Parallel Programming

Data-Parallel Primitives:
Split and Sort

Split and Sort

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Primitive: Split Input: R_{in}[1, ..., n], func(R_{in}[i]) \in [1, ..., F], i=1, ..., n. Output: R_{out}[1, ..., n]. Function: \{R_{out}[i], i=1, ..., n\} = \{R_{in}[i], i=1, ..., n\} and func(R_{out}[i]) \leq func(R_{out}[j]), \forall i, j \in [1, ..., n], i \leq j.
```

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Primitive: Sort 

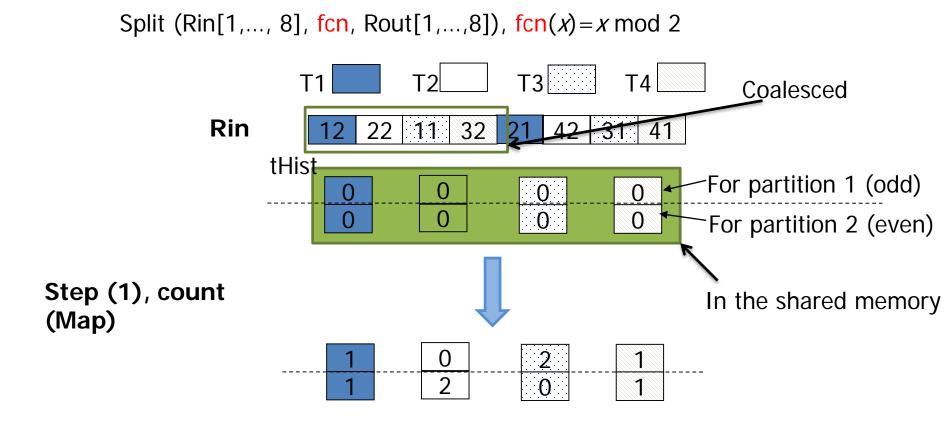
Input: R_{in}[1, ..., n]. 

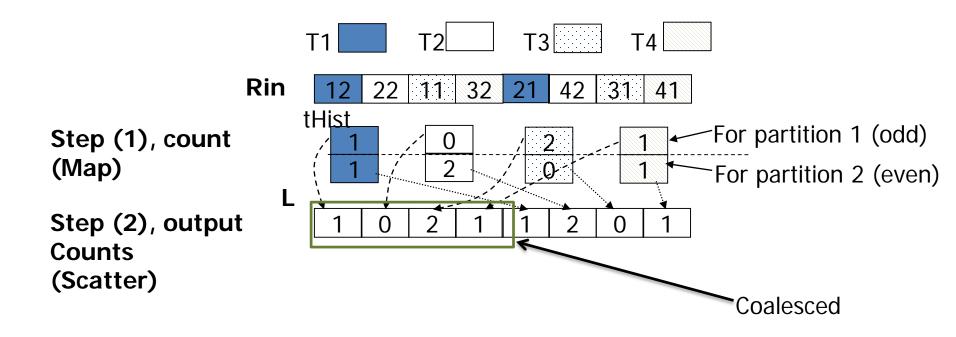
Output: R_{out}[1, ..., n]. 

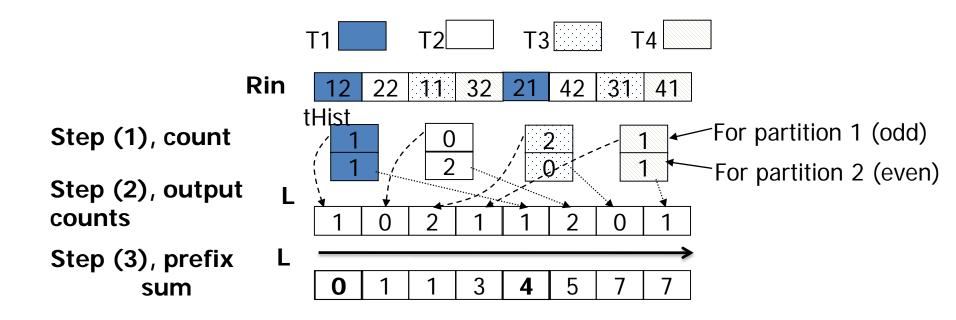
Function: \{R_{out}[i], i=1, ..., n\} = \{R_{in}[i], i=1, ..., n\} and R_{out}[i] \le R_{out}[j], \forall i, j \in [1,...,n] \text{ and } i \le j.
```

