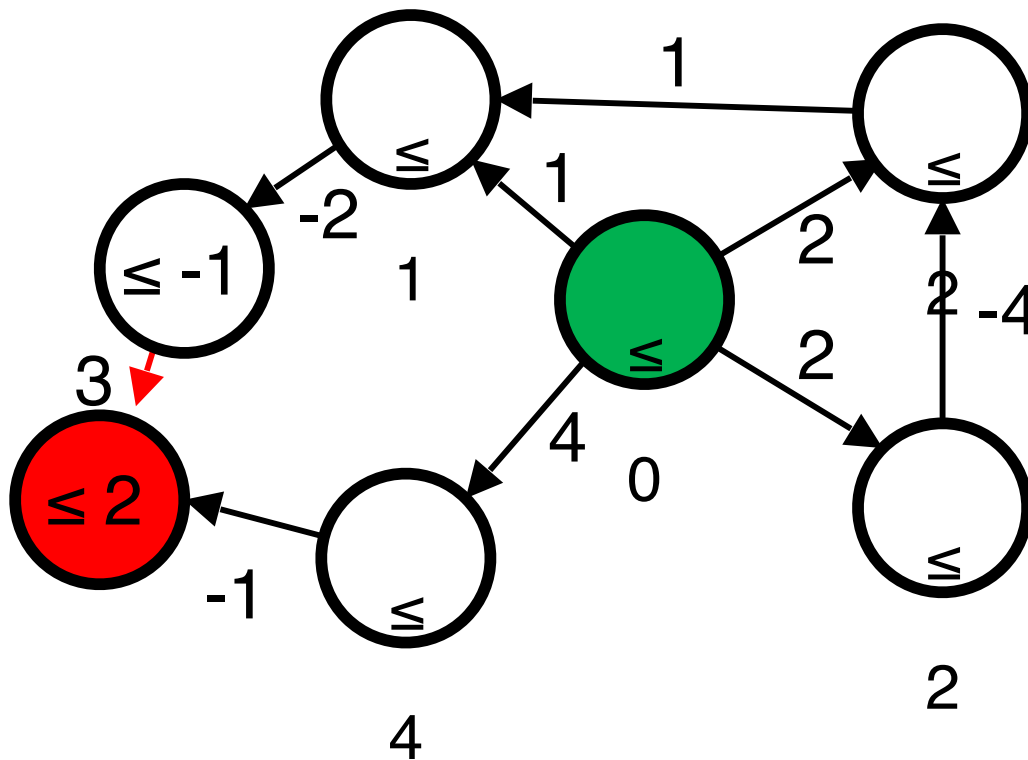
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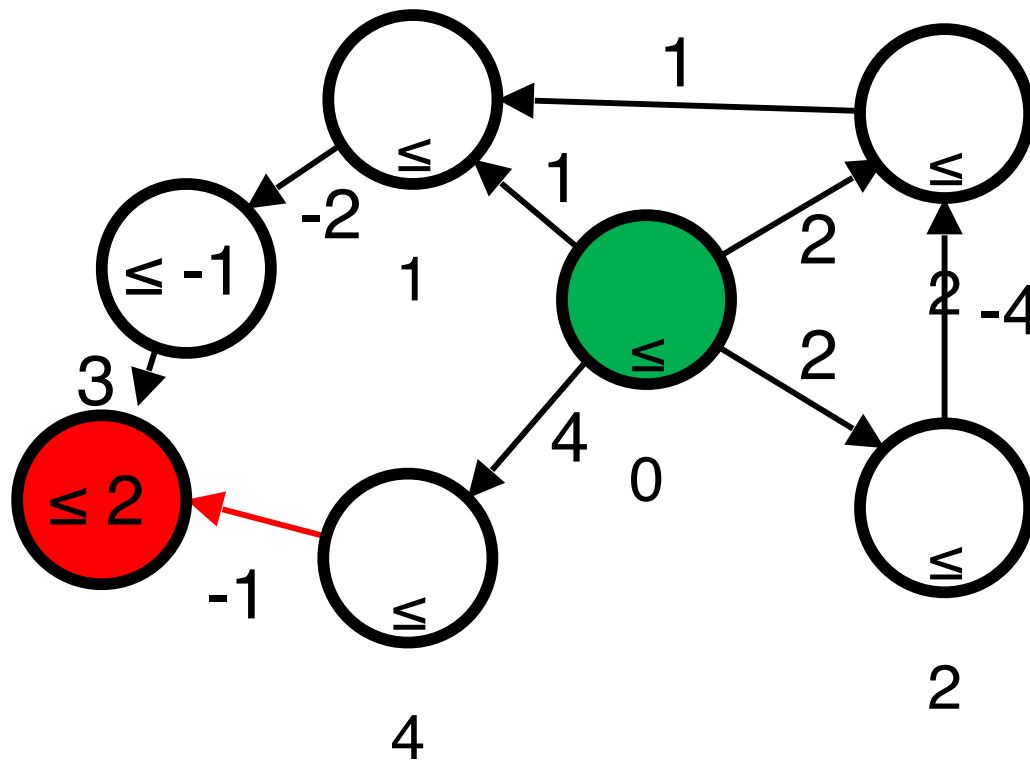
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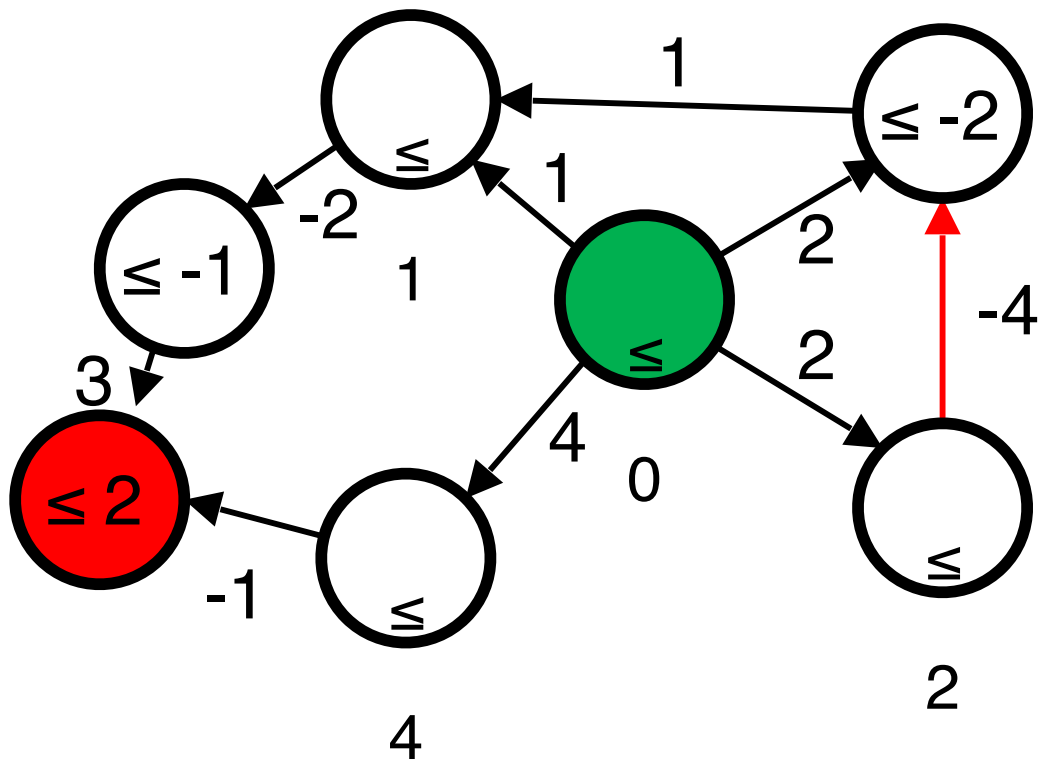
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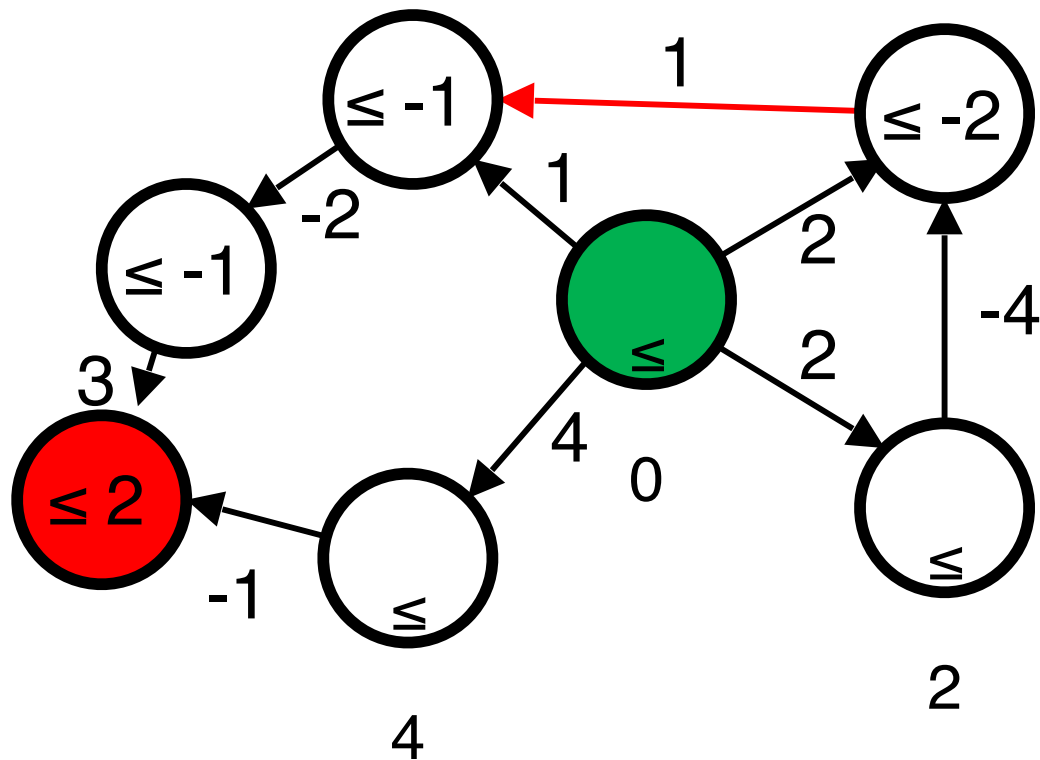
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Bellman-Ford



