

Convex Optimization

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optimization problem

- Mathematical optimization problem

$$\begin{array}{ll}\text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq b_i, \quad i = 1, \dots, m\end{array}$$

- optimization variable $\mathbf{x} = (x_1, \dots, x_n)$
- objective function $f_0: \mathbb{R}^n \rightarrow \mathbb{R}$
- (inequality) constraint functions $f_i: \mathbb{R}^n \rightarrow \mathbb{R}, i = 1, \dots, m$
- optimal or solution \mathbf{x}^*
 - ① 제약조건을 만족시키는 벡터 \mathbf{x} 중에서 objective의 값을 가장 작게 하는 벡터
 - ② for any $\mathbf{x} \in \mathbb{R}^n$ with $f_1(\mathbf{x}) \leq b_1, \dots, f_m(\mathbf{x}) \leq b_m$, we have $f_0(\mathbf{x}^*) \leq f_0(\mathbf{x})$

line

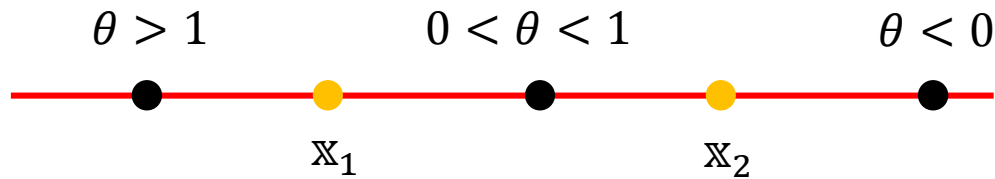
- line

- $\mathbf{x}_1 \neq \mathbf{x}_2$ and $\mathbf{x}_1, \mathbf{x}_2 \in \mathbb{R}^n$

- $\theta \in \mathbb{R}$

$$\mathbf{y} = \theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2$$

- \mathbf{y} 는 \mathbf{x}_1 과 \mathbf{x}_2 사이를 지나는 line을 만든다.



● Affine

○ $C \subseteq \mathbb{R}^n$ and C is affine,

① If the line through any two distinct points in C lies in C .

② (수학적 표현) For any $\mathbf{x}_1, \mathbf{x}_2 \in C$ and $\theta \in \mathbb{R} \Rightarrow \theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2 \in C$

○ If C is an affine set and $\mathbf{x}_1, \dots, \mathbf{x}_k \in C$ and $\theta_1 + \dots + \theta_k = 1$, then $\theta_1 \mathbf{x}_1 + \dots + \theta_k \mathbf{x}_k \in C$

● Affine hull

○ The set of all affine combinations of points in some set $C \in \mathbb{R}^n$

$$\mathbf{aff} C = \{\theta_1 \mathbf{x}_1 + \dots + \theta_k \mathbf{x}_k \mid \mathbf{x}_1, \dots, \mathbf{x}_k \in C, \theta_1 + \dots + \theta_k = 1\}$$

affine combination



convex (set)

● Convex

○ $\mathcal{C} \subseteq \mathbb{R}^n$ and \mathcal{C} is convex,

- ① If the **line segment** between any two points in \mathcal{C} lies in \mathcal{C} .
- ② (수학적) For any $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{C}$ and any θ with $0 \leq \theta \leq 1 \Rightarrow \theta \mathbf{x}_1 + (1 - \theta) \mathbf{x}_2 \in \mathcal{C}$
- ③ if and only if \mathcal{C} contains every convex combination of its points

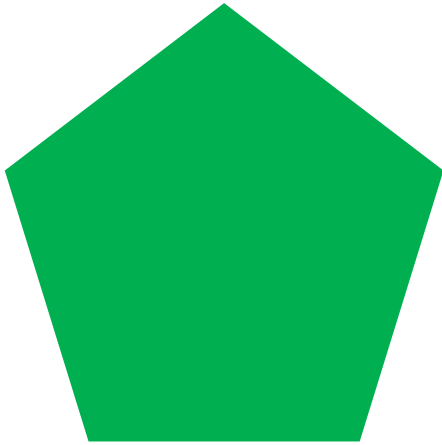
● Convex hull

○ the set of all convex combinations of points in \mathcal{C} ($i = 1, \dots, k$)