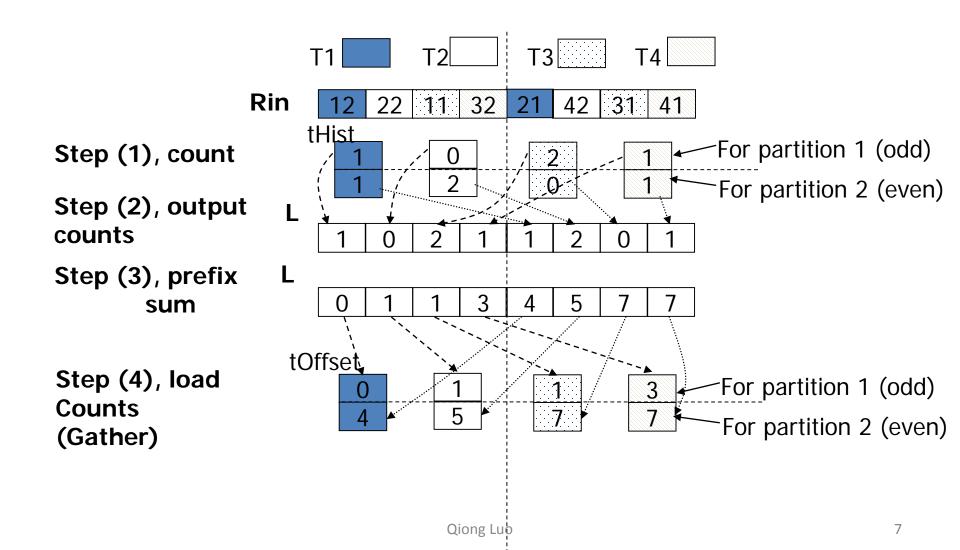
Algorithm for Split

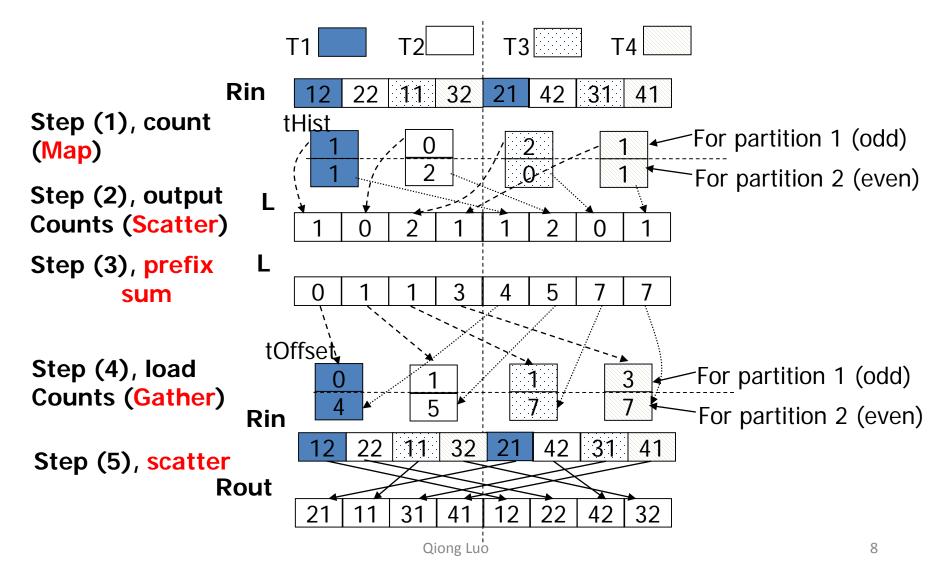
- A lock-free algorithm
 - Each thread is responsible for a portion of the input relation.
 - Each thread computes its local histogram (number of tuples in each output partition).
 - Given the local histograms, each thread computes its write locations.
 - Each thread writes the tuples to the output relation in parallel.







