

# DC-Micromotors

## Precious Metal Commutation

2,5 mNm

For combination with

Gearheads:

15A, 15/3, 15/4, 15/5, 15/8, 16A, 16/7

Encoders:

IE2 – 16 ... 512

### Series 1524 ... SR

	1524 T	003 SR	006 SR	009 SR	012 SR	018 SR	024 SR	
1 Nominal voltage	U <sub>N</sub>	3	6	9	12	18	24	Volt
2 Terminal resistance	R	1,1	5,1	10,4	19,8	44,0	79,6	Ω
3 Output power	P <sub>2 max.</sub>	1,92	1,70	1,88	1,75	1,78	1,75	W
4 Efficiency	η <sub>max.</sub>	77	77	77	76	77	78	%
5 No-load speed	n <sub>o</sub>	10 800	9 700	10 100	9 900	9 900	9 900	rpm
6 No-load current (with shaft ø 1,5 mm)	I <sub>o</sub>	0,047	0,021	0,014	0,011	0,007	0,005	A
7 Stall torque	M <sub>H</sub>	6,80	6,68	7,12	6,76	6,86	6,75	mNm
8 Friction torque	M <sub>R</sub>	0,12	0,12	0,12	0,13	0,12	0,11	mNm
9 Speed constant	k <sub>n</sub>	3 660	1 650	1 140	840	560	419	rpm/V
10 Back-EMF constant	k <sub>E</sub>	0,273	0,607	0,877	1,190	1,790	2,380	mV/rpm
11 Torque constant	k <sub>M</sub>	2,61	5,80	8,37	11,40	17,10	22,80	mNm/A
12 Current constant	k <sub>I</sub>	0,384	0,172	0,119	0,088	0,059	0,044	A/mNm
13 Slope of n-M curve	Δn/ΔM	1 590	1 450	1 420	1 460	1 440	1 470	rpm/mNm
14 Rotor inductance	L	17	70	150	250	560	1 000	μH
15 Mechanical time constant	τ <sub>m</sub>	10	10	10	10	10	10	ms
16 Rotor inertia	J	0,60	0,66	0,67	0,65	0,66	0,65	gcm <sup>2</sup>
17 Angular acceleration	α <sub>max.</sub>	110	100	110	100	100	100	·10 <sup>3</sup> rad/s <sup>2</sup>
18 Thermal resistance	R <sub>th 1</sub> / R <sub>th 2</sub>	4,5 / 31						K/W
19 Thermal time constant	τ <sub>w1</sub> / τ <sub>w2</sub>	2,4 / 300						s
20 Operating temperature range:								
– motor		– 30 ... + 85 (optional – 55 ... + 125)						°C
– rotor, max. permissible		+ 125						°C
21 Shaft bearings		sintered bronze sleeves		ball bearings		ball bearings, preloaded		
22 Shaft load max.:		(standard)		(optional)		(optional)		
– with shaft diameter		1,5		1,5		1,5		mm
– radial at 3 000 rpm (3 mm from bearing)		1,2		5		5		N
– axial at 3 000 rpm		0,2		0,5		0,5		N
– axial at standstill		20		10		10		N
23 Shaft play:								
– radial	≤	0,03		0,015		0,015		mm
– axial	≤	0,2		0,2		0		mm
24 Housing material		steel, black coated						
25 Weight		21						g
26 Direction of rotation		clockwise, viewed from the front face						
Recommended values - mathematically independent of each other								
27 Speed up to	n <sub>e max.</sub>	10 000	10 000	10 000	10 000	10 000	10 000	rpm
28 Torque up to	M <sub>e max.</sub>	2,5	2,5	2,5	2,5	2,5	2,5	mNm
29 Current up to (thermal limits)	I <sub>e max.</sub>	1,300	0,630	0,440	0,320	0,210	0,160	A

Orientation with respect to motor terminals not defined

