# Aayam K. Shrestha

idigitopia.github.io shrestaa@oregonstate.edu (+1) 541-368-8894

**NEWS:** I successfully defended my PhD in Computer Science in December 2024 - Currently working as a postdoctoral researcher with my PhD advisor as I transition to industry.

**About Me:** I enjoy solving complex AI problems through principled approaches. I am looking to join a team working towards developing sustainable and aligned AI systems with real-world impact.

## RESEARCH OVERVIEW

My research lies at the intersection of high-level reasoning and low-level control in AI systems, with a focus on building plannable representations for motion control of simulated characters and robots. I am particularly interested in applying my core RL background to digital humans and humanoid robot behaviors, enabling them to better reason and act in both virtual and real-world 3D environments.

Research Interests: Reinforcement Learning, Simulated Character control, Symbolic Planning, Robotics, Knowledge Graphs.

## **EDUCATION**

Ph.D. in Computer Science, Oregon State University [Thesis]

Advisor: Alan Fern Sept. 2018 – Dec. 2024

B.S. in Computer Engineering, Tribhuvan University

Valedictorian Aug. 2012 – Apr. 2016

#### Publications

- 1. Learning Multi-Modal Whole-Body Control for Real World Humanoid Robots Pranay Dugar, **Aayam Shrestha**, Fangzhou Yu, Alan Fern. *Under Submission ICRA 2025* [Project Page]
- 2. Learning Reconfigurable Multi-Biped Rigid Body Transport Bikram Pandit, Ashutosh Gupta, **Aayam Shrestha**, Addie, Alan Fern. CORL 2024 [Project Page]
- 3. Generating Physically Realistic and Directable Human Motions from Multi-Modal Inputs **Aayam Shrestha**\*, Pan Liu\*, Kai Yuan, German Ros, Alan Fern. *ECCV 2024* [Project Page]
- 4. Revisiting Reward Design and Evaluation for Robust Humanoid Walking Bart van Marum, **Aayam Shrestha**, Helei Duan, Alan Fern. *IROS 2024* [Project Page]
- 5. Fatored Reward Design for Page Level Widget Recommendation System **Aayam Shrestha**, Kai Yuan. *AMLC RL Workshop 2021*
- 6. DeepAveragers: Offline Reinforcement Learning by Solving Derived Non-Parametric MDPs **Aayam Shrestha**, Stefan Lee, Prasad Tadepalli and Alan Fern. *ICLR 2021* . [Project Page]
- 7. Structural Generalizability: The Case of Similarity Search Yodsawalai C., Arash T., Stephen A. R., **Aayam Shrestha**, Amy Glen, Zheng Liu SIGMOD 2021. [arXiv]

# EXPERIENCE

## Reality Labs, Meta

Los Angeles, CA

Software Engineering Intern (AI/ML Specialist)

June 2022 - Sept. 2022

- Project: Designed and implemented Upselling Module for Oculus Store. Deployed in production. (Fall 2023)
- Benchmark Results: The Averagers recommendation module extends model support for items, consummables as well as bundles for upselling. Offline evaluation demonstrated 150% improvement on suggested purchase conversion over KNN baseline.
- Research: User Journey Dataset/Modelling for in-app purchases across oculus store. Scraped and created a dataset for users journey (sequence of interactions) in order to gain insights for third party applications such as push notifications and recommendations.

Amazon Seattle, WA

Applied Scientist Intern

June 2021 - Sept. 2021

- Project: Designed and Implemented Page Level Reward for Cross-Slot Widget Ranking.
- Benchmark Results: New reward prediction model increased prediction accuration by 300% over baselines, 50% improvement for overall business metric predictions across different world regions.

# Logic Information Systems.

Blommington, MN
May 2016 - Aug. 2018

Business Intelligence Engineer

- Project: Developed and maintained large-scale enterprise Data Warehousing and Business Intelligence solutions.
- o BI Consulting: Off-shore consulting for clients Alex & Ani, Holland and Barett, Gander Mountain, and Makro.
- Research: Customer Experience Analytics over in-house data lake comprising customer call audio, text reviews, and curated twitter feeds.

# Professional

### • Invited Talks

- o Deep Non-Parametric Abstractions of Markov Decision Processes.
  - \* Microsoft Research, NYC. (2024) slides
- o The Masked Humanoid Controller for Natural Imitation of Human Behaviors.
  - \* NW Robotics Symposium, Corvallis. (2024) slides

## • Reviewing

- o Neural Information Processing Systems (NeurIPS). (2021, 2022, 2023)
- o International Conference of Representation Learning (ICLR). (2022, 2023, 2024, 2025)
- o International Conference of Machine learning (ICML). (2021, 2022, 2023, 2024)
- o AAAI Conference on Artificial Intelligence (AAAI). (2023, 2024, 2025)
- o International Conference on Intelligent Robots and Systems (IROS). (2024)
- Workshop on Reinforcement Learning Ready for Production (AAAI). (2023)

## Select Projects

- Clean VI : Hardware optimized single file implementations of Value Iteration for all popular frameworks.
- Obj2Obj GAN : Masked Image to Image translation using GANs for object inpainting. (2018)