$$\mathbf{conv} \mathcal{C} = \{\theta_1 \mathbf{x}_1 + \dots + \theta_k \mathbf{x}_k \mid \mathbf{x}_i \in \mathcal{C}, \theta_i \geq 0, \theta_1 + \dots + \theta_k = 1\}$$

convex combination

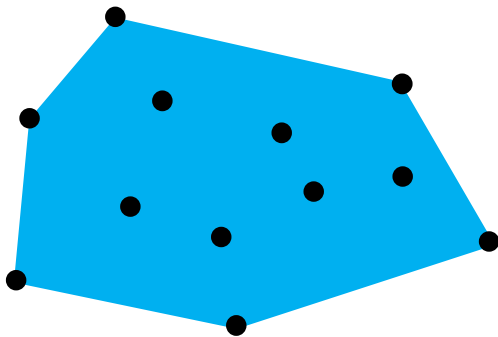




convex set



non convex set



12개 points의 convex hull



위의 non convex set의 convex hull

affine (function)

- Affine function

- a function composed of a linear function and constant (translation)

- in 1-dim

$$y = Ax + C$$

- in 2-dim

$$f(x, y) = Ax + By + C$$

- in 3-dim

$$f(x, y, z) = Ax + By + Cz + D$$

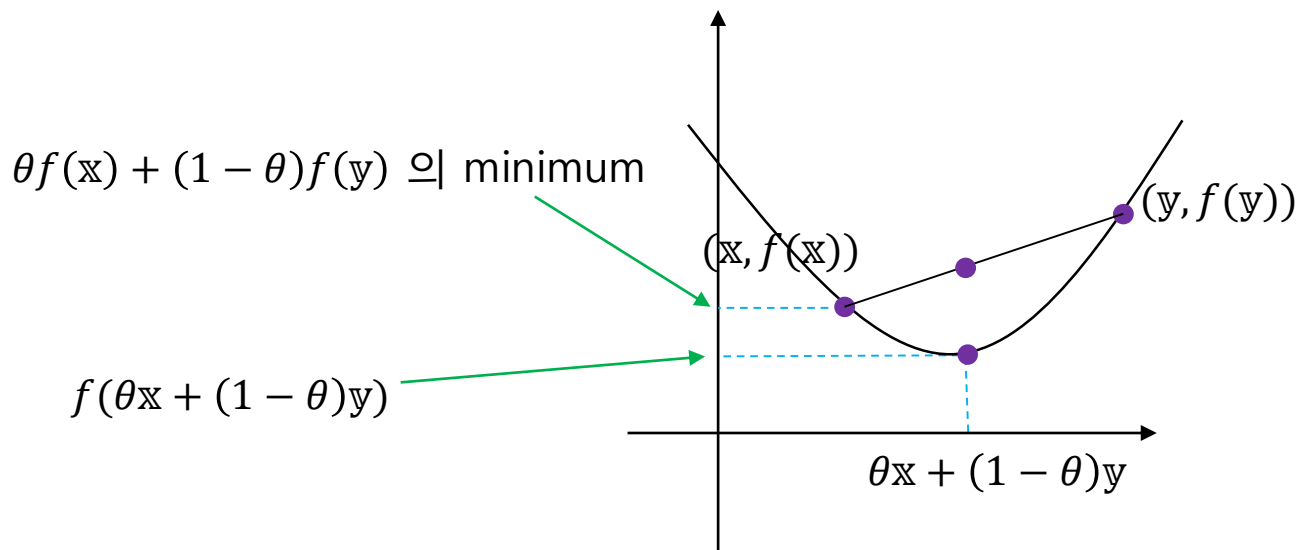
translation : a transformation consisting of a constant offset with no rotation or distortion

convex (function)

- $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if **dom** f is convex and

$$f(\theta \mathbf{x} + (1 - \theta)\mathbf{y}) \leq \theta f(\mathbf{x}) + (1 - \theta)f(\mathbf{y})$$

for $\forall \mathbf{x}, \mathbf{y} \in \mathbf{dom} f, 0 \leq \theta \leq 1$.



