# Project: Surface Tension on Sphere Updated: 03/06/20

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## 1 Definitions

 $f_i$ : nominal body force per unit volume

 $T_i$ : nominal traction on surface [force per area]

 $\sigma_{ij}$ : true stress  $\rightarrow S_{iJ}$ : nominal stress

$$\left[\frac{\text{Force}}{\text{Area}}\right]$$

U: free energy of the gel

 $U_e$ : elastic energy from stretching a polymer network  $U_m$ : energy of mixing the solvent with polymer chains

$$\frac{\text{Force}}{\text{Area}}$$

N: number of polymer chains per unit volume in the reference state

$$\left[\frac{\text{Number of polymer chains}}{\text{Volume}}\right]$$

 $k_B$ : Boltzmann's Constant

$$\left[\frac{\text{Energy}}{\text{Temperature}}\right] = \left[\frac{\text{Force} \times \text{Length}}{\text{Temperature}}\right]$$

T: [Temperature]

K: Shear Modulus (Same units as  $Nk_BT$ )

Number of Polymer Chains 
$$\times \frac{\text{Force}}{\text{Area}}$$

 $\chi$ : Flory-Huggins parameter for the enthalpy of mixing [dimensionless]

 $\mathbf{F} \colon \mathsf{Deformation} \ \mathsf{gradient} \ [\mathsf{dimensionless}]$ 

C(X): Nominal concentration of solvent per unit volume in reference state

 $c(\mathbf{X},t)$ : True concentration of solvent per unit volume in current state

$$\left\lceil \frac{\text{Concentration of Solvent}}{\text{Volume}} \right\rceil$$

 $\Omega$ : [Volume]

 $\mu(\mathbf{X},t)$ : chemical potential of the small molecules

$$\left[\frac{\text{Energy}}{\text{Concentration}}\right] = \left[\frac{\text{Force} \times \text{Length}}{\text{Concentration}}\right]$$

 $dA(\mathbf{X})$ : element of area [Area]  $\to dV(\mathbf{X})$ : element of volume [Volume]

 $N_K(\mathbf{X})$ : unit vector normal to the interface in the reference state  $\to n_i(\mathbf{X}, t)$ : current state [Dimensionless] Number of small molecules injected into:

 $r(\mathbf{X},t)$ : a volume element

$$\left\lceil \frac{\text{Number of small molecules}}{\text{Volume} \times \text{Time}} \right\rceil$$

 $i(\mathbf{X},t)$ : an interface element

$$\left\lceil \frac{\text{Number of small molecules}}{\text{Area} \times \text{Time}} \right\rceil$$

D: Solvent diffusivity

 $\left[\frac{\rm Area}{\rm Time}\right]$ 

 $J_K$ : nominal flux  $\rightarrow j_i(\mathbf{X}, t)$ : true flux

 $\left[\frac{\text{Number of Small Molecules}}{\text{Time} \times \text{Area}}\right]$ 

 $M_{KL}$ : Nominal mobility tensor

 $\left[\frac{\text{Number of Small Molecules}}{\text{Time} \times \text{Volume}}\right]$ 

## 2 Reformulation

References:

A. Javili and P. Steinmann titled A finite element framework for continua with boundary energies. Part I: The two-dimensional case

A. Javili and P. Steinmann titled A finite element framework for continua with boundary energies. Part II: The three-dimensional case

#### 2.1 Kinematics and energies of continua with boundaries

Surfaces of bodies and interfaces between bodies exhibit different properties from the bulk. These effects can be modeled in terms of surface tension or an added term to the total potential energy, denoted by a bar

$$Bulk: U = U_e + U_m - \mu C$$

Surface:  $u_o$ 

Surface deformation gradient:

$$\bar{\mathbf{F}} = \frac{\partial x_i}{\partial X_K} \cdot \bar{\mathbf{I}}$$

$$\bar{\mathbf{F}} = \mathbf{F} \cdot \bar{\mathbf{I}}$$
(2.1)

where the mixed-variant surface unit tensor in the material configuration is:

$$\bar{\mathbf{I}} = \mathbf{I} - \mathbf{N} \otimes \mathbf{N} \tag{2.2}$$

Just as how the Jacobian is related to the volume, the surface J is related to the surface:

$$J = \frac{dv}{dV} = \det \mathbf{F}$$
$$\bar{J} = \frac{da}{dA} = |\underbrace{\det \mathbf{F} \mathbf{F}^{-T}}_{\text{cofactor}} \mathbf{N}|$$

Can use the Nanson operator to define the surface jacobian,  $\bar{J}$ 

$$\bar{J} = |J\mathbf{F}^{-T}\mathbf{N}|$$

$$\bar{J} = |\underbrace{\det \mathbf{F}\mathbf{F}^{-T}}_{\text{cofactor}}\mathbf{N}|$$
(2.3)

#### 2.1.1 Neo-Hookean type boundary potential

The internal potential energy can be expressed as:

$$w_0(\mathbf{\bar{F}}) = \frac{\bar{\lambda}}{2} \log^2 \bar{J} + \frac{\bar{\mu}}{2} (\mathbf{\bar{F}} : \mathbf{\bar{F}} - 2 - 2 \log \bar{J})$$
(2.4)

#### 2.1.2 Surface tension boundary potential

The internal potential energy can be expressed as:

$$w_0(\bar{\mathbf{F}}) = \gamma \bar{J} \tag{2.5}$$

#### 2.2 Equilibrium Equations (Strong Forms)

Mechanical equilibrium equation:

$$\nabla_{X} \cdot \mathbf{P} + \mathbf{b_{0}} = \mathbf{0} \quad \text{in} \quad V$$

$$\mathbf{P} \cdot \mathbf{N} - \overline{\nabla}_{X} \cdot \overline{\mathbf{P}} = \check{\mathbf{T}} \quad \text{on} \quad S^{T}$$

$$\mathbf{u} = \check{\mathbf{u}} \quad \text{on} \quad S^{u}$$

$$[\overline{\mathbf{P}} \cdot \overline{\mathbf{N}}] = 0 \quad \text{on} \quad L$$

$$(2.6)$$

Mass conservation equation:

$$\dot{C} + \nabla_X \cdot \mathbf{J} = r \quad \text{in} \quad V$$

$$\mathbf{J} \cdot \mathbf{N} = -i \quad \text{on} \quad S^i$$

$$\mu = \check{\mu} \quad \text{on} \quad S^{\mu}$$
(2.7)

