# Data Stream Algorithms I

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#### Overview

- The data stream model
- Finding frequent items
- The MAJORITY problem
- The FREQUENT problem

- Many data generation processes can be modeled as data streams
  - Huge numbers of simple pieces of data
  - Arriving at enormous rates
  - Taken together lead to a complex whole
- Hundreds of gigabytes per day or higher!

- Sequence of queries posed to an Internet search engine
- Collection of transactions across all branches of a supermarket chain
- Sequence of packets in network traffic monitoring

. . .

- Such data may be archived and indexed within a data warehouse
- BUT, it may also be important to process it "as it happens"
- Up to the minute analysis and statistics on current trends

Quick response to each new piece of information

 Resources used very small when compared to the total quantity of data

# The streaming model

- Data arrives in a streaming fashion
  - Scan the sequence in the given order
  - No random access to the data tokens!
- Must be processed on the fly!
- Accurate computations

#### The streaming model

- Compute some function Φ(σ) of a massively long input stream σ
- Make just one pass over σ!
- Goal:
  - Use resources (space and time) sublinear on the size of the input!

### The streaming model

- When to produce output ?
- At the end of the stream
- When queried on the stream prefix observed so far
- Whenever there is a stream update
- On a "sliding window" of the most recent updates

#### The basic streaming model

The data stream:

$$\sigma = \langle a_1, a_2, \dots, a_m \rangle$$

Each data token a
 is drawn from a set of n
 elements

- Goal:
  - Process σ using a small amount of memory s
  - I.e., make s much smaller than m and n!

### The quality of an algorithm's answer

- ullet  $\Phi(\sigma)$  is usually a real-valued function
- Allow for
  - $\Box$  Computing an estimate or approximation of  $\Phi(\sigma)$
  - Possibly using randomized algorithms
    - That may err with a small, but controllable probability

How to evaluate the quality of the result ?

# The quality of an algorithm's answer

- ullet  $A(\sigma)$  is the output of a randomized algorithm
  - It is a random variable!
- (ε, δ)-approximation of  $\Phi(\sigma)$

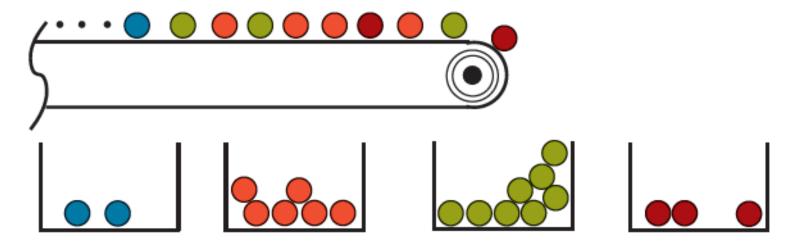
$$P\left(\left|\frac{A(\sigma)}{\Phi(\sigma)} - 1\right| > \varepsilon\right) \le \delta$$

• (ε, δ)-additive-approximation of  $\Phi(\sigma)$ 

$$P(|A(\sigma) - \Phi(\sigma)| > \varepsilon) \le \delta$$

- The frequent items / "heavy-hitters" problem
- Given a sequence of items, identify those which occur most frequently
- More formally :
- Find all items whose frequency exceeds a specified fraction of the total number of items

Figure 1. A stream of items defines a frequency distribution over items. In this example, with a threshold of  $\phi$  = 20% over the 19 items grouped in bins, the problem is to find all items with frequency at least 3.8—in this case, the green and red items (middle two bins).



[Cormode and Hadjieleftheriou]

- Network packet monitoring
  - Frequent items represent the heaviest bandwidth users
- Queries made to a search engine
  - Frequent items are the currently popular terms

\_ ...

