```
if not ret:
       break
   \# \dim = (1024, 720)
   \dim = (720, 480)
   frame = cv2.resize(frame, dim, interpolation=cv2.INTER AREA)
   # vertices = np.array(
         [[(0, 0), (0, 200), (200, 200), (200, 0)]], dtype=np.int32)
   # vertices = np.array(
         [[(50, 50), (50, 50+300), (50+300, 50+300), (50+300, 50)]],
dtype=np.int32)
   vertices = np.array(
       [[(250, 50), (250, 50+300), (250+300, 50+300), (250+300, 50)]],
dtype=np.int32)
   mask = np.zeros like(frame)
   ## cv2.fillPoly(mask, vertices, (255, 255, 255))
   cv2.fillPoly(mask, vertices, (255, 255, 255)) # BGR
   # cv2.imshow('mask', mask)
   masked frame= frame.copy()
   frame = cv2.bitwise and(frame, mask)
   # frame = cv2.resize(frame, dim, interpolation=cv2.INTER AREA)
   frame= cv2.cvtColor(frame, cv2.COLOR BGR2RGB)
   frame= cv2.cvtColor(frame, cv2.COLOR BGR2RGB)
   # frame= cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
   # frame= cv2.cvtColor(frame, cv2.COLOR GRAY2RGB)
   # Calculate the Average FPS
   frame counter += 1
   fps = (frame counter / (time.time() - start time))
   # Display the FPS
   cv2.putText(frame, 'FPS: {:.2f}'.format(
       fps), (20, 20), cv2.FONT HERSHEY SIMPLEX, 0.6, (0, 0, 255), 1)
   image= frame
   net.setInput(cv2.dnn.blobFromImage(image, 0.00392,
              (416, 416), (0, 0, 0), True, crop=False))
   outs = net.forward(output layers)
```