## Quiz week 3

Started: 20 Sep at 22:16

## **Quiz instructions**

Question 1 1 pts

Regarding minimum variance unbiased estimator (MVUE) and Cramer-Rao Lower Bound (CRLB), which of the following statement is **FALSE**.

- MVUE does not always exist. Even it exists, we may not be able to find it.
- O If an estimator exists whose variance equals the CRLB, then it must be the MVUE.
- O If no estimator has a variance that equals the CRLB, the MVUE doesn't exist.

Question 2 1 pts

The Cramer-Rao Lower Bound (CRLB) provides an lower bound on the variance of the estimate . Regarding CRLB, which of the following statement is **FALSE**.

- $\bigcirc$  In CRLB, the regularity condition is violated if the region of integration depends on the parameter  $\theta$ .
- The variance of estimator  $\mathbf{var}(\hat{\theta})$  is always larger than  $\mathcal{I}(\theta)^{-1}$ , where  $\mathcal{I}(\theta) = \mathbf{E}\Big[\frac{\partial^2 \ln p(\theta;\mathbf{x})}{\partial \theta^2}\Big]$  represents the Fisher information.
- $\bigcirc$  If the Fisher information from each single observation  $x_n$  is  $i(\theta)$ , the Fisher information from N such identical but independent observations is  $\mathcal{I}(\theta) = Ni(\theta)$ .
- $\bigcirc$  An efficient estimator  $\hat{ heta}=g(\mathbf{x})$  may be found if  $rac{\partial \ln p(\mathbf{x}; heta)}{\partial heta}=\mathcal{I}( heta)(g(x)- heta)$ .

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Question 3 1 pts

Let  $x_0, x_1, \ldots, x_{N-1}$  be IID and uniformly distributed in the interval [0, A], i.e.,  $x_n \sim \operatorname{Uniform}(0, A)$ . The unknown parameter A determines the length of the interval. The PDF of the observations is

$$p(\mathbf{x};A) = egin{cases} rac{1}{A^N}, & ext{for } 0 \leq x_n \leq A & n = 0,1,\dots N-1, \ 0, & ext{else}. \end{cases}$$

Check whether the CRLB for an estimate of A exists and if so, calculate it.

- $\bigcirc \operatorname{Var}(g(\mathbf{x})) \geq rac{N}{A^2}$
- $\bigcirc \operatorname{Var}(g(\mathbf{x})) \geq rac{N^2}{A^2}$
- $\bigcirc \ \mathrm{Var}(g(\mathbf{x})) \geq -rac{N}{A^2}$

Question 4 1 pts

Which of the following statements about the maximum likelihood estimator is FALSE?

- The maximum likelihood is asymptotically unbiased.
- O If the likelihood function has a maximum, it is unique.
- The maximum likelihood estimator is the value of  $\theta$  that maximized the likelihood function  $p(\mathbf{x}; \theta)$  for a given observation  $\mathbf{x}$ .
- O If an efficient estimator exists, it is also the maximum likelihood estimator.

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Question 5 1 pts

If we observe  ${\bf N}$  independent and identically distributed samples  $x_n$  from  ${\bf Binomial}(M,q)$  distribution with the probabilities  $p(x_n;q)=\binom{M}{x_n}q^{x_n}(1-q)^{M-x_n}$ , which of the following expression correctly describes the log-likelihood function  $\ln p({\bf x};q)$ .

O There is not enough information to calculate.

$$0 \ln p(\mathbf{x};q) = \sum_{n=0}^{N-1} \ln inom{M}{x_n} + \ln rac{q}{1-q} \sum_{n=0}^{N-1} x_n + \ln (1-q) M N$$

$$\log \ln p(\mathbf{x};q) = \sum_{n=0}^{N-1} \ln inom{M}{x_n} + \ln rac{1-q}{q} \sum_{n=0}^{N-1} x_n + \ln (1-q) MN$$

$$egin{aligned} igcip & \ln p(\mathbf{x};q) = \sum_{n=0}^{N-1} \ln inom{M}{x_n} + \ln rac{q}{1-q} \sum_{n=0}^{N-1} x_n + \ln(q)(M-1)N \end{aligned}$$

Question 6 1 pts

Continue with above question, which of the following expression is the correct maximum likelihood estimate of q.

$$igcap \hat{q}_{ ext{ML}} = rac{\sum_{n=0}^{N-1} x_n}{MN}$$

$$\bigcirc \hat{q}_{ ext{ML}} = rac{\sum_{n=0}^{N-1} x_n}{MN-1}$$

There is not enough information to calculate.

$$\hat{q}_{ ext{ML}} = rac{\sum_{n=0}^{N-1} x_n}{M(N-1)}$$

$$\hat{q}_{ ext{ML}} = rac{\sum_{n=0}^{N-1} x_n}{(M-1)N}$$

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Question 7	1 pts
Regarding efficient estimators for linear models, v	which of the following statement is
○ The efficient estimator is available when the signal n	nodel is linear.
$\bigcirc$ If the model is linear with additive white Gaussian no estimate is proportional to $\sigma^2$ .	oise of variance $oldsymbol{\sigma^2}$ , the covariance of the
When colored Gaussian noise is added to the linear	signal model, the noise covariance of . Here, <b>C</b> is the covariance matrix of the

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