The Terwilliger Algebra of a Directed Hamming Graph The 40th Algebraic Combinatorics Symposium

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June 19, 2024

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Association Schemes

Definition 1

Let X be a nonempty finite set, and $X \times X = X_0 \cup X_1 \cup \cdots \cup X_d$ be a partition of $X \times X$. Let A_i be matrices rows and columns indexed by X such that $A_i[x,y]=1$ if $(x,y)\in X_i$ and 0 otherwise. If A_0,A_1,\ldots,A_d satisfy the following conditions, then X with its partition becomes an association schemes.

- **1** $A_0 = I$, the identity matrix.
- **2** $A_i^{\top} = A_{i'}$ for some $i' \in \{0, 1, ..., d\}$.
- **9** For each $i, j \in \{0, 1, \dots, d\}$, there exist constants $p_{i,j}^0, \dots, p_{i,j}^d$ such that $A_i A_j = \sum_{k=0}^d p_{i,j}^k A_k$.

The algebra $\mathcal{B}=\langle A_0,A_1,\ldots,A_d\rangle\subseteq \operatorname{Mat}_X(\mathbb{C})$ is called the *Bose-Mesner algebra* of the association schme. If \mathcal{B} is commutative, it is called a *commutative* association scheme.

Examples of Association Schemes

$\mathcal{H}(H\backslash G/H)$

Let H be a subgroup of a finite group G. Let X = G/H be the set of left cosets. The orbits of G on $X \times X$ define an association scheme with respect to the following action.

$$g: X \times X \to X \times X: (g_1H, g_2H) \mapsto (gg_1H, gg_2H) \quad \text{for } g, g_1, g_2 \in G.$$

$\mathcal{H}(G_{\mathsf{x}}\backslash G/G_{\mathsf{x}})$

Let G be a transitive permutation group on a finite set X. Then, the orbits of G on $X \times X$ (called orbitals) define an association scheme.

Commutativity

The association scheme defined above is commutative if the permutation character of the permutation representation is multiplicity-free.

Primitive Idempotents

Let $\mathcal{B}=\langle A_0,A_1,\ldots,A_d\rangle\subseteq \operatorname{Mat}_X(\mathbb{C})$ be the Bose-Mesner algebra of a <u>commutative association scheme</u> with n=|X|. Then there are primitive idempotents E_0,E_1,\ldots,E_d satisfying the following.

- (i) $E_0 = \frac{1}{n}J$, where J is the all one's matrix of size n, and $E_iE_j = \delta_{i,j}E_i$ for all $i,j \in \{0,1,\ldots,d\}$.
- (ii) $E_j^{\top} = E_{\hat{j}}$ for some $\hat{j} \in \{0, 1, \dots, d\}$.
- (iii) For $i,j \in \{0,1,\ldots,d\}$, there exists $q_{i,j}^k \in \mathbb{R}$ such that $E_i \circ E_j = \frac{1}{n} \sum_{k=0}^n q_{i,j}^k E_k$, where \circ is the entry-wise product, called the Hadamard product.
- (iv) For $i, j \in \{0, 1, ..., d\}$, there exists $p_i(j), q_j(i) \in \mathbb{R}$ such that

$$A_i = \sum_{i=0}^d p_i(j)E_j, \quad E_j = \frac{1}{n}\sum_{i=0}^d q_j(i)A_i.$$

Definition 2 (DRGs and WDRDGs)

• Let $\Gamma = (X, \tilde{E})$, where \tilde{E} is a set of pairs of X. Γ is a distance-regular graph if Γ is connected of diamter d, and the following partition defines an association scheme. Here, $\partial(x, y)$ is the path distance.

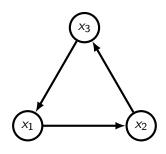
$$X \times X = \bigcup_{i=0}^d \Delta_i, \ \Delta_i = \{(x,y) \mid \partial(x,y) = i\}.$$

• Let $\Gamma = (X, E)$, where E is a set of ordered pairs of X. Γ is a weakly distance-regular digraph if Γ is strongly connected, and the following partition defines a nonsymmetric association scheme.

