OpenMDAO Optimization Report for Problem RunOAS

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Problem: RunOAS Script: RunOAS.py

Optimizer: ScipyOptimize_SLSQP

Number of driver iterations: 183 Number of model evals: 183 Number of deriv evals: 28

Execution start time: 2025-06-04 13:38:30

Wall clock run time: 00 hours 00 minutes 03 seconds 436.4 milliseconds

Exit status: FAIL

Objectives

name	val	ref	ref0	adder	scaler	units
flight_condition_0.wing_perf.CD	[11.83626939]	0.01			100.0	

Design Variables

name	alias	size	min	max	mean	lower	upper	equals	ref	ref0	units	visual	
												0.0	10.0

alpha		1	10	(10)	10	0	10		1	0	\deg		10
												0.2	1.0
													200000000000000000000000000000000000000
wing.taper		1	(0.2)	0.2	0.2	0.2	1		1	0		0.2	
												-1 -	
wing.twist_cp		2	1	(1)	1	-1	1		None	None		0	1
				(1 1/								0.0	30.0
												************	************
wing.sweep		1	14.5	14.5	14.5	0	30		1	0	\deg	14.5	

Constraints

name	alias	size	min	max	mean	lower	upper	equals	ref	ref0	units	visual
flight_condition_0.wing_perf.CL		1	0.796	0.796	0.796			2	1	0		Both lower and upper bounds are None.

Optimizer settings

Setting	Val	Description
debug_print		List of what type of Driver variables to print at each iteration.
invalid_desvar_behavior	warn	Behavior of driver if the initial value of a design variable exceeds its bounds. The default value may be using the 'OPENMDAO_INVALID_DESVA
optimizer	SLSQP	Name of optimizer to use
tol	1e-06	Tolerance for termination. For detailed control, use solver-specific options.
maxiter	200	Maximum number of iterations.
disp	True	Set to False to prevent printing of Scipy convergence messages
singular_jac_behavior	warn	Defines behavior of a zero row/col check after first call tocompute_totals:error - raise an error.warn - raise a warning.ignore - don't perform check.
$singular_jac_tol$	1e-16	Tolerance for zero row/column check.