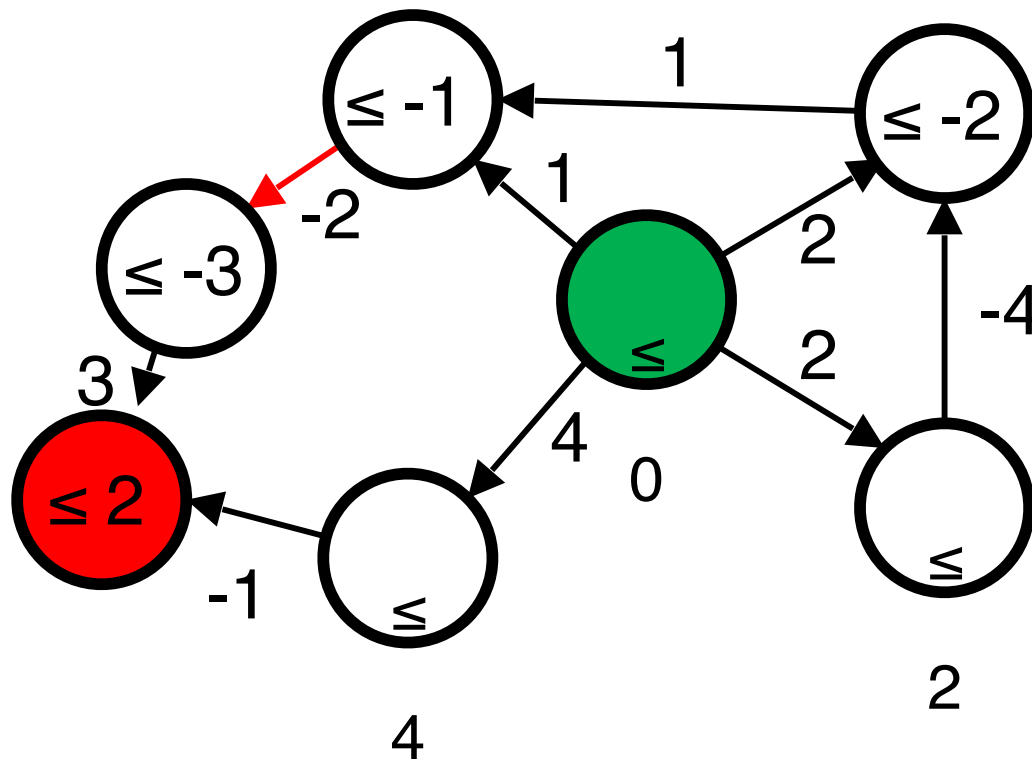
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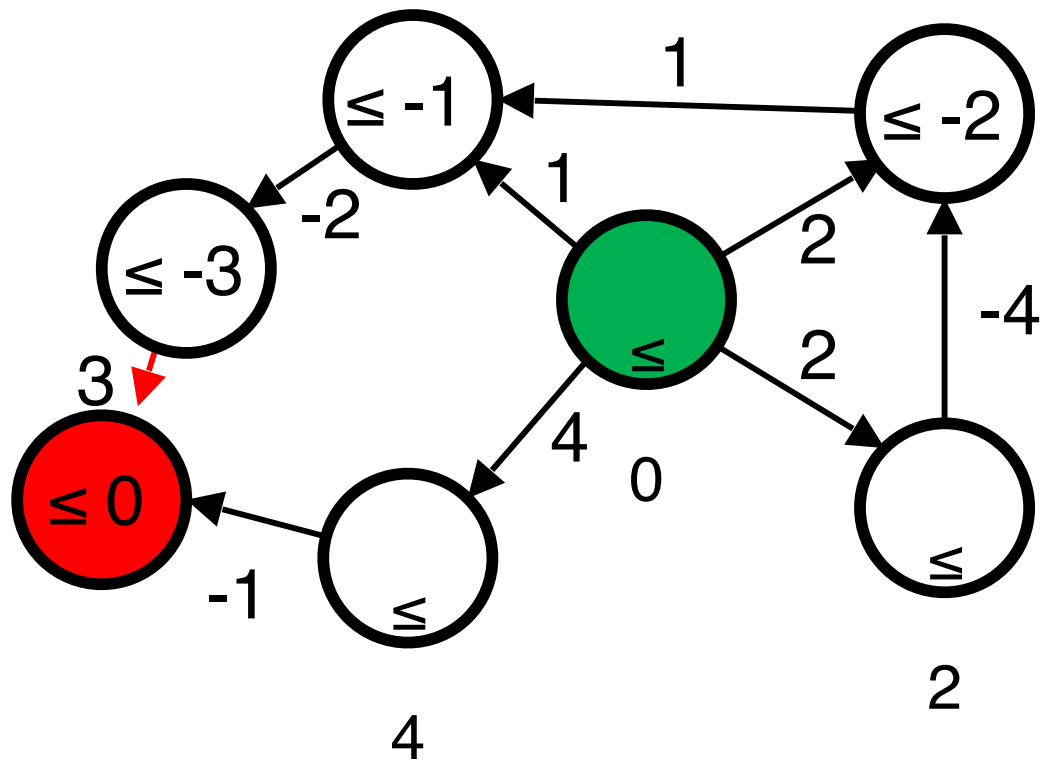
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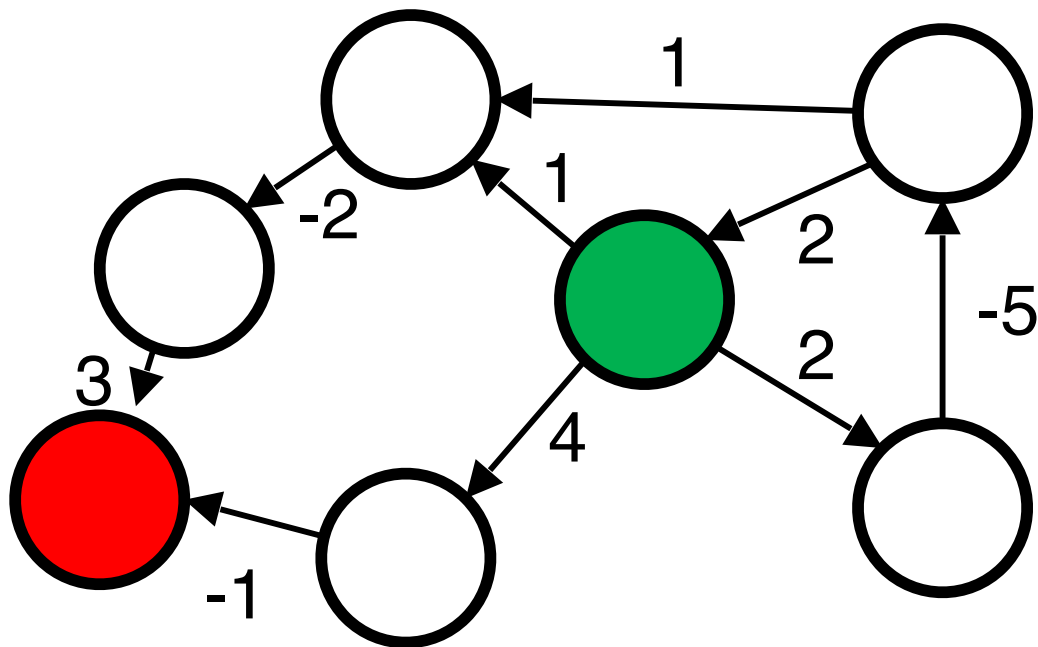
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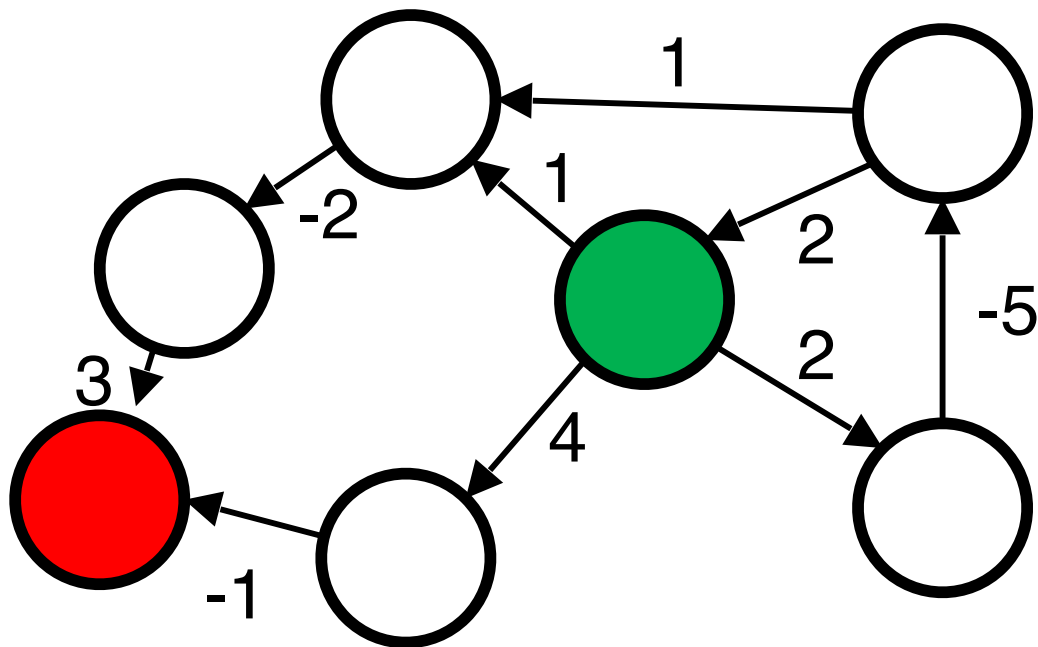
- start state
- goal states