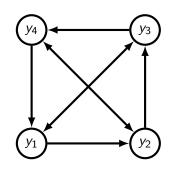
$$X \times X = \bigcup_{(i,j) \in \Delta} \Delta_{i,j}, \ \Delta_{i,j} = \{(x,y) \mid \widetilde{\partial}(x,y) = (i,j)\},$$

where $\widetilde{\partial}(x,y)$ denotes the two-way distance of x and y, and $\Delta(\Gamma) = \{\widetilde{\partial}(x,y) \mid x,y \in X\}.$

WDRDGs over K_3 and K_4



$$\Delta = \{(0,0), (1,2), (2,1)\}$$



$$\Delta = \{(0,0), (1,1), (1,2), (2,1)\}$$

WDRDGs over a Clique (Semicomplete WDRDGs)

Proposition 1 (Y. Yang, Q. Zeng and K. Wang [4, Proposition 3.5])

Let $\Gamma = (X, E)$ be a weakly distance-regular digraph (wdrdg) of diameter d and girth g whose underlying graph is a complete graph. Then d = 2, $g \leq 3$ and

$$\Delta(\Gamma) = \{(0,0),(1,2),(2,1)\}, \text{ or } \Delta(\Gamma) = \{(0,0),(1,1),(1,2),(2,1)\}.$$

Proof.

Suppose $x, y \in X$ with $\tilde{\partial}(x, y) = (1, p)$ and $p \ge 3$. Note that $X = \{x\} \cup \Gamma_{1,*}(x) \cup \Gamma_{*,1}(x)$. If $z \in \Gamma_{1,*}(y) \setminus (\{x\} \cup \Gamma_{1,*}(x))$, then

$$3 \le p = \partial(y, x) \le \partial(y, z) + \partial(z, x) = 2$$
,

which is absurd. Hence, $\{y\} \cup \Gamma_{1,*}(y) \subseteq \Gamma_{1,*}(x)$. A contradiction.



Two Types of Semicomplete WDRDGs

Type I: d = 2, g = 3, and $\Delta(\Gamma) = \{(0,0), (1,2), (2,1)\}$

- The existence is equivalent to that of a nonsymmetric association scheme with two classes with 4m-1 vertices.
- It exists if and only if a skew Hadamard matrix of size 4m exists.

Type II: d=2, g=2, and $\Delta(\Gamma)=\{(0,0),(1,1),(1,2),(2,1)\}$

Let $\mathcal{B} = \langle I, A, A^{\top}, B = B^{\top} \rangle$ be the Bose-Mesner Algebra of a nonsymmetric association scheme of class three.

- If the digraph defined by A is connected, it is semicomplete of type II.
- If the digraph defined by A is not connected, each connected component is a semicomplete wdrdg of type I.

Every association scheme of class at most four is commutative.

Weakly Distance-Regular Digraphs of Hamming Type

Theorem 2 (Y. Yang, Q. Zeng and K. Wang [4])

Let Γ be a <u>commutative</u> weakly distance-regular digraph. Then Γ has a Hamming graph as its underlying graph if and only if Γ is isomorphic to one of the following diagrams:

- (i) $Cay(\mathbb{Z}_4, \{1\}) [H(2,2)];$
- (ii) $Cay(\mathbb{Z}_4 \times \mathbb{Z}_2, \{(1,0),(0,1)\}) [H(3,2)];$
- (iii) Δ^1 or $\Delta^1 \Box \Delta^2 [H(1,q) \text{ or } H(2,q)];$
- (iv) $\Gamma^1 \square \Gamma^2 \square \cdots \square \Gamma^d [H(d,q) \text{ with } q \equiv 3 \pmod{4}].$

Here, Δ^i (resp Γ^i) is a semicomplete weakly distance-regular digraph of girth 2 (resp 3) with the same intersection numbers for each i.

The cases when the underlying graph is a folded cube and a Doob graph are determined. $Cay(\mathbb{Z}_4 \times \mathbb{Z}_4, \{(1,0),(0,1),(-1,-1)\})$ is the only nontrivial case comming from the Shrikhande graph.