#### 2.2.1 Mechanical Equilibrium

Rearrange and multiply with a test function  $\delta \varphi$  and integrate over domain

$$\int (\boldsymbol{\nabla} \cdot \mathbf{P}) \cdot \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0 \quad \text{Int by Parts}$$

$$\int \boldsymbol{\nabla} \cdot \left( \mathbf{P^T} \cdot \delta \boldsymbol{\varphi} \right) dV - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0 \quad \text{Divergence}$$

$$\int (\mathbf{P} \cdot \mathbf{N}) \cdot \delta \boldsymbol{\varphi} dS - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0 \quad \rightarrow \mathbf{P} \cdot \mathbf{N} = \boldsymbol{\nabla} \cdot \mathbf{\bar{P}} + \mathbf{\bar{b_o}}$$

$$\int (\boldsymbol{\nabla} \cdot \mathbf{\bar{P}}) \cdot \delta \boldsymbol{\varphi} dS + \int \mathbf{\bar{b_o}} \cdot \delta \boldsymbol{\varphi} dS - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0 \quad \text{Int by Parts}$$

$$\int \boldsymbol{\nabla} \cdot (\mathbf{\bar{P}}^T \cdot \delta \boldsymbol{\varphi}) dS - \int \mathbf{\bar{P}} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dS + \int \mathbf{\bar{b_o}} \cdot \delta \boldsymbol{\varphi} dS - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0 \quad \text{Divergence}$$

$$\int (\mathbf{\bar{P}} \cdot \mathbf{M}) \cdot \delta \boldsymbol{\varphi} dL - \int \mathbf{\bar{P}} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dS + \int \mathbf{\bar{b_o}} \cdot \delta \boldsymbol{\varphi} dS - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0$$

$$- \int \mathbf{\bar{P}} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dS + \int \mathbf{\bar{b_o}} \cdot \delta \boldsymbol{\varphi} dS - \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV + \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV = 0$$

Rearrange

$$\int \bar{\mathbf{P}} \cdot \bar{\nabla} \delta \boldsymbol{\varphi} dS + \int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV = \int \bar{\mathbf{b}}_{\mathbf{o}} \cdot \delta \boldsymbol{\varphi} dS + \int \mathbf{b}_{\mathbf{o}} \cdot \delta \boldsymbol{\varphi} dV$$
 (2.8)

#### 2.2.2 Mass Conservation

Multiply Eq. ?? with a test function  $\mu$  and follow the same steps as above:

$$\int \dot{C}\delta\mu dV + \int (\mathbf{\nabla} \cdot \mathbf{J})\delta\mu dV = \int r\delta\mu dV \quad \text{Int by Parts}$$

$$\int \dot{C}\delta\mu dV + \int \mathbf{\nabla} \cdot (\mathbf{J}^T\delta\mu) dV - \int \mathbf{J} \cdot \mathbf{\nabla}\delta\mu dV = \int r\delta\mu dV \quad \text{Divergence}$$

$$\int \dot{C}\delta\mu dV + \int (\mathbf{J} \cdot \mathbf{N})\delta\mu dV - \int \mathbf{J} \cdot \mathbf{\nabla}\delta\mu dV = \int r\delta\mu dV$$

$$\int \dot{C}\delta\mu dV - \int i\delta\mu dS - \int \mathbf{J} \cdot \mathbf{\nabla}\delta\mu dV = \int r\delta\mu dV$$

$$\int \dot{C}\delta\mu dV - \int i\delta\mu dV - \int \mathbf{J} \cdot \mathbf{\nabla}\delta\mu dV = \int r\delta\mu dV + \int i\delta\mu dS$$

#### 2.3 Thermodynamic Theory

Free energy density

$$U(\mathbf{F}, \mu) = U_e(\mathbf{F}) + U_m(C) - \mu C$$
$$\bar{U}(\bar{\mathbf{F}}) = u_e(\bar{\mathbf{F}})$$

The free energy density of the system changes at the rate:

$$\delta U(\mathbf{F}, \mu) = \frac{\partial U(\mathbf{F}, \mu)}{\partial \mathbf{F}} \delta \mathbf{F} + \frac{\partial U(\mathbf{F}, \mu)}{\partial \mu} \delta \mu$$
$$\delta \bar{U}(\bar{\mathbf{F}}) = \frac{\partial u(\bar{\mathbf{F}})}{\partial \bar{\mathbf{F}}} \delta \bar{\mathbf{F}}$$

Taking in the sum

$$\begin{split} \frac{\delta G_{bulk}}{\delta t} &= \int \frac{\delta U}{\delta t} dV - \int \mathbf{b_o} \frac{\delta \mathbf{x}}{\delta t} dV - \int \mu r dV - \int \mu i dS \\ \frac{\delta G_{surf}}{\delta t} &= \int \frac{\delta \bar{U}}{\delta t} dS - \int_S \check{\mathbf{T}} \frac{\delta \overline{\mathbf{x}}}{\delta t} dS \end{split}$$

Together the gel and field of weights and pumps form a thermodynamic system

$$\begin{split} \frac{\delta G}{\delta t} &= \frac{\delta G_{bulk}}{\delta t} + \frac{\delta G_{surf}}{\delta t} \\ \frac{\delta G}{\delta t} &= \int_{V} \frac{\delta U}{\delta t} dV + \int_{S} \frac{\delta \bar{U}}{\delta t} dS - \underbrace{\int_{V} \mathbf{b_{0}} \frac{\delta \mathbf{x}}{\delta t} dV - \int_{S} \check{\mathbf{T}} \frac{\delta \overline{\mathbf{x}}}{\delta t} dS}_{\text{Rate of mechanical work}} - \underbrace{\int_{V} \mu r dV - \int_{S} \mu i dS}_{\text{Rate of chemical work}} \end{split}$$

The change in free energy density over time

$$\frac{\partial U}{\partial t} = \frac{\partial U}{\partial \mathbf{F}} \frac{\delta \mathbf{F}}{\delta t} + \frac{\partial U}{\partial \mu} \frac{\delta \mu}{\delta t} + \frac{\delta(\mu C)}{\delta t}$$
$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial \mathbf{\bar{F}}} \frac{\delta \mathbf{\bar{F}}}{\delta t}$$