Termination?



- start state
- goal states

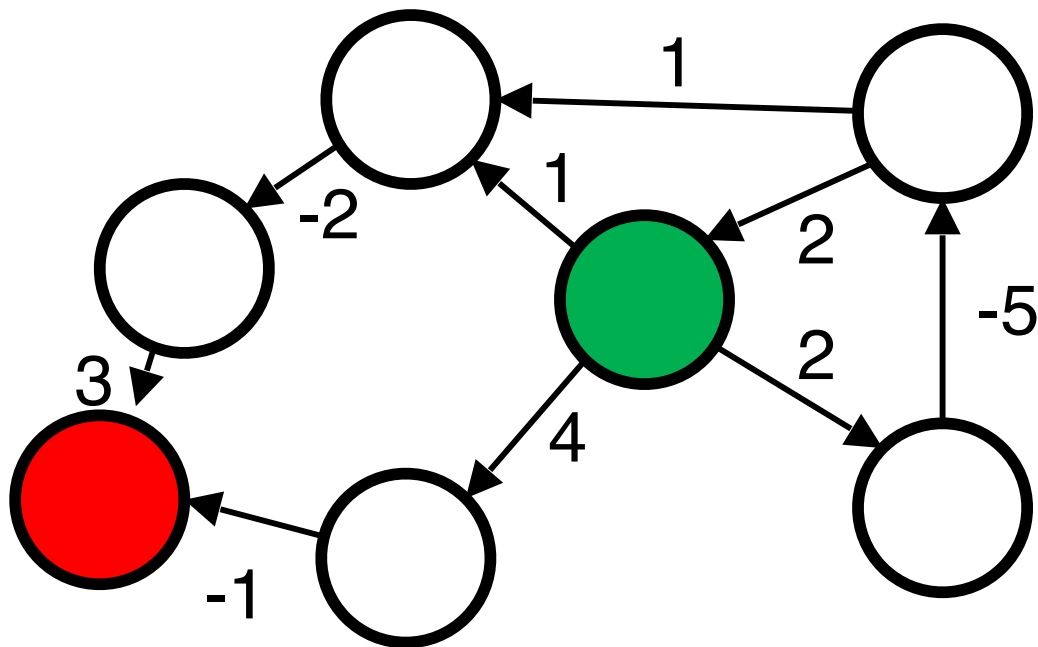
Termination?



changes on the $V+1^{\text{st}}$ iteration \Rightarrow negative cycle

- start state
- goal states

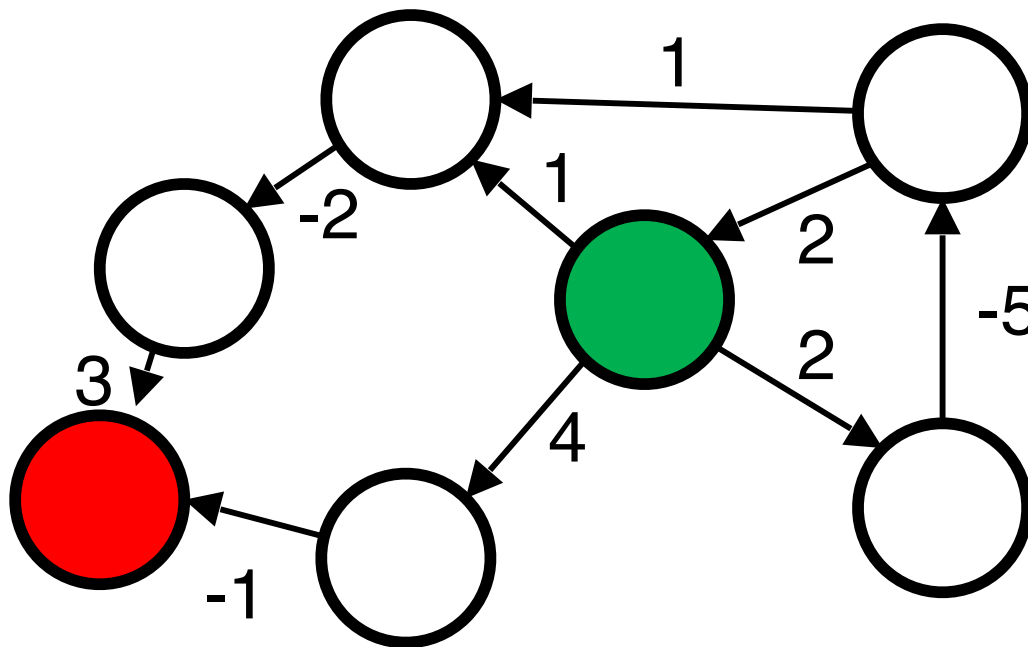
Bellman-Ford



What's the run time?

- start state
- goal states

Bellman-Ford



Changes past
iter $|V| \Rightarrow$ cycle

What's the run time? $O(|V||E|)$

Bellman-Ford Pseudocode

```
for i from 1 to  $|V| - 1$ :  
    for edge  $(u, v)$  with weight  $w$ :  
        if(  $\text{dist}(v) > \text{dist}(u) + w$ )  
             $\text{dist}(v) = \text{dist}(u) + w$ ;
```