- f is concave if $-f$ is convex.

dom f : 함수 f 의 유효한 입력 값의 집합. 이 영역을 f 가 define되는 영역이라고도 표현 한다.

Optimization problem in standard form

- optimization problem

$$\begin{array}{ll}\text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, m \\ & h_i(\mathbf{x}) = 0, \quad i = 1, \dots, p\end{array}$$

- $\mathbf{x} \in \mathbb{R}^n$ is the optimization variable.
- $f_0: \mathbb{R}^n \rightarrow \mathbb{R}$ is the objective function or cost function.
- $f_i: \mathbb{R}^n \rightarrow \mathbb{R}, i = 1, \dots, m$, are inequality constraint functions.
- $h_i: \mathbb{R}^n \rightarrow \mathbb{R}, i = 1, \dots, p$, are equality constraint functions.
- optimal value p^*

$$p^* = \inf\{f_0(\mathbf{x}) \mid f_i(\mathbf{x}) \leq 0, i = 1, \dots, m, h_i(\mathbf{x}) = 0, i = 1, \dots, p\}$$

Optimal and locally optimal points

● optimal point

- $\mathcal{D} = (\cap_{i=1}^m \mathbf{dom} f_i) \cap (\cap_{i=1}^p \mathbf{dom} h_i)$ is domain of the optimization problem.
- A point $\mathbf{x} \in \mathcal{D}$ is feasible, if it satisfies $f_i(\mathbf{x}) \leq 0, i = 1, \dots, m$ and $h_i(\mathbf{x}) = 0, i = 1, \dots, p$.
- A feasible \mathbf{x} is optimal if $f_0(\mathbf{x}) = p^*$ (p^* is the optimal value.)
- optimal set X_{opt}

$$X_{opt} = \{\mathbf{x} \mid f_i(\mathbf{x}) \leq 0, i = 1, \dots, m, h_i(\mathbf{x}) = 0, i = 1, \dots, p, f_0(\mathbf{x}) = p^*\}$$

● locally optimal point

- A feasible \mathbf{x} is locally optimal if there is an $R > 0$ such that

$$f_0(\mathbf{x}) = \inf\{f_0(\mathbf{z}) \mid f_i(\mathbf{z}) \leq 0, i = 1, \dots, m, h_i(\mathbf{z}) = 0, i = 1, \dots, p, \|\mathbf{z} - \mathbf{x}\|_2 \leq R\}$$

Convex optimization problem in standard form

- convex optimization problem

$$\begin{array}{ll}\text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, m \\ & \mathbf{a}_i^T \mathbf{x} = b_i, \quad i = 1, \dots, p\end{array}$$

- f_0, \dots, f_m are convex.
- $h_i(\mathbf{x}) = \mathbf{a}_i^T \mathbf{x} - b_i, \quad i = 1, \dots, p$ are affine.
- The feasible set of a convex optimization problem is convex.
 - ① Since f_1, \dots, f_m are convex, $\bigcap_{i=1}^m \text{dom } f_i$ is convex.
 - ② Since $\{\mathbf{x} \mid \mathbf{a}_i^T \mathbf{x} = b_i\}$ is hyperplane, $\bigcap_{i=1}^p \{\mathbf{x} \mid \mathbf{a}_i^T \mathbf{x} = b_i\}$ is affine(i.e convex).
- In a convex optimization, we minimize a convex objective function over a convex set.

Local and global optima

- Any locally optimal point of convex optimization problem is globally optimal.
 - 증명 아이디어 : local optimal value보다 더 작은 값을 가지는 point가 존재한다고 가정할 때, local optimal의 feasible 영역에 local optimal보다 더 작은 값이 존재하는 것을 보인다.

proof)

Recall, \mathbf{x} is local optimal, then there is an $R > 0$ such that

$$f_0(\mathbf{x}) = \inf\{f_0(\mathbf{w}) \mid \mathbf{w} \text{ is feasible}, \|\mathbf{w} - \mathbf{x}\|_2 \leq R\}$$

Suppose \mathbf{x} is not globally optimal, then there is a feasible \mathbf{y} with $f_0(\mathbf{y}) < f_0(\mathbf{x})$ and $\|\mathbf{y} - \mathbf{x}\| > R$.