Definition 3 (H(d,q))

Let $N = \{a_1, a_2, \dots, a_n\}$. The Hamming graph H(d, n) or more specifically, the Hamming graph of diameter d on the set N, H(d, N) is defined by X, the set of vertices, and \tilde{E} , the set of edges.

$$X = \{(x_1, \dots, x_d) \mid \text{ for all } i, x_i \in N\},$$

 $\tilde{E} = \{xy \mid \text{ exactly } 1 \text{ coordinate } i, x_i \neq y_i\} \subseteq X \times X.$

Definition 4 $(H^*(d,3))$

The directed graph $H^*(d,3)$ is defined by X, the set of vertices, and E, the set of arcs.

$$X = \{(x_1, \dots, x_d) \mid \text{ for all } i, x_i \in \mathbb{F}_3\},$$

 $E = \{xy \mid \text{ exactly } 1 \text{ coordinate } i, x_i + 1 = y_i\} \subseteq X \times X.$

(We assign the trivial direction on each coordinate, $0 \to 1 \to 2 \to 0$.)

Adjacecy Matrix

Definition 5

The adjacency matrix of $H^*(d,3)$, $A=A^{(d)}$ is defined by the following.

$$(A)_{ij} = \begin{cases} 1 & \text{if there exits an arc from } i \text{ to } j, \\ 0 & \text{otherwise.} \end{cases}$$

For x, y in X, $\partial(x,y)$ denotes the distance between x and y, i.e., the smallest number of arcs connecting from x to y. We also define the two-way distance $\tilde{\partial}(x,y)=(\partial(x,y),\partial(y,x))$, and Δ , the set of all two-way distances;

$$\Delta = { \tilde{\partial}(x, y) \mid x, y \in X }.$$

Vector Space V

Let $\Gamma = (X, E)$ be $H^*(d, 3)$. Fix a base vertex $x = (0, 0, \dots, 0) \in X$.

- $V = \mathbb{C}^{|X|}$: the vector space over the complex number field \mathbb{C} whose coordinates are indexed by the elements of X.
- $\bullet \ X_{i,j} = \{y \mid \partial(x,y) = i, \partial(y,x) = j\}.$
- If $y \in X$ has s ones, t twos, and r = d s t zeros, then $\partial(x,y) = s + 2t, \partial(y,x) = 2s + t.$
- If $\tilde{\partial}(x,y) = (i,j)$, then s = (2j-i)/3, and t = (2i-j)/3.
- We also write

 $X_{[s,t]} = \{y \mid \text{there are } s \text{ ones and } t \text{ twos}\} = X_{s+2t,2s+t}.$

$$E_{i,j}^*$$

For $(i,j) \in \Delta$, $E_{i,j}^* = E_{i,j}^{(d)*}$ denotes a diagonal matrix such that

$$E_{i,j}^*(z,z) = \begin{cases} 1, & \text{if } \partial(x,z) = (i,j), \\ 0 & \text{othersise,} \end{cases}$$

and the zero matrix of the same size if $(i,j) \notin \Delta$. Then,

$$E_{i,j}^*\mathbf{1} = \{\sum \hat{y} \mid y \in X, \partial(x,y) = i, \partial(y,x) = j\}.$$

We set

$$E_{i,j}^* = E_{[(2j-i)/3,(2i-j)/3]}^*$$
, and $E_{[s,t]}^* = E_{s+2j,2s+j}^*$.

If a vector $\mathbf{v} \in V$ satisfies $E_{[s,t]}^* \mathbf{v} = \mathbf{v}$, then we write

$$type(\mathbf{v}) = [r(\mathbf{v}), s(\mathbf{v}), t(\mathbf{v})]$$
: the type of \mathbf{v} .

Note that \mathbf{v} can be written as a linear combination of \hat{y} with $y \in X_{[s,t]}$.

The Terwilliger Algebra $\mathcal{T}(x)$

Definition 6

The Terwilliger algebra $\mathcal{T}(x)$ of $H^*(d,3)$ with respect to a base vertex x is a \mathbb{C} -algebra generated by A, A^{\top} and $E_{i,j}^*$ for $(i,j) \in \Delta$. We also write $\mathcal{T}(H^*(d,3))$ to specify the digraph.

Note

- $\Gamma = H^*(d,3)$ is a Cayley digraph defined on an abelian group \mathbb{Z}_3^d . Hence, it is commutative.
- ② It is easy to calculate eigenvalues of $A = A^{(d)}$.
- **3** $H^*(1,3)$ is a directed triangle, and the orientation of arcs of $H^*(d,3)$ is uniquely determined.
- $A^{(d)} = A^{(1)} \otimes I \otimes \cdots \otimes I + I \otimes A^{(1)} \otimes \cdots \otimes I + I \otimes I \otimes \cdots \otimes A^{(1)}.$

$$\mathcal{T}(H^*(1,3))$$

Lemma 7

Let \mathcal{T}_1 be the Terwilliger algebra of $H^*(1,3)$. Then

$$\mathcal{T}_1 = \left\langle \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right\rangle \simeq \mathrm{Mat}_3(\mathbb{C}).$$

Proof.