Time complexity $O(|V||E|)$

All-Pairs Shortest Path

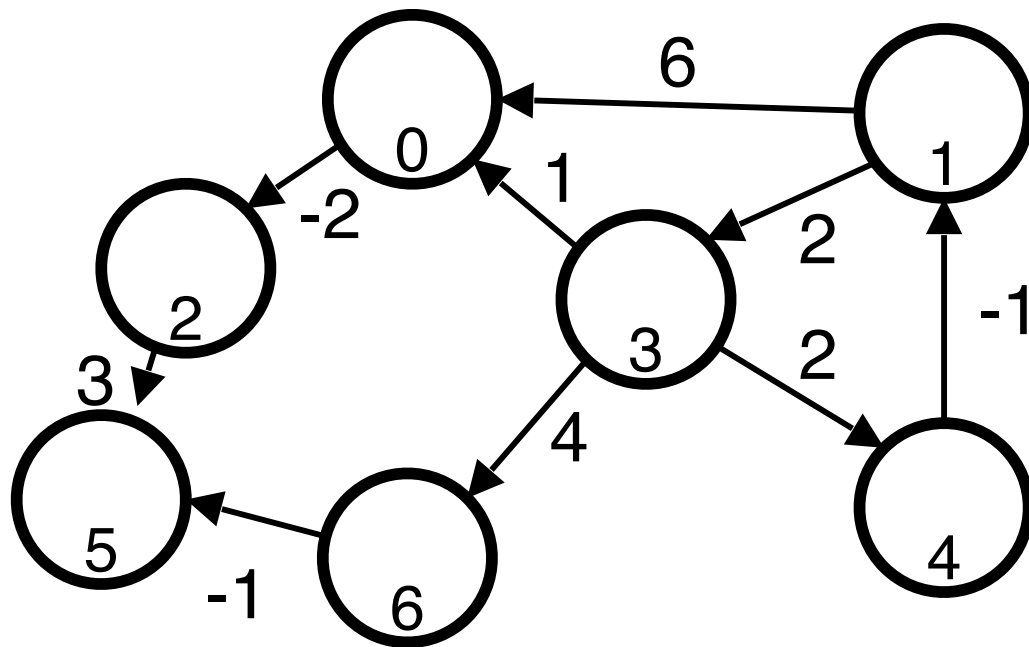
Given a weighted, directed graph (negative weights possible). For each pairs of vertices (**v**, **w**), return length of shortest path from **v** to **w**.

All-Pairs Shortest Path

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Run Bellman-Ford for each **v**: $O(|V|^2|E|)$

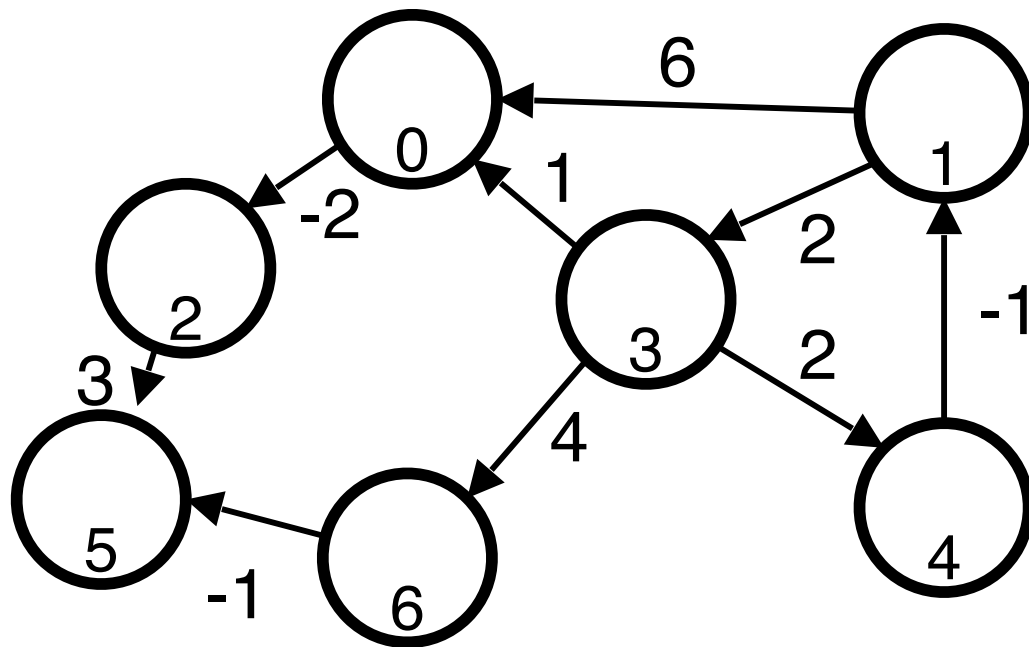
All-Pairs Shortest Path



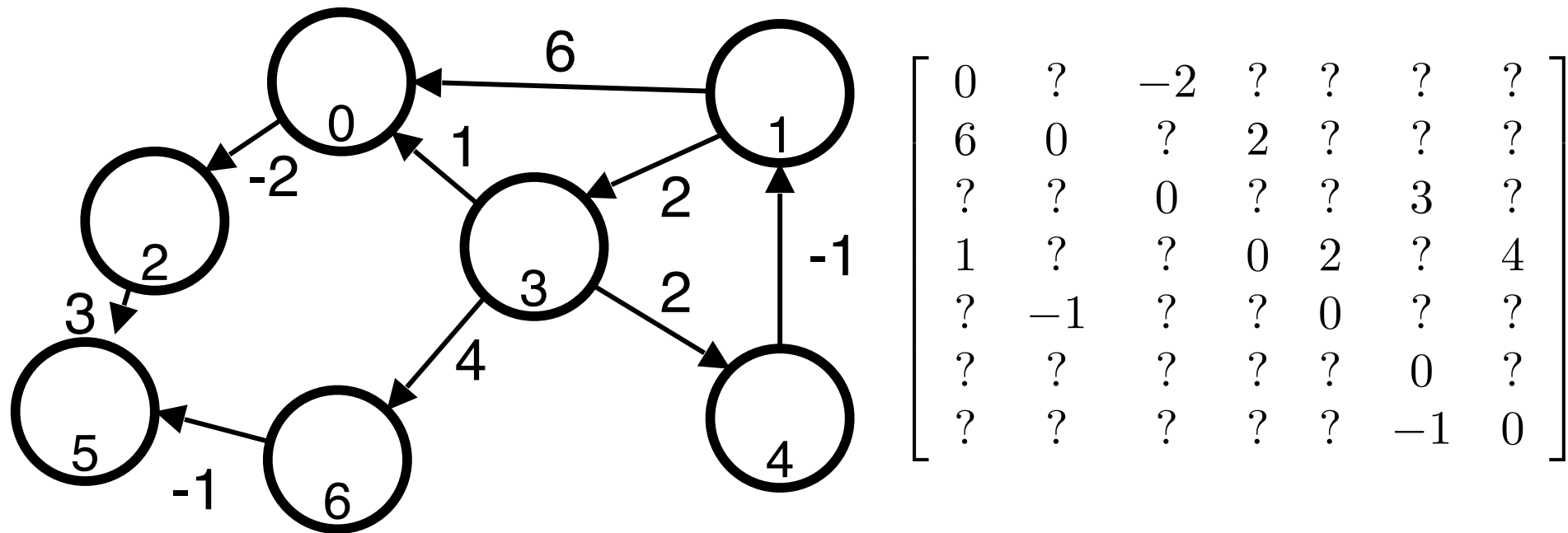
0	?	?	?	?	?	?
?	0	?	?	?	?	?
?	?	0	?	?	?	?
?	?	?	0	?	?	?
?	?	?	?	0	?	?
?	?	?	?	?	0	?
?	?	?	?	?	?	0