- Counter-based algorithms
  - Track and maintain counts associated with a (varying) subset of stream items
- Sketch algorithms
  - Randomized approach
  - Do not explicitely store stream elements

Other approaches

- Given a stream:  $\sigma = \langle a_1, a_2, ..., a_m \rangle$
- It induces a frequency vector:

$$f = (f_1, f_2, ..., f_n)$$
  
 $f_1 + f_2 + ..., +f_n = m$ 

- The MAJORITY problem
  - □ If  $\exists j: f_j > \frac{m}{2}$ , then output j, otherwise output null
- The FREQUENT problem, with parameter k

- Applications ?
- Elections
- Fault-tolerant computing
  - Perform multiple redundant computations
  - Check if a majority of the results agree

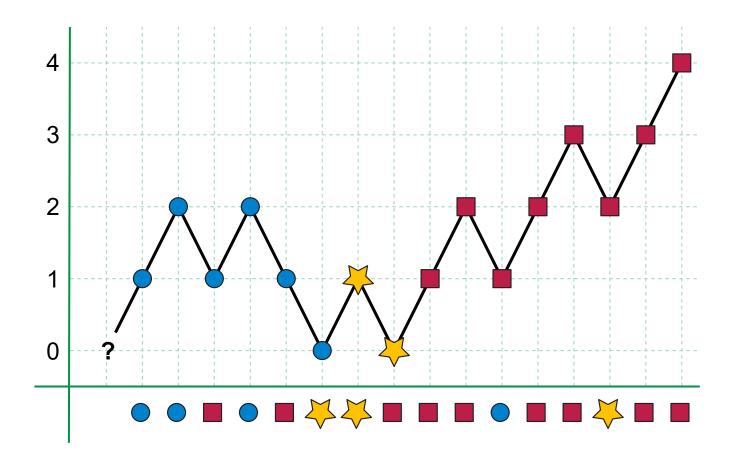
\_ ...

- Naïve algorithm for a non-sorted list of values
- Sort the list
- If there is a majority value, it is now the middle value
  - Odd vs even number of list elements
- O(n log n)
- BUT, not useful for data streams!

- Naïve algorithm
- n frequency counters
- Three-step algorithm
  - Scan the sequence and increment the counters
  - Scan the counters and find the most frequent element
  - Check if it is the majority element : > ( m / 2 )
- Efficiency?

- Boyer & Moore : A fast majority vote alg.
  - **1980**
  - http://www.cs.utexas.edu/~moore/best-ideas/mjrty/
- Provided there is such an element, it decides which sequence element is in the majority
- Two-pass algorithm
  - Scan the sequence to identify the majority candidate
  - Scan, again, the sequence, to verify if that candidate is indeed in the majority

```
// Initialization
candidate = null; counter = 0;
// First-pass
while (not end of sequence)
       x = current_token();
       if ( counter == 0 )
       then candidate = x; counter = 1;
            if ( candidate == x )
       else
              then counter++;
              else counter--;
```



[Wikipedia]

Efficiency?

- Can we skip the second pass?
  - Find a counter-example!
- O(1) extra space
- O(n) time
- BUT, we cannot perform a second pass over a data stream...
  - However, we have a "partial guarantee"

### Tasks – The MAJORITY problem

- Implement the naïve algorithm
- Implement the Boyer & Moore algorithm
- Compare their results and running times
  - For random strings over a given alphabet
- For the B & M algorithm, check how many times the majority candidate was indeed the majority

# The FREQUENT problem

- The FREQUENT problem, with parameter k
  - □ Output the set  $\{j: f_i > m/k\}$
- It solves the MAJORITY problem!

Similar naïve algorithm!

Can we do better?

#### Frequency estimation

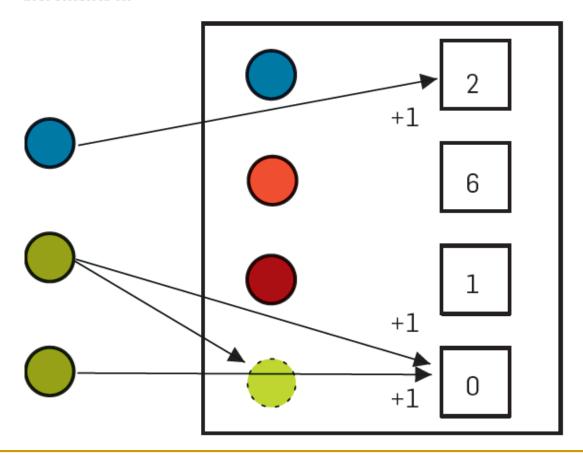
- The FREQUENCY-ESTIMATION problem
  - $\Box$  Process the stream  $\sigma$
  - Establish an estimate for the frequency of any stream token

- Misra & Gries: Finding repeated elements
  - 1982
  - http://www.sciencedirect.com/science/article/pii/0167642382900120

One-pass algorithm

- Parameter k controls the quality of the results given
- It maintains an associative array
  - The keys are tokens seen in the stream
  - Array values are counters associated with the keys / tokens
- At most (k 1) counters, at any time

Figure 2. Counter-based data structure: the blue (top) item is already stored, so its count is incremented when it is seen. The green (middle) item takes up an unused counter, then a second occurrence increments it.