Rephrase the two weak forms where  $\delta u$  is equivalent to  $\delta \mathbf{x}/\delta t$  or  $\delta \mathbf{\bar{x}}/\delta t$ 

$$\int \mathbf{\bar{P}} \cdot \nabla \frac{\delta \mathbf{\bar{x}}}{\delta t} dS = \int \mathbf{\bar{b}_o} \cdot \frac{\delta \mathbf{\bar{x}}}{\delta t} dS \quad \to \quad \int \mathbf{\bar{P}} \cdot \frac{\delta \mathbf{\bar{F}}}{\delta t} dS = \int \mathbf{\bar{b}_o} \cdot \frac{\delta \mathbf{\bar{x}}}{\delta t} dS$$

$$\int \mathbf{P} \cdot \mathbf{\nabla} \frac{\delta \mathbf{x}}{\delta t} dV = \int \mathbf{b_o} \cdot \frac{\delta \mathbf{x}}{\delta t} dV \quad \to \quad \int \mathbf{P} \cdot \frac{\delta \mathbf{F}}{\delta t} dV = \int \mathbf{b_o} \cdot \frac{\delta \mathbf{x}}{\delta t} dV$$

Rewrite the weak form from  $\delta\mu$  is  $\mu$ 

$$\int \frac{\partial C}{\partial t} \mu dV - \int r \mu dV - \int i \mu dS = \int \mathbf{J} \cdot \mathbf{\nabla} \mu dV$$

Bulk

$$\begin{split} \frac{\delta G_{bulk}}{\delta t} &= \int \frac{\delta U}{\delta t} dV - \int \mathbf{b_o} \frac{\delta \mathbf{x}}{\delta t} dV - \int \mu r dV - \int \mu i dS \\ &= \int \frac{\partial U}{\partial \mathbf{F}} \frac{\delta \mathbf{F}}{\delta t} dV + \int \frac{\partial U}{\partial \mu} \frac{\delta \mu}{\delta t} dV + \int \frac{\delta (\mu C)}{\delta t} dV - \int \mathbf{b_o} \frac{\delta \mathbf{x}}{\delta t} dV - \int \mu r dV - \int \mu i dS \\ &= \int \frac{\partial U}{\partial \mathbf{F}} \frac{\delta \mathbf{F}}{\delta t} dV + \int \frac{\partial U}{\partial \mu} \frac{\delta \mu}{\delta t} dV + \int \frac{\delta \mu}{\delta t} C dV + \int \mu \frac{\delta C}{\delta t} dV - \int \mathbf{P} \cdot \frac{\delta \mathbf{F}}{\delta t} dV - \int \mu r dV - \int \mu i dS \\ &= \int \left( \frac{\partial U}{\partial \mathbf{F}} - \mathbf{P} \right) \frac{\delta \mathbf{F}}{\delta t} dV + \int \left( \frac{\partial U}{\partial \mu} + C \right) \frac{\delta \mu}{\delta t} dV + \int \mu \frac{\delta C}{\delta t} dV - \int \mu r dV - \int \mu i dS \\ \frac{\delta G_{bulk}}{\delta t} &= \int \left( \frac{\partial U}{\partial \mathbf{F}} - \mathbf{P} \right) \frac{\delta \mathbf{F}}{\delta t} dV + \int \left( \frac{\partial U}{\partial \mu} + C \right) \frac{\delta \mu}{\delta t} dV + \int \mathbf{J} \cdot \mathbf{\nabla} \mu dV \end{split}$$

Surface

$$\begin{split} \frac{\delta G_{surf}}{\delta t} &= \int \frac{\delta u}{\delta t} dS - \int \bar{\mathbf{b}}_{\mathbf{o}} \frac{\delta \bar{x}}{\delta t} dS \\ &= \int \frac{\partial u}{\partial \bar{\mathbf{F}}} \frac{\delta \bar{\mathbf{F}}}{\delta t} dS - \int \bar{\mathbf{b}}_{\mathbf{o}} \frac{\delta \bar{x}}{\delta t} dS \\ &= \int \frac{\partial u}{\partial \bar{\mathbf{F}}} \frac{\delta \bar{\mathbf{F}}}{\delta t} dS - \int \bar{\mathbf{P}} \cdot \frac{\delta \bar{\mathbf{F}}}{\delta t} dS \\ &= \int \left( \frac{\partial u}{\partial \bar{\mathbf{F}}} - \bar{\mathbf{P}} \right) \frac{\delta \bar{\mathbf{F}}}{\delta t} dS \end{split}$$

Therefore

$$\frac{\delta G}{\delta t} = \int \left( \frac{\partial U}{\partial \mathbf{F}} - \mathbf{P} \right) \frac{\delta \mathbf{F}}{\delta t} dV + \int \left( \frac{\partial u}{\partial \bar{\mathbf{F}}} - \bar{\mathbf{P}} \right) \frac{\delta \bar{\mathbf{F}}}{\delta t} dS + \int \left( \frac{\partial U}{\partial \mu} + C \right) \frac{\delta \mu}{\delta t} dV + \int \mathbf{J} \cdot \frac{\partial \mu}{\partial X} dV$$

Thermodynamics dictates that the free energy of the system should never increase:

$$\frac{\delta G}{\delta t} \le 0 \tag{2.9}$$

This leads to

$$\mathbf{P} = \frac{\partial U}{\partial \mathbf{F}}$$
$$\bar{\mathbf{P}} = \frac{\partial u}{\partial \bar{\mathbf{F}}}$$
$$C = -\frac{\partial U}{\partial u}$$

We enforce the negative definite structure of the last integrand by adopting a kinetic law

$$\mathbf{J} = -\mathbf{M} \cdot \frac{\partial \mu}{\partial X} = -\mathbf{M} \cdot \nabla \mu \tag{2.10}$$

#### 2.4 Kinetic Law

The flux relates to the gradient of the chemical potential

$$\mathbf{j} = -\frac{cD}{kT}\frac{\partial\mu}{\partial x} \tag{2.11}$$

The true concentration relates to the nominal concentration as:

$$c = \frac{C}{\det \mathbf{F}} \tag{2.12}$$

Recall an identity

$$\det(\mathbf{F})\mathbf{N}dA = \mathbf{F}\mathbf{n}da \to \frac{\mathbf{N}dA}{\mathbf{n}da} = \frac{\mathbf{F}}{\det\mathbf{F}}$$
(2.13)