This is trivial. If $A^{(1)}$ is the adjacenct matrix of $H^*(1,3)$, then $A^{(1)^2} = A^{(1)^\top}$, and $E^{(1)}_{0,0}^*$, $E^{(1)}_{1,2}^*$ and $E^{(1)}_{2,1}^*$ are diagonal matrix units $e_{1,1}$, $e_{2,2}$ and $e_{3,3}$. Hence, every matrix unit is in \mathcal{T}_1 .

Note that if the principal module of dimension n is the only irreducible module of the algebra, it is isomorphic to $\operatorname{Mat}_n(\mathbb{C})$.

The Algebraic Structure of $\mathcal{T}(x)$

Theorem 3 (T.Miezaki, H.Suzuki, K.Uchida [5])

Let T(x) be the Terwilliger algebra of $H^*(d,3)$ with respect to a base vertex x. Then,

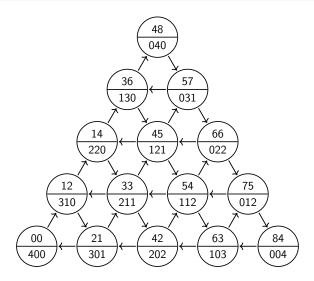
$$\mathcal{T}(x) \simeq \operatorname{Sym}^d(\operatorname{Mat}_3(\mathbb{C})).$$

Moreover,

$$\Lambda = \left\{ \frac{1}{2} (d - 3\ell - 2m + 1)(m + 1)(d - 3\ell - m + 2) \mid 0 \le \ell \le \left\lceil \frac{d}{3} \right\rceil, 0 \le m \le \left\lceil \frac{d - 3\ell}{2} \right\rceil \right\}.$$

Example: $H^*(4,3)$

Two-way distance: $\tilde{\partial}(x,y)=(i,j)$, and $\operatorname{type}(\mathbf{v})=[r(\mathbf{v}),s(\mathbf{v}),t(\mathbf{v})]$



Elements in $\mathcal{T}(x)$

Let
$$r = d - s - t$$
.

$$\begin{split} H_1 &= \sum_{s,t} (r-s) E_{[s,t]}^*, \ H_2 = \sum_{s,t} (s-t) E_{[s,t]}^*, \\ H_3 &= H_1 + H_2, \\ R_1 &= \sum_{s,t} E_{[s+1,t]}^* A E_{[s,t]}^*, \ R_2 = \sum_{s,t} E_{[s-1,t+1]}^* A E_{[s,t]}^*, \\ R_3 &= \sum_{s,t} E_{[s,t+1]}^* A^\top E_{[s,t]}^*, \\ L_1 &= \sum_{s,t} E_{[s-1,t]}^* A^\top E_{[s,t]}^*, \ L_2 = \sum_{s,t} E_{[s+1,t-1]}^* A^\top E_{[s,t]}^*, \\ L_3 &= \sum_{s,t} E_{[s,t-1]}^* A E_{[s,t]}^*. \end{split}$$

Note that $H_1, H_2, H_3, R_1, R_2, R_3, L_1, L_2, L_3$ are all in $\mathcal{T}(x)$.

Lemma 8

We have the following.

- (i) $A = R_1 + R_2 + L_3$ and $A^{\top} = L_1 + L_2 + R_3$.
- (ii) Let $\tilde{A} = A + A^{\top}$. Then \tilde{A} is the adjacency matrix of H(d,3).
- (iii) $\tilde{R} = R_1 + R_3$ is the raising operator, $\tilde{F} = R_2 + L_2$ the flat operator, and $\tilde{L} = L_1 + L_3$ the lowering operator of H(d,3).

For matrices M_1, M_2 , $[M_1, M_2] = M_1M_2 - M_2M_1$. Then $sl_n(\mathbb{C}) = \{M \in \operatorname{Mat}_n(\mathbb{C}), \operatorname{tr}(M) = 0\}$ becomes a simple Lie algebra.

