view_frames Result

Recorded at time: 68.641

map Broadcaster: /rtabmap/rtabmap Average rate: 20.274 Hz Most recent transform: 68.694 (-0.053 sec old) Buffer length: 3.650 sec odom Broadcaster: /gazebo Average rate: 10.283 Hz Most recent transform: 68.599 (0.042 sec old) Buffer length: 3.598 sec robot_footprint Broadcaster: /camera_rotate_tf Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (68.641 sec old) Most recent transform: 0.000 (68.641 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec chassis camera Broadcaster: /robot_state_publisher Broadcaster: /gazebo Broadcaster: /gazebo Average rate: 10000.000 Hz Average rate: 20.561 Hz Average rate: 20.561 Hz Most recent transform: 0.000 (68.641 sec old) Most recent transform: 68.600 (0.041 sec old) Most recent transform: 68.600 (0.041 sec old) Buffer length: 0.000 sec Buffer length: 3.599 sec Buffer length: 3.599 sec hokuyo left_wheel right_wheel