The number of molecules crossing the material element per unit time can be written:

$$\mathbf{j} \cdot \mathbf{n} da = \mathbf{J} \cdot \mathbf{N} dA \tag{2.14}$$

Consequently, relate the true flux to the nominal flux.

$$\mathbf{j} = \mathbf{J} \cdot \frac{\mathbf{N}dA}{\mathbf{n}da} \quad \text{substitute Eq. 2.13}$$

$$= \mathbf{J} \frac{\mathbf{F}}{\det \mathbf{F}} \quad \text{substitute Eq. 2.10}$$

$$= -\mathbf{M} \cdot \frac{\partial \mu}{\partial X} \frac{\mathbf{F}}{\det \mathbf{F}} \quad \text{use chain rule}$$

$$= -\mathbf{M} \frac{\partial \mu}{\partial x} \frac{\partial x}{\partial X} \frac{\mathbf{F}}{\det \mathbf{F}} \quad \text{use Eq. 2.11}$$

$$-\frac{cD}{k_B T} \frac{\partial \mu}{\partial x} = -\mathbf{M} \frac{\partial \mu}{\partial x} \frac{\partial x}{\partial X} \cdot \frac{\partial x}{\partial X} \frac{1}{\det \mathbf{F}}$$

$$-\frac{cD}{k_B T} \det \mathbf{F} = -\mathbf{M} \frac{\partial x}{\partial X} \cdot \frac{\partial x}{\partial X}$$

$$-\frac{CD}{k_B T} = -\mathbf{M} \frac{\partial x}{\partial X} \cdot \frac{\partial x}{\partial X}$$

Rearrange in terms of  $M_{KL}$ , use Eq. 2.12 and invoke incompressibility

$$\mathbf{M} = \frac{CD}{k_B T} \mathbf{F}^{-1} \mathbf{F}^{-T}$$

## 2.5 Strain Energy Density

The constituents of the hydrogel are assumed to be incompressible:

$$\det \mathbf{F} = 1 + \Omega C \tag{2.15}$$

Free energy due to stretching (Flory, 1953)

$$U_e(\mathbf{F}) = \frac{1}{2} N k_B T \left[ \operatorname{tr} \mathbf{C} - 3 - 2 \log(\det \mathbf{F}) \right]$$
 (2.16)

Flory-Huggins (Flory, 1942; Huggins, 1941) model for the energy of mixing

$$U_m(C) = -\frac{k_B T}{\Omega} \left[ \Omega C \log \left( \frac{1 + \Omega C}{\Omega C} \right) + \frac{\chi}{1 + \Omega C} \right] \quad \text{Use. Eq. 2.15}$$

$$U_m(C) = -\frac{k_B T}{\Omega} \left[ (\det \mathbf{F} - 1) \log \left( \frac{\det \mathbf{F}}{\det \mathbf{F} - 1} \right) + \frac{\chi}{\det \mathbf{F}} \right] \quad \text{Use log property}$$

$$U_m(C) = \frac{k_B T}{\Omega} \left[ (\det \mathbf{F} - 1) \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) - \frac{\chi}{\det \mathbf{F}} \right]$$
(2.17)

Total strain energy in terms of the deformation gradient:

$$U(\mathbf{F}, \mu) = \frac{1}{2} N k_B T \left[ \operatorname{tr} \mathbf{C} - 3 - 2 \log(\det \mathbf{F}) \right] + \frac{k_B T}{\Omega} \left[ (\det \mathbf{F} - 1) \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) - \frac{\chi}{\det \mathbf{F}} \right] - \mu \left( \frac{\det \mathbf{F} - 1}{\Omega} \right)$$

#### 2.6 Nominal Stress and Concentration

The nominal stress and the concentration of the solvent can be obtained from the free energy density:

#### 2.6.1 Nominal Stress

$$\mathbf{S} = \frac{\partial U}{\partial \mathbf{F}}$$

$$\mathbf{S} = \frac{\partial U}{\partial I_1} \frac{\partial I_1}{\partial \mathbf{F}} + \frac{\partial U}{\partial I_3} \frac{\partial I_3}{\partial \mathbf{F}}$$

where  $I_1 = \operatorname{tr} \mathbf{C}$ ,  $\mathbf{C} = \mathbf{F}^T \mathbf{F}$  and  $I_3 = \det \mathbf{F}$ ; therefore,

First Term:

$$\frac{\partial U}{\partial I_1} = \frac{\partial U}{\partial \operatorname{tr} \mathbf{C}} = \frac{1}{2} N k_B T$$

Second Term:

$$\begin{split} \frac{\partial I_1}{\partial \mathbf{F}} &= \frac{\partial I_1}{\partial \mathbf{C}} \frac{\partial \mathbf{C}}{\partial \mathbf{F}} \\ &= \frac{\partial \operatorname{tr} \mathbf{C}}{\partial \mathbf{C}} \frac{\partial (\mathbf{F}^T \mathbf{F})}{\partial \mathbf{F}} \quad \text{where } \frac{\partial \operatorname{tr} \mathbf{A}}{\partial \mathbf{A}} = I \\ &= \mathbf{I} \left[ \frac{\partial \mathbf{F}}{\partial \mathbf{F}} \mathbf{F} + \mathbf{F} \frac{\partial \mathbf{F}}{\partial \mathbf{F}} \right] \\ \frac{\partial I_1}{\partial \mathbf{F}} &= 2\mathbf{F} \end{split}$$