Vertex costs no longer useful; create **distance matrix**

All-Pairs Shortest Path

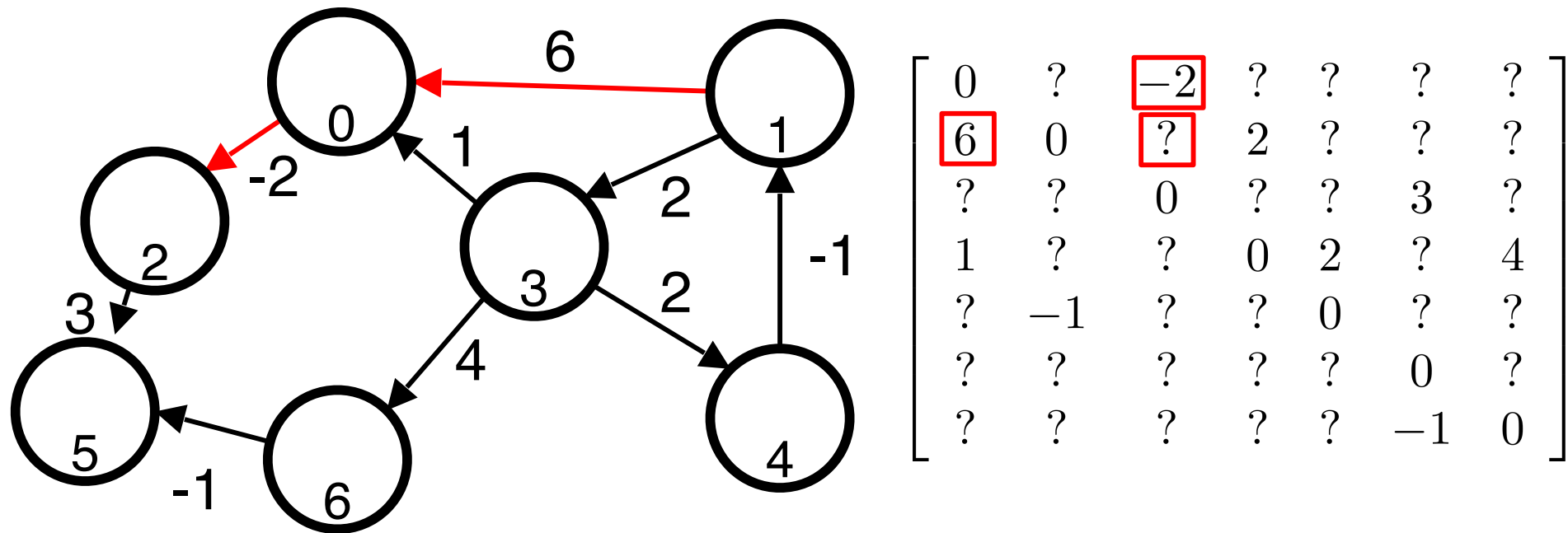

$$\begin{bmatrix} 0 & ? & -2 & ? & ? & ? & ? \\ 6 & 0 & ? & 2 & ? & ? & ? \\ ? & ? & 0 & ? & ? & 3 & ? \\ 1 & ? & ? & 0 & 2 & ? & 4 \\ ? & -1 & ? & ? & 0 & ? & ? \\ ? & ? & ? & ? & ? & 0 & ? \\ ? & ? & ? & ? & ? & -1 & 0 \end{bmatrix}$$

All-Pairs Shortest Path



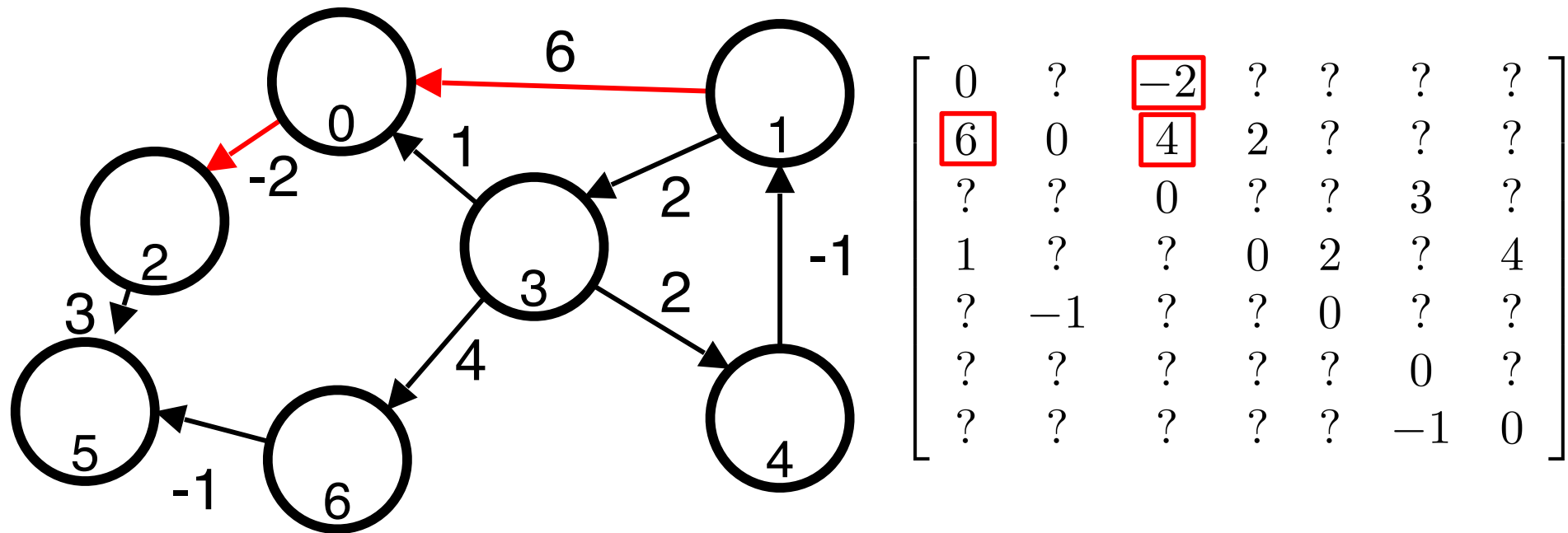
Which paths can improve by passing through node 0?