Lemma 9

The following hold.

- (i) $[L_1, R_1] = H_1$, $[H_1, L_1] = 2L_1$, and $[H_1, R_1] = -2R_1$.
- (ii) $[L_2, R_2] = H_2$, $[H_2, L_2] = 2L_2$, and $[H_2, R_2] = -2R_2$.
- (iii) $[L_3, R_3] = H_3$, $[H_3, L_3] = 2L_3$, and $[H_3, R_3] = -2R_3$.

The Relation Between $\mathcal{T}(x)$ and $sl_3(\mathbb{C})$

Proposition 4

The following hold.

- (i) The Lie algebra generated by H_1 , H_2 , L_1 , L_2 , R_1 , R_2 is isomorphic to $sl_3(\mathbb{C})$ with a Cartan subalgebra generated by H_1 and H_2 , and a Borel subalgebra generated by H_1 , H_2 , L_1 , L_2 , L_3 .
- (ii) The Lie algebra generated by the triple H_1 , L_1 , R_1 (resp. the triple H_2 , L_2 , R_2 and H_3 , L_3 , R_3) is isomorphic to $sl_2(\mathbb{C})$ with a Cartan subalgebra generated by H_1 (resp. H_2 , H_3) and a Borel subalgebra generated by H_1 , L_1 (resp. H_2 , L_2 , and H_3 , L_3).

Associative algebra $\mathcal{T}(x)$ and the associated Lie algebra

$$\mathcal{T}(x) = \langle A, A^{\top}, E_{i,j}^* \mid (i,j) \in \Delta(\Gamma) \rangle = \langle L_1, L_2, R_1, R_2 \rangle \supseteq \langle L_1, L_2, R_1, R_2 \rangle_{Lie}.$$

$\mathcal{T}(x)$ -modules and $sl_3(\mathbb{C})$ -modules

Proposition 5

The following hold. $\mathbb{C}[A] = \mathbb{C}[A^{\top}] = \mathbb{C}[A, A^{\top}]$ is the Bose-Mesner algebra of $H^*(d,3)$.

Proposition 6

The following hold.

- (i) $\mathcal{T} = \mathcal{T}(x) = \langle A, E_{i,i}^* \mid (i,j) \in \Delta \rangle$.
- (ii) $\mathcal{T}(x) = \langle L_1, L_2, R_1, R_2 \rangle \supseteq \langle L_1, L_2, R_1, R_2 \rangle_{Lie}$.
- (iii) Let $\mathcal L$ be the Lie algebra generated by L_1, L_2, R_1, R_2 . Then $\mathcal L \simeq sl_3(\mathbb C)$, and $\mathcal L$ submodules of V are $\mathcal T$ submodules and vice versa. Moreover, an $\mathcal L$ -submodule W of V is irreducible if and only if a $\mathcal T$ -module W of V is irreducible.

Poincaré–Birkhoff–Witt Theorem and $\mathcal{U}(\mathcal{L})$

Proposition 7 ([1, Theorem on page 108])

Let $\mathcal{L}=\langle L_1,L_2,L_2,R_1,R_2,R_3\rangle_{Lie}$, and W an irreducible submodule of V. Then there is a highest weight vector $\mathbf{v}\in W$ satisfying $L_1\mathbf{v}=L_2\mathbf{v}=L_3\mathbf{v}=\mathbf{0}\neq\mathbf{v}$, determined up to nonzero scalar multiple, and W is spanned by the set of vectors

$$\{R_3^k R_1^j R_2^i \mathbf{v} \mid i, j, k \ge 0\}.$$

Higest weight vectors

$$H_1 = \sum_{s,t} (r-s) E_{[s,t]}^*, \quad H_2 = \sum_{s,t} (s-t) E_{[s,t]}^*.$$

Hightst weight vector and the weight of $oldsymbol{v}=E_{[s,t]}^*oldsymbol{v}$

Definition 10

Let $\mathbf{v} \in V$ be a nonzero vector of V satisfying $H_1\mathbf{v} = m_1\mathbf{v}$ and $H_2\mathbf{v} = m_2\mathbf{v}$. Then we call $\lambda = (m_1, m_2)$ the weight of \mathbf{v} .