Third Term:

$$\begin{split} &\frac{\partial U}{\partial I_3} = \frac{\partial \hat{U}}{\partial \det \mathbf{F}} \\ &= \frac{\partial}{\partial \det \mathbf{F}} \left[ \frac{1}{2} N k_B T \left[ \operatorname{tr}(\mathbf{C}) - 3 - 2 \log(\det \mathbf{F}) \right] + \frac{k_B T}{\Omega} \left[ (\det \mathbf{F} - 1) \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) - \frac{\chi}{\det \mathbf{F}} \right] - \mu \left( \frac{\det \mathbf{F} - 1}{\Omega} \right) \right] \\ &= \frac{1}{2} N k_B T \left( -2 \frac{\partial \log(\det \mathbf{F})}{\partial \det \mathbf{F}} \right) + \frac{k_B T}{\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} \right] - \frac{\mu}{\Omega} \left( \frac{\partial \det \mathbf{F}}{\partial \det \mathbf{F}} \right) \\ &= -N k_B T \frac{1}{\det \mathbf{F}} + \frac{k_B T}{\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} \right] - \frac{\mu}{\Omega} \\ &= N k_B T \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} \right] - \frac{\mu}{N\Omega k_B T} \right\} \\ &\frac{\partial U}{\partial I_3} = N k_B T \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \frac{\mu}{k_B T} \right] \right\} \end{split}$$

Fourth Term:

$$\frac{\partial I_3}{\partial F_{iJ}} = \frac{\partial \det \mathbf{F}}{\partial F_{iJ}} \text{ where } \frac{\partial \det \mathbf{F}}{\partial F} = (\det \mathbf{F})\mathbf{F}^{-T}$$
$$= \det \mathbf{F}F_{iJ}^{-T}$$

Therefore:

$$\mathbf{P} = \frac{\partial \hat{U}}{\partial I_{1}} \frac{\partial I_{1}}{\partial \mathbf{F}} + \frac{\partial \hat{U}}{\partial I_{3}} \frac{\partial I_{3}}{\partial \mathbf{F}}$$

$$= \frac{1}{2} N k_{B} T (2\mathbf{F}) + N k_{B} T \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^{2}} - \frac{\mu}{k_{B} T} \right] \right\} \det \mathbf{F} \mathbf{F}^{-T}$$

$$P = N k_{B} T \left\langle \mathbf{F} + \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^{2}} - \frac{\mu}{k_{B} T} \right] \right\} \det \mathbf{F} \mathbf{F}^{-T} \right\rangle$$

#### 2.6.2 Concentration

$$C(\mathbf{F}, \mu) = -\frac{\delta \hat{U}}{\delta \mu} = -\left(-\frac{\det \mathbf{F} - 1}{\Omega}\right)$$

$$C(\mathbf{F}, \mu) = \frac{\det \mathbf{F} - 1}{\Omega}$$
(2.18)

#### 2.7 Weak Forms and Time Integration

The weak forms are as followed:

$$\int \mathbf{\bar{P}} \cdot \nabla \delta \boldsymbol{\varphi} dS = \int \mathbf{\bar{b}_o} \cdot \delta \boldsymbol{\varphi} dS$$

$$\int \mathbf{P} \cdot \boldsymbol{\nabla} \delta \boldsymbol{\varphi} dV = \int \mathbf{b_o} \cdot \delta \boldsymbol{\varphi} dV$$

$$\int \frac{\partial C}{\partial t} \delta \mu dV - \int \mathbf{J} \cdot \boldsymbol{\nabla} \delta \mu dV = \int r \delta \mu dV + \int i \delta \mu dS$$

The first two weak forms are not time-dependent (all in current time step)

Backward Euler Scheme on the second weak form where **superscript t indicates previous time step** and no superscript indicates current time step

$$\int \frac{C - C^t}{\Delta t} \delta \mu dV - \int \mathbf{J} \cdot \frac{\delta \mu}{\delta X} dV - \int i \delta \mu dS - \int r \delta \mu dV = 0$$
$$\int (C - C^t) \delta \mu dV - \int \mathbf{J} \cdot \frac{\delta \mu}{\delta X} \Delta t dV - \int i \delta \mu \Delta t dS - \int r \delta \mu \Delta t dV = 0$$

## 3 Normalization

Normalization parameters below:

Lengths normalized by thickness (dry) :  $l = \tilde{l}H$ 

Surfaces normalized by :  $dA = d\tilde{A}H^2$ 

Volumes normalized by :  $dV = d\tilde{V}H^3$  or  $dV = d\tilde{V}\Omega$ 

Time normalized by :  $t = \tilde{t}\tau$  where  $\tau = \frac{H^2}{D}$ 

Chemical Potential normalized by :  $\mu = \tilde{\mu}k_BT$ 

Stress normalized by :  $S = \tilde{S}Nk_BT$   $\gamma = \tilde{\gamma}Nk_BT$ 

Concentration normalized by :  $\Omega C = \tilde{C} \to C = \frac{\tilde{C}}{\Omega}$ 

Normalization of nominal stress

$$\mathbf{P} = Nk_B T \left\langle \mathbf{F} + \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \frac{\mu}{k_B T} \right] \right\} \det \mathbf{F} \mathbf{F}^{-T} \right\rangle$$

$$\tilde{\mathbf{P}} Nk_B T = Nk_B T \left\langle \mathbf{F} + \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \frac{\tilde{\mu}k_B T}{k_B T} \right] \right\} \det \mathbf{F} \mathbf{F}^{-T} \right\rangle$$

$$\tilde{\mathbf{P}} = \mathbf{F} + \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \tilde{\mu} \right] \right\} \det \mathbf{F} \mathbf{F}^{-T}$$

$$\tilde{\mathbf{P}} = \mathbf{F} + \left\{ -\frac{1}{J} + \frac{1}{N\Omega} \left[ \frac{1}{J} + \log \left( \frac{J - 1}{J} \right) + \frac{\chi}{J^2} - \tilde{\mu} \right] \right\} J \mathbf{F}^{-T}$$

Normalization of concentration

$$C = \frac{(\det \mathbf{F} - 1)}{\Omega}$$
$$\frac{\tilde{C}}{\Omega} = \frac{(\det \mathbf{F} - 1)}{\Omega}$$
$$\tilde{C} = \det \mathbf{F} - 1 = J - 1$$