Consider $\mathbf{z} = (1 - \theta)\mathbf{x} + \theta\mathbf{y}$ with $\theta = \frac{R}{2\|\mathbf{y} - \mathbf{x}\|_2}$.

Then, $\|\mathbf{z} - \mathbf{x}\|_2 = \frac{R}{2} < R$ and $\theta < \frac{1}{2}$ and \mathbf{z} is feasible. (\because convexity)

So, $f_0(\mathbf{z}) = (1 - \theta)f_0(\mathbf{x}) + \theta f_0(\mathbf{y}) < f_0(\mathbf{x})$

It contradicts \mathbf{x} is local optimal.

Hence, \mathbf{x} is globally optimal.

Lagrangian

- optimization problem in standard form (not necessarily convex)

$$\begin{array}{ll}\text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, m \\ & h_i(\mathbf{x}) = 0, \quad i = 1, \dots, p\end{array}$$

- variable $\mathbf{x} \in \mathbb{R}^n$, domain $\mathcal{D} = (\cap_{i=1}^m \mathbf{dom} f_i) \cap (\cap_{i=1}^p \mathbf{dom} h_i)$, optimal value p^*
- Lagrangian $\mathcal{L}: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$, with $\mathbf{dom} \mathcal{L} = \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p$

$$\mathcal{L}(\mathbf{x}, \Lambda, V) = f_0(\mathbf{x}) + \sum_{i=1}^m \lambda_i f_i(\mathbf{x}) + \sum_{i=1}^p v_i h_i(\mathbf{x})$$

- weighted sum of objective and constraint functions
- λ_i is Lagrange multiplier associated with $f_i(\mathbf{x}) \leq 0$ and $\Lambda = (\lambda_1, \dots, \lambda_m)$
- v_i is Lagrange multiplier associated with $h_i(\mathbf{x}) = 0$ and $V = (v_1, \dots, v_p)$

Lagrange dual Function

- Lagrange dual function $g: \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$

$$g(\Lambda, V) = \inf_{\mathbf{x} \in \mathcal{D}} \mathcal{L}(\mathbf{x}, \Lambda, V) = \inf_{\mathbf{x} \in \mathcal{D}} \left(f_0(\mathbf{x}) + \sum_{i=1}^m \lambda_i f_i(\mathbf{x}) + \sum_{i=1}^p v_i h_i(\mathbf{x}) \right)$$

- g is concave. ($\because g$ is pointwise infimum of a family of affine functions of (Λ, V)) (?)
- \mathbf{x}^* 가 g 를 최소화 시키는가?

- Lower bounds on optimal value

- If $\Lambda \geq 0$, then $g(\Lambda, V) \leq p^*$
- dual feasible is a pair of (Λ, V) with $\Lambda \geq 0$ and $(\Lambda, V) \in \mathbf{dom} \, g$

Lagrange dual problem

- Lagrange dual problem

$$\begin{array}{ll}\text{maximize} & g(\Lambda, V) \\ \text{subject to} & \Lambda \succcurlyeq 0\end{array}$$

- Find lower bound on p^* , obtained from Lagrange dual function.
- Λ, V are dual feasible if $\Lambda \succcurlyeq 0$ and $(\Lambda, V) \in \mathbf{dom} \, g$
- A convex optimization problem : objective function to be maximized is concave and constraint is convex.
 - ① Concave maximization problem is readily solved by minimizing the convex objective function $-f_0$.
- d^* is the optimal value of the Lagrange dual function.

Weak and strong duality

- Weak duality : $d^* \leq p^*$

- always holds (Whether original problem is convex or not.)
- can be used to find a lower bound on the optimal value of a problem that is difficult to solve.
- duality gap is $p^* - d^*$.

- Strong duality : $d^* = p^*$

- (usually) holds for convex problem
 - ① objective function is convex.
 - ② inequality constraint is convex.
 - ③ equality constraint is affine.

