



S1: Search

Rotate Waist



S2: Approach

*Left arm
approach handle*



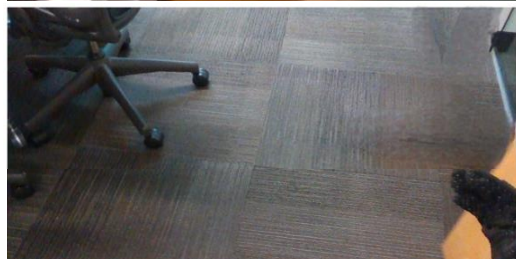
S3: Rotate

*Left arm
rotate handle*



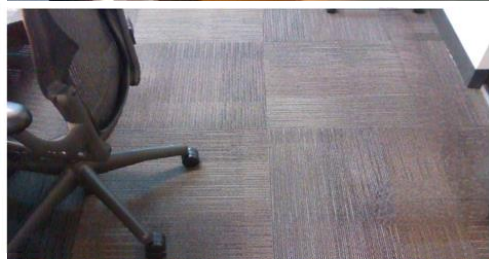
S4: Push

*Walk forward,
Right arm push*



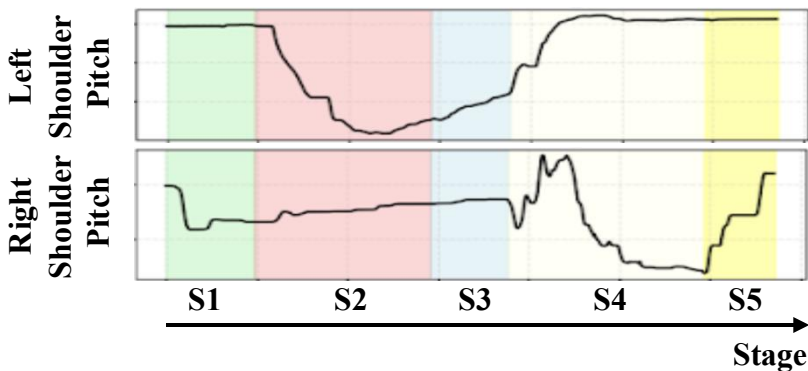
S5: Stop

*Right arm lower,
Walk stop*



End

Joint Position



Joint Torque