All-Pairs Shortest Path



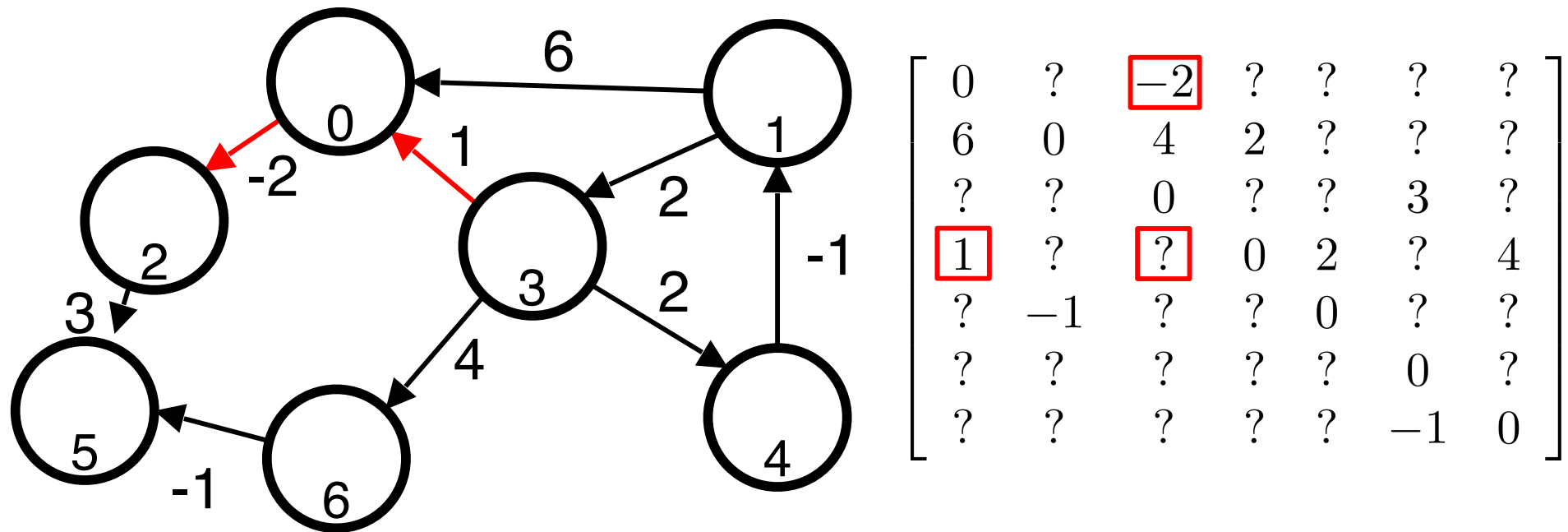
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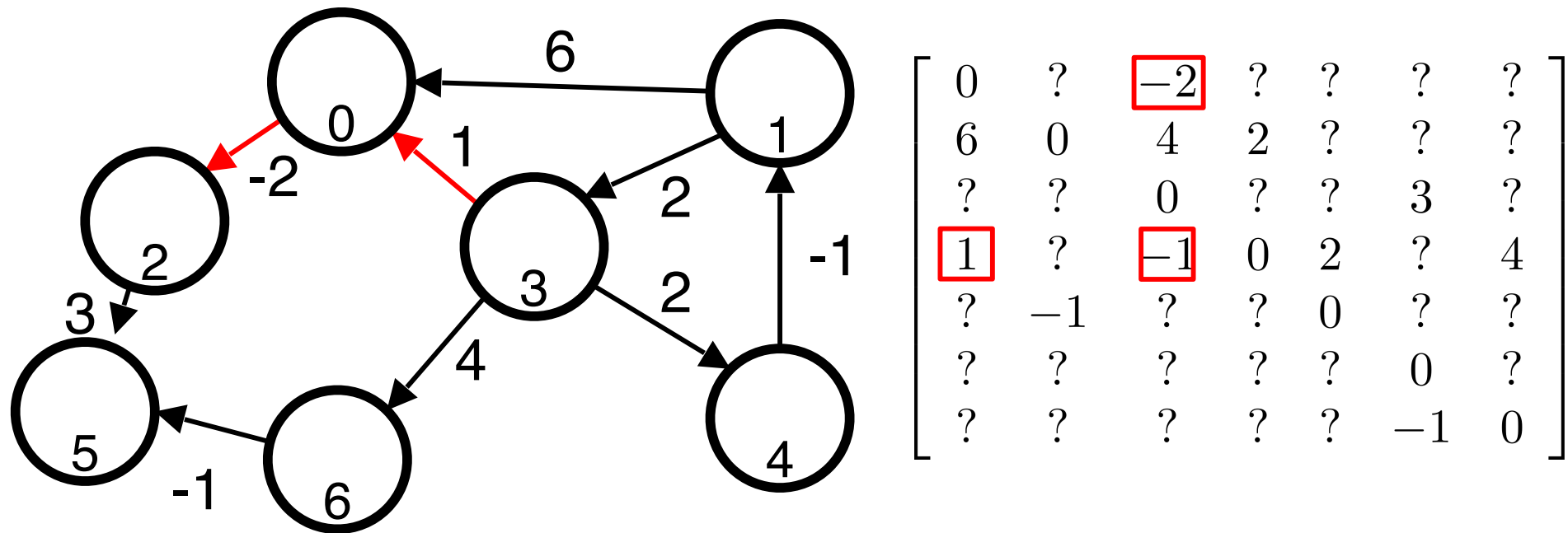
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