Complementary slackness

- Suppose that strong duality holds, \mathbb{x}^* is primal optimal, (Λ^*, V^*) is dual optimal.

$$\begin{aligned} f_0(\mathbb{x}^*) &= g(\Lambda^*, V^*) \\ &= \inf_{\mathbb{x} \in \mathcal{D}} \left(f_0(\mathbb{x}) + \sum_{i=1}^m \lambda_i^* f_i(\mathbb{x}) + \sum_{i=1}^p v_i^* h_i(\mathbb{x}) \right) \\ \text{모두 "="} &\begin{cases} \star \leq \left(f_0(\mathbb{x}^*) + \sum_{i=1}^m \lambda_i^* f_i(\mathbb{x}^*) + \sum_{i=1}^p v_i^* h_i(\mathbb{x}^*) \right) \\ \star \leq f_0(\mathbb{x}^*) \end{cases} \end{aligned}$$

★ ○ \mathbb{x}^* minimizes $\mathcal{L}(\mathbb{x}, \Lambda^*, V^*)$

★ ○ complementary slackness : $\lambda_i^* f_i(\mathbb{x}^*) = 0$, $i = 1, \dots, m$

① $\lambda_i^* > 0 \Rightarrow f_i(\mathbb{x}^*) = 0$

② $f_i(\mathbb{x}^*) < 0 \Rightarrow \lambda_i^* = 0$

- \mathbf{x}^* is a primal optimal, (Λ^*, V^*) is a dual optimal, $d^* = p^*$ (strong duality)
 - In strong duality, \mathbf{x}^* minimize $\mathcal{L}(\mathbf{x}, \Lambda^*, V^*)$
- Then, the KKT conditions must be satisfied. (f_i, h_i : differentiable)
 - primal constraints
 - ① $f_i(\mathbf{x}^*) \leq 0, i = 1, \dots, m$
 - ② $h_i(\mathbf{x}^*) = 0, i = 1, \dots, p$
 - dual constraints
 - ① $\lambda_i^* \geq 0, i = 1, \dots, m$
 - complementary slackness
 - ① $\lambda_i^* f_i(\mathbf{x}^*) = 0, i = 1, \dots, m$
 - gradient of Lagrangian with respect to \mathbf{x} vanishes at \mathbf{x}^*
 - ① $\nabla f_0(\mathbf{x}^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(\mathbf{x}^*) + \sum_{i=1}^p v_i^* \nabla h_i(\mathbf{x}^*) = 0$

- For any optimization problem with differentiable objective and constraint functions for which strong duality obtains, any pair of primal and dual optimal points must satisfy the KKT conditions.

$$\begin{array}{ccc} \mathbb{X}^* & & \\ (\Lambda^*, V^*) & \longrightarrow & \text{KKT conditions are} \\ d^* = p^* & & \text{satisfied.} \end{array}$$

- If f_i are convex and h_i are affine and $\mathbf{x}', \Lambda', V'$ are any points that satisfy the KKT conditions, then \mathbf{x}' is primal optimal and (Λ', V') is dual optimal with zero duality gap.

$$f_i(\mathbf{x}') \leq 0, i = 1, \dots, m$$

$$h_i(\mathbf{x}') = 0, i = 1, \dots, p$$

$$\lambda'_i \geq 0, i = 1, \dots, m$$

$$\lambda'_i f_i(\mathbf{x}') = 0, i = 1, \dots, m$$

$$\nabla f_0(\mathbf{x}') + \sum_{i=1}^m \lambda'_i \nabla f_i(\mathbf{x}') + \sum_{i=1}^p v'_i \nabla h_i(\mathbf{x}') = 0$$



\mathbf{x}' is primal optimal

(Λ', V') is dual optimal

zero duality gap

Since $\mathcal{L}(\mathbf{x}, \Lambda', V')$ is convex, $g(\Lambda', V') = \inf_{\mathbf{x} \in \mathbb{R}^n} \mathcal{L}(\mathbf{x}', \Lambda', V') = \mathcal{L}(\mathbf{x}', \Lambda', V')$