[Cormode and Hadjieleftheriou]

#### **Algorithm 1**: FREQUENT(k)

 $n \leftarrow 0$ ;

```
T \leftarrow \emptyset;
foreach i do
       n \leftarrow n + 1:
       if i \in T then
         c_i \leftarrow c_i + 1;
       else if |T| < k-1 then
               T \leftarrow T \cup \{i\};
c_i \leftarrow 1;
       else forall j \in T do
               c_j \leftarrow c_j - 1;
if c_j = 0 then T \leftarrow T \setminus \{j\};
```

[Cormode and Hadjieleftheriou]

```
// Initialization
A = empty associative array;
// Processing
while ( not end of sequence )
        j = current_token();
        if ( j in keys(A) ) then A[ j ] = A[ j ] + 1;
                 if ( | keys(A) | < ( k - 1 ) ) then A[j] = 1;
        else
                      for each i in keys(A) do
                 else
                              A[i] = A[i] - 1;
                              if (A[i] == 0) then remove i from A;
// Output
if( a in keys(A) ) then freq_estimate = A[ a ];
else freq_estimate = 0;
```

The algorithm, with parameter k, provides, for any token j, a freq. estimate  $f_i^*$  satisfying

$$f_j - \frac{m}{k} \le f_j^* \le f_j$$

- If some token has f<sub>j</sub> > m / k , its counter A[ j ] will be positive
- With an additional pass through the stream, to count the exact frequencies, we can now solve the FREQUENT problem!

#### Tasks – The Misra & Gries algorithm

- Implement the naïve algorithm
- Implement the Misra & Gries algorithm
  - Choose an appropriate data structure for the associative array
- Test them, using the same input sequences as for the B & M algorithm
  - For different k values !!

#### Misra & Gries – Recap

- Finds up to (k − 1) items that occur more than a 1/k fraction of the time in the input
- Keeps, at most, (k 1) candidates at the same time
- No item with frequency m / k is missed
- Algorithm "rediscovered" twice in 2002!

#### Implementation issues

- Basic steps
  - Lookup for an item
  - Update a counter
  - Decrement all counters
  - Delete an item with zero counts

- How to ?
  - Optimize speed and space

#### Implementation issues – Lookup

- Which dictionary data structure ?
- Misra & Gries used a balanced search tree
  - Worst and average case are O(log k)
- Hash table : hash to O(k) buckets
  - Collisions / deletions : how to handle ?
  - Use chaining?
  - Optimizations?
- Other ?

#### Implementation issues – Decrement

- Iterate through all counters : O(k)
- BUT, it happens O(n/k) times
- Optimize ?
- Use a linked list of lists to keep elements grouped by their frequency counts
- Memory space overhead
  - Circular linked lists
  - Also, pointers to and from hash table

# Additional algorithms

There are other algorithms which can be regarded as variations of Misra & Gries' algorithm:

- Lossy-Counting
  - Manku and Motwani, 2002
- Space-Saving
  - Metwally et al., 2005

#### The Manku & Motwani algorithm

#### **Algorithm 2**: LossyCounting(k)

```
n \leftarrow 0: \Delta \leftarrow 0: T \leftarrow \emptyset:
foreach i do
          n \leftarrow n + 1:
         if i \in T then c_i \leftarrow c_i + 1;
          else

\begin{array}{c}
T \leftarrow T \cup \{i\}; \\
c_i \leftarrow 1 + \Delta;
\end{array}

if \lfloor n/K \rfloor \neq \Delta then
          \Delta \leftarrow \lfloor n/k \rfloor;
           forall j \in T do
              \lfloor \text{ if } c_i < \Delta \text{ then } T \leftarrow T \setminus \{j\};
```

[Cormode and Hadjieleftheriou]

## Manku & Motwani – Lossy-Counting

- Keep item names and counts
  - Counter value is a lower bound initially zero
- And an "implicit" delta value
- A new item what to do ?
- If it has a counter, increment counter
- Otherwise, initiallize with a count of 1 + delta
- Whenever delta increases :
  - Delete tuples with a count smaller than delta

## Manku & Motwani – Lossy-Counting

- Deleting tuples reduces the required space!
- Monitored items can have their frequencies overestimated by no more than n / k = ε × n

BUT never underestimated !!