## 3.1 Normalization of Weak Forms

$$\int \bar{\mathbf{P}} \cdot \bar{\nabla} \delta \boldsymbol{\varphi} dS - \int \bar{\mathbf{b}}_{\mathbf{o}} \cdot \delta \boldsymbol{\varphi} dS = 0$$

$$\int \tilde{\mathbf{P}} H N k_B T \cdot \bar{\nabla} \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} H^2 - \int \tilde{\mathbf{b}}_{\mathbf{o}} N k_B T \cdot \delta \tilde{\boldsymbol{\varphi}} H d\tilde{S} H^2 = 0$$

$$\int \tilde{\mathbf{P}} \Omega N k_B T \cdot \bar{\nabla} \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} - \int \tilde{\mathbf{b}}_{\mathbf{o}} N k_B T \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} \Omega = 0$$

$$N \Omega k_B T \left[ \int \tilde{\mathbf{P}} \cdot \bar{\nabla} \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} \right] = 0$$

$$\int \mathbf{P} \cdot \nabla \delta \boldsymbol{\varphi} dV - \int \mathbf{b}_{\mathbf{o}} \cdot \delta \boldsymbol{\varphi} dV = 0$$

$$\int \tilde{\mathbf{P}} N k_B T \cdot \nabla \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} \Omega - \int \tilde{\mathbf{b}}_{\mathbf{o}} \frac{N k_B T}{H} \cdot \delta \tilde{\boldsymbol{\varphi}} H d\tilde{V} \Omega = 0$$

$$\int \tilde{\mathbf{P}} N \Omega k_B T \cdot \nabla \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} - \int \tilde{\mathbf{b}}_{\mathbf{o}} N \Omega k_B T \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} = 0$$

$$N \Omega k_B T \left[ \int \tilde{\mathbf{P}} \cdot \nabla \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} \right] = 0$$

Combine

$$N\Omega k_B T \left[ \int \tilde{\mathbf{P}} \cdot \nabla \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} + \int \tilde{\mathbf{P}} \cdot \boldsymbol{\nabla} \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} \right] = 0$$

Normalize kinetic law

$$\mathbf{J} = -\frac{CD}{k_B T} \mathbf{F}^{-1} \mathbf{F}^{-T} \frac{\partial \mu}{\partial X}$$

$$= -\frac{\tilde{C}}{\Omega} \frac{D}{k_B T} \mathbf{F}^{-1} \mathbf{F}^{-T} \frac{\partial \mu}{\partial X} \quad \text{where } \tau = H^2 / D$$

$$\tilde{\mathbf{J}} = -\frac{\tilde{C}}{\Omega} \frac{H^2}{\tau k_B T} \mathbf{F}^{-1} \mathbf{F}^{-T} \frac{\partial (\tilde{\mu} k_B T)}{\partial (\tilde{X} H)}$$

$$\tilde{\mathbf{J}} = -\frac{\tilde{C}}{\Omega} \frac{H}{\tau} \mathbf{F}^{-1} \mathbf{F}^{-T} \frac{\partial \tilde{\mu}}{\partial \tilde{X}}$$
(3.1)

Using the normalized Flux equation, Eq. 3.1 in the first step

$$\int (C - C^{t}) \delta \mu dV - \int \mathbf{J} \cdot \frac{\delta \mu}{\delta X} \Delta t dV - \int i \delta \mu \Delta t dS - \int r \delta \mu \Delta t dV = 0$$

$$\int \frac{(\tilde{C} - \tilde{C}^{t})}{\Omega} \delta \tilde{\mu} k_{B} T d\tilde{V} \Omega - \int \tilde{\mathbf{J}} \cdot \frac{\delta (\tilde{\mu} k_{B} T)}{\delta \tilde{X} H} \Delta \tilde{t} \tau d\tilde{V} \Omega - \int \frac{\tilde{i}}{H^{2} \tau} \delta \tilde{\mu} k_{B} T \Delta \tilde{t} \tau d\tilde{S} H^{2} - \int \frac{\tilde{r}}{\Omega \tau} \delta \tilde{\mu} k_{B} T \Delta \tilde{t} \tau d\tilde{V} \Omega = 0$$

$$k_{B} T \int (\tilde{C} - \tilde{C}^{t}) \delta \tilde{\mu} d\tilde{V} - k_{B} T \int \tilde{\mathbf{J}} \cdot \frac{\delta \tilde{\mu}}{\delta \tilde{X}} \Delta \tilde{t} \frac{\tau}{H} \Omega d\tilde{V} - k_{B} T \int \tilde{i} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{S} - k_{B} T \int \tilde{r} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{V} = 0$$

$$k_{B} T \left[ \int (\tilde{C} - \tilde{C}^{t}) \delta \tilde{\mu} d\tilde{V} + \int \frac{\tilde{C}}{\Omega} \frac{H}{\tau} \mathbf{F}^{-1} \mathbf{F}^{-1} \frac{\partial \tilde{\mu}}{\partial \tilde{X}} \cdot \frac{\delta \tilde{\mu}}{\delta \tilde{X}} \Delta \tilde{t} \frac{\tau}{H} \Omega d\tilde{V} - \int \tilde{i} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{S} - \int \tilde{r} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{V} \right] = 0$$

$$k_{B} T \left[ \int (\tilde{C} - \tilde{C}^{t}) \delta \tilde{\mu} d\tilde{V} + \int \tilde{C} \mathbf{F}^{-1} \mathbf{F}^{-1} \frac{\partial \tilde{\mu}}{\partial \tilde{X}} \cdot \frac{\delta \tilde{\mu}}{\delta \tilde{X}} \Delta \tilde{t} d\tilde{V} - \int \tilde{i} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{S} - \int \tilde{r} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{V} \right] = 0$$

Combine two equations and divide by  $N\Omega k_B T$ , leaving the final normalized weak form

$$\frac{1}{N\Omega} \left[ \int (\tilde{C} - \tilde{C}^t) \delta \tilde{\mu} d\tilde{V} + \int \tilde{C} \mathbf{F}^{-1} \mathbf{F}^{-\mathbf{T}} \frac{\partial \tilde{\mu}}{\partial \tilde{X}} \cdot \frac{\delta \tilde{\mu}}{\delta \tilde{X}} \Delta \tilde{t} d\tilde{V} - \int \tilde{i} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{S} - \int \tilde{r} \delta \tilde{\mu} \Delta \tilde{t} d\tilde{V} \right] = 0$$

$$\int \tilde{\mathbf{P}} \cdot \nabla \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} + \int \tilde{\mathbf{P}} \cdot \boldsymbol{\nabla} \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{S} - \int \tilde{\mathbf{b}}_{\mathbf{o}} \cdot \delta \tilde{\boldsymbol{\varphi}} d\tilde{V} = 0$$