Lemma 11

Let W be an irreducible \mathcal{L} submodule of V with the heighest weight vector $\mathbf{v} = E_{[s,t]}^* \mathbf{v}$ with weight $\lambda = (m_1, m_2)$. Set r = d - s - t, and $\mathbf{v}_{i_1,i_2,i_3} = R_3^{i_3} R_1^{i_1} R_2^{i_2} \mathbf{v}$. Then, the following hold.

- (i) The weight of \mathbf{v}_{i_1,i_2,i_3} is $(r-s-2i_1+i_2-i_3,s-t+i_1-2i_2-i_3)$. In particuar, $m_1=r-s$ and $m_2=s-t$.
- (ii) $\mathbf{v}_{i_1,i_2,i_3} = R_3^{i_3} R_1^{i_1} R_2^{i_2} \mathbf{v} \neq \mathbf{0}$ if and only if $0 \le i_2 \le s t$, $0 \le i_1 \le r s + i_2$ and $0 \le i_3 \le r t i_1 i_2$.

Highest weights

Lemma 12

Suppose $\lambda = m_1\lambda_1 + m_2\lambda_2$ be the heighest weight of an irreducible $\mathcal L$ submodule W of V, and $\mathbf v = E_{[s,t]}^*\mathbf v$ a highest weight vector. Set r = d - s - t. Then, the following hold.

- (i) $(r, s, t) = (m_1 + m_2 + t, m_2 + t, t)$, and $r \ge s \ge t$.
- (ii) $t \in \{0, 1, \dots, [\frac{d}{3}]\}.$
- (iii) $m_1 = r s = d 3t 2m_2$.
- (iv) $m_2 = s t \in \{0, 1, \dots, \left[\frac{d-3t}{2}\right]\}.$

The structure of an irreducible module

Lemma 13

Let \mathbf{v} be a heigest weight vector with weight $\lambda = (m_1, m_2)$ of an irreducible \mathcal{L} submodule of V. Let $\mathbf{v}_{i,j,k} = R_3^k R_1^j R_2^i \mathbf{v}$ for $0 \le i \le m_2, \ 0 \le j \le m_1 + i, \ 0 \le k \le m_1 + m_2 - i - j$. Let

$$W_{i,j} = \operatorname{Span}(\mathbf{v}_{i,j,k} \mid 0 \le k \le m_1 + m_2 - i - j),$$

and

$$U_i = \mathrm{Span}(\mathbf{v}_{i,j,k} \mid 0 \le j \le m_1, 0 \le k \le m_1 + m_2 - i - j).$$

Then $W_{i,j}$ is an irreducible $\mathcal{L}_3 = \langle L_3, R_3 \rangle \simeq sl_2(\mathbb{C})$ module of heigest weight $m_1 + m_2 - i - j$ with a heighest weight vector $\mathbf{v}_{i,j,0}$ of dimenstion $m_1 + m_2 - i - j + 1$. Moreover, $W_{i,j}$ and $W_{i',j'}$ are orthogonal if $i + j \neq i' + j'$.

We also have that $R_1 \mathbf{v}_{i,m_1,0} \in U_{i-1} + \cdots + U_0$.

The highest weight and the dimension of an irreducible module

Lemma 14

For each (r, s, t) with $r \ge s \ge t$, there is a highest weight vector \mathbf{v} with $\lambda = (m_1, m_2) = (r - s, s - t)$ such that $(r(\mathbf{v}), s(\mathbf{v}), t(\mathbf{v})) = (r, s, t)$. Every highest-weight vector is of this type.

Proposition 8

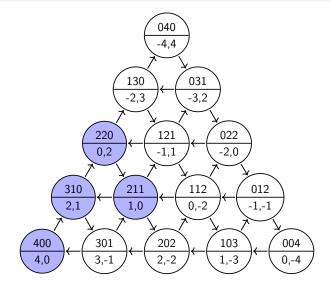
Let \mathbf{v} be a heigest weight vector with weight $\lambda = (m_1, m_2)$ of an irreducible \mathcal{L} submodule W of V. Let $\mathbf{v}_{i,j,k} = R_3^k R_1^j R_2^j \mathbf{v}$. Then the set

$$\{ \mathbf{v}_{i,j,k} \mid 0 \le i \le m_2, 0 \le j \le m_1, 0 \le k \le m_1 + m_2 - i - j \}$$

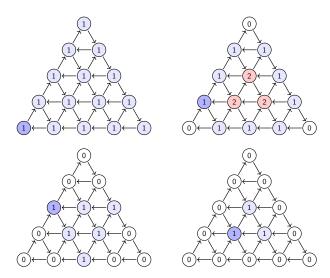
forms a basis of W. Moreover, dim $W = \frac{1}{2}(m_1 + 1)(m_2 + 1)(m_1 + m_2 + 2)$.