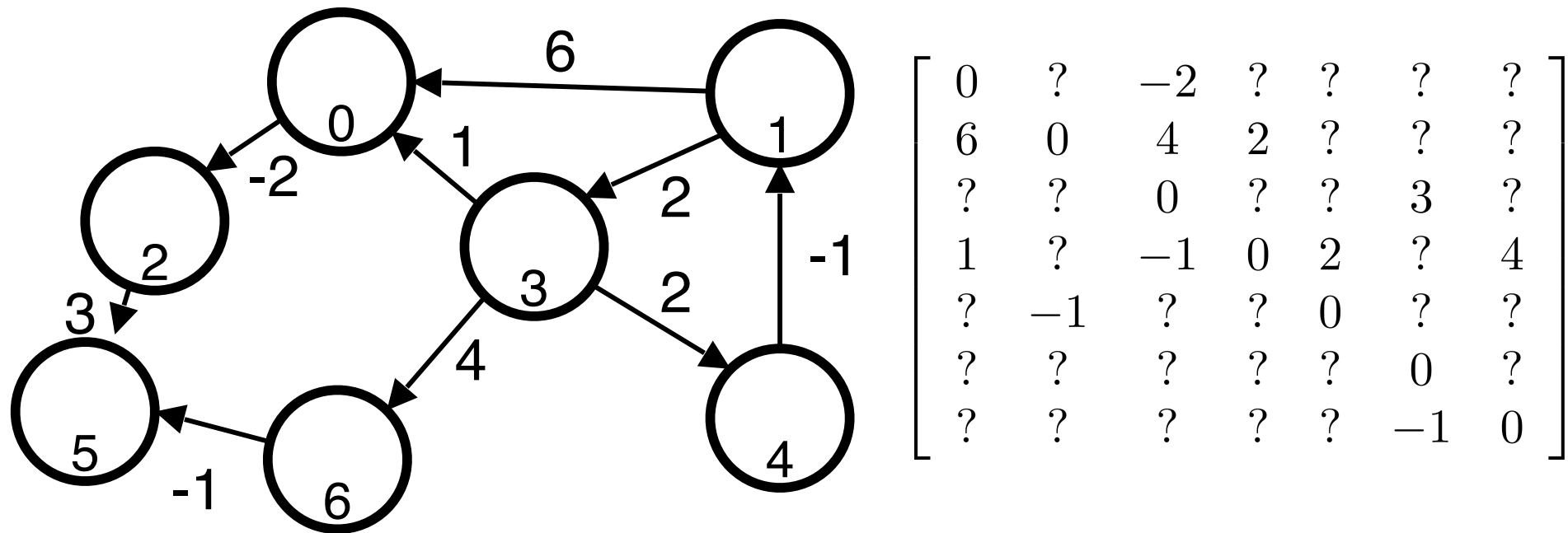
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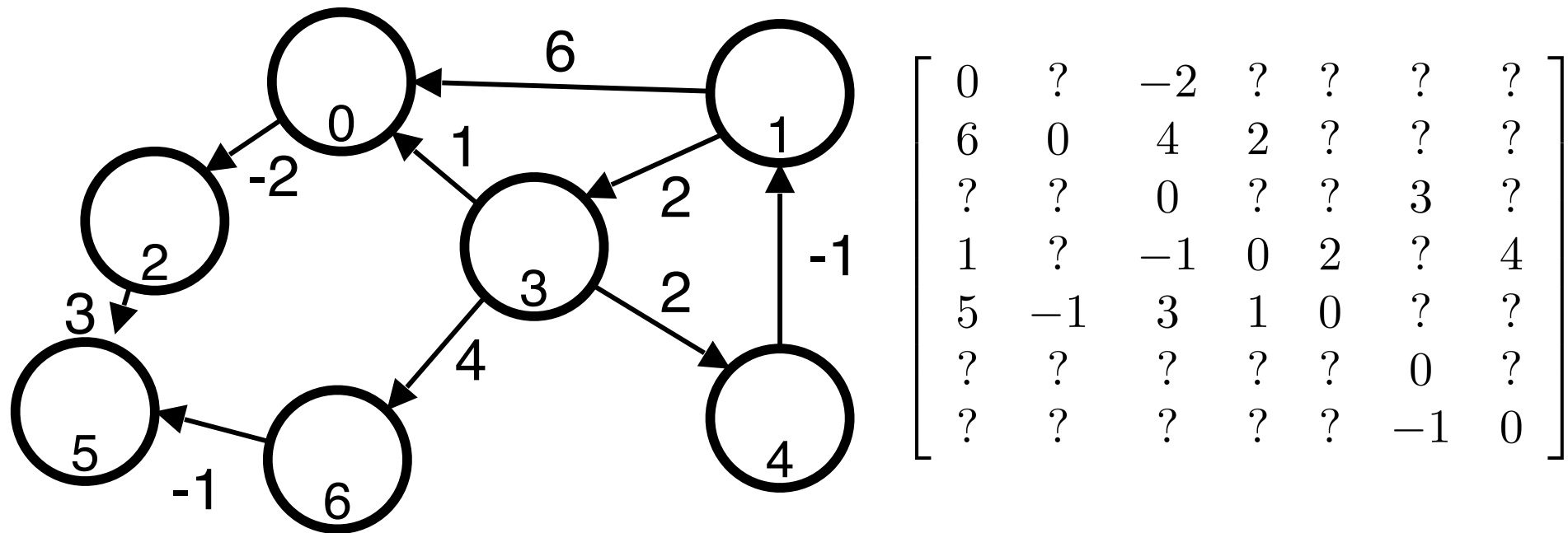
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All-Pairs Shortest Path