where the previous time step is  $\tilde{C}^t$ 

### 4 Initial Conditions

## 4.1 Initial Condition for Chemical Potential without Surface Tension

Initially stress free gel:

$$\begin{split} \tilde{S} &= F_{iJ} + \left\{ -\frac{1}{\det \mathbf{F}} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \tilde{\mu} \right] \right\} \det \mathbf{F} F_{iJ}^{-T} = 0 \\ &F_{iJ} - F_{iJ}^{-T} + \frac{1}{N\Omega} \left[ \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} - \tilde{\mu} \right] \det \mathbf{F} F_{iJ}^{-T} = 0 \\ &F_{iJ} - F_{iJ}^{-T} + \frac{1}{N\Omega} \left[ F_{iJ}^{-T} + \det \mathbf{F} F_{iJ}^{-T} \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{\det \mathbf{F}} F_{iJ}^{-T} \right] = \tilde{\mu} \frac{1}{N\Omega} \det \mathbf{F} F_{iJ}^{-T} \\ &\frac{N\Omega}{\det \mathbf{F} F_{iJ}^{-T}} \left( F_{iJ} - F_{iJ}^{-T} \right) + \frac{1}{\det \mathbf{F} F_{iJ}^{-T}} \left[ F_{iJ}^{-T} + \det \mathbf{F} F_{iJ}^{-T} \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{\det \mathbf{F}} F_{iJ}^{-T} \right] = \tilde{\mu} \\ &\frac{N\Omega}{\det \mathbf{F} F_{iJ}^{-T}} \left( F_{iJ} - F_{iJ}^{-T} \right) + \frac{1}{\det \mathbf{F}} + \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) + \frac{\chi}{(\det \mathbf{F})^2} = \tilde{\mu} \quad \text{where } \det \mathbf{F} = \lambda_o^3 \\ &N\Omega \frac{\lambda_o}{\lambda_o^3} \left( \lambda_o - \frac{1}{\lambda_o} \right) + \frac{1}{\lambda_o^3} + \log \left( \frac{\lambda_o^3 - 1}{\lambda_o^3} \right) + \frac{\chi}{\lambda_o^6} = \tilde{\mu} \end{split}$$

This gives the initial normalized chemical potential

$$\tilde{\mu} = N\Omega \left( \frac{1}{\lambda_o} - \frac{1}{\lambda_o^3} \right) + \frac{1}{\lambda_o^3} + \log \left( \frac{\lambda_o^3 - 1}{\lambda_o^3} \right) + \frac{\chi}{\lambda_o^6}$$

#### 4.2 Initial Condition for Chemical Potential with Surface Tension

Paper Reference: Elatocapillarity: Surface Tension and the Mechanics of Soft Solids by Style, Jagota, Hui, and Dufresne.

The essential idea is a connection between surface stress and bulk stress at the interface. The governing interfacial equation is a condition for static equilibrium.

$$\int_{S} \sigma_{1} \cdot \mathbf{n} dS - \int_{S} \boldsymbol{\sigma}_{2} \cdot \mathbf{n} dS + \oint_{C} \boldsymbol{\Upsilon} \cdot \mathbf{b} dl = 0$$

Using the surface divergence theorem, we can obtain the generalization of Laplace's Law

$$\boldsymbol{\sigma} \cdot \mathbf{n} + \tilde{\boldsymbol{\nabla}} \cdot \boldsymbol{\Upsilon} = 0 \quad \text{Assume surface stress is isotropic}$$

$$\boldsymbol{\sigma} \cdot \mathbf{n} + \tilde{\boldsymbol{\nabla}} \cdot (\gamma \mathbf{I}) = 0$$

$$\boldsymbol{\sigma} \cdot \mathbf{n} + \gamma \tilde{\boldsymbol{\nabla}} \cdot \mathbf{I} = 0$$

$$\boldsymbol{\sigma} \cdot \mathbf{n} + \gamma (\tilde{\boldsymbol{\nabla}} \cdot \mathbf{n}) \mathbf{n} = 0$$

$$\boldsymbol{\sigma} \cdot \mathbf{n} + \gamma \kappa \mathbf{n} = 0$$

Written in spherical coordinates

$$\begin{bmatrix} \sigma_{rr} & 0 & 0 \\ 0 & \sigma_{\theta\theta} & 0 \\ 0 & 0 & \sigma_{\varphi\varphi} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \gamma\kappa \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\sigma_{rr} + \gamma\kappa = 0$$

What is  $\kappa$  in the case of a sphere?

Principal/Mean : 
$$\kappa = \frac{1}{r}$$
  
Gaussian :  $\kappa = \frac{1}{r^2}$ 

Here we use two times the mean curvature

$$\sigma_r = -\frac{2\gamma}{r_{out}} \text{ where } \lambda_r = \frac{r_{out}}{R_{out}} \to r_{out} = \lambda_r R_{out}$$

$$\sigma_r = -\frac{2\gamma}{\lambda_r R_{out}} \text{ where } R_{out} = 1.0$$

$$\sigma_r = -\frac{2\gamma}{\lambda}$$

Another way to think about this derivation is in terms of the Young-Laplace Equation, where we have two mediums  $\alpha$  and  $\beta$ .

$$\gamma = (P^{\beta} - P^{\alpha}) \frac{\partial V^{\beta}}{\partial A^{\beta}}$$

The volume and surface area of a sphere are given as:

Volume: 
$$V^{\beta} = \frac{4}{3}\pi r^3$$
  
Surface Area:  $A^{\beta} = 4\pi r^2$ 

Therefore

$$\gamma = (P^{\beta} - P^{\alpha})^{\frac{r}{2}}$$
$$\frac{2\gamma}{r} = \Delta P$$

The constitutive expression given is (spherical coordinates)

$$\sigma_i = \frac{\lambda_i}{J} \frac{\partial}{\partial \lambda_i} U_e + \frac{d}{dJ} U_m - \frac{\mu}{\Omega}$$
$$\sigma_r = \frac{\lambda_r}{J} \frac{\partial}{\partial \lambda_r} U_e + \frac{d}{dJ} U_m - \frac{\mu}{\Omega}$$

