

Joshua R. Wiens

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Education

Bachelor of Science – Mechanical Engineering

University of Oklahoma, Norman, OK, May 2017

- Minor: Electrical and Computer Engineering
- **Primary Focus:** Electromechanical Systems & Project Management

Skills

Hardware/Design

- Control of Electromechanical Devices
- Electrical Troubleshooting w/ Tools
- Extrusion 3D Printing
- Rapid Prototyping
- Fabrication/Installation of Cable & Wiring
- CAD (Solidworks/Autodesk)

Programming/Scripting

- C/C++
- Python 3
- VBA in Excel
- MATLAB
- Embedded Digital Control
- Data Acquisition & Processing

Interpersonal

- Leadership
- Team Communication
- Information Presentation
- Personnel Training
- Customer Service

Professional Experience

Systems Engineering Internship

Ion Beam Applications (IBA), Nov 2015 - Present

- Proton Therapy system maintenance involving various subsystem including:
 - o High power distribution
 - o Large scale cooling
 - o Mechanical patient positioning and beam delivery
 - o High vacuum particle acceleration and transport
- Troubleshooting and resolving day-to-day system failures using various software and measurement tools.
- Trained to work in hazardous environments including: at heights, high voltage, live electricity, and radiation.

Shift Manager

Five Guys, Jan 2014 – Nov 2015

- Team Leader, coordinator, and personnel training specialist.
- Detail oriented inventory and money management.

Academic Experience/Achievements

Capstone Team Leader

- Managed simultaneous development of two modular electro-hydraulic subsystems including test systems.
- Fabricated control/power infrastructure for electrical and hydraulic power distribution.
- Developed plug-and-play control module capable of independently controlling each of our 3 subsystems.
 - o Designed hierarchical control system for simultaneous sensor acquisition/processing and control.
 - o Fabricated microcontroller network via the I²C serial communication protocol.
 - o Capable of receiving 5 Hall effect sensor inputs and control 2 stepper or brushless DC motors using 2 cables.

Autonomous Design Competition

- Proposed the successful use of hexagonal matrix for ideal strength-weight characteristics in 3D printed chassis.
- Manually machined aluminum for rigidity-sensitive components such as the axels and steering column.
- Designed, fabricated, and installed electrical control and power subsystems.
- Developed embedded control system applying digital signal processing to external sensor feedback.
- Achieved highest score out of 30+ 4-man-teams with an unmatched 2 flawless attempts.

References

- Kevin Sturm – Director of Operation IBA, North America; (571) 250-5831; Kevin.Sturm@iba-group.com
- Ruben Reyes – Site Technical Leader IBA, Oklahoma City, OK; (405) 773-6789; Ruben.Reyes@iba-group.com
- Harold Stalford – Professor, OU AME, Norman, OK; (405) 325-1742; stalford@ou.edu
- See LinkedIn projects and SlideShare presentations for examples of some things listed above.