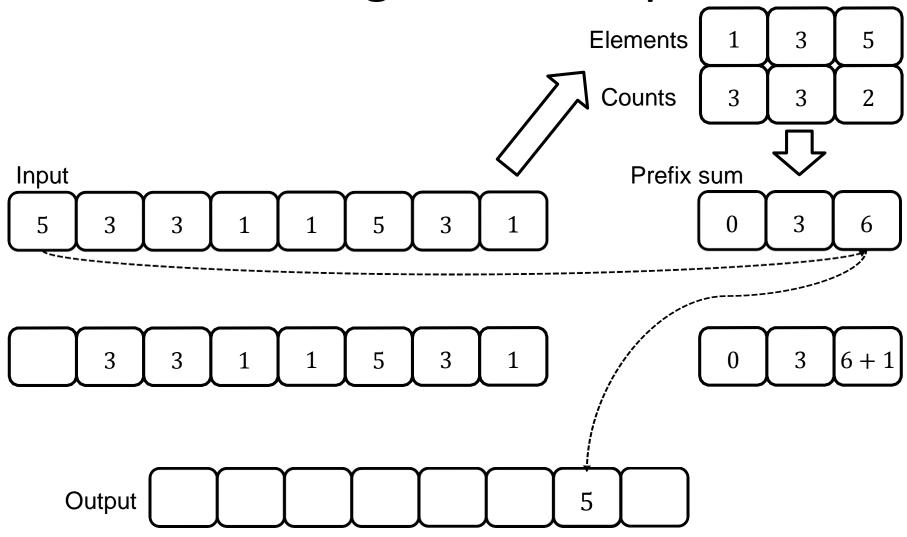




Counting Sort Algorithm

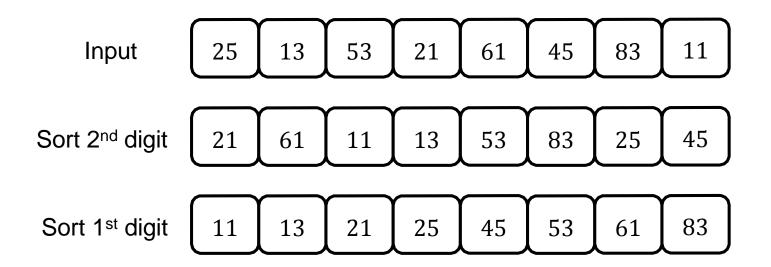
- Sorting for equality-comparison elements, e.g., integers
- Assume
 - Constant number of possible values
 - Possible values known in advance
- Algorithm outline
 - Compute the histogram of each element
 - Prefix sum over the histogram
 - Move each element to its location
- Complexity (sequential) O(n)

Counting Sort Example

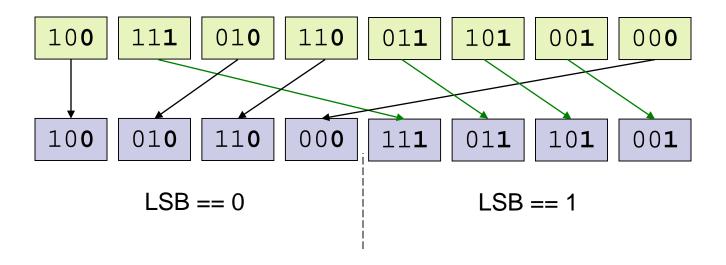


Radix Sort

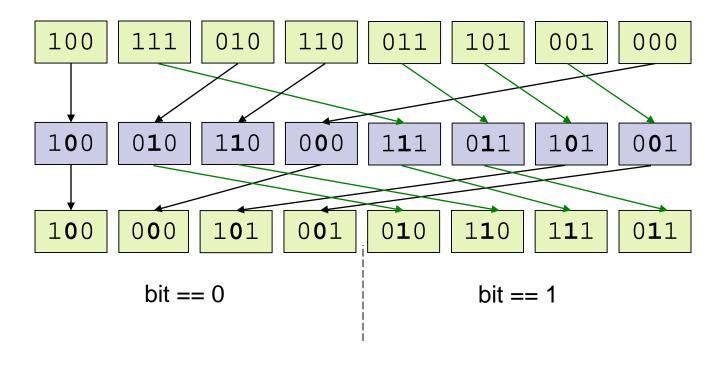
- Iterated counting sort on individual digits (radix)
- Sort from the least significant bit (LSB) to the most significant bit (MSB)