Example: $H^*(4, 3)$

$$\mathsf{type}(\mathbf{v}) = [r(\mathbf{v}), s(\mathbf{v}), t(\mathbf{v}), \text{ and weight}(\mathbf{v}) = (\ell, m) = (r(\mathbf{v}) - s(\mathbf{v}), s(\mathbf{v}) - t(\mathbf{v})))$$



Example: $H^*(4,3)$ - Irreducible Modules



Examples for small d

Example 15

For a small d, we list (r, s, t) of the highest weight vector and the highest weight $\lambda = (m_1, m_2)$ as $[r, s, t], (m_1, m_2)$: dim, m, where dim denotes the dimension of the corresponding irreducible module, and m the multiplicity in the standard module in the following.

- d = 1: [0, 0, 0], (1, 0): 3, 1.
- d = 2: [2,0,0],(2,0):6,1,[1,1,0],(0,1):3,1.
- d = 3: [3,0,0],(3,0):10,1, [2,1,0],(1,1):8,2, [1,1,1],(0,0):1,1
- d = 4: [4,0,0], (4,0): 15,1, [3,1,0], (2,1): 15,3, [2,2,0], (0,2): 6,2, [2,1,1], (1,0): 3,3.
- d = 5: [5,0,0],(5,0): 21,1, [4,1,0],(3,1): 24,4, [3,2,0],(1,2): 15,5, [3,1,1],(2,0): 6,6, [2,2,1],(0,1): 3,5.

Algebra generated by two matrices

Theorem 9

A and A^* Let A be the adjacency matrix of $H^*(d,3)$. Let $\omega \in \mathbb{C}$ such that $\omega^2 + \omega + 1 = 0$ and

$$A^* = \sum_{s,t} ((d-s-t) + s\omega + t\omega^2) E^*_{[s,t]}.$$

Then, the following hold.

$$[A, [A, [A, A^*]]] = (1 - \omega)^3 A^*$$
$$[A^*, [A^*, [A^*, A]]] = -(1 - \omega)^3 A.$$

The Algebra defined by generators A, B, and relations

$$\mathcal{L} = \langle A, B \mid [A, [A, A, B]] \rangle = B, [B, B, B, B, A] \rangle = A \rangle$$

Special type of distance-regular graphs

Q-polynomial distance-regular graphs

Most of the distance regular graphs of large diameter satisfy the following. There is a primitive idempotent E with the following property by setting

$$A^* = \frac{1}{|X|} \text{diagonal}(E_{0,0}, E_{0,1}, \dots, E_{0,d}).$$

$$[A, [A, [A, A^*]]] = b^2[A, A^*]$$
$$[A^*, [A^*, [A^*, A]]] = b^{*2}[A^*, A].$$

Onsagar Algebra

Let $\mathcal O$ be a Lie algebra generated by A and A^* with the relation above. If A and A^* act on a finite dimensional algebra as linear transformations. Then A,A^* acts on V as a tridiagonal pair.

Problems

- **1** Find the multiplicity formula of the standard module of $H^*(d,3)$.
- ② Study the structure of the irreducible modules of the Terwilliger algebra of $H^*(d,q)$, $(q \equiv 3 \pmod{4})$.
- Study finite dimensional irreducible module of the following algebra generated by two elements and two relations.

$$\mathcal{L} = \langle A, B \mid [A, [A, [A, B]]] = B, [B, [B, [B, A]]] = A \rangle$$

- Oevelop an algebraic theory of weakly distance-regular digraphs, and find a good class. Or, find a good class of commutative but not symmetric assocation scheme.
- Are there noncommutative weakly distance-regular digraphs?

References

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THANK YOU!!