## The Metwally et al. algorithm

#### **Algorithm 3**: SpaceSaving (k)

```
n \leftarrow 0:
T \leftarrow \emptyset;
foreach i do
         n \leftarrow n + 1:
          if i \in T then c_i \leftarrow c_i + 1;
         else if |T| < k then
                    T \leftarrow T \cup \{i\};
                 c_i \leftarrow 1;
       else
              j \leftarrow \operatorname{arg\ min}_{j \in T\ c_j};

c_i \leftarrow c_j + 1;

T \leftarrow T \cup \{i\} \setminus \{j\};
```

[Cormode and Hadjieleftheriou]

## Metwally et al. – Space-Saving

- Keep k=1/ε item names and counts
  - Initially zero
- Count first k items exactly!
- A new item what to do ?
- If it has a counter, increment counter
- Otherwise, replace item with least count
- And increment count

#### Metwally et al. – Space-Saving

- Counters sum to n!
- Average count value is  $n / k = \epsilon \times n$ 
  - Smallest count min cannot be larger than ε × n
- True count of an uncounted item is between
   0 and ε × n
- All items whose true count is > ε x n are stored!

#### Tasks

- Implement the Lossy-Counting and the Space-Saving algorithms
- Test them, using the same input sequences as for the M & G algorithm
- Compare the behavior of the three algorithms

#### Implementation issues

- Similar to Misra & Gries
- Finding the min item is a standard problem
  - Use a min-heap!
  - □ Binary, binomial, Fibonacci, ...?
  - O(log k)

#### Question

What can you say about the estimated counts for items which are stored by the algorithms early in the stream and are not removed?

#### Question

Have we been discussing deterministic algorithms or randomized/probabilistic algorithms?

#### Experimental comparison

- Cormode & Hadjieleftheriou
  - □ VLDB 2008 <a href="https://dl.acm.org/citation.cfm?id=1454225">https://dl.acm.org/citation.cfm?id=1454225</a>
  - □ CACM 2009 <a href="https://dl.acm.org/citation.cfm?id=1562789">https://dl.acm.org/citation.cfm?id=1562789</a>
- SPACESAVING has benefits over others!
- Very fast: 20M 30M updates per second
- Implementation choices: speed vs space
  - E.g., a heap or lists of items grouped by frequencies

#### 2017 – Recent progress

# A High-Performance Algorithm for Identifying Frequent Items in Data Streams

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#### ABSTRACT

Estimating frequencies of items over data streams is a common building block in streaming data measurement and analysis. Misra and Gries introduced their seminal algorithm for the problem in 1982, and the problem has since been revisited many times due its practicality and applicability. We describe a highly optimized version of Misra and Gries' algorithm that is suitable for deployment in industrial settings. Our code is made public via an open source library called Data Sketches that is already used by several companies and production systems.

been studied intensely [6, 7, 9, 13, 14, 17, 21, 31–35]. These algorithms process a massive dataset in a single pass, and compute very small *summaries* of the dataset, from which it is possible to derive accurate—though approximate—answers to frequent items queries and point queries.

It may seem as though streaming frequency approximation is well-understood, with little room for further insight or improvement. However, when we set about implementing an algorithm suitable for industrial use on web-scale data, we found that existing algorithms have two significant shortcomings. First, they are not

https://dl.acm.org/citation.cfm?doid=3131365.3131407

https://datasketches.github.io/

<sup>\*</sup>Research performed while at Yahoo Research.

#### References

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- G. Cormode & M. Hadjieleftheriou, Finding the frequent items in streams of data, *Commun. ACM*, Vol. 52, N. 10, 2009