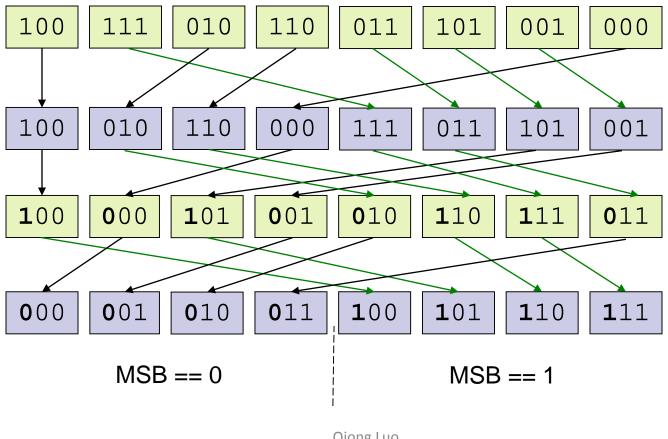
First pass: partition based on LSB



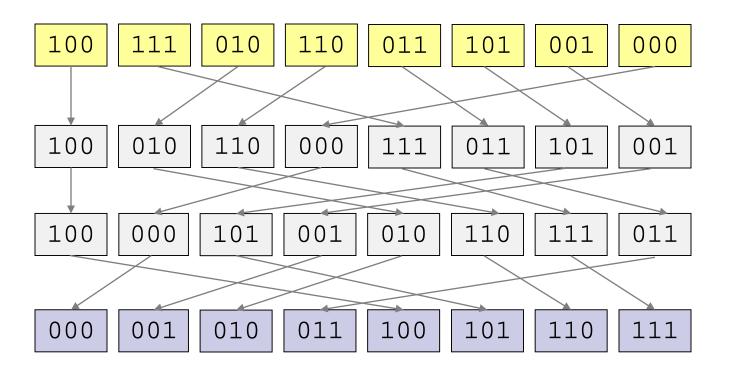
Second pass: partition based on second LSB



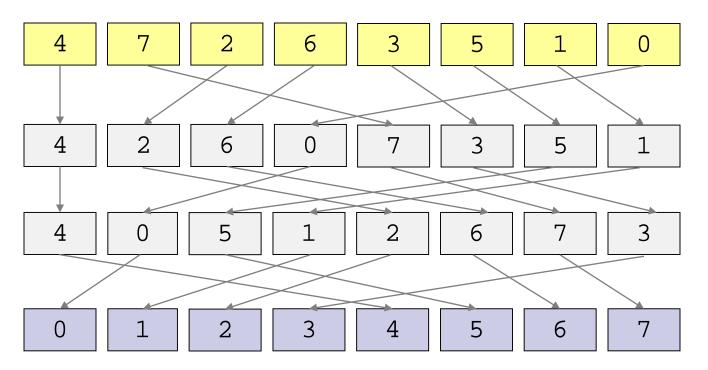
Final pass: partition based on MSB



Completed:



• Completed:



- 1. Break input array into tiles
 - Each tile fits into shared memory for a thread block
- 2. Sort tiles in *parallel* with *radix sort*
- 3. Merge pairs of tiles using a *parallel bitonic merge* until all tiles are merged.

Our focus is on Step 2

- Where is the parallelism?
 - Each tile is sorted in parallel
 - Where is the parallelism within a tile?
 - Each pass is done in sequence after the previous pass.
 No parallelism
 - Can we parallelize an individual pass? How?
 - Merge also has parallelism

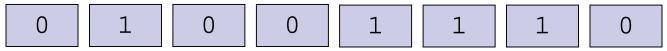
Parallel Radix Sort in Each Pass

- Implement Split on the current bit under comparison
 - Histogram-based computation to count the number of 0/1s
 - Prefix scan to determine the output position of each element.
 - Efficient scatter of elements to target locations
 - Shared memory optimization
 - Histograms are stored in the shared memory.

- Implement split. Given:
 - Array, i, at pass n:

```
100 111 010 110 011 101 001 000
```

— Array, b, which is true/false for bit n:



Output array with false keys before true keys:

```
100 010 110 000 111 011 101 001
```

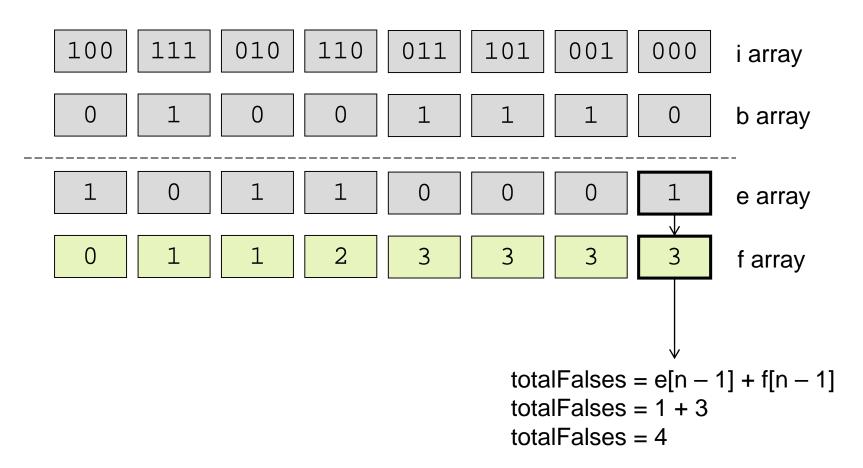
• Step 1: Compute *e* array

100	111	010	110	011	101	001	000	i array
0	1	0	0	1	1	1	0	b array
 1	0	1	1	0	0	0	1	e array

• Step 2: Exclusive Scan e

100	111	010	110	011	101	001	000	i array
0	1	0	0	1	1	1	0	b array
 1	0	1	1	0	0	0	1	e array
0	1	1	2	3	3	3	3	f array