Which paths can improve by passing through node 1?

All-Pairs Shortest Path



Which paths can improve by passing through node 1?

Floyd-Warshall

for each vertex **k**:

for each vertex **v**:

for each vertex **w**:

if($\text{dist}(\mathbf{v}, \mathbf{w}) > \text{dist}(\mathbf{v}, \mathbf{k}) + \text{dist}(\mathbf{k}, \mathbf{w})$)

$\text{dist}(\mathbf{v}, \mathbf{w}) = \text{dist}(\mathbf{v}, \mathbf{k}) + \text{dist}(\mathbf{k}, \mathbf{w});$

Floyd-Warshall

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Claim: if no negative cycles, will find all shortest paths

Floyd-Warshall

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$\text{dist}(\mathbf{v}, \mathbf{w}) = \text{dist}(\mathbf{v}, \mathbf{k}) + \text{dist}(\mathbf{k}, \mathbf{w});$

How can we tell if there are negative cycles?

Floyd-Warshall

for each vertex **k**:

for each vertex **v**:

for each vertex **w**:

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$\text{dist}(\mathbf{v}, \mathbf{w}) = \text{dist}(\mathbf{v}, \mathbf{k}) + \text{dist}(\mathbf{k}, \mathbf{w});$

How can we tell if there are negative cycles?

Check for $\text{dist}(\mathbf{v}, \mathbf{v}) < 0$

Floyd-Warshall

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for each vertex **v**:

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Danger: watch for overflow is using **MAXINT** to denote missing edges

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Time complexity $O(|V|^3)$