Free energy due to stretching (Flory, 1953) and mixing:

$$U_e(\mathbf{F}) = \frac{1}{2} N k_B T \left[ F_{iK} F_{iK} - 3 - 2 \log(\det \mathbf{F}) \right]$$

$$U_e(\lambda_r, \lambda_\theta, \lambda_\varphi) = \frac{1}{2} N k_B T \left[ \lambda_r^2 + \lambda_\theta^2 + \lambda_\varphi^2 - 3 - 2 \log(\lambda_r \lambda_\theta \lambda_\varphi) \right]$$

$$U_m(\mathbf{F}) = \frac{k_B T}{\Omega} \left[ (\det \mathbf{F} - 1) \log \left( \frac{\det \mathbf{F} - 1}{\det \mathbf{F}} \right) - \frac{\chi}{\det \mathbf{F}} \right]$$
$$U_m(J) = \frac{k_B T}{\Omega} \left[ (J - 1) \log \left( \frac{J - 1}{J} \right) - \frac{\chi}{J} \right]$$

Calculate the derivatives

$$\frac{\partial U_e}{\partial \lambda_r} = \frac{1}{2} N k_B T \frac{\partial}{\partial \lambda_r} \left[ \lambda_r^2 + \lambda_\theta^2 + \lambda_\varphi^2 - 3 - 2 \log(\lambda_r \lambda_\theta \lambda_\varphi) \right] 
= \frac{1}{2} N k_B T \left[ 2 \lambda_r - 2 \frac{\lambda_\theta \lambda_\varphi}{\lambda_r \lambda_\theta \lambda_\varphi} \right] 
\frac{\partial U_e}{\partial \lambda_r} = N k_B T \left[ \lambda_r - \frac{1}{\lambda_r} \right] 
\frac{dU_m}{\partial \lambda_r} = \frac{k_B T}{2} \frac{d}{\lambda_r} \left[ (J - 1) \log \left( \frac{J - 1}{\lambda_r} \right) - \frac{\chi}{2} \right]$$

$$\frac{dU_m}{dJ} = \frac{k_B T}{\Omega} \frac{d}{dJ} \left[ (J - 1) \log \left( \frac{J - 1}{J} \right) - \frac{\chi}{J} \right]$$

$$\frac{dU_m}{dJ} = \frac{k_B T}{\Omega} \left[ \frac{1}{J} + \log \left( 1 - \frac{1}{J} \right) + \frac{\chi}{J^2} \right]$$

Substitute into constitutive relationship:

$$\begin{split} \sigma_r &= \frac{\lambda_r}{J} \frac{\partial}{\partial \lambda_r} U_e + \frac{d}{dJ} U_m - \frac{\mu}{\Omega} \\ \sigma_r &= N k_B T \frac{\lambda_r}{J} \left[ \lambda_r - \frac{1}{\lambda_r} \right] + \frac{k_B T}{\Omega} \left[ \frac{1}{J} + \log \left( 1 - \frac{1}{J} \right) + \frac{\chi}{J^2} \right] - \frac{\mu}{\Omega} \\ \tilde{\sigma}_r N k_B T &= N k_B T \frac{\lambda_r}{J} \left[ \lambda_r - \frac{1}{\lambda_r} \right] + \frac{k_B T}{\Omega} \left[ \frac{1}{J} + \log \left( 1 - \frac{1}{J} \right) + \frac{\chi}{J^2} \right] - \frac{\tilde{\mu} k_B T}{\Omega} \\ \tilde{\sigma}_r &= \frac{1}{\lambda_r} - \frac{1}{\lambda_r^3} + \frac{1}{N\Omega} \left[ \frac{1}{\lambda_r^3} + \log \left( 1 - \frac{1}{\lambda_r^3} \right) + \frac{\chi}{\lambda_r^6} \right] - \frac{\tilde{\mu}}{N\Omega} \\ \frac{\tilde{\mu}}{N\Omega} &= \frac{1}{\lambda_r} - \frac{1}{\lambda_r^3} + \frac{1}{N\Omega} \left[ \frac{1}{\lambda_r^3} + \log \left( 1 - \frac{1}{\lambda_r^3} \right) + \frac{\chi}{\lambda_r^6} \right] - \tilde{\sigma}_r \\ \tilde{\mu} &= N\Omega \left( \frac{1}{\lambda_r} - \frac{1}{\lambda_r^3} \right) + \frac{1}{\lambda_r^3} + \log \left( 1 - \frac{1}{\lambda_r^3} \right) + \frac{\chi}{\lambda_r^6} - N\Omega \tilde{\sigma}_r \quad \text{Substitute } \sigma_r = -\frac{2\gamma}{\lambda_r} \\ \tilde{\mu} &= N\Omega \left( \frac{1}{\lambda_r} - \frac{1}{\lambda_r^3} \right) + \frac{1}{\lambda_r^3} + \log \left( 1 - \frac{1}{\lambda_r^3} \right) + \frac{\chi}{\lambda_r^6} + N\Omega \frac{2\gamma}{\lambda_r} \end{split}$$

## 5 Length-Scales

#### 5.1 Elastocapillary Length Scale

Refer to the paper *Elastocapillarity: Surface Tension and the Mechanics of Soft Solids* by Style, Jagota, Hui, and Dufresne

The length scale is given by:

$$l_e = \frac{\gamma}{G_0} \tag{5.1}$$

where in Bouklas and Huang

$$G_0 = \frac{Nk_BT}{\lambda_0} \qquad G_\infty = \frac{Nk_BT}{\lambda_\infty^f}$$

The elastocapillary number (dimensionless) is defined with the curvature

$$n_{ec} = \frac{\gamma \kappa}{G_0} \tag{5.2}$$

Considering instantaneous length scale, we can derive the elastocapillary length scale with respect to the constants we define:

$$l_e = \frac{\gamma}{G_0}$$

$$l_e = \frac{\gamma \lambda_0}{Nk_B T}$$

where the normalization for the surface energy,  $\gamma$ , is

$$\tilde{\gamma} = \frac{\gamma H^2}{k_B T}$$

 ${\bf Normalized}$ 

$$\begin{split} \tilde{l}_e &= \frac{k_B T \tilde{\gamma}}{H^2} \frac{\lambda_0}{N k_B T} \quad \text{where } H = 1 \\ \tilde{l}_e &= \frac{\tilde{\gamma} \lambda_0}{N} \end{split}$$