• Step 3: Compute *totalFalses*



• Step 4: Compute *t* array

t[i] = i - f[i] + totalFalses

totalFalses = 4

• Step 4: Compute *t* array

$$t[0] = 0 - f[0] + totalFalses$$

 $t[0] = 0 - 0 + 4$

$$t[0] = 4$$

totalFalses = 4

• Step 4: Compute *t* array

$$t[1] = 1 - f[1] + totalFalses$$

 $t[1] = 1 - 1 + 4$
 $t[1] = 4$

totalFalses = 4

• Step 4: Compute *t* array

$$t[2] = 2 - f[2] + totalFalses$$

 $t[2] = 2 - 1 + 4$

$$t[2] = 5$$

totalFalses = 4

• Step 4: Compute *t* array

$$t[i] = i - f[i] + totalFalses$$

totalFalses = 4

Step 5: Scatter based on address d

100 111 010 110 011 101 001	000	i array
	0	b array
1 0 1 1 0 0	1	e array
0 1 2 3 3	3	f array
4 5 5 5 6 7	8	t array
0		d[i] = b[i] ? t[i] : f[i]

Step 5: Scatter based on address d

100	111	010	110	011	101	001	000	i array
0	1	0	0	1	1	1	0	b array
 1	0	1	1	0	0	0	1	e array
0	1	1	2	3	3	3	3	f array
4	4	5	5	5	6	7	8	t array
0	4							d[i] = b[i] ? t[i] : f[i]

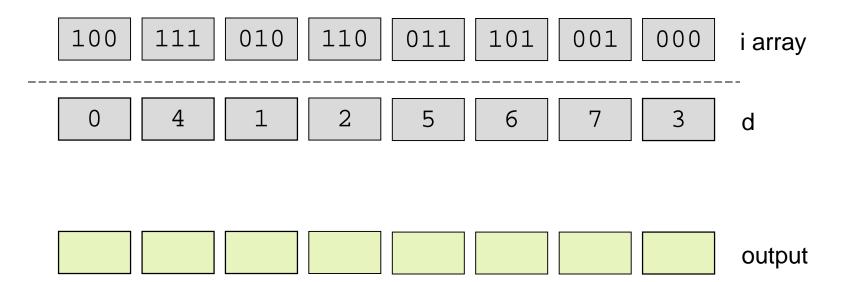
Step 5: Scatter based on address d

100 111	010 110	011 101	001 000	i array
0 1	0 0	1 1	1 0	b array
1 0	1 1	0 0	0 1	e array
0 1	1 2	3 3	3 3	f array
4	5 5	5 6	7 8	t array
0 4	1			d[i] = b[i] ? t[i] : f[i]

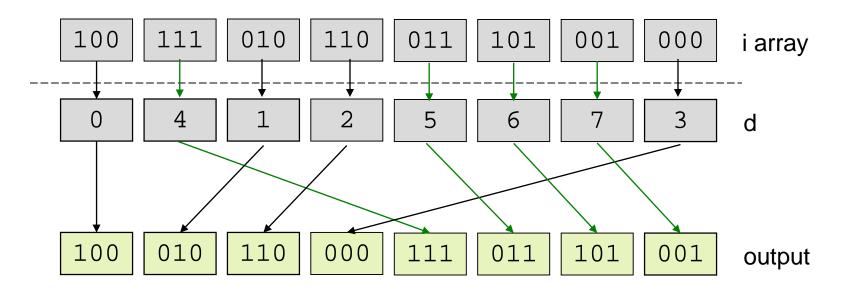
Step 5: Scatter based on address d

100	111	010	110	011	101	001	000	i array
0	1	0	0	1	1	1	0	b array
1	0	1	1	0	0	0	1	e array
0	1	1	2	3	3	3	3	f array
4	4	5	5	5	6	7	8	t array
0	4	1	2	5	6	7	3	d[i] = b[i] ? t[i] : f[i]

Step 5: Scatter based on address d



Step 5: Scatter based on address d



Radix Sort Analysis

- Integer sort
- Complexity O(kn)
 - -n number of elements
 - k number of digits (constant)
- Parallel implementation (naïve)
 - For each radix (digit)
 - Compute radix histogram
 - Scan the histogram to compute offset for each element
 - Write the sorted elements
 - Work O(kn)
 - Time $O(k \log n)$

Summary

- Split and Sort are two common data-parallel primitives.
- They can be composed using simpler primitives.
- They are used widely in higher-level applications.
- Radix sort is currently the fastest sorting algorithm on the GPU.