Matrices, Part I

Let r = d - s - t.

$$\begin{split} H_1 &= \sum_{s,t} (r-s) E_{[s,t]}^* \sim h_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \\ H_2 &= \sum_{s,t} (s-t) E_{[s,t]}^* \sim h_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \\ H_3 &= H_1 + H_2, \text{ where } r = d - s - t, \\ R_1 &= \sum_{s,t} E_{[s+1,t]}^* A E_{[s,t]}^* \sim e_{-s} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \\ R_2 &= \sum_{s,t} E_{[s-1,t+1]}^* A E_{[s,t]}^* \sim e_{-t} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \end{split}$$

Matrices - Part II

$$R_{3} = \sum_{s,t} E_{[s,t+1]}^{*} A^{\top} E_{[s,t]}^{*} \sim e_{-s-t} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix},$$

$$L_{1} = \sum_{s,t} E_{[s-1,t]}^{*} A^{\top} E_{[s,t]}^{*} \sim e_{s} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

$$L_{2} = \sum_{s,t} E_{[s+1,t-1]}^{*} A^{\top} E_{[s,t]}^{*} \sim e_{t} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

$$L_{3} = \sum_{s,t} E_{[s,t-1]}^{*} A E_{[s,t]}^{*} \sim e_{-s-t} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Note that $H_1, H_2, H_3, R_1, R_2, R_3, L_1, L_2, L_3$ are all in $\mathcal{T}(x)$.

$$[A, [A, [A, B]]] = B, [B, [B, [B, A]]] = A$$

Recall [M, N] = MN - NM. Hence,

$$[A, [A, [A, B]]] = A^3B - 3A^2BA + 3ABA^2 - BA^3.$$

Suppose A, B are diagonalizable linear transformations on a finite dimentional vector space V, and E_i (resp. F_j) are projections onto the eigenspaces written as a polynomial in A (resp. B). satisfying $AE_i = E_i A = \phi_i E_i$ and $BF_i = F_i B = \psi_i F_i$.

Then, [A, [A, [A, B]]] = B implies

$$E_{i}BE_{j} = E_{i}[A, [A, [A, B]]]E_{j} = (\phi_{i}^{3} - 3\phi_{i}^{2}\phi_{j} + 3\phi_{i}\phi_{j}^{2} - \phi_{j}^{3})E_{i}BE_{j}$$
$$= (\phi_{i} - \phi_{j})^{3}E_{i}BE_{j}.$$

Therefore, if [A, [A, [A, B]]] = B, and [B, [B, [B, A]]] = A,

$$E_iBE_j \neq O \Rightarrow \phi_i - \phi_j \in \{1, \omega, \omega^2\}, \text{ and}$$

 $F_iAF_i \neq O \Rightarrow \psi_i - \psi_i \in \{1, \omega, \omega^2\},$

where $1 + \omega + \omega^2 = 0$.

Hexagonal Pairs

Let A and B be linear transformations on a finite dimensional vector space $V \neq 0$ satisfying the following four conditions.

- (i) A and B are diagonazable on V.
- (ii) There is an indexing $V_{i,j}, (i,j) \in \Phi$ of the eigenspaces of A such that

$$BU_{i,j} \subseteq U_{i+1,j} + U_{i-1,j+1} + U_{i,j-1}, \quad (i,j) \in \Phi.$$

(iii) There is an indexing $V_{i,j}, (i,j) \in \Psi$ of the eigenspaces of A such that

$$BV_{i,j} \subseteq V_{i+1,j} + V_{i-1,j+1} + V_{i,j-1}, \quad (i,j) \in \Psi.$$

(iv) There is no subspace W of V such that $AW \subseteq W$, $BW \subseteq W$, other than W = 0 and W = V.

Examples with small number of vertices

Hanaki-Miyamoto, Classification of association schemes with a small number of vertices at http://math.shinshu-u.ac.jp/~hanaki/as/.

http://math.shinshu-u.ac.jp/~hanaki/as/data/as07 No. 2

An example of a wdrdg with seven vertices:

```
\begin{bmatrix} 0 & 1 & 1 & 1 & 2 & 2 & 2 \\ 2 & 0 & 1 & 2 & 1 & 1 & 2 \\ 2 & 2 & 0 & 1 & 1 & 2 & 1 \\ 2 & 1 & 2 & 0 & 2 & 1 & 1 \\ 1 & 2 & 2 & 1 & 0 & 1 & 2 \\ 1 & 2 & 1 & 2 & 2 & 0 & 1 \\ 1 & 1 & 2 & 2 & 1 & 2 & 0 \end{bmatrix}
```